## Numerical Analysis

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Oxford Mathematical Institute

HT 2019

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## Recap on Gaussian Quadrature

#### Theorem

Let  $x_0 < x_1 < \cdots < x_n$  be the roots of the  $n + 1$ -st degree orthogonal polynomial  $\phi_{n+1}$  with respect to the inner product

$$
\langle g, h \rangle = \int_a^b w(x) g(x) h(x) \, dx,
$$

then the quadrature formula

$$
\int_{a}^{b} w(x)f(x) dx \approx \sum_{j=0}^{n} w_j f(x_j)
$$
 (14.1)

with weights  $w_j = \int_a^b w(x) L_{n,j}(x) dx$  is exact whenever  $f \in \Pi_{2n+1}$ .

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$$
\int_{1}^{2} \frac{1}{x} dx \stackrel{\text{2-pt Gauss-Legrendre}}{=} \frac{1}{2} \int_{-1}^{1} \frac{2}{t+3} dt
$$

$$
\approx \frac{1}{3 + \frac{1}{\sqrt{3}}} + \frac{1}{3 - \frac{1}{\sqrt{3}}} = 0.6923077 \dots,
$$

$$
\int_{1}^{2} \frac{1}{x} dx \stackrel{\text{2-pt Newton-Cotes}}{=} \frac{1}{2} \left[ \frac{1}{2} + 1 \right] = 0.75,
$$

$$
\int_{1}^{2} \frac{1}{x} dx \stackrel{\text{exact}}{=} 0.6931472 \dots
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### Example

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Gaussian quadrature seems to be much more accurate than Newton-Cotes quadrature with the same number of nodes, not just for polynomials!

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### Theorem (Error of Gaussian Quadrature)

Let  $f \in C^{2n+2}(a, b)$ , and let  $x_j$  and  $w_j$  be as defined above. Then,

$$
\int_{a}^{b} w(x)f(x) dx = \sum_{j=0}^{n} w_j f(x_j) + \frac{f^{(2n+2)}(\eta)}{(2n+2)!} \int_{a}^{b} w(x) \prod_{j=0}^{n} (x - x_j)^2 dx
$$

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for some  $\eta \in (a, b)$ .

Recall from Lecture 2: Given data  $f_i = f(x_i)$  and  $g_i = f'(x_i)$  at  $n + 1$ distinct points

$$
x_0 < x_1 < \cdots < x_n
$$

there exists a unique polynomial  $p \in \Pi_{2n+1}$  such that  $p(x_i) = f_i$  and  $p'(x_i) = g_i$  for  $i=0,1,\ldots,n,$  the Hermite interpolating polynomial

$$
p_{2n+1}(x) = \sum_{k=0}^{n} [f_k H_{n,k}(x) + g_k K_{n,k}(x)],
$$

which can be constructed as follows,

$$
L_{n,k}(x) = \frac{(x - x_0) \cdots (x - x_{k-1})(x - x_{k+1}) \cdots (x - x_n)}{(x_k - x_0) \cdots (x_k - x_{k-1})(x_k - x_{k+1}) \cdots (x_k - x_n)},
$$
  
\n
$$
H_{n,k}(x) = [L_{n,k}(x)]^2 (1 - 2(x - x_k)L'_{n,k}(x_k))
$$
  
\n
$$
K_{n,k}(x) = [L_{n,k}(x)]^2 (x - x_k).
$$

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Proof of Theorem (Error of Gaussian Quadrature). The proof is based on the Hermite Interpolating Polynomial  $H_{2n+1}$  to f at  $x_0, x_1, \ldots, x_n$ .

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The error in Hermite interpolation is (see Lecture 2)

$$
f(x) - H_{2n+1}(x) = \frac{1}{(2n+2)!} f^{(2n+2)}(\eta(x)) \prod_{j=0}^{n} (x - x_j)^2
$$

for some  $\eta(x) \in (a, b)$ .



