

Topics in fluids sheet 4 Answers

1. $p = \frac{\rho R T}{M_a}$

$$\frac{\partial p}{\partial z} = -\rho g$$

$$\rho c_p \frac{dT}{dz} - \frac{dp}{dz} = 0 \Rightarrow \rho c_p \frac{\partial T}{\partial z} = \frac{\partial p}{\partial z} = -\rho g$$

$$\Rightarrow \frac{\partial T}{\partial z} = -\frac{g}{c_p}$$

$$\Rightarrow T = \bar{T} = T_0 - \frac{gz}{c_p}, \quad p = \bar{p} = p_0 p^*(z)$$

$$\text{where } p_0 p^{*'} = \frac{\partial p}{\partial z} = -\rho g = -\frac{M_a \rho g}{RT} = -\frac{M_a p_0 p^* g}{R(T_0 - \frac{gz}{c_p})}$$

$$\text{So } \frac{p^{*'}}{p^*} = \frac{-M_a g}{RT_0(1 - \frac{gz}{c_p T_0})}, \quad p^*(0) = 1$$

$$\Rightarrow \ln p^* = \frac{M_a g}{RT_0} \cdot \frac{c_p T_0}{g} \ln \left[1 - \frac{gz}{c_p T_0} \right]$$

$$\Rightarrow p^* = \left(1 - \frac{gz}{c_p T_0} \right)^{M_a c_p / R}$$

$$\text{Define } H = \frac{RT_0}{M_a g}, \quad p^* = \left(1 - \frac{z}{H} \frac{RT_0}{M_a g} \cdot \frac{g}{c_p T_0} \right)^{M_a c_p / R}$$

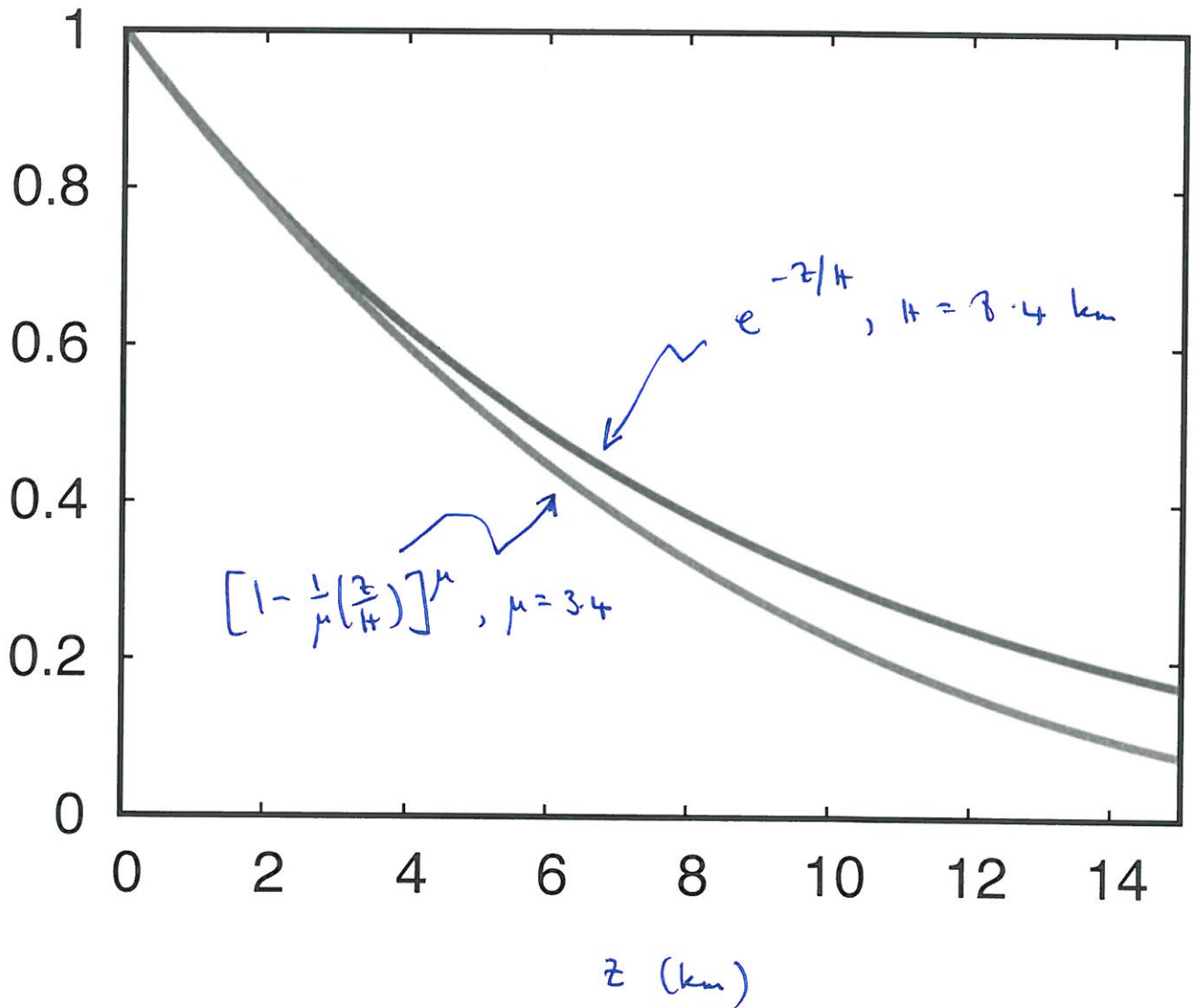
$$= \left[1 - \frac{1}{\mu} \left(\frac{z}{H} \right) \right]^\mu, \quad \mu = \frac{M_a c_p}{R} = 3.4$$

$$\text{So for } z \sim H \text{ \& \textit{since } } \mu \gg 1, \quad p^* \approx \exp\left(-\frac{z}{H}\right)$$

(2)

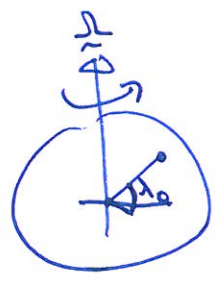
The approximation is not bad for $z \leq H$

(and is anyway unphysical above the tropopause).



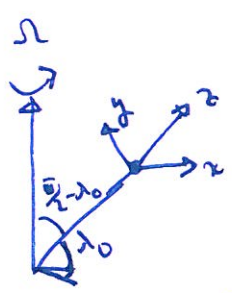
$$\rho_t + \nabla \cdot (\rho \underline{u}) = 0$$

$$\rho \left[\frac{d\underline{u}}{dt} + 2\underline{\Omega} \times \underline{u} \right] = -\nabla p - \rho g \hat{k}$$



The magnitude of $\underline{\Omega}$ is

$$2\bar{\omega} \text{ d}^{-1} = \frac{2\bar{\omega}}{24 \times 3600} \text{ s}^{-1} \approx 0.73 \times 10^{-4} \text{ s}^{-1}$$



Note $\underline{\Omega} = (0, \Omega \cos \lambda_0, \Omega \sin \lambda_0)$

$$\text{so } \underline{\Omega} \times \underline{u} = \begin{pmatrix} i & j & k \\ 0 & \Omega \cos \lambda_0 & \Omega \sin \lambda_0 \\ u & v & w \end{pmatrix} \approx (-\Omega v \sin \lambda_0, \Omega u \sin \lambda_0, -\Omega u \cos \lambda_0)$$

since $w \ll u, v$

Scaling the variables as prescribed in the question, we get

$$\rho_t + \nabla \cdot (\rho \underline{u}) = 0$$

$$\rho_0 \rho \left[\frac{U^2}{L} \frac{d\underline{u}}{dt} + \frac{2\Omega U \sin \lambda_0}{L} \underline{u} \right] = -\frac{\rho_0 \Omega U \sin \lambda_0}{L} \rho \underline{u}$$

