

Waves and Compressible Flow

Lecture 15

Weak solutions

P.1

- When physical variables are:
 - continuously differentiable, have PDEs;
 - discontinuous, have Rankine-Hugoniot conditions.
- A weak formulation provides a way to encompass both.
- Consider a general conservation law

$$\frac{\partial \underline{P}}{\partial t} + \frac{\partial \underline{Q}}{\partial x} = \underline{0},$$

where \underline{P} and \underline{Q} are continuously differentiable functions of x , t and $\underline{u}(x, t)$, the vector of state variables for which we must solve.

Example: one-dimensional gas dynamics

• $\rho_t + (\rho u)_x = 0, (\rho u)_t + (\rho u^2 + p)_x = 0, (\rho e)_t + (\rho e u + p u)_x = 0,$

where $p = \rho R T, e = \frac{1}{2} u^2 + C_v T$, may be written in the form $\underline{P}_t + \underline{Q}_x = 0$

with $\underline{P} = \begin{pmatrix} \rho \\ \rho u \\ \rho u^2/2 + p/(\gamma-1) \end{pmatrix}, \underline{Q} = \begin{pmatrix} \rho u \\ \rho u^2 + p \\ \rho u^3/2 + \delta p u / (\gamma-1) \end{pmatrix}, \underline{u} = \begin{pmatrix} \rho \\ u \\ p \end{pmatrix}.$

Example: shallow water equations

• $h_t + (hu)_x = 0, (hu)_t + (hu^2 + gh^2/2)_x = 0$ may be written in the form

$\underline{P}_t + \underline{Q}_x = 0$, with

$\underline{P} = \begin{pmatrix} h \\ hu \end{pmatrix}, \underline{Q} = \begin{pmatrix} hu \\ hu^2 + gh^2/2 \end{pmatrix}, \underline{u} = \begin{pmatrix} h \\ u \end{pmatrix}.$

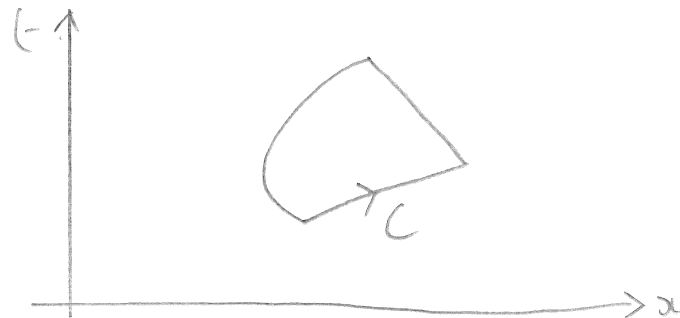
- Not all PDEs can be written in the form

$$\underline{P}_t + \underline{Q}_x = \underline{Q}, \quad (1)$$

but physical models based on conservation principles can almost always.

- We define a weak solution of (1) to be a function $u(x,t)$ such that

$$\oint_C \underline{Q} dt - \underline{P} dx = \underline{Q} \text{ for all piecewise-smooth simple closed curves } C. \quad (2)$$



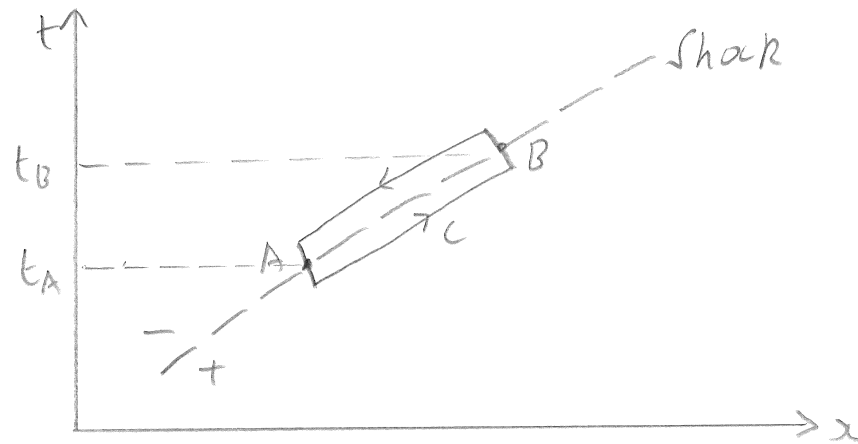
Classical solutions

P.4

- Suppose a weak solution \underline{u} is continuously differentiable. Then Green's theorem gives $\iint_S \underline{P}_t + \underline{Q}_x dx dt = 0$ for all regions S whose boundaries C are as in (2)
- Since \underline{P}_t and \underline{Q}_x are continuous by assumption and S is arbitrary, it follows that \underline{u} satisfies the PDE (1).
- Conversely, if \underline{u} is a continuously differentiable solution of (1), then it satisfies (2) by Green's theorem.
- Hence, (1) \equiv (2) for continuously differentiable \underline{u} . Such a solution is called a classical solution.

