

Waves and Compressible Flow

Lecture 7

Travelling waves

- Last lecture: normal modes for wave equation in finite domains using separation of variables.
- This lecture: travelling harmonic waves and Fourier transforms for infinite domains.

Example: waveguide

p.2

- Acoustic waves in a 2D channel have potential $\phi(x, z, t)$ s.t.

$$\phi_z = 0 \quad z = h$$

$$\phi_{tt} = c_0^2 (\phi_{xx} + \phi_{zz})$$

$$\phi_z = 0 \quad z = 0$$

- Try travelling harmonic wave $\phi = f(z) e^{i(kx - \omega t)}$, then
 $f'' + \left(\frac{\omega^2}{c_0^2} - k^2\right) f = 0$ for $0 < z < h$; $f'(0) = f'(h) = 0$.

- Hence, $f(z) = A \cos\left(\frac{n\pi z}{h}\right)$, $\omega^2 = c_0^2 \left(k^2 + \frac{n^2 \pi^2}{h^2}\right)$, where $k \in \mathbb{R}, n \in \mathbb{Z}$.

Example: Stokes waves

p.3

- Suppose $\phi(x, z, t)$ and $\eta(x, t)$ satisfy the following linearized problem:

$\phi_z = \eta_t, \phi_t + g\eta = 0$ on $z=0$

$\phi_{xx} + \phi_{zz} = 0$ for $-h < z < 0$

$\phi_z = 0$ on $z = -h$

- Try $\eta = Ae^{i(kx - \omega t)}$, $\phi = f(z)e^{i(kx - \omega t)}$, then $f'' - k^2f = 0$ for $-h < z < 0$, with $f'(-h) = 0$, $f'(0) = -i\omega A$, $-i\omega f(0) + gA = 0$.

- Hence, $f(z) = \frac{gA}{i\omega} \frac{\cosh k(h-z)}{\cosh kh}$ and $\omega^2 = gk \tanh(kh)$

- For infinite domain problems, there is a continuous spectrum, i.e. set of allowable wavenumbers \underline{k} , with dispersion relation $\omega(\underline{k})$ say.
- Write general solution as an integral over wavenumbers, i.e. a Fourier transform.