∴ this $(\frac{2\Omega U \sin \lambda_0}{L} \rho)$

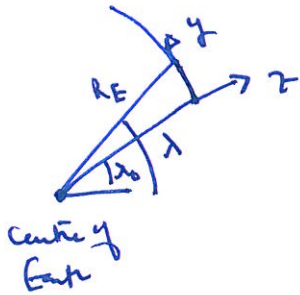
$$\frac{U^2}{2\rho \Omega U \sin \lambda_0} \frac{d\underline{u}}{dt} - f \underline{u} = -\frac{1}{\rho} \rho \underline{u}, \quad f = \frac{\Omega \sin \lambda_0}{L}$$

$$\text{i.e. } \underline{\varepsilon} \frac{d\underline{u}}{dt} - f \underline{u} = -\frac{1}{\rho} \rho \underline{u}$$

$$\underline{\varepsilon} = \frac{U}{2\Omega L \sin \lambda_0} \quad \text{Rossby number}$$

Similarly (the scales of the two are the same)

$$\varepsilon \frac{dv}{dt} + f u = -\frac{1}{\rho} P_y$$



we have $y = R_E \sin(\lambda - \lambda_0)$

and for $y \ll R_E$, $\lambda \approx \lambda_0$ & $y \approx R_E (\lambda - \lambda_0)$

thus $\lambda \approx \lambda_0 + \frac{y}{R_E}$

$$b \quad f = \frac{\sin(\lambda_0 + \frac{y}{R_E})}{\sin \lambda_0} \approx \frac{\sin \lambda_0 \cos \frac{y}{R_E} + \cos \lambda_0 \sin \frac{y}{R_E}}{\sin \lambda_0}$$

$$= \cancel{\sin \lambda_0} \left[1 - \frac{y^2}{2R_E^2} \dots + \cot \lambda_0 \frac{y}{R_E} \dots \right]$$

Δ non-dimensionally $f \approx 1 + \frac{\lambda \cot \lambda_0}{R_E} y$

$$= 1 + \varepsilon \beta y,$$

$$\beta = \frac{\lambda \cot \lambda_0}{\varepsilon R_E}$$

$$p = \frac{\Pi}{T}, \quad T = \theta \Pi^\alpha, \quad -\frac{\partial \Pi}{\partial z} = \rho$$



$$\Pi = \bar{\Pi} + \epsilon^2 P \quad \theta = \bar{\theta} + \epsilon^2 \Theta$$

$$p = \frac{\Pi^{1-\alpha}}{\theta} = \bar{p} + O(\epsilon^2), \quad \bar{p} = \frac{\bar{\Pi}^{1-\alpha}}{\bar{\theta}}$$

Now (non-d)

$$\rho_t + (\rho u)_x + (\rho v)_y + (\rho w)_z = 0$$

Thus $\bar{p}(u_x + v_y) + (\bar{p}w)_z = O(\epsilon^2)$

But also $-\bar{p}v = -p_x + O(\epsilon)$
 $\bar{p}u = -p_y + O(\epsilon)$ from momentum eqn

so $\bar{p}(u_x + v_y) = O(\epsilon)$

$\Rightarrow w = O(\epsilon)$ (from mass continuity)

Now we take $p = p_0 \Pi = p_0 \bar{\Pi} + \epsilon^2 P$
 but also $p = p_0 \bar{\Pi} + 2p_0 \Omega l U \sin \lambda_0 P$

and thus $\epsilon^2 = 2p_0 \Omega l U \sin \lambda_0$
 i.e. $\frac{p_0 \Omega^2 U^2}{(2\Omega l \sin \lambda_0)^2} = p_0 U (2\Omega l \sin \lambda_0)$

(earlier we had $p_0 \sim \rho_0 g h$)

so $U = \frac{g h}{\Omega l \sin \lambda_0}$

(6)

$$\lambda_0 = 45^\circ \Rightarrow \sin \lambda_0 = 0.7$$

$$U = \frac{8 \left[0.73 \times 10^{-4} \cdot 10^6 \text{ m} \cdot 0.7 \text{ s}^{-1} \right]^3}{9.8 \cdot 10^3 \text{ m s}^{-2}}$$

$$= \frac{8 \cdot 0.357^3 \cdot (0.7 \times 0.73)^3 \cdot 10^6 \text{ m s}^{-1}}{9.8 \cdot 10^3}$$

$$\sim 12 \text{ m s}^{-1}$$

Note that

$$\epsilon = \frac{12}{2 \cdot 0.73 \cdot 10^{-4} \cdot 0.7 \cdot 10^6} \sim 0.12$$

Next we have

$$-\frac{\partial \Pi}{\partial z} = p = \frac{\Pi^{1-\alpha}}{\Theta}, \quad \Pi = \bar{p} + \epsilon^2 P$$

$$\Theta = \bar{\theta} + \epsilon^2 \Theta$$

$$\begin{aligned} \Rightarrow -\frac{\partial \bar{p}}{\partial z} - \epsilon^2 \frac{\partial P}{\partial z} &= \frac{(\bar{p} + \epsilon^2 P)^{1-\alpha}}{\bar{\theta} + \epsilon^2 \Theta} = \frac{\bar{p}^{1-\alpha}}{\bar{\theta}} \left[1 + \epsilon^2 (1-\alpha) \frac{P}{\bar{p}} \dots \right] \left[1 - \frac{\epsilon^2 \Theta}{\bar{\theta}} \dots \right] \\ &= \frac{\bar{p}^{1-\alpha}}{\bar{\theta}} + \epsilon^2 \left\{ \frac{(1-\alpha) P}{\bar{\theta} \bar{p}^\alpha} - \frac{\bar{p}^{1-\alpha} \Theta}{\bar{\theta}^2} \right\} \dots \end{aligned}$$

Thus equating to terms of $O(\epsilon^2)$

$$\frac{\bar{p}^{1-\alpha}}{\bar{\theta}^2} \Theta = \frac{(1-\alpha) P}{\bar{\theta} \bar{p}^\alpha} + \frac{\partial P}{\partial z} \quad \left(\text{as well as } \frac{\partial \bar{p}}{\partial z} = -\frac{\bar{p}^{1-\alpha}}{\bar{\theta}} \right)$$

$$\Rightarrow \Theta = \bar{\theta}^2 \left[\frac{(1-\alpha) P}{\bar{\theta} \bar{p}^\alpha} + \frac{1}{\bar{p}^{1-\alpha}} \frac{\partial P}{\partial z} \right]$$

$$\text{Now note } \frac{\partial}{\partial z} \frac{1}{\bar{p}^{1-\alpha}} = -\frac{(1-\alpha)}{\bar{p}^{2-\alpha}} \frac{\partial \bar{p}}{\partial z} = \frac{(1-\alpha)}{\bar{p}^{2-\alpha}} \frac{\bar{p}^{1-\alpha}}{\bar{\theta}} = \frac{(1-\alpha)}{\bar{\theta} \bar{p}}$$