Shocks

- Suppose now a weak solution u is continuously differentiable except on a shock at $x = s(t)$ across which it is discontinuous.



- Label regions either side of shock by + and -.
- Take A, B to be points on shock and C to be a narrow pill-box contour through them enclosing the shock.

- If we shrink C toward the shock on either side, then in (2) we are left with

$$\underline{Q} = \oint_C \underline{Q} dt - \underline{P} dx$$

$$= \int_A^B \underline{Q}_+ dt - \underline{P}_+ dx + \int_B^A \underline{Q}_- dt - \underline{P}_- dx$$

$$= \int_A^B [\underline{Q}]_-^+ dt - [\underline{P}]_-^+ dx$$

$$= \int_{t_A}^{t_B} ([\underline{Q}]_-^+ - \dot{s} [\underline{P}]_-^+) dt, \quad \text{since } \frac{dx}{dt} = \dot{s}(t) \text{ and } x = s(t).$$

- Since A and B are arbitrary, we have (assuming the integrand is continuous)

$$V [P]_{-}^{+} = [Q]_{-}^{+}, \quad (3)$$

where $V = \dot{s}(t)$ is the shock speed.

- (3) are the Rankine-Hugoniot conditions - they can be read off from the conservation form (1) of the PDE.
- NB: We assumed continuity of u_{+} and u_{-} in deriving (3), which is a weaker condition than for the derivation from the integral conservation laws.

Example: shallow water equations

$$\textcircled{3} \Rightarrow V \begin{bmatrix} h \\ hu \end{bmatrix}_-^+ = \begin{bmatrix} hu \\ hu^2 + gh^2/2 \end{bmatrix}_-^+$$

$$\Rightarrow V[h]_-^+ = [hu]_-^+, \quad V[hu]_-^+ = [hu^2 + \frac{1}{2}gh^2]_-^+ = 0$$

$$\Rightarrow [h(u-v)]_-^+ = 0, \quad [hu(u-v) + \frac{1}{2}gh^2]_-^+ - v[h(u-v)]_-^+ = 0$$

$$\Rightarrow [h(u-v)]_-^+ = 0, \quad [h(u-v)^2 + \frac{1}{2}gh^2]_-^+ = 0$$

- These are the same as before as found from first principles.
- Can perform a similar analysis for 1D gas dynamics - see online notes.

Nonuniqueness of conservation laws

- The conservation form ① of the PDE is not unique.
- Thus, to get the 'correct' Rankine-Hugoniot conditions we need to choose the correct physical quantities to conserve.
- There is no mathematical way to tell which is correct.

Example: shallow water equations

- $h_t + uh_x + hu_x = 0$, $u_t + uu_x + gh_x = 0 \Rightarrow \underline{P}_t + \underline{Q}_x = \underline{0}$, where

$$\underline{P} = \begin{pmatrix} h \\ u \end{pmatrix}, \quad \underline{Q} = \begin{pmatrix} hu \\ \frac{1}{2}u^2 + gh \end{pmatrix}, \quad \underline{u} = \begin{pmatrix} h \\ u \end{pmatrix}.$$

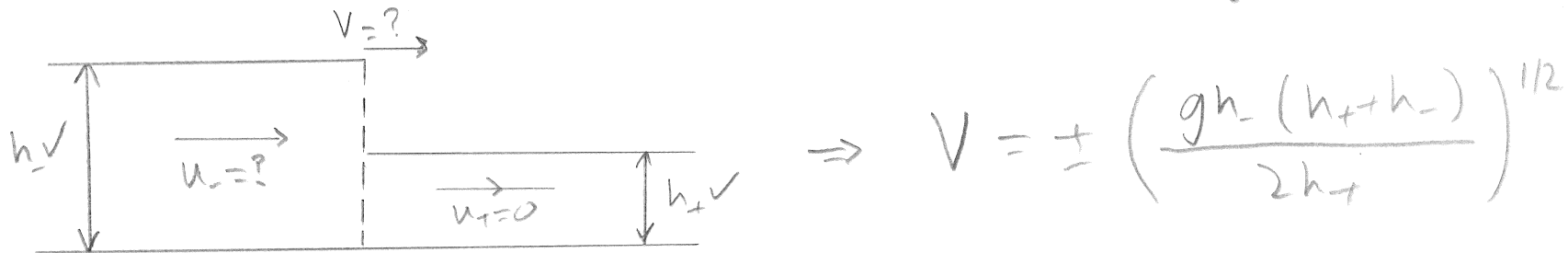
- These give the Rankine-Hugoniot conditions

$$V [h^-]^+ = [hu]^+ , \quad V [u^-]^+ = [\frac{1}{2}u^2 + gh]^+$$

- These are different jump conditions which conserve mass and energy across the shock, rather than mass and momentum.

