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# Lecture 2: Methods for local unconstrained optimization. Linesearch methods

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C6.2/B2: Continuous Optimization

# Methods for local unconstrained optimization

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minimize  $f(x)$  subject to  $x \in \mathbb{R}^n$  (UP) [ $f \in \mathcal{C}^1(\mathbb{R}^n)$  or  $f \in \mathcal{C}^2(\mathbb{R}^n)$ ]

## A Generic Method (GM)

Choose  $\epsilon > 0$  and  $x^0 \in \mathbb{R}^n$ .

While (TERMINATION CRITERIA not achieved), REPEAT:

- compute the change

$$x^{k+1} - x^k = F(x^k, \text{problem data}), \quad [\text{linesearch, trust-region}]$$

to ensure  $f(x^{k+1}) \leq f(x^k)$ .

- set  $x^{k+1} := x^k + F(x^k, \text{prob. data})$ ,  $k := k + 1$ .  $\square$

- TC:  $\|\nabla f(x^k)\| \leq \epsilon$ ; maybe also,  $\lambda_{\min}(\nabla^2 f(x^k)) \geq -\epsilon$ .
- e.g.,  $x^{k+1} \equiv$  minimizer of some (simple) model of  $f$  around  $x^k$   
→ linesearch, trust-region methods.
- if  $F = F(x_k, x_{k-1}, \text{problem data})$  → conjugate gradients mthd.

# Issues to consider about GM

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**Finite termination of GM:** for any  $\epsilon > 0$ , there exists  $k$  such that  $\|\nabla f(x^k)\| \leq \epsilon$ ?  $\iff \liminf_{k \rightarrow \infty} \|\nabla f(x^k)\| = 0$

**Global convergence of GM:** if  $\epsilon := 0$  and any  $x^0 \in \mathbb{R}^n$ :  
 $\nabla f(x^k) \rightarrow 0$ , as  $k \rightarrow \infty$ ? all limit points of  $\{x^k\}$  are then stationary.  
[maybe also,  $\liminf_{k \rightarrow \infty} \lambda_{\min}(\nabla^2 f(x^k)) \geq 0$ ?]

**Local convergence of GM:**

if  $\epsilon := 0$  and  $x^0$  sufficiently close to  $x^* \equiv$  stationary/local minimizer of  $f$ :  $x^k \rightarrow x^*$ ,  $k \rightarrow \infty$ ?

**Global/local complexity of GM:** count number of iterations and their cost required by GM to generate  $x^k$  within desired accuracy  $\epsilon > 0$ , e.g., such that  $\|\nabla f(x^k)\| \leq \epsilon$ .

[connection to convergence and its rate]

**Rate of global/local convergence of GM.**

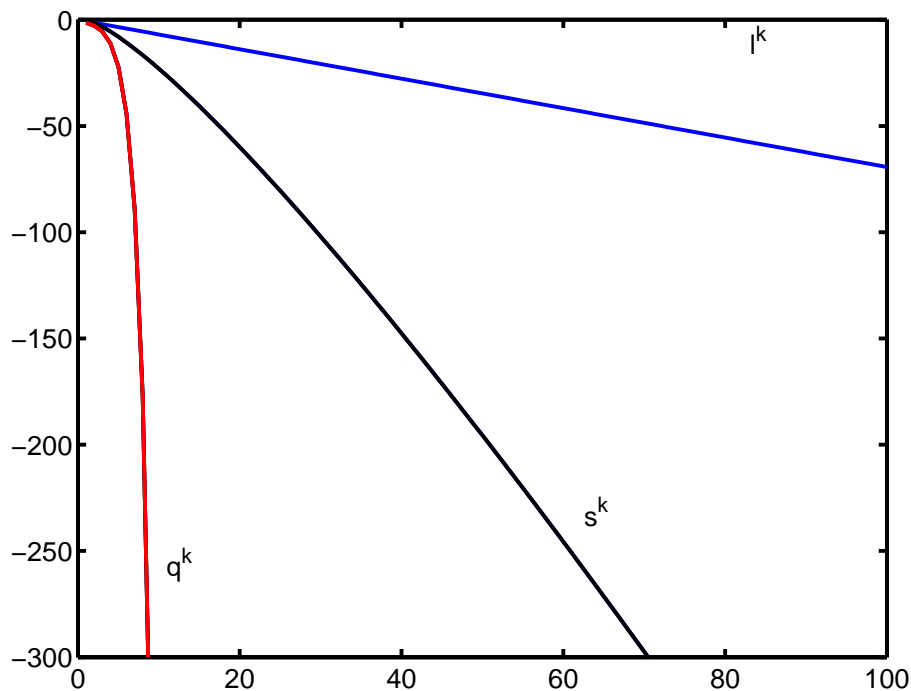
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# Rates of convergence of sequences: an example