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$$

for some  $\eta(x) \in (a, b)$ . Now  $H_{2n+1} \in \Pi_{2n+1}$ , so

$$
\int_a^b w(x)H_{2n+1}(x) dx = \sum_{j=0}^n w_j H_{2n+1}(x_j) = \sum_{j=0}^n w_j f(x_j),
$$

the first identity because Gaussian Quadrature is exact for polynomials of this degree and the second by interpolation.

Thus

$$
\int_{a}^{b} w(x)f(x) dx - \sum_{j=0}^{n} w_{j}f(x_{j})
$$
  
= 
$$
\int_{a}^{b} w(x)[f(x) - H_{2n+1}(x)] dx
$$
  
= 
$$
\frac{1}{(2n+2)!} \int_{a}^{b} f^{(2n+2)}(\eta(x))w(x) \prod_{j=0}^{n} (x - x_{j})^{2} dx,
$$

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Thus

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Thus

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$$
\int_{a}^{b} w(x)f(x) dx - \sum_{j=0}^{n} w_{j}f(x_{j}) = \frac{f^{(2n+2)}(\eta)}{(2n+2)!} \int_{a}^{b} w(x) \prod_{j=0}^{n} (x - x_{j})^{2} dx. \quad \Box
$$

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Remark: the "direct" approach of finding Gaussian Quadrature formulae sometimes works for small  $n$ , but is usually hard.

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Example. To find the two-point Gauss–Legendre rule  $w_0f(x_0) + w_1f(x_1)$ on  $(-1, 1)$  with weight function  $w(x) \equiv 1$ , we need to be able to integrate any cubic polynomial exactly, so

$$
2 = \int_{-1}^{1} 1 \, \mathrm{d}x = w_0 + w_1 \tag{14.2}
$$

$$
0 = \int_{-1}^{1} x \, dx = w_0 x_0 + w_1 x_1 \tag{14.3}
$$

$$
\frac{2}{3} = \int_{-1}^{1} x^2 dx = w_0 x_0^2 + w_1 x_1^2 \tag{14.4}
$$

$$
0 = \int_{-1}^{1} x^3 dx = w_0 x_0^3 + w_1 x_1^3. \tag{14.5}
$$

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$$
\left(\begin{array}{cc} x_0 & x_1 \\ x_0^3 & x_1^3 \end{array}\right) \left(\begin{array}{c} w_0 \\ w_1 \end{array}\right) = \left(\begin{array}{c} 0 \\ 0 \end{array}\right),
$$

which implies that

$$
x_0 x_1^3 - x_1 x_0^3 = 0
$$

for  $w_1, w_2 \neq 0$ , i.e.,

$$
x_0 x_1 (x_1 - x_0)(x_1 + x_0) = 0.
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$$
x_0 = -\frac{1}{\sqrt{3}}
$$
 and  $x_1 = \frac{1}{\sqrt{3}}$ ,

which are the roots of the Legendre polynomial  $x^2 - \frac{1}{3}$  $x^2 - \frac{1}{3}$  $x^2 - \frac{1}{3}$  $x^2 - \frac{1}{3}$ [.](#page-14-0)

## <span id="page-21-0"></span>Piecewise Polynomial Interpolation: Splines

Sometimes a 'global' approximation like Lagrange Interpolation is not appropriate, e.g., for 'rough' data.





# Piecewise Polynomial Interpolation: Splines

Sometimes a 'global' approximation like Lagrange Interpolation is not appropriate, e.g., for 'rough' data.



On the left the Lagrange Interpolant  $p_7$  'wiggles' through the points, while on the right a piecewise linear interpolant ('join the dots'), or linear spline interpolant,  $s$  appears to represent the data better.

 $\left\{ \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right.$ 



Suppose that  $a = x_0 < x_1 < \cdots < x_n = b$ . Then, s is linear on each interval  $[x_{i-1}, x_i]$  for  $i = 1, \ldots, n$  and continuous on  $[a, b]$ .

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The  $x_i$ ,  $i = 0, 1, \ldots, n$ , are called the **knots** of the **linear spline**.

