

Numerical Solution of Partial Differential Equations

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Lecture 7

Iterative solution of linear systems: linear stationary iterative methods

We require a few technical tools. Consider the eigenvalue problem:

$$\begin{aligned} -u''(x) + c u(x) &= \lambda u(x), & x \in (0, 1), \\ u(0) &= 0, & u(1) = 0, \end{aligned}$$

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$$u^k(x) := \sin(k\pi x) \quad \text{and} \quad \lambda_k := c + k^2\pi^2, \quad k = 1, 2, \dots$$

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Clearly, $c + \pi^2 \leq \lambda_k$ for all $k = 1, 2, \dots$, and $\lambda_k \rightarrow +\infty$ as $k \rightarrow +\infty$.

The finite difference approximation of this eigenvalue problem on the mesh $\{x_i : i = 0, \dots, N\}$ of uniform spacing $h = 1/N$, with $N \geq 2$, and $x_i = ih$, $i = 0, \dots, N$, is given by

$$-\frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} + c U_i = \Lambda U_i, \quad i = 1, \dots, N-1,$$
$$U_0 = 0, \quad U_N = 0.$$

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A simple calculation yields the nontrivial solution: $U_i := U^k(x_i)$ where

$$U^k(x) := \sin(k\pi x), \quad x \in \{x_0, x_1, \dots, x_N\} \quad \text{and} \quad \Lambda_k := c + \frac{4}{h^2} \sin^2 \frac{k\pi h}{2}$$

for $k = 1, 2, \dots, N-1$.

This can be verified by inserting

$$U_i = U^k(x_i) = \sin(k\pi x_i) \quad \text{and} \quad U_{i\pm 1} = U^k(x_{i\pm 1}) = \sin(k\pi x_{i\pm 1})$$

into the finite difference scheme and noting that

$$\sin(k\pi x_{i\pm 1}) = \sin(k\pi(x_i \pm h)) = \sin(k\pi x_i) \cos(k\pi h) \pm \cos(k\pi x_i) \sin(k\pi h)$$

and

$$1 - \cos(k\pi h) = 2 \sin^2 \frac{k\pi h}{2}$$

for $k = 1, 2, \dots, N - 1$ and $i = 1, 2, \dots, N - 1$.

Using matrix notation the finite difference approximation of the eigenvalue problem can be written as

$$\begin{bmatrix} \frac{2}{h^2} + c & -\frac{1}{h^2} & & & 0 \\ -\frac{1}{h^2} & \frac{2}{h^2} + c & -\frac{1}{h^2} & & \\ & \ddots & \ddots & \ddots & \\ 0 & & -\frac{1}{h^2} & \frac{2}{h^2} + c & -\frac{1}{h^2} \\ & & -\frac{1}{h^2} & \frac{2}{h^2} + c & \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ \vdots \\ U_{N-2} \\ U_{N-1} \end{bmatrix} = \Lambda \begin{bmatrix} U_1 \\ U_2 \\ \vdots \\ U_{N-2} \\ U_{N-1} \end{bmatrix},$$

or, more compactly, $AU = \Lambda U$, where A is the symmetric tridiagonal $(N - 1) \times (N - 1)$ matrix displayed above, and $U = (U_1, \dots, U_{N-1})^T$ is a column vector of size $N - 1$.

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or, more compactly, $AU = \Lambda U$, where A is the symmetric tridiagonal $(N - 1) \times (N - 1)$ matrix displayed above, and $U = (U_1, \dots, U_{N-1})^T$ is a column vector of size $N - 1$. The calculation performed above implies that the eigenvalues of the matrix A are

$$\Lambda_k = c + \frac{4}{h^2} \sin^2 \frac{k\pi h}{2}, \quad k = 1, 2, \dots, N - 1$$

and the corresponding eigenvectors are, respectively,

$$(U^k(x_1), \dots, U^k(x_{N-1}))^T, \quad k = 1, \dots, N - 1.$$

Clearly,

$$c + 8 \leq \Lambda_k \leq c + \frac{4}{h^2} \quad \text{for all } k = 1, 2, \dots, N - 1.$$

