C5.2 Elasticity and Plasticity

Lecture 3 — Elementary Steady Solutions

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Recap

• $u = (u_i) = \text{displacement}$ $\mathcal{E} = (e_{ij}) = \text{strain tensor}$ $\mathcal{T} = (\tau_{ij}) = \text{stress tensor}$

Momentum equation

$$\rho \frac{\partial^2 \boldsymbol{u}}{\partial t^2} = \boldsymbol{\nabla} \cdot \boldsymbol{\mathcal{T}} + \rho \boldsymbol{g} \qquad \text{or} \qquad \rho \frac{\partial^2 u_i}{\partial t^2} = \frac{\partial \tau_{ij}}{\partial x_j} + \rho g_i$$

Constitutive relation (linear, isotropic)

$$\tau_{ij} = \lambda(e_{kk})\delta_{ij} + 2\mu e_{ij} = \lambda(\boldsymbol{\nabla} \cdot \boldsymbol{u})\delta_{ij} + \mu\left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i}\right)$$

Linear displacement

$$\begin{array}{l} \blacktriangleright \text{ In Cartesians: } \boldsymbol{x} = (x, y, z), \ \boldsymbol{u} = (u, v, w) \dots \\ \mathcal{T} = \lambda (\boldsymbol{\nabla} \cdot \boldsymbol{u}) \mathbb{I} + \mu \begin{pmatrix} 2\partial u/\partial x & \partial u/\partial y + \partial v/\partial x & \partial u/\partial z + \partial w/\partial x \\ \partial u/\partial y + \partial v/\partial x & 2\partial v/\partial y & \partial v/\partial z + \partial w/\partial y \\ \partial u/\partial z + \partial w/\partial x & \partial v/\partial z + \partial w/\partial y & 2\partial w/\partial z \end{pmatrix}$$

In steady state with no body force, Navier equation reduces to

$$\frac{\partial \tau_{ij}}{\partial x_j} = 0$$

Whenever u is a linear function of x, then T is constant, and the Navier equation is automatically satisfied.

Example 1 — isotropic expansion

• Consider the linear displacement $u = \frac{\alpha}{3} x = \frac{\alpha}{3} \begin{pmatrix} x \\ y \end{pmatrix}$

• Represents isotropic expansion by a factor $(1 + \alpha/3)$



- ► Relative volume change $\left(1 + \frac{\alpha}{3}\right)^3 1 \sim \alpha = \nabla \cdot \boldsymbol{u}$
- Stress tensor is isotropic as well: $\mathcal{T} = \left(\lambda + \frac{2}{3}\mu\right) \alpha \mathbb{I}$
- $K = \lambda + \frac{2}{3}\mu =$ bulk modulus measures resistance to volume change

Simple shear



• $\mu =$ shear modulus — measures resistance to shear

Unixial stretching

The linear displacement

$$\boldsymbol{u} = \alpha \begin{pmatrix} \boldsymbol{x} \\ -\nu \boldsymbol{y} \\ -\nu \boldsymbol{z} \end{pmatrix}$$

corresponds to. . .

stretch by a factor α in the *x*-direction

• shrink by a factor $\nu \alpha$ in the transverse directions.



Corresponding stress tensor (Problem Sheet 1)

$$\mathcal{T} = \alpha \begin{pmatrix} (1-2\nu)\lambda + 2\mu & 0 & 0\\ 0 & (1-2\nu)\lambda - 2\nu\mu & 0\\ 0 & 0 & (1-2\nu)\lambda - 2\nu\mu \end{pmatrix}$$



The boundary is stress free iff $0 = \tau_{yy} = \tau_{zz} = \alpha [(1 - 2\nu)\lambda - 2\nu\mu]$

i.e.
$$\nu = \frac{\lambda}{2(\lambda + \mu)}$$
 = Poisson's ratio

Stretching of a bar



When the bar stretches by a factor α , it also shrinks by a factor $\nu \alpha$ in transverse direction.

• Thermodynamic constraints $\mu > 0$ and $\lambda + \frac{2}{3}\mu > 0$ imply

$$-1 < \nu < \frac{1}{2}$$

Most "normal" solids have ν > 0, but there exist "auxetic" materials with ν < 0.</p>

e.g. cork, crumpled paper,...

Stretching of a bar



- Only remaining stress component is $\tau_{xx} = \alpha [(1 2\nu)\lambda + 2\mu]$
- Substitute for ν to get...

$$au_{xx} = E lpha$$
 i.e. Stress \propto strain

Proportionality constant $E = \frac{\mu(3\lambda + 2\mu)}{(\lambda + \mu)} =$ Young's modulus

Bending a beam

Consider the displacement
$$u = \begin{pmatrix} u \\ v \\ w \end{pmatrix} = \frac{\kappa}{2} \begin{pmatrix} -2xz \\ 2\nu yz \\ x^2 - \nu y^2 + \nu z^2 \end{pmatrix}$$

Only nonzero stress component (after some calculation!)

$$\tau_{xx} = -E\kappa z$$



Bending a beam



Q: What shape cross-section for max stiffness but min area...?