

B5.6: Nonlinear Systems-Sheet 1

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Q1 Consider the system $\dot{x} = Ax$ where $x \in \mathbb{R}^3$ and

$$A = \begin{bmatrix} 0 & 2 & 0 \\ -2 & 0 & 0 \\ 2 & 0 & 6 \end{bmatrix}. \quad (1)$$

Without solving the system, find the stable, unstable and center subspaces and sketch the phase portrait.

Q2 (invariant set) The system

$$\dot{x} = -x, \quad (2)$$

$$\dot{y} = -y + x^2, \quad (3)$$

$$\dot{z} = z + x^2 \quad (4)$$

defines a flow $\varphi_t : \mathbb{R}^3 \rightarrow \mathbb{R}^3$. Show that the set $S = \{(x, y, z) \in \mathbb{R}^3 \mid z = -x^2/3\}$ is an invariant set of this flow. Sketch this set in the phase space and identify other interesting orbits (such as fixed points).

Q3 (attracting set) The system

$$\dot{x} = -y + x(1 - z^2 - x^2 - y^2), \quad (5)$$

$$\dot{y} = x + y(1 - z^2 - x^2 - y^2), \quad (6)$$

$$\dot{z} = 0 \quad (7)$$

defines a flow $\varphi_t : \mathbb{R}^3 \rightarrow \mathbb{R}^3$. Show that the union of the unit sphere with the portions of the z-axis outside the sphere is an attracting set for this flow. Find its domain of attraction. (Hint: rewrite the system in cylindrical coordinates).

Q4 (attracting set) Consider the system

$$\dot{r} = r(1 - r), \quad (8)$$

$$\dot{\theta} = \sin^2 \frac{\theta}{2}, \quad (9)$$

where (r, θ) are the usual polar coordinates of a point in the plane. Show that this system has two fixed points. Show that the fixed point $(x = 1, y = 0)$ is the ω -limit set of almost all initial conditions. That is $\varphi_t(x_0) \rightarrow (1, 0)$ for all initial conditions $x_0 \neq (0, 0)$. Despite that, show that $(1, 0)$ is not stable. Is it an attracting set? Is the unit circle an attracting set? Find the domain of attraction (if any).

Q5* (the variational equation and its adjoint): Consider the system $\dot{x} = f(x)$, where $x \in \mathbb{R}^n$ and $f(x)$ is a C^1 -vector field. Let $\bar{x} = \bar{x}(t)$ be a particular solution and consider the linear system obtained by looking at a nearby solution $x(t) = \bar{x}(t) + \varepsilon u$:

$$\dot{u} = Df(\bar{x})u$$

- (i) Show that $\dot{\bar{x}}(t)$ is a solution of the linear system, and it represents the tangent vector along the orbit.
- (ii) For planar flows ($n = 2$), use this property to give a complete solution of this system of linear equations.