$l^k := (1/2)^k \longrightarrow 0$  linearly,

$q^k := (1/2)^{2^k} \longrightarrow 0$  quadratically,

$s^k := k^{-k} \longrightarrow 0$  superlinearly as  $k \longrightarrow \infty$ .



$k$	$l^k$	$q^k$
0	1	0.5
1	0.5	0.25
2	0.25	$0.6 \cdot (-1)$
3	0.12	$0.4 \cdot (-2)$
4	$0.6 \cdot (-2)$	$0.1 \cdot (-4)$
5	$0.3 \cdot (-2)$	$0.2 \cdot (-9)$
6	$0.2 \cdot (-2)$	$0.5 \cdot (-19)$

Rates of convergence on a log scale.

Notation:  $(-i) := 10^{-i}$ .

# Rates of convergence of sequences

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$\{x^k\} \subset \mathbb{R}^n, x^* \in \mathbb{R}^n; x^k \rightarrow x^*$  as  $k \rightarrow \infty$ .

**p-Rate of convergence:**  $x^k \rightarrow x^*$  with rate  $p \geq 1$  if  $\exists \rho > 0$  and  $k_0 \geq 0$  such that

$$\|x^{k+1} - x^*\| \leq \rho \|x^k - x^*\|^p, \quad \forall k \geq k_0.$$

■  $\rho$  convergence factor;  $e^k := x^k - x^*$  error in  $x^k \approx x^*$ .

**Linear convergence:**  $p = 1 \Rightarrow \rho < 1$ ; (asymptotically,  
no of correct digits grows linearly in the number of iterations.)

**Quadratic convergence:**  $p = 2$ ; (asymptotically,  
no of correct digits grows exponentially in the number of  
iterations.)

**Superlinear convergence:**  $\|x^{k+1} - x^*\| / \|x^k - x^*\| \rightarrow 0$  as  
 $k \rightarrow \infty$ . [faster than linear, slower than quadratic; practically very acceptable]

# Summary: methods for local unconstrained probs.

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Consider (UP), with  $f \in \mathcal{C}^1(\mathbb{R}^n)$  or  $\mathcal{C}^2(\mathbb{R}^n)$ .

## Methods:

- iterative: start from any initial ‘guess’  $x^0$ , generate  $x^k$ ,  $k \geq 0$ .
- find (approximate) local solutions, unless special structure (convexity, etc.)
- terminate when iterate within  $\epsilon$  of local optimality.

**Issues:** global convergence, local convergence, rate of convergence, complexity.

## Information employed on each iteration:

current  $x^k$ : **linesearch** and **trust-region** methods

current+previous: **conjugate-gradients** method etc

# A generic linesearch method

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(UP): minimize  $f(x)$  subject to  $x \in \mathbb{R}^n$ , where  $f \in \mathcal{C}^1$  or  $\mathcal{C}^2(\mathbb{R}^n)$ .

## A Generic Linesearch Method (GLM)

Choose  $\epsilon > 0$  and  $x^0 \in \mathbb{R}^n$ .