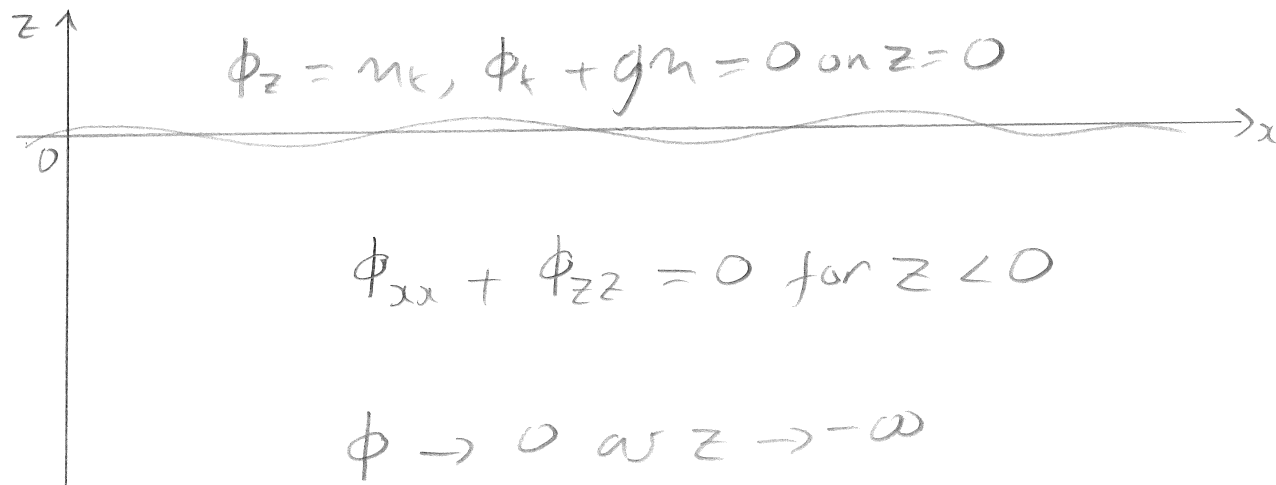
Fourier Transforms

- Recall $\hat{f}(k) = \int_{-\infty}^{\infty} f(x) e^{-ikx} dx$ (for suitably integrable f)
- Inverse: $f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{f}(k) e^{ikx} dk$
- Convolution: $\hat{f}(k) = \hat{g}(k) \hat{h}(k) \Leftrightarrow f(x) = \int_{-\infty}^{\infty} g(\xi) h(x-\xi) d\xi$
- Derivatives: $\widehat{\frac{d^n f}{dx^n}} = (ik)^n \hat{f}$

Stokes waves: IBVP

LP.6

- Suppose $\phi(x, z, t)$ and $\eta(x, t)$ satisfy the following linearized problem:



$\phi_z = \eta_t, \phi_t + g\eta = 0$ on $z=0$

$\phi_{xx} + \phi_{zz} = 0$ for $z < 0$

$\phi \rightarrow 0$ as $z \rightarrow -\infty$

- If fluid starts from rest with free surface displacement $\eta_0(x)$,

then problem is closed by the ICs

$$\eta(x, 0) = \eta_0(x), \eta_t(x, 0) = 0$$

- Take Fourier transform in x :

$$\hat{\phi}(k, z, t) = \int_{-\infty}^{\infty} \phi(x, z, t) e^{-ikx} dx, \quad \hat{\eta}(k, t) = \int_{-\infty}^{\infty} \eta(x, t) e^{-ikx} dx.$$

- $\phi_{xx} + \phi_{zz} = 0$ in $z < 0 \Rightarrow (ik)^2 \hat{\phi} + \hat{\phi}_{zz} = 0$ in $z < 0$

- $\phi_z = \eta_t, \phi_t + g\eta = 0$ on $z = 0 \Rightarrow \hat{\phi}_z = \hat{\eta}_t, \hat{\phi}_t + g\hat{\eta} = 0$ on $z = 0$

- $\phi \rightarrow 0$ as $z \rightarrow -\infty \Rightarrow \hat{\phi} \rightarrow 0$ as $z \rightarrow -\infty$

- $\eta = \eta_0, \eta_t = 0$ at $t = 0 \Rightarrow \hat{\eta} = \hat{\eta}_0, \hat{\eta}_t = 0$ at $t = 0$

- $-k^2 \hat{\phi} + \hat{\phi}_{zz} = 0 \Rightarrow \hat{\phi} = A(k,t) e^{|k|z} + B(k,t) e^{-|k|z}$

- Write in this form to simplify algebra: since $\hat{\phi} \rightarrow 0$ as $z \rightarrow -\infty$, can now set $B \equiv 0$.

- $\hat{\phi}_z = \hat{\eta}_t, \hat{\phi}_t + g\hat{\eta} = 0$ on $z=0 \Rightarrow |k|A = \hat{\eta}_t, A_t + g\hat{\eta} = 0$

- Eliminate A : $\hat{\eta}_{tt} = |k|A_t = -g|k|\hat{\eta}$ for $t > 0$

- Solve for $\hat{\eta}$: $\hat{\eta}(k,t) = C(k) \cos \omega t + D(k) \sin \omega t, \omega(k) := \sqrt{g|k|}$

• ICS: $\hat{n} = \hat{n}_0, \hat{n}_t = 0$ at $t = 0 \Rightarrow C(k) = \hat{n}_0(k), D(k) = 0 \Rightarrow A(k) = -\frac{\omega \hat{n}_0}{|k|} \sin \omega t$

