

# Numerical Analysis

Raphael Hauser  
with thanks to Endre Süli

Oxford Mathematical Institute

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# Recap on Cubic Splines

## Proposition

*The set of cubic splines on a given set of knots  $x_0 < x_1 < \dots < x_n$  is a vector space.*

Given nodes  $x_0, x_1, \dots, x_n$  and function values  $f_0, f_1, \dots, f_n$ , the unique interpolating natural spline  $s(x)$  that satisfies  $s(x_i) = f_i$  ( $i = 0, \dots, n$ ) can be constructed as

$$s(x) = \sum_{i=0}^n f(x_i) C_i(x),$$

where  $C_0, \dots, C_i$  are the *cardinal spline* basis of the vector space of natural cubic splines on the knots  $x_0, \dots, x_n$ , defined by

$$C_i(x_j) = \begin{cases} 1 & \text{if } i = j, \\ 0 & \text{if } i \neq j. \end{cases}$$

Using the basis of **B-splines** is better, because B-splines are locally defined by the requirement that  $B_i$  is a cubic spline with knots  $x_0, \dots, x_n$  and

$$\begin{aligned} B_i(x_i) &= 1 \quad \text{for } i = 2, 3, \dots, n-2, \\ B_i(x) &\equiv 0, \quad \text{for } x \notin (x_{i-2}, x_{i+2}). \end{aligned}$$

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Each  $B_i$  consists of 4 patches of cubic polynomials on the intervals  $[x_{i-2}, x_{i-1}]$ ,  $[x_{i-1}, x_i]$ ,  $[x_i, x_{i+1}]$  and  $[x_{i+1}, x_{i+2}]$ , uniquely defined by

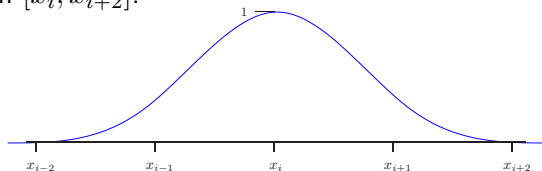
- $0 = s(x_{i-2}) = s'(x_{i-2}) = s''(x_{i-2})$ ,
- continuity of  $s(x)$ ,  $s'(x)$  at  $x_{i-1}$ ,
- $s(x_i) = 1$ ,  $s'(x_i) = 0$ ,
- symmetry on  $[x_i, x_{i+2}]$ .

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## Construction on uniformly spaced knots:

B-spline on  $x_i = a + hi$ , where  $h = (b - a)/n$ .

$$B_i(x) = \begin{cases} 0 & \text{for } x < x_{i-2}, \\ \frac{(x-x_{i-2})^3}{4h^3} & \text{for } x \in [x_{i-2}, x_{i-1}], \\ -\frac{3(x-x_{i-1})^3}{4h^3} + \frac{3(x-x_{i-1})^2}{4h^2} + \frac{3(x-x_{i-1})}{4h} + \frac{1}{4} & \text{for } x \in [x_{i-1}, x_i], \\ -\frac{3(x_{i+1}-x)^3}{4h^3} + \frac{3(x_{i+1}-x)^2}{4h^2} + \frac{3(x_{i+1}-x)}{4h} + \frac{1}{4} & \text{for } x \in [x_i, x_{i+1}], \\ \frac{(x_{i+2}-x)^3}{4h^3} & \text{for } x \in [x_{i+1}, x_{i+2}], \\ 0 & \text{for } x > x_{i+2}. \end{cases}$$

The 'end' B-splines  $B_0$ ,  $B_1$ ,  $B_{n-1}$  and  $B_n$  are defined analogously by introducing 'phantom' knots  $x_{-2} = a - 2h$ ,  $x_{-1} = a - h$ ,  $x_{n+1} = b + h$  and  $x_{n+2} = b + 2h$ .