Therefore $\Theta = \bar{\theta}^2 \left[P \frac{\partial}{\partial z} \frac{1}{\bar{p}^{1-\alpha}} + \frac{1}{\bar{p}^{1-\alpha}} \frac{\partial P}{\partial z} \right]$

$$= \bar{\theta}^2 \frac{\partial}{\partial z} \left[\frac{P}{\bar{p}^{1-\alpha}} \right]$$

Define $P = \bar{p} \Psi$ and assume $\bar{\theta} \approx 1$

Then (geostrophy) $v \approx \frac{1}{\bar{p}} P_x$, $u \approx -\frac{1}{\bar{p}} P_y$
recip 3

$$\text{so } u \approx -\Psi_y, v \approx \Psi_x$$

$$\text{and } \Theta = \bar{\theta}^2 \frac{\partial}{\partial z} \left[\frac{\bar{p} \Psi}{\bar{p}^{1-\alpha}} \right] = \bar{\theta}^2 \frac{\partial}{\partial z} \left[\frac{\Psi}{\bar{\theta}} \right]$$

$$\left(\bar{p} \approx \frac{\bar{p}^{1-\alpha}}{\bar{\theta}} \right)$$

$$\Rightarrow \Theta \approx \Psi_z$$

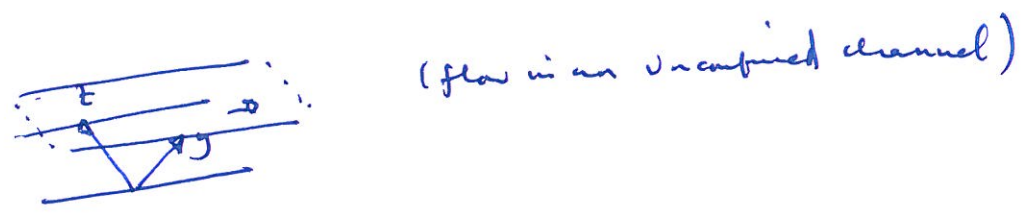
$$\text{thus } \frac{\partial u}{\partial z} \approx -\frac{\partial \Theta}{\partial y}, \quad \frac{\partial v}{\partial z} \approx \frac{\partial \Theta}{\partial x}$$

3/ with \bar{p} & S constant, $\beta = k = 0$,

$$\left[\frac{\partial}{\partial t} - \psi_y \frac{\partial}{\partial x} + \psi_x \frac{\partial}{\partial y} \right] \left[\nabla^2 \psi + \frac{1}{5} \psi_{zz} \right] = 0 \quad \left(\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right)$$

$\psi (\partial_t - \psi_y \partial_x + \psi_x \partial_y) \psi_z = 0$ at $z = 0, 1$

$\psi_x = 0$ at $y = 0, 1$



$\psi = -yz$ is a particular solution satisfying the bc's + eq.

with $\Theta = \psi_z = -y$

$\frac{\partial u}{\partial z} = -\Theta_y = 1, \frac{\partial v}{\partial z} = \Theta_x = 0$ (or just $u = -\psi_y = z, v = \psi_x = 0$)

this corresponds to ^{uniform} ~~total~~ shear flow.

Let $\psi = -yz + \Phi, \psi_y = -z + \Phi_y, \psi_x = \Phi_x, \psi_z = -y + \Phi_z$

$$\nabla^2 \psi + \frac{1}{5} \psi_{zz} = \nabla^2 \Phi + \frac{1}{5} \Phi_{zz} \ll 1$$

So linearized QGPVE is

$$\left(\frac{\partial}{\partial t} + z \frac{\partial}{\partial x} \right) \left(\nabla^2 \Phi + \frac{1}{5} \Phi_{zz} \right)$$

the linearized bc's are $\Phi_x = 0$ at $y = 0, 1$

$-\Phi_x + \left(\frac{\partial}{\partial t} + z \frac{\partial}{\partial x} \right) \Phi_z = 0$ at $z = 0, 1$.

(from ~~the~~ ψ)
 $\left[\frac{\partial}{\partial t} + (-z + \psi_y) \frac{\partial}{\partial x} + \psi_x \frac{\partial}{\partial y} \right] [-y + \psi_z]$

These are normal mode solutions

$$\Psi = A(z) e^{ik(z-ct)} \text{ satisfying } \text{which satisfy the } y=0, 1 \text{ b.c.'s}$$

[Note $\text{Re}[-ikc] = \text{Re}[-ik(c_r + i c_i)] = k c_i$ so stability is $\text{Im } c > 0$
The wave speed is $-\frac{\text{Im}[-ik(c_r + i c_i)]}{k} = c_r = \text{Re } c$]

and then

$$(-ikc + ikz) \left[-(k^2 + n^2 \pi^2) A + \frac{1}{S} A'' \right] = 0$$

where $(z-c)(A'' - \mu^2 A) = 0$ $\mu^2 = (k^2 + n^2 \pi^2) S > 0$

the b.c. is

$$-ikA + ik(z-c)A' = 0$$

~~$ik(z-c)A' = 0$ at $z=0, 1$~~

where

~~$A=0$ at $z=0, 1$~~
 $-A + (z-c)A' = 0$ at $z=0, 1$

(we exclude the trivial case $k=0$)

If $0 < c < 1$ then ~~the b.c.~~

~~for $z > c$ solutions $A'' - \mu^2 A = 0$ & $A' = 0$ at $z=0, 1$
 $\Rightarrow A=0$ at $z=0, 1$ for $z < c$.~~

~~However~~ these are solutions

$$A' - \mu^2 A = f(z-c)$$

which gives the Green's function $G(z, c)$ for the o.d.e. + homogeneous b.c.'s.

Since c is ^{then} real, these solutions are not unstable.

~~Some ...~~

The general solution is

$$A = a \cosh \mu z + b \sinh \mu z$$

$$\Rightarrow A' = \mu [a \sinh \mu z + b \cosh \mu z]$$

$$\text{at } z=0, \quad cA' + A = 0$$

$$\Rightarrow \mu cb + a = 0$$

$$\text{at } z=1, \text{ write } c_h = \cosh \mu, \quad s_h = \sinh \mu, \quad (1-c)A' = A$$

$$\text{Then } (1-c)\mu [a s_h + b c_h] = a c_h + b s_h$$

Since $a = -\mu cb$,

$$\Rightarrow (1-c)\mu [-\mu c s_h + c_h] = -\mu c c_h + s_h$$

$$\Rightarrow \mu^2 s_h (c^2 - c) + \mu c_h (1-c) + \mu c_h c - s_h = 0$$

$$\Rightarrow c^2 - c = \frac{s_h - \mu c_h}{\mu^2 s_h}$$

$$\text{so } c = \frac{1}{2} \pm \left[\frac{1}{4} + \frac{s_h - \mu c_h}{\mu^2 s_h} \right]^{\frac{1}{2}}$$

Comparing this with answer, we write

$$c = \frac{1}{2} \pm \frac{1}{\mu} \left[\frac{1}{4} \mu^2 + 1 + \frac{s_h - \mu c_h}{s_h} - 1 \right]^{\frac{1}{2}}$$

$$= \frac{1}{2} \pm \frac{1}{\mu} \left[\frac{1}{4} \mu^2 + 1 - \mu \coth \mu \right]^{\frac{1}{2}}$$