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The first of these inequalities follows by noting that

$$\Lambda_k \geq \Lambda_1 = c + \frac{4}{h^2} \sin^2 \frac{\pi h}{2} \quad \text{for } k = 1, \dots, N - 1$$

and $\sin x \geq \frac{2\sqrt{2}}{\pi}x$ for $x \in [0, \frac{\pi}{4}]$ (recall that $h \in [0, \frac{1}{2}]$ because $N \geq 2$, whereby $0 < \frac{\pi h}{2} \leq \frac{\pi}{4}$).

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The second inequality is the consequence of $0 \leq \sin x \leq 1$ for all $x \in \mathbb{R}$.

Example

Suppose that $\Omega = (0, 1)^2$, the open unit square in \mathbb{R}^2 , and consider the problem

$$\begin{aligned} -\Delta u + cu &= \lambda u && \text{in } \Omega, \\ u &= 0 && \text{on } \Gamma := \partial\Omega, \end{aligned}$$

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where $c \geq 0$ is a given real number.

Find the eigenfunctions and the associated eigenvalues for the boundary-value problem, and for the finite difference approximation of the boundary-value problem on a mesh of uniform spacing $h = 1/N$ in the x and y directions.

Solution:

$$u^{k,m}(x, y) = \sin(k\pi x) \sin(m\pi y), \quad \lambda_{k,m} = c + (k^2 + m^2)\pi^2, \quad k, m = 1, 2, \dots$$

Solution:

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The finite difference approximation of this eigenvalue problem posed on a uniform mesh $\{(x_i, y_j) : i, j = 0, \dots, N\}$ of spacing $h = 1/N$, $N \geq 2$, is:

$$\begin{aligned} -\frac{U_{i+1,j} - 2U_{i,j} + U_{i-1,j}}{h^2} - \frac{U_{i,j+1} - 2U_{i,j} + U_{i,j-1}}{h^2} + c U_{i,j} &= \Lambda U_{i,j}, & i, j = 1, \dots, N-1, \\ U_{i,j} &= 0 & \text{for } (x_i, y_j) \in \Gamma_h, \end{aligned}$$

where, Γ_h is the set of mesh-points on Γ .

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where, Γ_h is the set of mesh-points on Γ . This can be rewritten as an algebraic eigenvalue problem of the form $AU = \Lambda U$, where now A is a symmetric $(N-1)^2 \times (N-1)^2$ matrix with positive eigenvalues

$$\Lambda_{k,m} = c + \frac{4}{h^2} \left(\sin^2 \frac{k\pi h}{2} + \sin^2 \frac{m\pi h}{2} \right),$$

with $c + 16 \leq \Lambda_{k,m} \leq c + \frac{8}{h^2}$, and eigenvectors/(discrete) eigenfunctions $U_{i,j} = U^{k,m}(x_i, y_j)$, where

$$U^{k,m}(x, y) = \sin(k\pi x) \sin(m\pi y),$$

for $i, j = 1, \dots, N-1$ and $k, m = 1, \dots, N-1$. \square

Now we are ready to focus on the key questions to be addressed. Consider

$$\begin{aligned} -u''(x) + c u(x) &= f(x), & x \in (0, 1), \\ u(0) &= 0, & u(1) = 0, \end{aligned}$$

where $c \geq 0$ and $f \in C([0, 1])$.

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$$\begin{aligned} -\frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} + c U_i &= f(x_i), & i = 1, \dots, N-1, \\ U_0 &= 0, & U_N = 0. \end{aligned} \tag{1}$$

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In terms of matrix notation, we this can be rewritten as the linear system:

$$AU = F \tag{2}$$

where A is the same $(N-1) \times (N-1)$ symmetric tridiagonal matrix as in the univariate case considered above, with distinct positive eigenvalues Λ_k , $k = 1, \dots, N-1$, as above, $F = (f(x_1), \dots, f(x_{N-1}))^T$, and $U = (U_1, \dots, U_{N-1})^T$ is the associated vector of unknowns.

