Numerical Analysis Hilary Term 2018 Lecture 11: Least-Squares Approximation

For the problem of least-squares approximation, $\langle f, g \rangle = \int_a^b w(x) f(x) g(x) \, dx$ and $||f||_2^2 = \langle f, f \rangle$ where w(x) > 0 on (a, b). **Theorem.** If $f \in L^2_w(a, b)$ and $p_n \in \Pi_n$ is such that

$$\langle f - p_n, r \rangle = 0 \qquad \forall r \in \Pi_n,$$
 (1)

then

$$||f - p_n||_2 \le ||f - r||_2 \qquad \forall r \in \Pi_n,$$

i.e., p_n is a best (weighted) least-squares approximation to f on [a, b]. **Proof.**

$$\begin{split} \|f - p_n\|_2^2 &= \langle f - p_n, f - p_n \rangle \\ &= \langle f - p_n, f - r \rangle + \langle f - p_n, r - p_n \rangle \quad \forall r \in \Pi_n \\ &\text{Since } r - p_n \in \Pi_n \text{ the assumption (1) implies that} \\ &= \langle f - p_n, f - r \rangle \\ &\leq \|f - p_n\|_2 \|f - r\|_2 \text{ by the Cauchy-Schwarz inequality.} \end{split}$$

Dividing both sides by $||f - p_n||_2$ gives the required result.

Remark: the converse is true too (see Problem Sheet 6, Q9).

This gives a direct way to calculate a best approximation: we want to find $p_n(x) = \sum_{k=0}^n \alpha_k x^k$ such that

$$\int_{a}^{b} w(x) \left(f - \sum_{k=0}^{n} \alpha_k x^k \right) x^i \, \mathrm{d}x = 0 \quad \text{for} \quad i = 0, 1, \dots, n.$$

$$\tag{2}$$

[Note that (2) holds if, and only if,

$$\int_{a}^{b} w(x) \left(f - \sum_{k=0}^{n} \alpha_{k} x^{k} \right) \left(\sum_{i=0}^{n} \beta_{i} x^{i} \right) \, \mathrm{d}x = 0 \qquad \forall q = \sum_{i=0}^{n} \beta_{i} x^{i} \in \Pi_{n}.]$$

However, (2) implies that

$$\sum_{k=0}^{n} \left(\int_{a}^{b} w(x) x^{k+i} \, \mathrm{d}x \right) \alpha_{k} = \int_{a}^{b} w(x) f(x) x^{i} \, \mathrm{d}x \text{ for } i = 0, 1, \dots, n$$

which is the component-wise statement of a matrix equation

$$A\alpha = \varphi, \tag{3}$$

to determine the coefficients $\alpha = (\alpha_0, \alpha_1, \dots, \alpha_n)^{\mathrm{T}}$, where $A = \{a_{i,k}, i, k = 0, 1, \dots, n\}$, $\varphi = (f_0, f_1, \dots, f_n)^{\mathrm{T}}$,

$$a_{i,k} = \int_a^b w(x) x^{k+i} \, \mathrm{d}x$$
 and $f_i = \int_a^b w(x) f(x) x^i \, \mathrm{d}x$.

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The system (3) are called the **normal equations**.

the best least-squares approximation to e^x on [0,1] from Π_1 in $\langle f,g \rangle$ Example: $\int_{-\infty}^{\infty} f(x)g(x) \, \mathrm{d}x.$ We want $\int_0^1 [e^x - (\alpha_0 1 + \alpha_1 x)] 1 \, dx = 0 \text{ and } \int_0^1 [e^x - (\alpha_0 1 + \alpha_1 x)] x \, dx = 0.$ $\alpha_0 \int_0^1 \mathrm{d}x + \alpha_1 \int_0^1 x \,\mathrm{d}x = \int_0^1 \mathrm{e}^x \,\mathrm{d}x$ $\alpha_0 \int_0^1 x \, \mathrm{d}x + \alpha_1 \int_0^1 x^2 \, \mathrm{d}x = \int_0^1 \mathrm{e}^x x \, \mathrm{d}x$

i.e.,

$$\begin{bmatrix} 1 & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{3} \end{bmatrix} \begin{bmatrix} \alpha_0 \\ \alpha_1 \end{bmatrix} = \begin{bmatrix} e-1 \\ 1 \end{bmatrix}$$

 $\implies \alpha_0 = 4e - 10$ and $\alpha_1 = 18 - 6e$, so $p_1(x) := (18 - 6e)x + (4e - 10)$ is the best approximation.

Proof that the coefficient matrix A is nonsingular will now establish existence and uniqueness of (weighted) $\|\cdot\|_2$ best-approximation.

Theorem. The coefficient matrix A is nonsingular.

Proof. Suppose not $\implies \exists \alpha \neq 0$ with $A\alpha = 0 \implies \alpha^{\mathrm{T}} A\alpha = 0$

$$\iff \sum_{i=0}^{n} \alpha_i (A\alpha)_i = 0 \iff \sum_{i=0}^{n} \alpha_i \sum_{k=0}^{n} a_{ik} \alpha_k = 0,$$

and using the definition $a_{ik} = \int^b w(x) x^k x^i \, \mathrm{d}x$,

$$\iff \sum_{i=0}^{n} \alpha_i \sum_{k=0}^{n} \left(\int_a^b w(x) x^k x^i \, \mathrm{d}x \right) \alpha_k = 0.$$

Rearranging gives

$$\int_{a}^{b} w(x) \left(\sum_{i=0}^{n} \alpha_{i} x^{i}\right) \left(\sum_{k=0}^{n} \alpha_{k} x^{k}\right) dx = 0 \text{ or } \int_{a}^{b} w(x) \left(\sum_{i=0}^{n} \alpha_{i} x^{i}\right)^{2} dx = 0$$

which implies that $\sum_{i=0} \alpha_i x^i = 0$ and thus $\alpha_i = 0$ for i = 0, 1, ..., n. This contradicts the initial supposition, and thus A is nonsingular.

Remark: This result does not imply that the normal equations are usable in practice: the method would need to be stable with respect to small perturbations. In fact, difficulties arise from the "ill-conditioning" of the matrix A as n increases. The next lecture looks at a fix.