Now note that

$$\begin{aligned} & \frac{1}{2} (\coth \mu/2 + \tanh \mu/2) \\ &= \frac{1}{2} \left[\frac{\cosh \mu/2}{\sinh \mu/2} + \frac{\sinh \mu/2}{\cosh \mu/2} \right] \\ &= \frac{\cosh^2 \mu/2 + \sinh^2 \mu/2}{2 \sinh \mu/2 \cosh \mu/2} \\ &= \frac{\cosh \mu}{\sinh \mu} = \coth \mu \end{aligned}$$

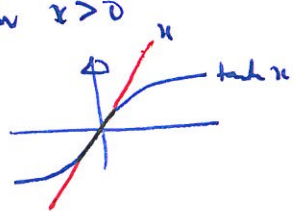
$$\begin{aligned} \text{thus } c &= \frac{1}{2} \pm \frac{1}{\mu} \left[\frac{1}{4} \mu^2 + 1 - \frac{\mu}{2} (\coth \mu/2 + \tanh \mu/2) \right]^{1/2} \\ &= \frac{1}{2} \pm \frac{1}{\mu} \left[(\mu - \coth \mu/2)(\mu - \tanh \mu/2) \right]^{1/2} \end{aligned}$$

The bond flow is unstable if $\text{Im } c > 0$

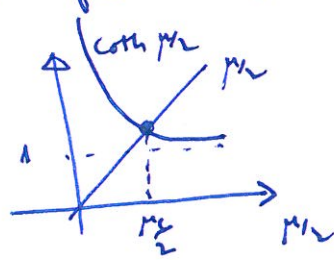
& since there are two conjugate roots, the sufficient condition is that $[] < 0$ in above.

Now μ is real and positive w.l.o.g. Also $\tanh x < x$ for $x > 0$

so $\mu - \tanh \mu > 0$.



Therefore the flow is unstable iff $\mu < \coth \mu/2$



iff $\mu < \mu_c$, where $\frac{\mu_c}{2} = \coth \frac{\mu_c}{2}$
 $(\mu_c \approx 2.4)$

So flow is unstable for

iff $S < \frac{\mu_c^2}{k^2 + n^2 \pi^2}$. Excluding $n=0$ (trivial) $\Rightarrow S < S_c = \frac{\mu_c^2}{\pi^2}$ for $n=1$ & $k \rightarrow 0$ (long wavelength)

4

$$(\alpha p_s)_t + (\alpha p_s v)_z = \Gamma$$

$$[p_e(1-\alpha)]_t + [p_e(1-\alpha)u]_z = -\Gamma$$

$$p_s(v_t + vv_z) = -p_z - M$$

$$p_e(u_t + u u_z) = -p_z + M$$

If written in the form $A\underline{y}_t + B\underline{y}_z = \underline{c}$

First if \underline{y} was scalar, the characteristics would be $\dot{z} = \frac{B}{A} = A^{-1}B$

↳ this generalises to systems:

$$\text{Suppose } A\underline{y}_t + B\underline{y}_z = \underline{c} \quad \text{or} \quad A^{-1}B\underline{w} = \lambda\underline{w}$$

$$\Rightarrow \det(A^{-1}B - \lambda) = 0$$

↳ suppose $A^{-1}B$ is diagonalisable,

$$A^{-1}B = PDP^{-1}, \quad D = \text{diag}(\lambda_i)$$

$$\text{Put } \underline{y} = P\underline{w}$$

$$\text{then } A(P\underline{w}_t + P\underline{w}_z) + B P\underline{w} = \underline{c}$$

$$\Rightarrow \underline{w}_t + P^{-1}A^{-1}BP\underline{w}_z = P^{-1}A^{-1}\underline{c} \quad \& \quad -P^{-1}A^{-1}AP_t\underline{w}$$

$$\text{i.e. } \underline{w}_t + D\underline{w}_z = P^{-1}A^{-1}\underline{c} - P^{-1}P_t\underline{w}$$

↳ the characteristics are $\dot{z} = \lambda_i$

$$\text{or which } \underline{u}_i = [P^{-1}A^{-1}\underline{c} - P^{-1}P_t\underline{w}]_i$$

More generally, $\det(\lambda A - B) = 0$.

(i) p_s, p_e constant, $\frac{p_s}{p_e} = \delta \ll 1$

$$\text{Thus } \alpha_f + v\alpha_z + a v_z = \frac{r}{p_s}$$

$$-\alpha_f = -u\alpha_e + (1-u)v_z = -\frac{r}{p_e}$$

$$p_s v_f + p_s v v_z + p_z = -M$$

$$p_e v_f + p_e u v_z + p_z = M$$

Let write $\underline{y} = \begin{pmatrix} \alpha \\ v \\ v_z \\ p \end{pmatrix}$

$$\underbrace{\begin{pmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & p_s & 0 \\ 0 & p_e & 0 & 0 \end{pmatrix}}_A \underline{y}_f + \underbrace{\begin{pmatrix} v & 0 & a & 0 \\ -u & (1-u) & 0 & 0 \\ 0 & 0 & p_s v & 1 \\ 0 & p_e u & 0 & 1 \end{pmatrix}}_B \underline{y}_z = \begin{pmatrix} r/p_s \\ -r/p_e \\ -M \\ M \end{pmatrix}$$

$\det(\lambda A - B)$

$$= \begin{vmatrix} \lambda - v & 0 & -a & 0 \\ -(\lambda - u) & -(1-u) & 0 & 0 \\ 0 & 0 & p_s(\lambda - v) & -1 \\ 0 & p_e(\lambda - u) & 0 & -1 \end{vmatrix} = 0$$

This gives

$$(\lambda - v) \left[-(1 - \alpha) p_g (\lambda - v) - 1 \right] - \alpha \left[-(\lambda - u) p_e (\lambda - D_e u) \right] = 0$$

$$u \approx p_g (1 - \alpha) (\lambda - v)^2 + p_e \alpha (\lambda - u) (\lambda - D_e u) = 0$$

with $\delta = \frac{p_g}{p_e} \ll 1$

$$\delta (1 - \alpha) (\lambda - v)^2 + \alpha (\lambda - u) (\lambda - D_e u) = 0$$

$$(\lambda - u) (\lambda - D_e u) \approx - \frac{\delta (1 - \alpha)}{\alpha} (\lambda - v)^2$$

Approximately $\lambda = u$ & $\lambda = D_e u$ are the (real) roots

& \approx connects u to u

$$\lambda - u = \frac{-\delta (1 - \alpha) (\lambda - v)^2}{\alpha (\lambda - D_e u)}$$

$$\Rightarrow \lambda \approx u + \frac{\delta (1 - \alpha) (u - v)^2}{\alpha (D_e - 1) u} \quad \text{etc.}$$

This only goes wrong if $D_e \sim \delta$.