**Spline interpolation:** find the cubic spline

$$s(x) = \sum_{j=0}^n c_j B_j(x),$$

that interpolates  $f_i$  at  $x_i$  for  $i = 0, 1, \dots, n$ . Require

$$f_i = \sum_{j=0}^n c_j B_j(x_i) = c_{i-1} B_{i-1}(x_i) + c_i B_i(x_i) + c_{i+1} B_{i+1}(x_i).$$

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For equally-spaced data

$$f_i = \frac{1}{4}c_{i-1} + c_i + \frac{1}{4}c_{i+1},$$

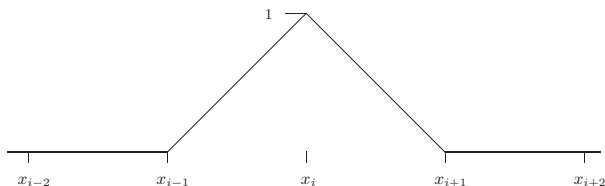
i.e.,

$$\begin{pmatrix} 1 & \frac{1}{4} & & & \\ \frac{1}{4} & 1 & \ddots & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & 1 & \frac{1}{4} \\ & & & \frac{1}{4} & 1 \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \\ \vdots \\ c_{n-1} \\ c_n \end{pmatrix} = \begin{pmatrix} f_0 \\ f_1 \\ \vdots \\ f_{n-1} \\ f_n \end{pmatrix}.$$



For linear splines, a similar local basis of ‘hat functions’ or **Linear B-splines**  $\phi_i(x)$  exist:

$$\phi_i(x) = \begin{cases} \frac{x - x_{i-1}}{x_i - x_{i-1}} & x \in (x_{i-1}, x_i) \\ \frac{x - x_{i+1}}{x_i - x_{i+1}} & x \in (x_i, x_{i+1}) \\ 0 & x \notin (x_{i-1}, x_{i+1}) \end{cases}$$



and provide a  $C^0$  piecewise basis.

# Matlab:

```
% needs the number N of interpolation points to be defined
N=9;

% these will be the knot points and the interpolation points
x=linspace(-4,4,N);

% a vector of the values of the function  $f=1/(1+x^2)$  at the interpolation points
ypoints=1./(1+x.^2);
y=[8/(17^2),ypoints,-8/(17^2)];

% calculates the spline interpolant: see help spline
% an extended vector to include the slope at the first and last
% interpolation point - this is one of the end-point choices available with
% the matlab command spline (and is what is called option (a) in lectures)
% ( $f' = -2x/(1+x^2)^2$ , so  $f'(-4) = 8/17^2$  and  $f'(4) = -8/17^2$ )
s=spline(x,y);

% a fine mesh on which we plot f
fine=linspace(-4,4,200);

%> help ppval
%
% PPVAL Evaluate piecewise polynomial.
% V = PPVAL(PP,XX) returns the value at the points XX of the piecewise
% polynomial contained in PP, as constructed by SPLINE or the spline utility
% MKPP.
%
% See also SPLINE, MKPP, UNMKPP.
plot(fine,ppval(s,fine)),pause

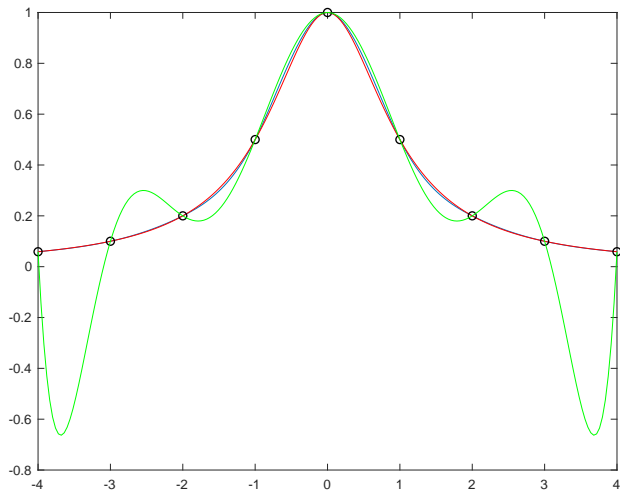
% the function f on the fine mesh
```

```
f=1./(1+fine.^2);

% to see the function (in red) and the spline interpolant (in blue) on the
% same figure
hold on
plot(fine,f,'r'),pause

% marks the interpolating values (with black circles)
plot(x,ypoints,'ko'),pause

% To see how the Lagrange interpolating polynomial (in green) does:
p=lagrange(x,ypoints);
plot(fine,polyval(p,fine),'g'),pause
```



## Error analysis for cubic splines

### Theorem (Smooth Interpolation)

*Amongst all functions  $t \in C^2[x_0, x_n]$  that interpolate  $f$  at the knots  $x_i$ ,  $i = 0, 1, \dots, n$ , the unique function that minimizes*

$$\int_{x_0}^{x_n} [t''(x)]^2 dx$$

*is the natural cubic spline  $s$ . Moreover, for any such  $t$ ,*

$$\int_{x_0}^{x_n} [t''(x)]^2 dx - \int_{x_0}^{x_n} [s''(x)]^2 dx = \int_{x_0}^{x_n} [t''(x) - s''(x)]^2 dx.$$