While  $\|\nabla f(x^k)\| > \epsilon$ , REPEAT:

- compute a descent search direction  $s^k \in \mathbb{R}^n$ ,

$$\nabla f(x^k)^T s^k < 0;$$

- compute a stepsize  $\alpha^k > 0$  along  $s^k$  such that

$$f(x^k + \alpha^k s^k) < f(x^k);$$

- set  $x^{k+1} := x^k + \alpha^k s^k$  and  $k := k + 1$ .  $\square$

Recall property of descent directions (Lemma 1, Lecture 1).

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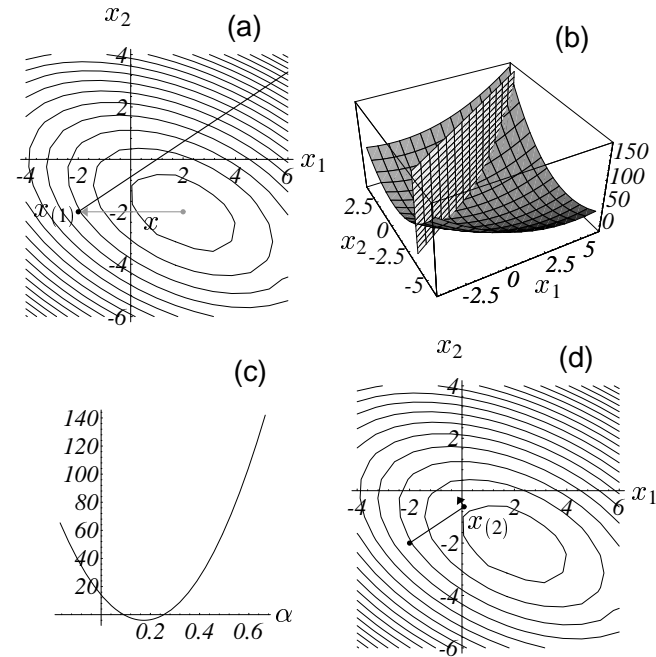
# Performing a linesearch

How to compute  $\alpha^k$ ?

Exact linesearch:

$$\alpha^k := \arg \min_{\alpha > 0} f(x^k + \alpha s^k).$$

- computationally expensive for nonlinear objectives.



Exact linesearch for quadratic functions

**Example:**  $q(x) = \frac{1}{2}x^T \begin{pmatrix} 3 & 2 \\ 2 & 6 \end{pmatrix} x + (-2 \ 8)^T x$ , where  $x \in \mathbb{R}^2$ .

Let  $x^1 := (-2 \ -2)^T$  and  $s^1 := -\nabla q(x^1) = (12 \ 8)^T$ .

Figure (a): contours of  $q$  and the line  $x^1 + \alpha s^1$ ; (b): the plane  $z(\alpha) = x^1 + \alpha s^1$  is shown cutting the  $q$ -surface; (c): plot of  $\phi(\alpha)$ ; (d):  $x^2$  is shown and  $\phi'(\alpha^*) = 0$ . (see next slide) □



# Exact linesearches for quadratic objectives

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$$q(x) = g^T x + \frac{1}{2} x^T H x, \quad x \in \mathbb{R}^n,$$

and let  $\phi_k(\alpha) := q(x^k + \alpha s^k)$ . Then

$$\begin{aligned} \phi'(\alpha) &= \frac{d}{d\alpha} \phi(\alpha) = \sum_{i=1}^n \frac{dx_i}{d\alpha} \cdot \frac{\partial}{\partial x_i} \phi(\alpha) \\ &= \sum_{i=1}^n s_i^k \frac{\partial}{\partial x_i} q(x^k + \alpha s^k) = (s^k)^T \nabla q(x^k + \alpha s^k). \end{aligned}$$

$$\blacksquare \nabla q(x) = g + Hx \text{ and } \nabla q(x^k + \alpha s^k) = g + H(x^k + \alpha s^k).$$

$$\implies \phi'(\alpha) = (s^k)^T \nabla q(x^k) + \alpha (s^k)^T H s^k.$$

Thus  $\alpha^*$  stationary point of  $\phi(\alpha)$  iff  $(s^k)^T H s^k \neq 0$  and

$$\phi'(\alpha^*) = 0 \implies \alpha^* = - (s^k)^T \nabla q(x^k) / (s^k)^T H s^k.$$