(ii) Now suppose $\frac{dp_s}{dp} = \frac{1}{c_s^2}$, $\frac{dp_l}{dp} = \frac{1}{c_l^2}$

(c^s are sound speeds)

then equations are

$$p_g \alpha_T + \frac{\alpha}{c_g^2} p_T + p_g v \alpha_z + p_g \alpha v_z + \frac{\alpha v}{c_g^2} p_z = \Gamma$$

$$-p_l \alpha_T + \frac{(1-\alpha)}{c_l^2} p_T + p_l u \alpha_z + p_l (1-\alpha) u_z + \frac{(1-\alpha)u}{c_l^2} p_z = -\Gamma$$

~ (define $\Pi_h = p_h c_h^2$)

$$\alpha_T + \frac{\alpha}{\Pi_g} p_T + v \alpha_z + \alpha v_z + \frac{\alpha v}{\Pi_g} p_z = \frac{\Gamma}{p_g}$$

$$-\alpha_T + \frac{1-\alpha}{\Pi_l} p_T - u \alpha_z + (1-\alpha) u_z + \frac{(1-\alpha)u}{\Pi_l} p_z = -\frac{\Gamma}{p_l}$$

And $p_g v_T + p_g v v_z + p_z = -M$

$p_l u_T + p_l u u_z + p_z = M$

The red terms are the additions, thus

$$A = \begin{pmatrix} 1 & 0 & 0 & \frac{\alpha}{\Pi_g} \\ -1 & 0 & 0 & \frac{(1-\alpha)u}{\Pi_l} \\ 0 & 0 & p_g v & 1 \\ 0 & p_l u & 0 & 1 \end{pmatrix}, B = \begin{pmatrix} v & 0 & \alpha & \frac{\alpha v}{\Pi_g} \\ -u & (1-\alpha) & 0 & \frac{(1-\alpha)u}{\Pi_l} \\ 0 & 0 & p_g v & 1 \\ 0 & p_l u & 0 & 1 \end{pmatrix}$$

and thus

$$\det(\lambda A - B) = \begin{vmatrix} \lambda - v & 0 & -\alpha & \frac{\alpha}{n_g}(\lambda - v) \\ -(\lambda - u) & -(1-\alpha) & 0 & \frac{(1-\alpha)}{n_e}(\lambda - u) \\ 0 & 0 & p_g(\lambda - v) & -1 \\ 0 & p_e(\lambda - \theta_e u) & 0 & -1 \end{vmatrix} = 0$$

$$\begin{aligned} \Downarrow \\ \text{If } (\lambda - v) \left[(1-\alpha) p_g (\lambda - v) - \frac{(1-\alpha)}{n_e} (\lambda - u) p_g p_e (\lambda - v) (\lambda - \theta_e u) \right] \\ - \alpha \left[-(\lambda - u) p_e (\lambda - \theta_e u) \right] \\ - \frac{\alpha}{n_g} (\lambda - v) \left[-(\lambda - u) \cdot -p_g p_e (\lambda - v) (\lambda - \theta_e u) \right] = 0 \end{aligned}$$

$$\text{i.e. } p_g (1-\alpha) (\lambda - v)^2 + p_e \alpha (\lambda - u) (\lambda - \theta_e u)$$

$$- p_g p_e \left[\frac{1-\alpha}{n_e} + \frac{\alpha}{n_g} \right] (\lambda - v)^2 (\lambda - u) (\lambda - \theta_e u) = 0$$

Previously, we had $\lambda \sim u$

Let's suppose $v \sim u$ and $c_g \sim c_l$

If $\lambda \sim u$ the new term is $\sim \left[\frac{p_3}{c_l^2}, \frac{p_4}{c_g^2} \right] u^4 \ll p_l u^2$

So two approximate roots are $\lambda = u, \partial_l u$ as before.

As the new term is negligible, the other two roots are large

$$\text{Approximately } p_l \approx (\lambda - u)(\lambda - \partial_l u) - \frac{\alpha p_l}{c_g^2} (\lambda - v)^2 (\lambda - u)(\lambda - \partial_l u) \approx 0$$

So the other two roots are

$$\underline{\lambda = v \pm c_g} \quad \text{two round waves}$$

5)

Energy equation is

$$\rho L + \frac{\rho g}{\rho_s} (T_t + v T_z) + (1-\alpha) \rho_e c_{pe} (T_t + u T_z) - \{(\alpha \rho_s)_t + (\alpha \rho_s v)_z\} - [\{(1-\alpha) \rho_e\}_t + \{(1-\alpha) \rho_e u\}_z] = Q$$

where $\Gamma = (\alpha \rho_s)_t + (\alpha \rho_s v)_z = -[\{(1-\alpha) \rho_e\}_t + \{(1-\alpha) \rho_e u\}_z]$

Energy is thus

$$\rho L + \alpha \rho_s (h_{st} + v h_{sz}) + (1-\alpha) \rho_e (h_{et} + u h_{ez}) - \{(\alpha \rho_s)_t + (\alpha \rho_s v)_z\} - [\{(1-\alpha) \rho_e\}_t + \{(1-\alpha) \rho_e u\}_z] = Q$$

~~Now subtract~~ $(\alpha \rho_s)_t + (\alpha \rho_s v)_z$

viz $\Gamma (h_s - h_e) + \dots$

$$viz \rho_s [(\alpha \rho_s)_t + (\alpha \rho_s v)_z] + \alpha \rho_s (h_{st} + v h_{sz}) + h_e [\{(1-\alpha) \rho_e\}_t + \{(1-\alpha) \rho_e u\}_z] + (1-\alpha) \rho_e (h_{et} + u h_{ez}) - \dots = Q$$

$$viz (\alpha \rho_s h_s)_t + (\alpha \rho_s v h_s)_z - \{(\alpha \rho_s)_t - (\alpha \rho_s v)_z\} + \{(1-\alpha) \rho_e h_e\}_t + \{(1-\alpha) \rho_e h_e u\}_z - \{(1-\alpha) \rho_e\}_t - \{(1-\alpha) \rho_e u\}_z = Q$$

$$viz \{ \alpha (\rho_s h_s - \rho_s) \}_t + \{ \alpha v (\rho_s h_s - \rho_s) \}_z + \{ (1-\alpha) (\rho_e h_e - \rho_e) \}_t + \{ (1-\alpha) (\rho_e h_e - \rho_e) u \}_z = Q$$

$$u \frac{\partial}{\partial z} (\alpha \rho_g e_g)_t + (\alpha \rho_g e_g v) \frac{\partial}{\partial z} \\ + \{ (1-\alpha) \rho_l e_l \}_t + \{ (1-\alpha) \rho_l e_l u \}_z = Q$$

□

$$p = \rho_l (1-\alpha) + \rho_g \alpha$$

$$p = (1-\alpha) \rho_l + \alpha \rho_g$$

$$\rho e = \alpha \rho_g e_g + (1-\alpha) \rho_l e_l$$

$$h = e + \frac{p}{\rho}$$

$$\Rightarrow \rho h = \rho e + p = \alpha \rho_g e_g + (1-\alpha) \rho_l e_l \\ + \alpha \rho_g + (1-\alpha) \rho_l \\ = \alpha \rho_g h_g + (1-\alpha) \rho_l h_l$$

□

Now suppose $u = v$ (homogeneous flow)

The energy equation is then

$$\{ \alpha \rho_g e_g + (1-\alpha) \rho_l e_l \}_t + [\{ \alpha \rho_g e_g + (1-\alpha) \rho_l e_l \} u]_z = Q$$

$$\text{i.e. } (\rho e)_t + (\rho e u)_z = Q$$

$$\hookrightarrow \rho_t + (\rho u)_z = 0 \quad \text{so } \underline{\rho \frac{de}{dt} = Q}, \quad \frac{d}{dt} = \frac{\partial}{\partial t} + u \frac{\partial}{\partial z}$$