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Proof. See exercises (uses integration by parts and telescopic cancellation, and is similar to the proof of existence above).  $\square$

## Lemma (Cauchy–Schwarz Inequality)

Let  $f, g \in C([a, b])$ ; then,

$$\left[ \int_a^b f(x)g(x) \, dx \right]^2 \leq \int_a^b [f(x)]^2 \, dx \times \int_a^b [g(x)]^2 \, dx.$$

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$$\langle f, g \rangle \leq \|f\| \times \|g\|,$$

see Lecture 9. Taking squares on both sides yields the claim. □

## Theorem

For the natural cubic spline interpolant  $s$  of  $f \in C^2[x_0, x_n]$  at  $x_0 < x_1 < \cdots < x_n$  with  $h = \max_{1 \leq i \leq n} (x_i - x_{i-1})$ , we have that

$$\|f' - s'\|_{\infty} \leq h^{\frac{1}{2}} \left[ \int_{x_0}^{x_n} [f''(x)]^2 dx \right]^{\frac{1}{2}}$$

and

$$\|f - s\|_{\infty} \leq h^{\frac{3}{2}} \left[ \int_{x_0}^{x_n} [f''(x)]^2 dx \right]^{\frac{1}{2}}.$$

Proof. Write  $e = f - s$ . Take any  $x \in [x_0, x_n]$ , in which case  $x \in [x_{j-1}, x_j]$  for some  $j \in 1, \dots, n$ .

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Hence  $e'(x) = \int_c^x e''(t) dt$ . Then the Cauchy–Schwarz inequality gives that

$$\begin{aligned} (e'(x))^2 &= \left[ \int_c^x e''(t) dt \right]^2 \\ &\leq \left| \int_c^x 1 dt \right| \times \left| \int_c^x [e''(t)]^2 dt \right|. \end{aligned} \tag{14.1}$$

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Since  $x \in [x_{j-1}, x_j]$ , we have  $\left| \int_c^x 1 dt \right| \leq h$ ,



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Since  $x \in [x_{j-1}, x_j]$ , we have  $\left| \int_c^x 1 dt \right| \leq h$ , and Theorem (Smooth Interpolation) gives

$$\left| \int_c^x [e''(t)]^2 dt \right| \leq \int_{x_0}^{x_n} [e''(t)]^2 dt \leq \int_{x_0}^{x_n} [f''(x)]^2 dx.$$

Therefore,  $\|f' - s'\|_\infty = \max_{x \in [x_0, x_n]} |e'(x)| \stackrel{(14.1)}{\leq} h^{\frac{1}{2}} \|f''\|_2$ , as claimed.

To prove the second claim, still using  $x \in (x_{j-1}, x_j)$ , Taylor's Theorem yields that there exists  $\eta(x) \in (x_{j-1}, x)$  such that

$$|e(x)| = |e(x_{j-1}) + (x - x_{j-1})e'(\eta(x))| \leq 0 + h |e'(\eta(x))|,$$

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hence

$$\|f - s\|_\infty = \max_{x \in [x_0, x_n]} |e(x)| \leq h \|e'\|_\infty = h^{\frac{3}{2}} \|f''\|_2,$$

as claimed. □

## Recall from Lecture 13:

### Theorem

Let  $s$  be the linear spline interpolation of a function  $f \in C^2[a, b]$  at nodes  $x_0 < x_1 < \cdots < x_n$ . Then,

$$\|f - s\|_{\infty} \leq \frac{1}{8}h^2\|f''\|_{\infty}.$$

## Recall from Lecture 13:

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Is it possible to prove a similar result for cubic splines?

## Theorem

Suppose that  $f \in C^4[a, b]$  and  $s$  satisfies end-conditions (a). Then,

$$\|f - s\|_{\infty} \leq \frac{5}{384} h^4 \|f^{(4)}\|_{\infty}$$

and

$$\|f' - s'\|_{\infty} \leq \frac{9 + \sqrt{3}}{216} h^3 \|f^{(4)}\|_{\infty},$$

where  $h = \max_{1 \leq i \leq n} (x_i - x_{i-1})$ .

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Proof. Beyond the scope of this course. □

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Proof. Beyond the scope of this course. □

Similar bounds exist for natural cubic splines and splines satisfying end-condition (c).