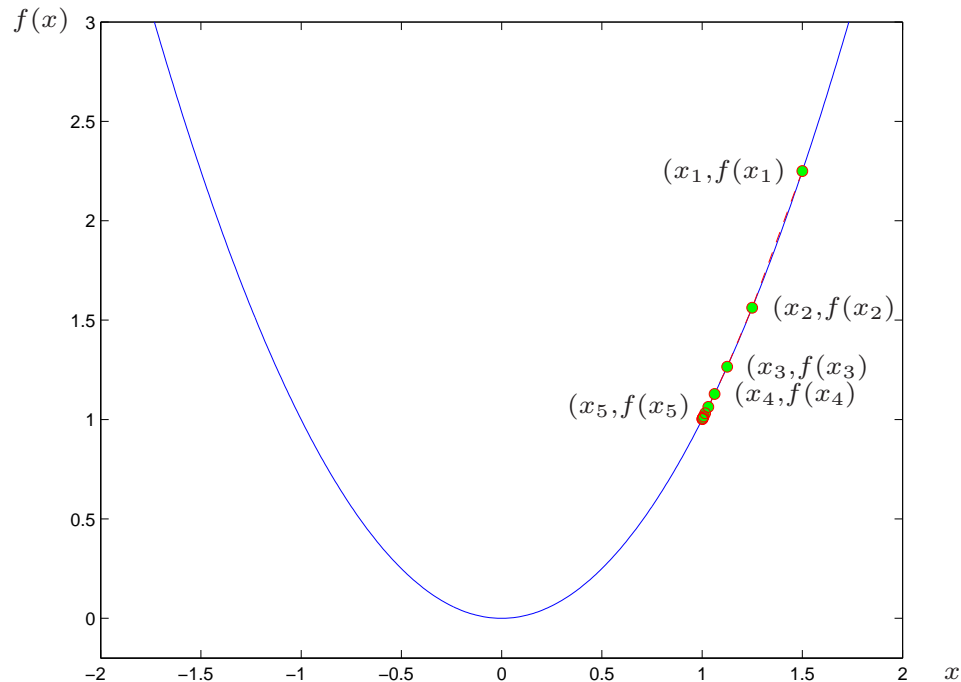
$$\blacksquare \alpha^* \text{ global minimizer of } \phi(\alpha) \text{ if } (s^k)^T H s^k > 0.$$

■ for general  $f$ , no explicit expression of  $\alpha^k$ ; approximate minimizers of  $f(x^k + \alpha s^k)$  may be used instead. [see Pb Sheet 1]

# Inexact linesearch

- want stepsize  $\alpha^k$  not “too short”.

Example:  $f(x) = x^2$ ;  $x^0 = 2$ ;  $s^k = -1$  and  $\alpha^k = 1/(2^{k+1})$  for all  $k$ . Then GLM gives  $x^k \rightarrow 1$  as  $k \rightarrow \infty$ . [see Pb Sheet 1]



# Inexact linesearch ...

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- want stepsize  $\alpha^k$  not “too short”.

## A backtracking linesearch algorithm

Choose  $\alpha_{(0)} > 0$  and  $\tau \in (0, 1)$ .

While  $f(x^k + \alpha_{(i)} s^k) \geq f(x^k)$ , REPEAT:

- set  $\alpha_{(i+1)} := \tau \alpha_{(i)}$  and  $i := i + 1$ .

END.