We have $h = e + \frac{p}{\rho}$. When $\alpha = 0$, $p = \rho_l$, $e = e_l$, $p = \rho_l$

$$\Rightarrow h = h_l$$

$$\text{Similarly } \alpha = 1 \quad h = h_g$$

$$\text{So as } \alpha : 0 \rightarrow 1 \quad \Delta h \approx h_2 - h_1 = L$$

$$\text{and } \Delta h = \Delta e + \frac{\Delta p}{\rho}$$

$$\Delta \left(\frac{p}{\rho} \right) < \frac{\Delta p}{\rho_2}$$

$$\text{So if } \Delta p \ll \rho_2 L \text{ then } \Delta \left(\frac{p}{\rho} \right) \ll \Delta h$$

$$\Rightarrow \underline{h \approx e}$$

$$\text{In this case } \rho \frac{dh}{dt} \approx Q$$

$$\text{Now } p = p_e - \Delta p <$$

$$\Delta p = p_e - p_s$$

$$\Rightarrow \alpha = \frac{p_e - p_s}{\Delta p}$$

$$\Delta p h = \alpha p_s h_s + (1 - \alpha) p_e h_e$$

$$= p_e h_e + (p_s h_s - p_e h_e) \frac{(p_e - p_s)}{\Delta p}$$

$$= \frac{p_e h_e (p_e - p_s) + (p_s h_s - p_e h_e) p_e}{\Delta p} - (p_s h_s - p_e h_e) p$$

$$\text{thus } h = \frac{p_e p_s L}{\Delta p \rho} - \frac{(p_s h_s - p_e h_e)}{\Delta p}$$

$$\text{then } \rho \frac{dh}{dt} = \frac{p_e p_s L}{\Delta p} \cdot \rho \cdot \frac{-1}{c^2} \frac{dp}{dt} = \frac{p_e p_s L}{\Delta p} u_z = Q$$

(note $\frac{dp}{dt} = -\rho u_z$)

$$\Rightarrow \underline{u_z = \frac{(p_e - p_s) Q}{p_e p_s L}}$$

6/

$$\rho_t + u \rho_z = -u_z \rho$$

$$\rho(u_t + u u_z) = -\rho_z - \rho g - \frac{4\beta \rho_e u^2}{d}$$

$$\rho(h_t + u h_z) = Q$$

$$h \approx h^* + \frac{\rho_g L}{\rho} \quad (\text{if } \alpha > 0)$$

$$z=0 \quad h=h_0, \quad u=U(t)$$

$$z=r \quad h=h_{\text{set}}$$

$$\text{For } z < r, \quad \rho = \rho_e, \quad h_t + u h_z = \frac{Q}{\rho_e}, \quad u = U(t) \quad (\text{as } u_z = 0)$$

$$\text{characteristics} \quad \begin{aligned} \dot{z} &= U \\ \dot{h} &= \frac{Q}{\rho_e} \end{aligned}, \quad z=0, \quad t=\eta, \quad h=h_0$$

$$\Rightarrow h = \frac{Q}{\rho_e} (t - \eta) + h_0, \quad z = \int_{\eta}^t U(s) ds$$

$$\text{on } z=r(t), \quad h=h_{\text{set}} \Rightarrow \eta = t - \frac{\rho_e (h_{\text{set}} - h_0)}{Q} = t - \tau, \quad \tau = \frac{\rho_e (h_{\text{set}} - h_0)}{Q}$$

$$\text{thus } r = \int_{t-\tau}^t U(s) ds$$

In the single-phase region the pressure drop is

$$\begin{aligned} \Delta p_{\text{sp}} &= \int_0^r -\rho_z dz = \int_0^r \left[\rho_e \dot{U} + \rho_e g + \frac{4\beta \rho_e U^2}{d} \right] dz \\ &= \left[\rho_e \dot{U} + \rho_e g + \frac{4\beta \rho_e U^2}{d} \right] r \end{aligned}$$

Non-dimensionalise via

$$p \sim p_e, z, r \sim l, t \sim \tau, u, V \sim u_0 = \frac{Q}{\pi}$$

(non-d)

$$\Rightarrow \Delta p_{sp} = \left[\rho_e u_0^2 \dot{U} + \rho_e g l + \frac{4 f l \rho_e u_0^2}{d} U^2 \right] r$$

$$= \left[\Delta p_i \dot{U} + \Delta p_g + \Delta p_f U^2 \right] r, \text{ also } r = \int_{t-1}^t u(s) ds$$

$$\Delta p_i = \rho_e u_0^2$$

$$\Delta p_g = \rho_e g l$$

$$\Delta p_f = \frac{4 f l \rho_e u_0^2}{d}$$

(all non-d)

For $z \gg r$

$$p_t + u p_z = -u_z p$$

↳ also (dimensional): $p \cdot \rho_3 L \cdot -\frac{1}{\rho^2} \frac{dp}{dz} = Q$

$$\text{or } \rho_3 L u_z = Q$$

$$\left(\frac{dp}{dz} = -u_z \rho \right)$$

$$\text{non-d } u_z = \frac{Q l}{\rho_3 L u_0} = \frac{Q \tau}{\rho_3 L} = \frac{\rho_e \Delta h}{\rho_3 L}, \Delta h = h_{\text{stat}} - h_0$$

Define $\varepsilon = \frac{\rho_3 L}{\rho_e \Delta h}$

then $u_z = \frac{1}{\varepsilon} \Rightarrow u = U$ at $z = r$

$$\Rightarrow u = U + \frac{z-r}{\varepsilon}$$

The characteristics for p are thus (non-d)

$$\dot{z} = u = U + \frac{z-r}{\epsilon}$$

$$\dot{p} = -\frac{1}{\epsilon} p$$

$$\Delta \quad t = \eta, \quad z = r(\eta), \quad p = 1$$

solving $p = \exp[-(t-\eta)/\epsilon] \Rightarrow \eta = t - \epsilon \ln \frac{1}{p}$

$$\dot{z} = U + \frac{z-r}{\epsilon}$$

$$\dot{z} - \frac{z}{\epsilon} = U - \frac{r}{\epsilon}$$

$$(z e^{-t/\epsilon})' = (U - \frac{r}{\epsilon}) e^{-t/\epsilon}$$

$$z e^{-t/\epsilon} = ~~r(\eta)~~ r(\eta) e^{-\eta/\epsilon} + \int_{\eta}^t \left\{ U(s) - \frac{r(s)}{\epsilon} \right\} e^{-s/\epsilon} ds$$

$$\text{or } z = r(\eta) e^{\frac{t-\eta}{\epsilon}} + \int_{\eta}^t \left\{ U(s) - \frac{r(s)}{\epsilon} \right\} e^{\frac{t-s}{\epsilon}} ds$$

making $s = t - \epsilon \xi, \eta = t - \epsilon \ln \frac{1}{p}$, note when $s = \eta, \xi = \ln \frac{1}{p}$

$$z = r\left(t - \epsilon \ln \frac{1}{p}\right) \frac{1}{p} + \int_0^{\ln \frac{1}{p}} \left\{ \epsilon U(t - \epsilon \xi) - r(t - \epsilon \xi) \right\} e^{\xi} d\xi$$

Integrating by parts, $\int_0^{\ln \frac{1}{p}} r(t - \epsilon \xi) e^{\xi} d\xi$

$$= \left[e^{\xi} r(t - \epsilon \xi) \right]_0^{\ln \frac{1}{p}} + \epsilon \int_0^{\ln \frac{1}{p}} e^{\xi} r'(t - \epsilon \xi) d\xi$$

$$= r\left(t - \epsilon \ln \frac{1}{p}\right) \frac{1}{p} - r(t) + \epsilon \int_0^{\ln \frac{1}{p}} e^{\xi} [U(t - \epsilon \xi) - U_1(t - \epsilon \xi)] d\xi$$

