Numerical Analysis

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Oxford Mathematical Institute

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Recap on Gaussian Quadrature

Theorem

Let $x_0 < x_1 < \cdots < x_n$ be the roots of the n + 1-st degree orthogonal polynomial ϕ_{n+1} with respect to the inner product

$$\langle g,h\rangle = \int_a^b w(x)g(x)h(x)\,\mathrm{d}x,$$

then the quadrature formula

$$\int_{a}^{b} w(x)f(x) \,\mathrm{d}x \approx \sum_{j=0}^{n} w_j f(x_j) \tag{14.1}$$

with weights $w_j = \int_a^b w(x) L_{n,j}(x) \, dx$ is exact whenever $f \in \Pi_{2n+1}$.

Example

$$\int_{1}^{2} \frac{1}{x} dx \stackrel{2-\text{pt Gauss-Legrendre}}{=} \frac{1}{2} \int_{-1}^{1} \frac{2}{t+3} dt$$
$$\simeq \frac{1}{3 + \frac{1}{\sqrt{3}}} + \frac{1}{3 - \frac{1}{\sqrt{3}}} = 0.6923077 \dots,$$
$$\int_{1}^{2} \frac{1}{x} dx \stackrel{2-\text{pt Newton-Cotes}}{=} \frac{1}{2} \left[\frac{1}{2} + 1 \right] = 0.75,$$
$$\int_{1}^{2} \frac{1}{x} d \stackrel{\text{exact}}{=} 0.6931472 \dots$$

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Gaussian quadrature seems to be much more accurate than Newton-Cotes quadrature with the same number of nodes, not just for polynomials!

Theorem (Error of Gaussian Quadrature)

Let $f \in C^{2n+2}(a,b)$, and let x_j and w_j be as defined above. Then,

$$\int_{a}^{b} w(x)f(x) \, \mathrm{d}x = \sum_{j=0}^{n} w_{j}f(x_{j}) + \frac{f^{(2n+2)}(\eta)}{(2n+2)!} \int_{a}^{b} w(x) \prod_{j=0}^{n} (x-x_{j})^{2} \, \mathrm{d}x$$

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for some $\eta \in (a, b)$.

Recall from Lecture 2: Given data $f_i = f(x_i)$ and $g_i = f'(x_i)$ at n + 1 distinct points

$$x_0 < x_1 < \dots < x_n,$$

there exists a unique polynomial $p \in \Pi_{2n+1}$ such that $p(x_i) = f_i$ and $p'(x_i) = g_i$ for i = 0, 1, ..., n, the Hermite interpolating polynomial

$$p_{2n+1}(x) = \sum_{k=0}^{n} [f_k H_{n,k}(x) + g_k K_{n,k}(x)],$$

which can be constructed as follows,

$$L_{n,k}(x) = \frac{(x-x_0)\cdots(x-x_{k-1})(x-x_{k+1})\cdots(x-x_n)}{(x_k-x_0)\cdots(x_k-x_{k-1})(x_k-x_{k+1})\cdots(x_k-x_n)},$$

$$H_{n,k}(x) = [L_{n,k}(x)]^2(1-2(x-x_k)L'_{n,k}(x_k))$$

$$K_{n,k}(x) = [L_{n,k}(x)]^2(x-x_k).$$

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Proof of Theorem (Error of Gaussian Quadrature). The proof is based on the Hermite Interpolating Polynomial H_{2n+1} to f at x_0, x_1, \ldots, x_n .

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The error in Hermite interpolation is (see Lecture 2)

$$f(x) - H_{2n+1}(x) = \frac{1}{(2n+2)!} f^{(2n+2)}(\eta(x)) \prod_{j=0}^{n} (x-x_j)^2$$

for some $\eta(x) \in (a, b)$.



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for some $\eta(x) \in (a,b)$. Now $H_{2n+1} \in \Pi_{2n+1}$, so

$$\int_{a}^{b} w(x) H_{2n+1}(x) \, \mathrm{d}x = \sum_{j=0}^{n} w_j H_{2n+1}(x_j) = \sum_{j=0}^{n} w_j f(x_j),$$

the first identity because Gaussian Quadrature is exact for polynomials of this degree and the second by interpolation.

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Thus

$$\int_{a}^{b} w(x)f(x) \, \mathrm{d}x - \sum_{j=0}^{n} w_{j}f(x_{j})$$

= $\int_{a}^{b} w(x)[f(x) - H_{2n+1}(x)] \, \mathrm{d}x$
= $\frac{1}{(2n+2)!} \int_{a}^{b} f^{(2n+2)}(\eta(x))w(x) \prod_{j=0}^{n} (x-x_{j})^{2} \, \mathrm{d}x,$

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$$\int_{a}^{b} w(x)f(x) \, \mathrm{d}x - \sum_{j=0}^{n} w_{j}f(x_{j}) = \frac{f^{(2n+2)}(\eta)}{(2n+2)!} \int_{a}^{b} w(x) \prod_{j=0}^{n} (x-x_{j})^{2} \, \mathrm{d}x. \quad \Box$$

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Remark: the "direct" approach of finding Gaussian Quadrature formulae sometimes works for small n, but is usually hard.