Non-uniqueness of weak solutions

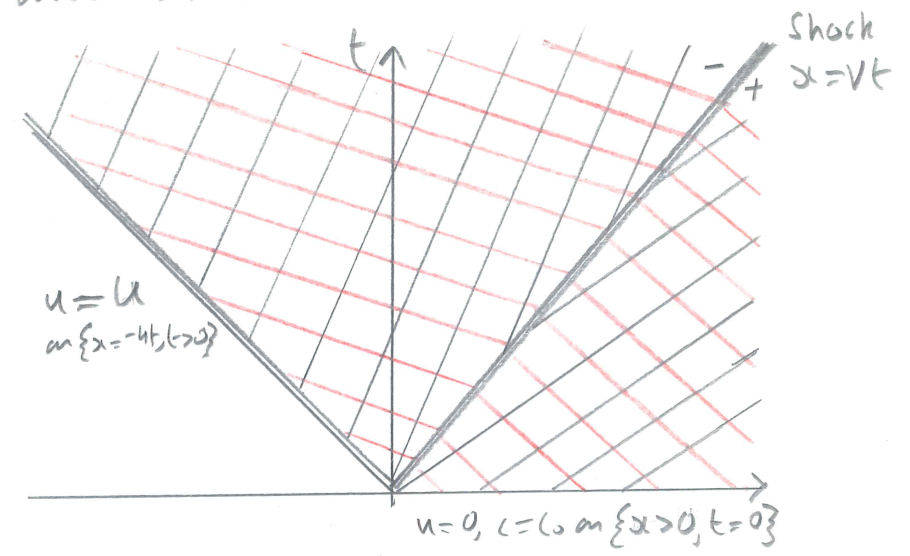
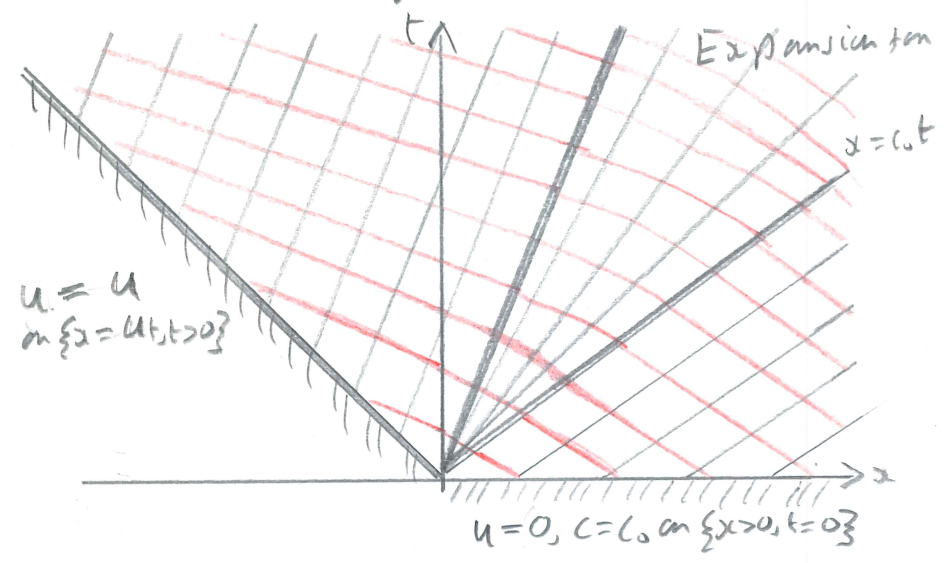
- Even once P and Q have been chosen, the weak solution may not be uniquely determined.
- For example, the choice of direction of the maining bore.



- This nonuniqueness is resolved by the energy condition for the shallow water equations and by the entropy condition for the equations of 1D gas dynamics.

Example: piston withdrawal in 1D gas dynamics

- Characteristic diagrams for two possible solutions when $U < 0$:



- Expansion fan solution valid for $-U \leq \frac{2c_0}{\gamma-1}$, while shock solution predicts $V = c_0(a + \sqrt{a^2 + 1})$, where $a = \frac{\gamma+1}{4} \frac{U}{c_0}$, which gives a possible shock speed when $U < 0$.
- But $V^2 - \frac{1}{2}(\gamma+1)UV - c_0^2 = 0 \Rightarrow M_+^2 = \left(\frac{0-V}{c_0}\right)^2 = 1 + \frac{(\gamma+1)UV}{2c_0^2} < 1$ for $U < 0$
- \Rightarrow flow changes from subsonic to supersonic as gas crosses shock \Rightarrow entropy decreases \Rightarrow invalid.