$\{ U_1(t) = U(t-1) \}$

Thus

$$z = r(t - \epsilon \ln \frac{1}{\rho}) \cdot \frac{1}{\rho} + \int_0^{\ln \frac{1}{\rho}} \epsilon U(t - \epsilon \xi) e^{\xi} d\xi$$

$$- \left[r(t - \epsilon \ln \frac{1}{\rho}) \cdot \frac{1}{\rho} - r(t) + \epsilon \int_0^{\ln \frac{1}{\rho}} e^{\xi} [U(t - \epsilon \xi) - U_1(t - \epsilon \xi)] d\xi \right]$$

$$= r(t) + \epsilon \int_0^{\ln \frac{1}{\rho}} U_1(t - \epsilon \xi) e^{\xi} d\xi$$

In dimensional terms, the two-phase pressure drop is

$$\Delta p_{tp} = \int_r^z \left[(\rho u)_t + (\rho u^2)_z + \rho g + \frac{4f\rho}{d} u^2 \right] dz$$

The LHS in dimensional terms $\Phi(p, u)$ is

$$\Delta p_i \int_r^z \underbrace{[(\rho u)_t + (\rho u^2)_z]}_{\Phi_i} dz + \Delta p_g \int_r^z \underbrace{\rho}_{\Phi_g} dz + \Delta p_f \int_r^z \underbrace{\rho u^2}_{\Phi_f} dz$$

Steady state

$U = V$, $r = V$. We need $V < 1$ so there is a two-phase region!

We have in the two-phase region $u = V + \frac{z-V}{\epsilon}$, $\rho u = V$

Then $\Delta p = \Delta p_g + \Delta p_{tp}$

$$= (\Delta p_g + \Delta p_f V^2) V$$

$$+ \Delta p_i \left[\Phi u \right]_r^z + \Delta p_g \int_r^z \frac{V dz}{u} + \Delta p_f \int_r^z u dz$$

Use $\Delta p = (\Delta p_s + \Delta p_f v^2) V$

$$+ \Delta p_i \frac{(1-v)}{\epsilon} + \Delta p_f V \epsilon \ln \left[\frac{v + \frac{(1-v)}{\epsilon}}{v} \right] + \Delta p_f \left[v^2 + \frac{(2-v)^2}{2\epsilon} \right]_v^1$$

Use

$$\Delta p = \Delta p_i \frac{(1-v)}{\epsilon} + \Delta p_f V \left[1 + \epsilon \ln \left\{ 1 + \frac{(1-v)}{\epsilon v} \right\} \right] + \Delta p_f \left[v^3 + v(1-v) + \frac{(1-v)^2}{2\epsilon} \right]$$

If v is sufficiently close to 1

$$\Delta p \sim \Delta p_f v + \Delta p_f v^3 \quad \uparrow \text{ with } v$$

small ϵ

$$\Delta p \approx \frac{1}{\epsilon} \left[\Delta p_i (1-v) + \frac{1}{2} \Delta p_f (1-v)^2 \right] \quad \downarrow \text{ with } v (< 1)$$

[This is the Ledney instability, since $\frac{d\Delta p}{dv} < 0$.] □

Next, $\Delta p_i = \Delta p_s = 0$, thus

$$\Delta p \approx \Delta p_f \frac{\Delta p}{\Delta p_f} = \Pi, \text{ say, } = U^2 r \quad + \int_r^1 \rho u^2 dz$$

Single phase two phase

Linear stability

(26)

with

$$U = V + v, \quad r = r_0 + r_1, \quad u = u_0 + u_1, \quad p = p_0 + p_1$$

we have $r_0 = V, \quad u_0 = V + \frac{z-V}{\epsilon}, \quad p_0 = \frac{\rho_0}{\rho_0} \frac{V}{u_0} = \frac{V}{V + \frac{z-V}{\epsilon}}$

$$r = \int_{t-1}^t U(s) ds$$

$$\text{so } r_1 = \int_{t-1}^t v ds$$

$$u = U + \frac{z-r}{\epsilon} \Rightarrow u_1 = v - \frac{r_1}{\epsilon}$$

Note also $z = r(t) + \epsilon \int_0^{\frac{t}{\epsilon}} U_1(t-\epsilon\xi) e^{\xi} d\xi$

$$= r_0 + r_1 + \epsilon \int_0^{\frac{t}{\epsilon}} \left\{ V + v_1(t-\epsilon\xi) \right\} e^{\xi} d\xi$$

$$\begin{aligned} \ln \frac{1}{p} &= -\ln p \\ &= -\ln(p_0 + p_1) \\ &= -\ln p_0 - \frac{p_1}{p_0} \dots \end{aligned}$$

linearizing

$$0 = r_1 + \epsilon \int_0^{\frac{t}{\epsilon}} v_1(t-\epsilon\xi) e^{\xi} d\xi$$

$$-\frac{\epsilon p_1}{p_0} \frac{V}{p_0}$$

$$\Rightarrow p_1 \approx \frac{\rho_0^2}{V} \left[\frac{r_1}{\epsilon} + \int_0^{\frac{t}{\epsilon}} v_1(t-\epsilon\xi) e^{\xi} d\xi \right]$$

$$\approx U^2 r + \int_r^1 \rho u^2 dz$$

Linearizing the condition $\frac{\Delta p}{\Delta p_1} = \text{constant}$, we have

$$0 = V^2 r_1 + 2V^2 v \quad \neq \quad -r_1 p_0 u_0^2 \Big|_{r_0} + \int_{r_0}^1 p_1 u_0^2 dz + \int_{r_0}^1 2p_0 u_0 u_1 dz$$

$$= \underbrace{V^2 r_1 + 2V^2 v}_{\text{single phase}} - V^2 r_1 + \int_{r_0}^1 (p_1 u_0^2 + 2p_0 u_0 u_1) dz$$

$$\text{ii } 2V^2 v + \int_{r_0}^1 (p_1 u_0^2 + 2p_0 u_0 u_1) dz = 0$$

s.p.

$$\text{Since } p_0 u_0 = V,$$

$$p_1 u_0^2 = V \left[\frac{\eta}{\varepsilon} + \int_0^{\frac{1}{p_0}} v_1(t - \varepsilon \xi) e^{\xi} d\xi \right]$$

$$\text{So } \left[+V^2 r_1 \quad -V^2 r_1 \right] \\ 0 = 2V^2 r + \int_{r_0}^1 V \left[2u_1 + \frac{\eta}{\varepsilon} + \int_0^{\frac{1}{p_0}} v_1(t - \varepsilon \xi) e^{\xi} d\xi \right] dz \quad \leftarrow$$

s.p.