• Hence, $\hat{n}(k,t) = \hat{n}_0(k) \cos \omega(k)t, \hat{\phi}(k,z,t) = -\frac{\omega(k) \hat{n}_0(k)}{|k|} \sin \omega(k)t e^{|k|z}$

• Focus on n . Inverting gives

$$n(x,t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{n}_0(k) \cos \omega(k)t e^{ikx} dk$$

$$= \frac{1}{4\pi} \int_{-\infty}^{\infty} \hat{n}_0(k) \left(e^{i(kx - \omega(k)t)} + e^{i(kx + \omega(k)t)} \right) dk,$$

i.e. superposition of travelling waves with wavenumber k , frequency $\omega(k)$, phase speed $c_p(k) = \frac{\omega(k)}{k}$ travelling left and right.

Multidimensional Fourier transform

- Can generalize Fourier transforms to higher dimensions.

- For e.g. $f(x, y, z)$, can define $\hat{f}(k, l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y, z) e^{-ikx - ily - imz} dx dy dz$

- With wavenumber vector $\underline{k} = (k, l, m)^T$, $\hat{f}(\underline{k}) = \iiint_{\mathbb{R}^3} f(\underline{x}) e^{-i\underline{k} \cdot \underline{x}} d\underline{x}$.

- The inverse then reads $f(\underline{x}) = \frac{1}{(2\pi)^3} \iiint_{\mathbb{R}^3} \hat{f}(\underline{k}) e^{i\underline{k} \cdot \underline{x}} d\underline{k}$.

Example: internal gravity waves.

- Recall that $w(x, y, z, t)$ satisfies (after linearization)

$$\frac{\partial^2}{\partial t^2} \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) = -\beta g \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} - \frac{1}{g} \frac{\partial^3 w}{\partial z \partial t^2} \right)$$

[NB: $\beta \leftrightarrow -\beta$ in online notes.]

- Suppose initially $w = w_0(x)$, $\frac{\partial w}{\partial t} = 0$ at $t = 0$.

- Take a Fourier transform in x, y, z , i.e. $\hat{w}(\underline{k}) = \iiint_{\mathbb{R}^3} w(\underline{x}, t) e^{-i\underline{k} \cdot \underline{x}} d\underline{x}$,
where $\underline{k} = (k, l, m)^T$.

• PDE $\Rightarrow \frac{\partial^2}{\partial t^2} \left((ik)^2 \hat{w} + (il)^2 \hat{w} + (im)^2 \hat{w} \right) = -\beta g \left((ik)^2 \hat{w} + (il)^2 \hat{w} - \frac{im}{g} \frac{\partial^2 \hat{w}}{\partial t^2} \right)$

$\Rightarrow \frac{\partial^2 \hat{w}}{\partial t^2} + \lambda(\underline{k})^2 \hat{w} = 0, \quad \lambda(\underline{k})^2 = \frac{\beta g (k^2 + l^2)}{k^2 + l^2 + m^2 + im\beta}$

$\Rightarrow \hat{w} = A(\underline{k}) \cos \lambda(\underline{k})t + B(\underline{k}) \sin \lambda(\underline{k})t$

• IG $\Rightarrow A(\underline{k}) = \hat{w}_0(\underline{k}), \quad B(\underline{k}) = 0, \quad \hat{w}(\underline{k}, t) = \hat{w}_0(\underline{k}) \cos \lambda(\underline{k})t$

• Inverting $\Rightarrow w(\underline{x}, t) = \frac{1}{8\pi^3} \iiint_{\mathbb{R}^3} \hat{w}_0(\underline{k}) \cos(\lambda(\underline{k})t) e^{i\underline{k} \cdot \underline{x}} d\underline{k}$

• NB: Since $\text{Im}(\lambda(\underline{k})) \neq 0$ for $m \neq 0$, base state is stable iff \hat{w}_0 is ind. m , i.e. w_0 is ind. z .