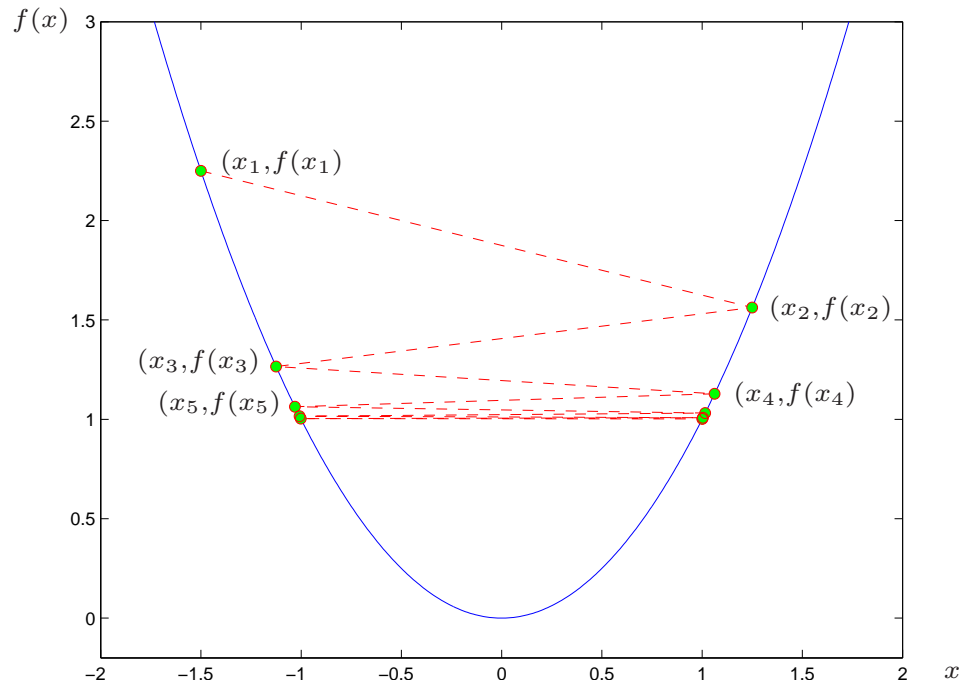
Set  $\alpha^k := \alpha_{(i)}$ .  $\square$

- $\alpha_{(0)} := 1; \tau := 0.5 \implies \alpha_{(0)} := 1, \alpha_{(1)} := 0.5, \alpha_{(2)} := 0.25, \dots$
- “<”: simple or more sophisticated decrease in  $f$  at  $x^k$ .

# Inexact linesearch ...

- want stepsize  $\alpha^k$  not “too long” compared to the decrease in  $f$ .

Example:  $f(x) = x^2$ ;  $x^0 = 2$ ;  $s^k = (-1)^{k+1}$  and  $\alpha^k = 2 + 3/2^{k+1}$  for all  $k$ . Then GLM gives  $x^k \rightarrow \pm 1$  as  $k \rightarrow \infty$ . [see Pb Sheet 1]



# Inexact linesearch ...

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- want stepsize  $\alpha^k$  not “too long” compared to the decrease in  $f$ .

## The Armijo condition

Choose  $\beta \in (0, 1)$ .

Compute  $\alpha^k > 0$  such that

$$f(x^k + \alpha^k s^k) \leq f(x^k) + \beta \alpha^k \nabla f(x^k)^T s^k \quad (*)$$

