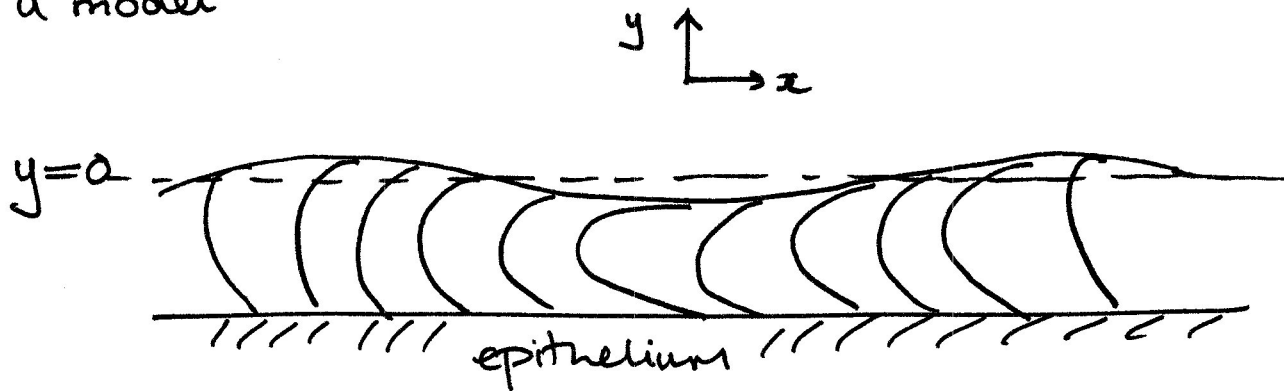


Ciliary Pumping

Ciliary beating in the lung drives fluid above the cilia up the airway, resulting in mucociliary pumping. As a model



we consider the envelope formed by the cilia, which is given by

$$x_e = x + \varepsilon a \cos(x-t)$$

$$y_e = \varepsilon b \sin(x-t)$$

where $y_e = 0$ is the midplane of the envelope. Hence on the envelope

$$u_e = \varepsilon a \sin(x-t)$$

$$v_e = -\varepsilon b \cos(x-t)$$

with $(u, v) \rightarrow (u, 0)$ as $y \rightarrow \infty$, with u unknown a-priori.

$\therefore$

We have

$$\nabla \cdot \underline{u} = 0 \quad 0 = -\nabla p + \nabla^2 \underline{u}$$

with $(u, v) = (u_e, v_e)$ on $(x, y) = (x_e, y_e)$

$(u, v) \rightarrow (u, 0)$ as $y \rightarrow \infty$; u to be found.

$\nabla \cdot \underline{u} = 0$ and 2D $\therefore u = \psi_y \quad v = -\psi_x$ where ψ is a streamfunction.

$$\left. \begin{aligned} 0 &= \nabla_\perp \nabla_\perp^2 \underline{u} = \nabla^2 (\nabla_\perp \underline{u}) \\ \nabla_\perp \underline{u} &= \begin{vmatrix} \underline{e}_1 & \underline{e}_2 & \underline{e}_3 \\ \partial_x & \partial_y & \partial_z \\ \psi_y(x,y) & -\psi_x(x,y) & 0 \end{vmatrix} = -\nabla^2 \psi \underline{e}_3 \end{aligned} \right\} \therefore \underline{\underline{\nabla^4 \psi = 0}}$$

Seek a perturbative solution

If $\varepsilon = 0$, nothing driving flow $\therefore \underline{u} = 0, \begin{cases} u = 0 \\ \psi = 0 \end{cases}$. Hence we try

$$\psi = \varepsilon \psi_1(x, y) + \varepsilon^2 \psi_2(x, y) + O(\varepsilon^3)$$

$$u = \varepsilon u_1 + \varepsilon^2 u_2 + O(\varepsilon^3)$$

$$\therefore 0 = \nabla^4 \psi = (\partial_{xx} + \partial_{yy})^2 \psi$$

$O(\varepsilon^1)$

$$0 = \nabla^4 \psi_1$$

$$\left. \begin{aligned} \text{on } x = x_e \\ y = y_e \end{aligned} \right\} \begin{aligned} \psi_y(x_e, y_e) &= u_e = \varepsilon a \sin(x-t) \\ \psi_x(x_e, y_e) &= -v_e = \varepsilon b \cos(x-t) \end{aligned}$$

$$\therefore \psi_{1y}(x, 0) + \text{h.o.t} = a \sin(x-t)$$

$$\psi_{1x}(x, 0) + \text{h.o.t} = b \cos(x-t)$$

$$\lim_{y \rightarrow \infty} \psi_{1y}(x, y) = 0, \quad \lim_{y \rightarrow \infty} \psi_{1x}(x, y) = 0$$

$$\therefore \text{let } \psi_1 = f(y) \sin(x-t)$$

$$0 = \nabla^4 \psi_1 = (\partial_{xx} + \partial_{yy}) [f'' - f] \sin(x-t) = [f'''' - f''] \sin(x-t) - [f'' - f] \sin(x-t)$$