$$\text{Now we put } v = e^{\sigma t};$$

$$\text{then } r_1 = \frac{1}{\sigma} (1 - e^{-\sigma}) e^{\sigma t}$$

$$u_1 = \left[1 - \frac{1}{\varepsilon \sigma} (1 - e^{-\sigma}) \right] e^{\sigma t}$$

$$\text{we have } \int_0^{\frac{1}{p_0}} v_1(t - \varepsilon \xi) e^{\xi} d\xi = \int_0^{\frac{1}{p_0}} e^{\sigma(t - \varepsilon \xi)} e^{\xi} d\xi \\ = e^{\sigma t} \int_0^{\frac{1}{p_0}} e^{(1 - \varepsilon \sigma) \xi} d\xi \times e^{-\sigma} \\ = e^{\sigma t} \left[\frac{e^{-\sigma}}{1 - \varepsilon \sigma} \left\{ \frac{1}{p_0^{1 - \varepsilon \sigma}} - 1 \right\} \right] \\ = \frac{e^{\sigma t} e^{-\sigma}}{1 - \varepsilon \sigma} \left[\left(1 + \frac{2 - V}{\varepsilon V} \right)^{1 - \varepsilon \sigma} - 1 \right],$$

$$\text{So } \left[+V^2 r_1 \quad -V^2 r_1 \right] \\ 2V^2 r + \underbrace{V(1-V) \left[2 \left\{ 1 - \frac{1}{\varepsilon \sigma} (1 - e^{-\sigma}) \right\} + \frac{1}{\varepsilon \sigma} (1 - e^{-\sigma}) \right]}_{2 - \frac{1}{\varepsilon \sigma} (1 - e^{-\sigma})} \\ + \frac{V e^{\sigma}}{1 - \varepsilon \sigma} \int_V^1 \left\{ \left(1 + \frac{2 - V}{\varepsilon V} \right)^{1 - \varepsilon \sigma} - 1 \right\} dz = 0 \quad \text{s.p.}$$

viz

$$2V^2 \left[+V^2 \frac{1}{\sigma} (1-e^{-\sigma}) - V^2 \frac{1}{\sigma} (1-e^{-\sigma}) \right]$$

single phase $0 \leq \tau < \infty$

$$+ v(1-v) \left[2 - \frac{1}{\varepsilon\sigma} (1-e^{-\sigma}) \right]$$

$$+ \frac{v e^{-\sigma}}{(1-\varepsilon\sigma)} \left[\frac{\varepsilon v}{2-\varepsilon\sigma} \left\{ \left(1 + \frac{1-v}{\varepsilon v} \right)^{2-\varepsilon\sigma} - 1 \right\} - (1-v) \right] = 0$$

(9) only include the single-phase pressure drop:

$$\Rightarrow 2V^2 + V^2 \frac{1}{\sigma} (1-e^{-\sigma}) = 0$$

$$\text{Then } \frac{1}{\sigma} (1-e^{-\sigma}) + 2 = 0$$

$$\Rightarrow \underline{\sigma = -\frac{1}{2}(1-e^{-\sigma})}$$

Suppose $\text{Re}\sigma > 0$: then $|e^{-\sigma}| < 1$, so $\text{Re}(1-e^{-\sigma}) > 0$

$$\text{so } \text{Re}\sigma = -\frac{1}{2} \text{Re}(1-e^{-\sigma}) < 0 \cdot \lambda \Rightarrow \text{Re}\sigma < 0$$

(note $\sigma = 0$ is always a root: since $\frac{\Delta p}{\Delta p_f} = U^2(t) \int_{t-1}^t U(s) ds$)

this is associated with time translational invariance.)

(b) only two-phase pressure drop:

$$\Rightarrow -V^2 \frac{1}{\sigma} (1 - e^{-\sigma}) + 2V(1-V) - V(1-V) \frac{1}{\epsilon \sigma} (1 - e^{-\sigma}) \sim \frac{1}{\epsilon}$$

$$+ \frac{V e^{-\sigma}}{1 - \epsilon \sigma} \left[\underbrace{\frac{\epsilon V}{2 - \epsilon \sigma} \left\{ \left(1 + \frac{1-V}{\epsilon V}\right)^{2 - \epsilon \sigma} - 1 \right\}}_{\sim \frac{1}{\epsilon}} - (1-V) \right] = 0$$

$\epsilon \ll 1$,

$$\text{approx } -V(1-V) \frac{1}{\sigma} (1 - e^{-\sigma}) + V e^{-\sigma} \frac{\epsilon V}{2} \left(\frac{1-V}{\epsilon V} \right)^2 = 0$$

$$\Rightarrow -V(1-V) \frac{2V^2}{V^2 (1-V)^2} (e^{\sigma} - 1) + \sigma = 0$$

$$\Rightarrow \sigma = \gamma (e^{\sigma} - 1), \quad \gamma = \frac{2V}{1-V} > 0$$

As $\sigma \rightarrow \infty$ (LHS) we must have $e^{\sigma} \rightarrow \infty \Rightarrow \text{Re } \sigma > 0 \text{ and } \sigma \rightarrow \infty$

\Rightarrow ill-posedness

(c) Use both pressure drops for the small ϵ approx

$$\Rightarrow 2V^2 - \frac{V(1-V)}{\epsilon} \frac{1}{\sigma} (1 - e^{-\sigma}) + \frac{\epsilon V^2 e^{-\sigma}}{2} \frac{(1-V)^2}{\epsilon^2 V^2} \approx 0$$

$$\Rightarrow \frac{4\epsilon V^2}{(1-V)^2} - \gamma \frac{1}{\sigma} (1 - e^{-\sigma}) + e^{-\sigma} = 0$$

$$\text{Define } \delta = \frac{4\epsilon V^2}{(1-V)^2}, \quad \Rightarrow \delta \sigma - \gamma + \gamma e^{-\sigma} + \sigma e^{-\sigma} = 0$$

$$\Rightarrow \sigma = \frac{\gamma(1 - e^{-\sigma})}{\delta + e^{-\sigma}}$$

Now as $\sigma \rightarrow \infty$ (LHS) we must have

$$e^{-\sigma} \rightarrow -\delta$$

$$\approx e^{\sigma} \rightarrow -\frac{1}{\delta}$$

$$\sigma \rightarrow \ln \frac{1}{\delta} + (2n+1)i\pi$$

is ill-posed for $\delta < 1$ (as then $\text{Re } \sigma > 0$ as $n \rightarrow \infty$)

(d) If we also include the inertial term in the single-phase region

$\Delta p_i \dot{U}$, then (c) is modified to

$$\frac{\Delta p_i}{\Delta p_f} \sigma + 2v^2 - \frac{v(1-v)}{\varepsilon} \frac{1}{\sigma} (1-e^{-\sigma}) + \frac{(1-v)^2}{2\varepsilon} e^{-\sigma} = 0$$

$$\Rightarrow v\sigma + \delta - \gamma \frac{1}{\sigma} (1-e^{-\sigma}) + e^{-\sigma} = 0, \quad v = \frac{2\varepsilon \Delta p_i}{(1-v)^2 \Delta p_f}$$

$$\Rightarrow v\sigma^2 + \sigma(\delta + e^{-\sigma}) - \gamma(1-e^{-\sigma}) = 0$$

$$\delta = \frac{4\varepsilon v^2}{(1-v)^2}$$

Now as $\sigma \rightarrow \infty$ we must have $\sigma(\delta + e^{-\sigma}) \gg \gamma(1-e^{-\sigma})$

So we must have

$$v\sigma^2 \approx -\sigma(\delta + e^{-\sigma})$$

$$\text{i.e. } \underline{v\sigma \approx -\delta - e^{-\sigma}}$$

LHS $\rightarrow \infty \Rightarrow e^{-\sigma} \rightarrow 0 \Rightarrow \text{Re } \sigma \rightarrow -\infty \Rightarrow$ well-posed.

Instability Clearly as $v, \delta \rightarrow 0$ there is instability because of (b)

Therefore the steady state is unstable for sufficiently small v & δ , i.e. small enough ε .