

## B3.2 GEOMETRY OF SURFACES - EXERCISE SHEET 4

Comments and corrections are welcome: [ritter@maths.ox.ac.uk](mailto:ritter@maths.ox.ac.uk)

### Exercise 1. Holomorphic maps between Riemann surfaces.

Using the local form of a holomorphic map between Riemann surfaces, deduce:

*Open mapping theorem:* any holomorphic map  $f : R \rightarrow S$  between Riemann surfaces, with  $R$  connected, is either constant or an open map, meaning  $f(\text{any open set})$  is open.<sup>1</sup>

Deduce the following, for  $f : R \rightarrow S$  holomorphic,  $R, S$  Riemann surfaces:

- (1) If  $f$  is non-constant,  $R$  compact connected, then  $f(R) \subset S$  is a connected component.
- (2) If  $f$  is non-constant,  $R, S$  both compact connected, then  $f$  is surjective:  $f(R) = S$ .
- (3) If  $R$  is compact connected,  $S$  non-compact connected, then  $f$  is constant.
- (4) A holomorphic map  $S \rightarrow \mathbb{C}$  on a compact connected Riemann surface is constant.
- (5) Fundamental theorem of algebra: non-constant complex polynomials have a root.

### Exercise 2. Riemann-Hurwitz formula.

In the following, all spaces are compact connected Riemann surfaces, and all maps are holomorphic maps. Deduce from the Riemann-Hurwitz formula that:

- (1) if  $f : R \rightarrow S$  is not constant, then the genus  $g(R) \geq g(S)$ .
- (2) if  $f : \mathbb{C}P^1 \rightarrow S$  is not constant, then  $S$  is homeomorphic to a sphere.
- (3) if  $f : R \rightarrow S$  has degree 1 then  $f$  is a biholomorphism.
- (4) if  $R$  admits a meromorphic function with only one pole of order 1, then  $R \cong \mathbb{C}P^1$ .

### Exercise 3. Implicit function theorem.

Consider  $R = \{(z, w) \in \mathbb{C}^2 : w^3 = z^3 - z\}$ . Use the implicit function theorem to check that  $R$  is a Riemann surface. Now consider the projection  $\pi : R \rightarrow \mathbb{C}$ ,  $\pi(z, w) = z$ . Find the branch points of  $\pi$  and the valency  $v_\pi(p)$  at the ramification points.

Next, we seek how many points are “missing” at infinity. Write  $z^3 - z = z^3(1 - z^{-2})$  for large  $|z|$ , and briefly explain that there are three holomorphic solution functions to  $w^3 = z^3 - z$ . Deduce that  $\pi^{-1}(\{z \in \mathbb{C} : |z| > 100\})$  is biholomorphic to three punctured discs.

Compute the Euler characteristic of  $R$  using the Riemann-Hurwitz formula. Deduce that  $R$  is homeomorphic to a torus with three points removed.

### Exercise 4. Meromorphic functions on Riemann surfaces.

Show that a map  $f : S \rightarrow \mathbb{C}P^1$  is meromorphic if and only if locally  $f$  is expressible as a quotient of holomorphic functions (where the denominator is not identically zero).

Show that if  $f, g$  are two meromorphic functions on a compact connected Riemann surface having the same zeros and the same poles (including multiplicities) then  $f = \text{constant} \cdot g$ .

By comparing Taylor series of  $\wp, \wp'$  near ramification points, deduce by the previous part (by viewing the two sides of the equation below as meromorphic functions) that:

$$\wp'(z)^2 = 4(\wp(z) - e_1)(\wp(z) - e_2)(\wp(z) - e_3)$$

where  $e_1 = \wp(\frac{1}{2}\omega_1)$ ,  $e_2 = \wp(\frac{1}{2}\omega_2)$ ,  $e_3 = \wp(\frac{1}{2}(\omega_1 + \omega_2))$ ,  $\infty = \wp(0)$  are the branch points of  $\wp$ .

**Please turn over.**

---

*Date:* This version of the notes was created on November 16, 2017.

<sup>1</sup>*Hint.* Notice that to show a map is open, it's enough to show that for each  $p$ , there are some nice arbitrarily small open neighbourhoods of  $p$  which map to open sets.

**Exercise 5. Elliptic curves and the Weierstrass  $\wp$ -function.**

The goal is to prove that the following is a biholomorphism:

$$\begin{aligned} \mathbb{C}/\Lambda &\rightarrow S = \{(Z, W) \in \mathbb{C}^2 : W^2 = 4(Z - e_1)(Z - e_2)(Z - e_3)\} \cup \{\infty\} \\ z &\mapsto (\wp(z), \wp'(z)) \end{aligned}$$

where on the right we compactify as done in Exercise Sheet 1. *Here is a checklist/hints:*

- (1) Explain why  $e_1, e_2, e_3$  are distinct,
- (2) Show  $S$  is a Riemann surface. In particular, what is the local holomorphic coordinate?
- (3) Explain why the map is well-defined,
- (4) Show that the map is holomorphic (do this carefully, locally),
- (5) For very general reasons, explain why the map has to be surjective,
- (6) Show that the degree of the map is 1, and use Exercise 2.

**Exercise 6. Hyperbolic Geometry.**

For  $k \in (0, \infty) \subset \mathbb{R}$ , show that the dilation  $\mathbb{H} \rightarrow \mathbb{H}$ ,  $z \mapsto kz$  is an isometry, by directly verifying that the hyperbolic metric is preserved.

Verify directly that the geodesic equation holds for the curve  $\gamma : \mathbb{R} \rightarrow \mathbb{H}$ ,  $t \mapsto e^ti$ .

Find the locus of all points in  $\mathbb{H}$  that are equidistant from  $\gamma$  (by a given fixed distance).

Describe the locus of all points in  $\mathbb{H}$  equidistant from a general geodesic in  $\mathbb{H}$ . (*You may use your knowledge of the isometries of  $\mathbb{H}$  and the geodesics in  $\mathbb{H}$ .*)