is satisfied.  $\square$

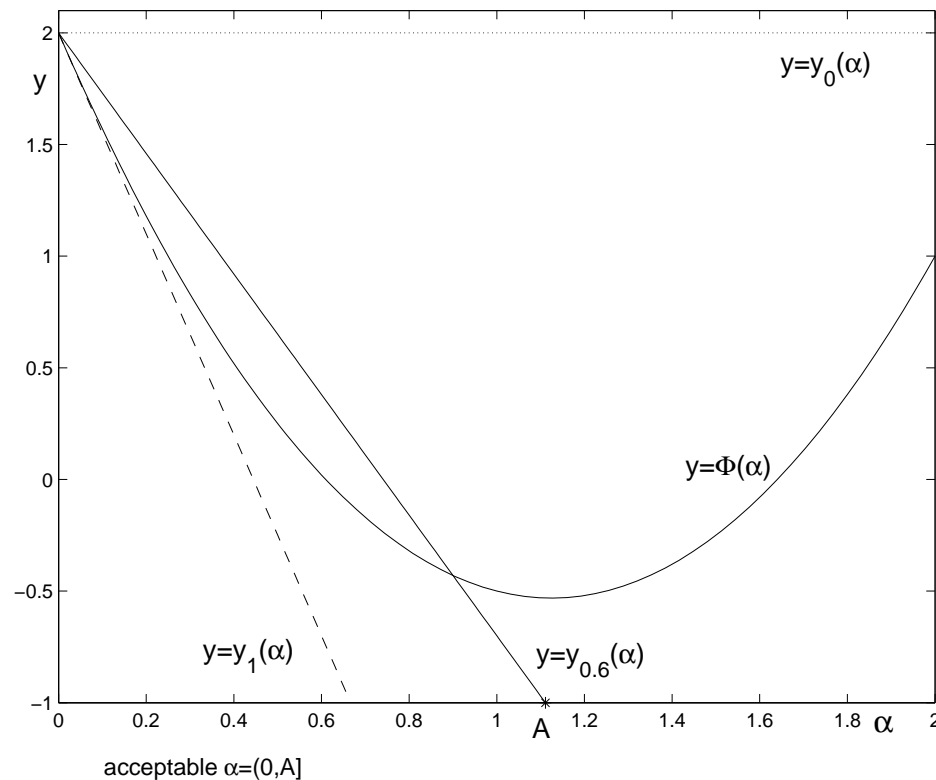
- in practice,  $\beta := 0.1$  or even  $\beta := 0.001$ .
- due to the descent condition,  $\exists \bar{\alpha}^k > 0$  (unknown explicitly in general) such that  $(*)$  holds for all  $\alpha \in [0, \bar{\alpha}^k]$ . [see Pb Sheet 2]  
Choose  $\alpha^k$  as large as possible in  $(0, \bar{\alpha}^k]$  or in other (greater) intervals of positive  $\alpha$ -values that may satisfy  $(*)$ .

# Inexact linesearch ...

■  $\Phi_k : \mathbb{R} \rightarrow \mathbb{R}$ ,  $\Phi_k(\alpha) := f(x^k + \alpha s^k)$ ,  $\alpha \geq 0$ . Then

$$\text{Armijo} \iff \Phi_k(\alpha^k) \leq \Phi_k(0) + \beta \alpha^k \Phi'(0).$$

Let  $y_\beta(\alpha) := \Phi_k(0) + \beta \alpha \Phi'(0)$ ,  $\alpha \geq 0$ .



# Inexact linesearch ...

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## The backtracking-Armijo (bArmijo) linesearch algorithm

Choose  $\alpha_{(0)} > 0$ ,  $\tau \in (0, 1)$  and  $\beta \in (0, 1)$  [at the start of GLM].

While  $f(x^k + \alpha_{(i)} s^k) > f(x^k) + \beta \alpha_{(i)} \nabla f(x^k)^T s^k$ , REPEAT:

■ set  $\alpha_{(i+1)} := \tau \alpha_{(i)}$  and  $i := i + 1$ .

END.