Similarly, if one considers the elliptic boundary-value problem

$$\begin{aligned} -\Delta u + cu &= f(x, y) && \text{in } \Omega, \\ u &= 0 && \text{on } \Gamma := \partial\Omega, \end{aligned}$$

where $c \geq 0$ is a given real number and $f \in C(\Omega)$, whose finite difference approximation posed on a uniform mesh $\{(x_i, y_j) : i, j = 0, \dots, N\}$ of spacing $h = 1/N$, $N \geq 2$, in the x and y directions, is

$$\begin{aligned} -\frac{U_{i+1,j} - 2U_{i,j} + U_{i-1,j}}{h^2} - \frac{U_{i,j+1} - 2U_{i,j} + U_{i,j-1}}{h^2} + c U_{i,j} &= f(x_i, y_j), \\ U_{i,j} &= 0 \end{aligned} \tag{3}$$

where, Γ_h is the set of mesh-points on Γ , then this, too, can be rewritten as a system of linear algebraic equations of the form $AU = F$, where now A is a symmetric $(N-1)^2 \times (N-1)^2$ matrix with positive eigenvalues, $\Lambda_{k,m}$, $k, m = 1, \dots, N-1$, given in the Example above.

Objective

Motivated by these examples, we shall be interested in developing a simple iterative method for the approximate solution of systems of linear algebraic equations of the form

$$AU = F,$$

where $A \in \mathbb{R}^{M \times M}$ is a symmetric matrix with positive eigenvalues, which are contained in a nonempty closed interval $[\alpha, \beta]$, with $0 < \alpha < \beta$, $U \in \mathbb{R}^M$ is the vector of unknowns and $F \in \mathbb{R}^M$ is a given vector.

To this end, we consider the following iteration for the approximate solution of the linear system $AU = F$:

$$U^{(j+1)} := U^{(j)} - \tau(AU^{(j)} - F), \quad j = 0, 1, \dots, \quad (4)$$

where $U^{(0)} \in \mathbb{R}^M$ is a given initial guess, and $\tau > 0$ is a parameter to be chosen so as to ensure that the sequence of iterates $\{U^{(j)}\}_{j=0}^{\infty} \subset \mathbb{R}^M$ converges to $U \in \mathbb{R}^M$ as $j \rightarrow \infty$.

We are interested in exploring the speed of convergence of this iteration.

We begin by observing that $U = U - \tau(AU - F)$. Therefore, upon subtraction of (4) from this equality we find that, for $j = 0, 1, \dots$,

$$U - U^{(j+1)} = U - U^{(j)} - \tau A(U - U^{(j)}) = (I - \tau A)(U - U^{(j)}), \quad (5)$$

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where $I \in \mathbb{R}^{M \times M}$ is the identity matrix. Consequently,

$$U - U^{(j)} = (I - \tau A)^j (U - U^{(0)}), \quad j = 1, 2, \dots$$

Recall that if $\|\cdot\|$ is a(ny) norm on \mathbb{R}^M , then the *induced matrix norm* is defined, for a matrix $B \in \mathbb{R}^{M \times M}$, by

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Thanks to this definition, $\|BV\| \leq \|B\|\|V\|$ for all $V \in \mathbb{R}^M$, and hence, by induction $\|B^j V\| \leq \|B\|^j \|V\|$ for all $j = 1, 2, \dots$ and all $V \in \mathbb{R}^M$.

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Therefore, with $B := I - \tau A$ and $V := U - U^{(0)}$, we have that

$$\|U - U^{(j)}\| = \|(I - \tau A)^j (U - U^{(0)})\| \leq \|I - \tau A\|^j \|U - U^{(0)}\|. \quad (6)$$

In order to continue, we need to bound $\|I - \tau A\|$, and to this end we need a few tools from linear algebra; we shall therefore make a brief detour.