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The  $x_i$ ,  $i = 0, 1, \ldots, n$ , are called the **knots** of the **linear spline**.

Notation:  $f \in \mathrm{C}^k[a,b]$  if  $f, f', \ldots, f^k$  exist and are continuous on  $[a,b].$ 

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### Theorem

Let s be the linear spline interpolation of a function  $f \in C^2[a,b]$  at nodes  $x_0 < x_1 < \cdots < x_n$ . Then,

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$$
||f - s||_{\infty} \le \frac{1}{8}h^2||f''||_{\infty}
$$
  
where  $h = \max_{1 \le i \le n} (x_i - x_{i-1})$  and  $||f''||_{\infty} = \max_{x \in [a,b]} |f''(x)|$ .

Proof. For  $x \in [x_{i-1}, x_i]$ , the error from linear interpolation is

$$
f(x) - s(x) = \frac{1}{2}f''(\eta(x))(x - x_{i-1})(x - x_i)
$$

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where  $\eta(x) \in (x_{i-1}, x_i)$ , by the error formula of the Lagrange interpolating polynomial  $p_1$  that interpolates f at  $x_{i-1}$  and  $x_i$  (see Lecture 1).

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However,

$$
|(x-x_{i-1})(x-x_i)| = (x-x_{i-1})(x_i-x) = -x^2 + x(x_{i-1}+x_i) - x_{i-1}x_i,
$$

which has its maximum value when  $2x = x_i + x_{i-1}$ , i.e., when

$$
x - x_{i-1} = x_i - x = \frac{1}{2}(x_i - x_{i-1}).
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Thus for any  $x \in [x_{i-1}, x_i]$ ,  $i = 1, 2, ..., n$ ,

$$
|f(x) - s(x)| \le \frac{1}{2} ||f''||_{\infty} \max_{x \in [x_{i-1}, x_i]} |(x - x_{i-1})(x - x_i)| \le \frac{1}{8} h^2 ||f''||_{\infty}.
$$

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Note that  $s$  may have discontinuous derivatives, but it is a locally defined approximation, since changing the value of one data point affects the approximation in only two intervals.

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Note that s may have discontinuous derivatives, but it is a locally defined approximation, since changing the value of one data point affects the approximation in only two intervals.

To get greater smoothness but retain some 'locality', we can define **cubic** splines  $s \in \mathrm{C}^2[a,b]$ . For a given 'partition',

$$
a = x_0 < x_1 < \cdots < x_n = b,
$$

there are (generally different!) cubic polynomials in each interval  $(x_{i-1}, x_i)$ ,  $i = 1, \ldots, n$ , which are 'joined' at each knot to have continuity and continuity of  $s'$  and  $s''$ .

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**Interpolating cubic splines** also satisfy  $s(x_i) = f_i$  for given data  $f_i$ ,  $i=0,1,\ldots,n$ .

Remark: if there are n intervals, there are  $4n$  free coefficients (four for each cubic 'piece'), but  $2n$  interpolation conditions (one each at the ends of each interval),  $n-1$  derivative continuity conditions (at  $x_1, \ldots, x_{n-1}$ ) and  $n-1$ second derivative continuity conditions (at the same points), giving a total of  $4n-2$  conditions (which are linear in the free coefficients).

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Thus the spline is not unique.

So we need to add two extra conditions to generate a spline that might be unique.

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(a) specify 
$$
s'(x_0) = f'(x_0)
$$
 and  $s'(x_n) = f'(x_n)$ ; or

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(b) specify  $s''(x_0) = 0 = s''(x_n)$  — this gives a **natural** cubic spline; or

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(c) enforce continuity of  $s'''$  at  $x_1$  and  $x_{n-1}$  (which implies that the first two pieces are the same cubic spline, i.e., on  $[x_0, x_2]$ , and similarly for the last two pieces, i.e., on  $[x_{n-2}, x_n]$ , from which it follows that  $x_1$ and  $x_{n-1}$  are not knots! — this is usually described as the 'not a knot' end-conditions).

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