Set  $\alpha^k := \alpha_{(i)}$ . □

- $\alpha_{(0)}$ ,  $\beta$  and  $\tau$  chosen as before.
  - on each GLM iteration  $k$ , the bArmijo linesearch algorithm terminates in a finite number of steps with  $\alpha^k > 0$ , due to the descent condition. [see Pb Sheet 2]  
[without any additional assumptions on  $f \in \mathcal{C}^1$ ]
  - other popular/useful inexact linesearch techniques: Wolfe, Goldstein-Armijo, etc.
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# Global convergence of GLM

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- $f \in \mathcal{C}^1(\mathbb{R}^n)$ ;  $\nabla f$  is Lipschitz continuous (on  $\mathbb{R}^n$ ) iff  $\exists L > 0$ ,  
$$\|\nabla f(y) - \nabla f(x)\| \leq L\|y - x\|, \quad \forall x, y \in \mathbb{R}^n.$$

**Lemma 2.** Let  $f \in \mathcal{C}^1(\mathbb{R}^n)$  with  $\nabla f$  Lipschitz continuous with Lipschitz constant  $L$ . Then the Armijo condition is satisfied:

$f(x^k + \alpha s^k) \leq f(x^k) + \beta \alpha \nabla f(x^k)^T s^k$  for all  $\alpha \in [0, \alpha_{\max}^k]$ ,  
where  $\alpha_{\max}^k = (\beta - 1) \nabla f(x^k)^T s^k / [L \|s^k\|^2]$ .

**Proof.** First-order Taylor: for any  $\alpha > 0$  and some  $\tilde{\alpha} \in (0, \alpha)$ ,

$$\begin{aligned} f(x^k + \alpha s^k) &= f(x^k) + \alpha \nabla f(x^k)^T s^k + \alpha [\nabla f(x^k + \tilde{\alpha} s^k) - \nabla f(x^k)]^T s^k \\ &\leq f(x^k) + \alpha \nabla f(x^k)^T s^k + \alpha \|\nabla f(x^k + \tilde{\alpha} s^k) - \nabla f(x^k)\| \cdot \|s^k\| \\ &\leq f(x^k) + \alpha \nabla f(x^k)^T s^k + \alpha L \tilde{\alpha} \|s^k\|^2 \leq f(x^k) + \alpha \nabla f(x^k)^T s^k + \alpha^2 L \|s^k\|^2. \end{aligned}$$

Thus Armijo condition (\*) satisfied for all  $\alpha \geq 0$  such that

$$f(x^k) + \alpha \nabla f(x^k)^T s^k + \alpha^2 L \|s^k\|^2 \leq f(x^k) + \beta \alpha \nabla f(x^k)^T s^k,$$

which is equivalent to  $\alpha \in [0, \alpha_{\max}^k]$ .  $\square$



# Global convergence of GLM ...

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**Lemma 3.** Let  $f \in \mathcal{C}^1(\mathbb{R}^n)$  with  $\nabla f$  Lipschitz continuous with Lipschitz constant  $L$ . Then the bArmijo stepsize  $\alpha^k$  satisfies

$$\alpha^k \geq \min\{\alpha_{(0)}, \tau \alpha_{\max}^k\} \text{ for all } k \geq 0.$$

**Proof of Lemma 3.** If  $\alpha_{(0)}$  satisfies the Armijo condition (\*), bArmijo terminates with  $i = 0$  and  $\alpha^k = \alpha_{(0)}$ . Else, it will terminate as soon as  $\alpha^k \leq \alpha_{\max}^k$ . Then, let  $(i - 1)$  be the last iteration such that  $\alpha_{(i-1)} > \alpha_{\max}^k$  and  $\alpha_{(i)} \leq \alpha_{\max}^k$ . It follows that  $\alpha^k = \alpha_{(i)} = \tau \alpha_{(i-1)} > \tau \alpha_{\max}^k$ . Note that if  $\alpha_{(0)} > \alpha_{\max}^k$ , then  $\alpha_{(i)} = \tau^i \alpha_{(0)} \leq \alpha_{\max}^k$  for any  $i \geq \log(\alpha_{(0)} / \alpha_{\max}^k) / |\log \tau|$ .  $\square$

- for the global convergence of GLM, we need a lower bound on the bArmijo stepsize (as in Lemma 3), not just to know that such a stepsize exists; hence we required stronger

assumptions on  $f$ .

(global convergence of GLM to be continued ...)

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