¹Suppose that \mathcal{V} is a linear space and $\|\cdot\|_1$ and $\|\cdot\|_2$ are two norms on \mathcal{V} ; then $\|\cdot\|_1$ and $\|\cdot\|_2$ are said to be *equivalent* if there exist positive constants C_1 and C_2 such that $C_1\|V\|_1 \leq \|V\|_2 \leq C_2\|V\|_1$ for all $V \in \mathcal{V}$.

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$$\|V\| := \left(\sum_{i=1}^M V_i^2 \right)^{1/2}, \quad V = (V_1, \dots, V_M)^T \in \mathbb{R}^M.$$

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$$\|V\| = \left(\sum_{i=1}^M \alpha_i^2 \right)^{1/2} \quad \text{and} \quad \|BV\| = \left(\sum_{i=1}^M \alpha_i^2 \lambda_i^2 \right)^{1/2} .$$

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Clearly, $\|BV\| \leq \max_{i=1, \dots, M} |\lambda_i| \|V\|$ for all $V \in \mathbb{R}^M$, and the inequality becomes an equality if V is the eigenvector of B associated with the largest in absolute value eigenvalue of B .

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Clearly, $\|BV\| \leq \max_{i=1, \dots, M} |\lambda_i| \|V\|$ for all $V \in \mathbb{R}^M$, and the inequality becomes an equality if V is the eigenvector of B associated with the largest in absolute value eigenvalue of B . Therefore,

$$\|B\| = \max_{i=1, \dots, M} |\lambda_i|,$$

where now $\|\cdot\|$ is the matrix norm induced by the Euclidean norm.

We are now ready to return to (6) to find that $\|I - \tau A\|$ on the r.h.s. of (6), where again $\|\cdot\|$ denotes the matrix norm induced by the Euclidean norm, is equal to the largest in absolute value eigenvalue of the symmetric matrix $I - \tau A$.

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As the eigenvalues of A are assumed to belong to the interval $[\alpha, \beta]$, where $0 < \alpha < \beta$, and the parameter τ is by assumption positive, the eigenvalues of $I - \tau A$ are contained in the interval $[1 - \tau\beta, 1 - \tau\alpha]$, whereby

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As $\tau > 0$ is a free parameter, to be suitably chosen, we would like to select it so that the iterative method (4) converges as fast as possible, and to this end we see from (6) that it is desirable to choose τ so that $\|I - \tau A\|$ is as small as possible, and less than 1.

We are now ready to return to (6) to find that $\|I - \tau A\|$ on the r.h.s. of (6), where again $\|\cdot\|$ denotes the matrix norm induced by the Euclidean norm, is equal to the largest in absolute value eigenvalue of the symmetric matrix $I - \tau A$.

As the eigenvalues of A are assumed to belong to the interval $[\alpha, \beta]$, where $0 < \alpha < \beta$, and the parameter τ is by assumption positive, the eigenvalues of $I - \tau A$ are contained in the interval $[1 - \tau\beta, 1 - \tau\alpha]$, whereby

$$\|I - \tau A\| \leq \max\{|1 - \tau\beta|, |1 - \tau\alpha|\}.$$

As $\tau > 0$ is a free parameter, to be suitably chosen, we would like to select it so that the iterative method (4) converges as fast as possible, and to this end we see from (6) that it is desirable to choose τ so that $\|I - \tau A\|$ is as small as possible, and less than 1. We shall therefore seek $\tau > 0$ s.t.

$$\min_{\tau > 0} \max\{|1 - \tau\beta|, |1 - \tau\alpha|\} < 1.$$

By plotting the nonnegative piecewise linear functions

$$\tau \mapsto |1 - \tau\beta| \quad \text{and} \quad \tau \mapsto |1 - \tau\alpha|$$

for $\tau \in [0, \infty)$, we see that they vanish at $\tau = 1/\beta$ and $\tau = 1/\alpha$, respectively; their graphs intersect at $\tau = 0$ and at $\tau = \frac{2}{\alpha+\beta}$.