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Example. To find the two-point Gauss-Legendre rule $w_0f(x_0) + w_1f(x_1)$ on (-1, 1) with weight function $w(x) \equiv 1$, we need to be able to integrate any cubic polynomial exactly, so

$$2 = \int_{-1}^{1} 1 \,\mathrm{d}x = w_0 + w_1 \tag{14.2}$$

$$0 = \int_{-1}^{1} x \, \mathrm{d}x = w_0 x_0 + w_1 x_1 \tag{14.3}$$

$$\frac{2}{3} = \int_{-1}^{1} x^2 \,\mathrm{d}x = w_0 x_0^2 + w_1 x_1^2$$
 (14.4)

$$0 = \int_{-1}^{1} x^3 \, \mathrm{d}x = w_0 x_0^3 + w_1 x_1^3. \tag{14.5}$$

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Solution: These are four nonlinear equations in four unknowns w_0 , w_1 , x_0 and x_1 .

$$\left(\begin{array}{cc} x_0 & x_1 \\ x_0^3 & x_1^3 \end{array}\right) \left(\begin{array}{c} w_0 \\ w_1 \end{array}\right) = \left(\begin{array}{c} 0 \\ 0 \end{array}\right),$$

which implies that

$$x_0 x_1^3 - x_1 x_0^3 = 0$$

for w_1 , $w_2 \neq 0$, i.e.,

$$x_0 x_1 (x_1 - x_0) (x_1 + x_0) = 0.$$

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$$x_0 = -\frac{1}{\sqrt{3}}$$
 and $x_1 = \frac{1}{\sqrt{3}}$

which are the roots of the Legendre polynomial $x^2 - \frac{1}{3}$.

Piecewise Polynomial Interpolation: Splines

Sometimes a 'global' approximation like Lagrange Interpolation is not appropriate, e.g., for 'rough' data.



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On the left the Lagrange Interpolant p_7 'wiggles' through the points, while on the right a **piecewise** linear interpolant ('join the dots'), or linear **spline** interpolant, *s* appears to represent the data better.

Suppose that $a = x_0 < x_1 < \cdots < x_n = b$. Then, s is linear on each interval $[x_{i-1}, x_i]$ for $i = 1, \ldots, n$ and continuous on [a, b].

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The x_i , i = 0, 1, ..., n, are called the **knots** of the **linear spline**.

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Notation: $f \in C^k[a, b]$ if f, f', \dots, f^k exist and are continuous on [a, b].

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Theorem

Let s be the linear spline interpolation of a function $f \in C^2[a, b]$ at nodes $x_0 < x_1 < \cdots < x_n$. Then,

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$$\|f - s\|_{\infty} \leq \frac{1}{8}h^2 \|f''\|_{\infty}$$

where $h = \max_{1 \leq i \leq n} (x_i - x_{i-1})$ and $\|f''\|_{\infty} = \max_{x \in [a,b]} |f''(x)|$.

Proof. For $x \in [x_{i-1}, x_i]$, the error from linear interpolation is

$$f(x) - s(x) = \frac{1}{2} f''(\eta(x))(x - x_{i-1})(x - x_i)$$

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where $\eta(x) \in (x_{i-1}, x_i)$, by the error formula of the Lagrange interpolating polynomial p_1 that interpolates f at x_{i-1} and x_i (see Lecture 1).

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$$|(x - x_{i-1})(x - x_i)| = (x - x_{i-1})(x_i - x) = -x^2 + x(x_{i-1} + x_i) - x_{i-1}x_i,$$

which has its maximum value when $2x = x_i + x_{i-1}$, i.e., when

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Thus for any $x \in [x_{i-1}, x_i]$, i = 1, 2, ..., n,

$$|f(x) - s(x)| \le \frac{1}{2} \|f''\|_{\infty} \max_{x \in [x_{i-1}, x_i]} |(x - x_{i-1})(x - x_i)| \le \frac{1}{8} h^2 \|f''\|_{\infty}. \quad \Box$$

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Note that s may have discontinuous derivatives, but it is a locally defined approximation, since changing the value of one data point affects the approximation in only two intervals.

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To get greater smoothness but retain some 'locality', we can define **cubic** splines $s \in C^2[a, b]$. For a given 'partition',

$$a = x_0 < x_1 < \dots < x_n = b,$$

there are (generally different!) cubic polynomials in each interval (x_{i-1}, x_i) , $i = 1, \ldots, n$, which are 'joined' at each knot to have continuity and continuity of s' and s''.

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Interpolating cubic splines also satisfy $s(x_i) = f_i$ for given data f_i , i = 0, 1, ..., n.

Remark: if there are n intervals, there are 4n free coefficients (four for each cubic 'piece'), but 2n interpolation conditions (one each at the ends of each interval), n-1 derivative continuity conditions (at x_1, \ldots, x_{n-1}) and n-1 second derivative continuity conditions (at the same points), giving a total of 4n-2 conditions (which are linear in the free coefficients).

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Thus the spline is not unique.

So we need to add two extra conditions to generate a spline that might be unique.

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(a) specify
$$s'(x_0) = f'(x_0)$$
 and $s'(x_n) = f'(x_n)$; or

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(c) enforce continuity of s''' at x_1 and x_{n-1} (which implies that the first two pieces are the same cubic spline, i.e., on $[x_0, x_2]$, and similarly for the last two pieces, i.e., on $[x_{n-2}, x_n]$, from which it follows that x_1 and x_{n-1} are not knots! — this is usually described as the 'not a knot' end-conditions).

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