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Next, by plotting the continuous piecewise linear function

$$\tau \mapsto \max\{|1 - \tau\beta|, |1 - \tau\alpha|\}$$

for $\tau \in [0, \infty)$, we observe that it attains its minimum at $\tau = \frac{2}{\alpha+\beta}$ where $1 - \tau\beta = \tau\alpha - 1$.

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for $\tau \in [0, \infty)$, we observe that it attains its minimum at $\tau = \frac{2}{\alpha + \beta}$ where $1 - \tau\beta = \tau\alpha - 1$. Thus,

$$\min_{\tau > 0} \max\{|1 - \tau\beta|, |1 - \tau\alpha|\} = \max\{|1 - \tau\beta|, |1 - \tau\alpha|\}_{\tau = \frac{2}{\alpha + \beta}} = \frac{\beta - \alpha}{\beta + \alpha} < 1.$$

In summary then, the iterative method proposed for the approximate solution of the linear system $AU = F$ is the one stated in (4), with $\tau := \frac{2}{\beta + \alpha}$, and $[\alpha, \beta]$ being a closed subinterval of $(0, \infty)$ that contains all eigenvalues of the symmetric matrix $A \in \mathbb{R}^{M \times M}$.

Example

In the case of the finite difference scheme (1), $\alpha = c + 8$ and $\beta = c + \frac{4}{h^2}$, while in the case of (3), $\alpha = c + 16$ and $\beta = c + \frac{8}{h^2}$.

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In the case of the finite difference scheme (1), $\alpha = c + 8$ and $\beta = c + \frac{4}{h^2}$, while in the case of (3), $\alpha = c + 16$ and $\beta = c + \frac{8}{h^2}$. In both cases

$$\frac{\beta - \alpha}{\beta + \alpha} = 1 - \frac{2\alpha}{\beta + \alpha} = 1 - \text{Const. } h^2;$$

thus, while the sequence of iterates $\{U^{(j)}\}_{j=0}^{\infty}$ defined by the iterative method (4) is guaranteed to converge to the exact solution U of the linear system $AU = F$, the right-hand side in the inequality

$$\|U - U^{(j)}\| \leq \left(\frac{\beta - \alpha}{\beta + \alpha}\right)^j \|U - U^{(0)}\| \quad (7)$$

will gradually deteriorate as $h \rightarrow 0$.

An alternative, computable bound on the iteration error

We note that by multiplying (5) by the matrix A and recalling that $AU = F$, one has that

$$F - AU^{(j+1)} = (I - \tau A)(F - AU^{(j)}),$$

and therefore, by proceeding as above,

$$\|F - AU^{(j)}\| \leq \|I - \tau A\|^j \|F - AU^{(0)}\| \leq \left(\frac{\beta - \alpha}{\beta + \alpha}\right)^j \|F - AU^{(0)}\|. \quad (8)$$

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As α and β are available (in the case of the simple boundary-value problems considered here, at least) as are F , A and the initial guess $U^{(0)}$, it is possible to quantify the number of iterations required to ensure that the Euclidean norm of the so-called *residual* $F - AU^{(j)}$ of the j -th iterate becomes smaller than a chosen tolerance $\text{TOL} > 0$.

A sufficient condition for this is that the right-hand side of (8) is smaller than TOL, which will hold as soon as

$$j > \log \frac{\|F - AU^{(0)}\|}{\text{TOL}} \left[\log \left(\frac{\beta + \alpha}{\beta - \alpha} \right) \right]^{-1}. \quad (9)$$

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In the case of the two boundary-value problems considered above,

$$\frac{\beta - \alpha}{\beta + \alpha} = 1 - \text{Const.}h^2$$

and therefore (because $\log(1 - \text{Const.}h^2) \sim -\text{Const.}h^2$ as $h \rightarrow 0$) the right-hand side of the inequality (9) is $\sim \text{Const.}h^{-2} \log(1/\text{TOL})$.

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We see in particular that the smaller the value of the mesh-size h the larger the number of iterations j will need to be to ensure that

$$\|F - AU^{(j)}\| < \text{TOL}.$$