$$= [f'''' - 2f'' + f] \sin(x-t) \quad \therefore f \propto e^{my} \quad \begin{aligned} (m^2)^2 - 2m^2 + 1 &= 0 \\ (m^2 - 1)^2 &= 0 \\ \therefore m^2 &= 1 \therefore m = \pm 1 \end{aligned}$$

$$\therefore f = Ae^y + Be^{-y} + Cy e^y + Dy e^{-y}$$

$$\text{Need } \partial f / \partial y \text{ finite as } y \rightarrow \infty \quad \therefore f = (B + Cy) e^{-y}$$

$$\begin{aligned} \therefore \psi_1 &= (B + Cy) e^{-y} \sin(x-t) \\ \therefore \psi_{1,y} &= (-B - Cy + C) e^{-y} \sin(x-t) \\ \psi_{1,x} &= (B + Cy) e^{-y} \cos(x-t) \end{aligned} \quad \left. \begin{array}{l} \therefore \text{on } y=0 \quad \underline{\underline{B=b}} \\ -B + C = -b + C = a \\ \therefore C = a + b. \end{array} \right\}$$

$$\therefore \boxed{\psi_1 = (b + (a+b)y) e^{-y} \sin(x-t)} \quad \therefore \underline{u_1 = 0 \text{ by matching at } \infty}$$

$\therefore$ We need to consider higher orders

$O(\epsilon^2)$

$$a \cos(x-t) \psi_{yyx}(x,0) + b \sin(x-t) \psi_{yy} + \psi_{2y}(x,0) = 0$$

$$a \cos(x-t) \psi_{xx}(x,0) + b \sin(x-t) \psi_{yx} + \psi_{2x}(x,0) = 0$$

$$\therefore \psi_{2y}(x,0) = -a^2 \cos^2(x-t) + b(b+2a) \sin^2(x-t)$$

$$\psi_{2x}(x,0) = +a b \sin(x-t) \cos(x-t) - a b \cos(x-t) \sin(x-t) = 0$$

$$\therefore \psi_{2y} = \frac{1}{2} (b^2 + 2ab - a^2) + \underbrace{8 \cos(2(x-t))}_{\text{on } y=0}$$

$$\psi_{2x} = 0$$

linearity... this will generate terms that will not contribute to U .

Consider only η where

$$\nabla^4 \eta = 0$$

$$\eta_y = \frac{1}{2} (b^2 + 2ab - a^2) \quad \text{on } (x, c)$$

$$\eta_x = 0 \quad \text{on } (x, 0)$$

$$\eta_y \rightarrow U \text{ to be determined as } y \rightarrow \infty.$$

let $\eta = g(y)$.

$\eta_y = \text{Const}$ a solution $\therefore \eta_y = \frac{1}{2} (b^2 + 2ab - a^2) \in U$ is a solution.

Changing η by a constant has no effect; higher powers of y don't match BC

$$\therefore \boxed{U_2 = \frac{1}{2} (b^2 + 2ab - a^2)} \quad \therefore U = \frac{1}{2} (b^2 + 2ab - a^2) \epsilon^2 + \text{h.o.t.}$$

Cellular Motility

Singularity solutions for Stokes Equations

The point force solution... the Stokeslet

Stokes Equations are linear... we can build up solutions in terms of point force solutions, dipoles, quadrupoles etc, as in electrostatics for example

Suppose a point force of strength $\underline{m}$ is located at $\underline{x}_0$. Then

$$-\nabla p + \mu \nabla^2 \underline{u} + \underline{m} \delta(\underline{x} - \underline{x}_0) = 0 \quad \nabla \cdot \underline{u} = 0$$

By translational invariance, wlog $\underline{x}_0 = \underline{0}$. Let $r = |\underline{x}|$.

$$\delta(\underline{x}) = -\frac{1}{4\pi} \nabla^2 \left(\frac{1}{r} \right) \text{ as } \int_{r < \epsilon} \nabla^2 \left(\frac{1}{r} \right) dV = \int_{r=\epsilon} \underline{n} \cdot \nabla \left(\frac{1}{r} \right) dS = -4\pi.$$

$$\therefore -\nabla^2 p + \underline{m} \cdot \nabla \delta(\underline{x}) = 0 = -\nabla^2 p + \underline{m} \cdot \nabla \left(-\frac{1}{4\pi} \nabla^2 \left(\frac{1}{r} \right) \right)$$

$$\therefore p = -\frac{1}{4\pi} \underline{m} \cdot \nabla \left(\frac{1}{r} \right)$$

$$\therefore \mu \nabla^2 \underline{u} = \underline{m} \frac{1}{4\pi} \nabla^2 \left(\frac{1}{r} \right) - \frac{1}{4\pi} \nabla (\underline{m} \cdot \nabla \left(\frac{1}{r} \right))$$

$$\therefore \mu \nabla^2 u_i = \frac{m_j}{4\pi} \left[\delta_{ij} \nabla^2 - \frac{\partial^2}{\partial x_i \partial x_j} \right] \frac{1}{r}$$

Suppose $\nabla^2 G(r) = +1/r$.

$$\text{Then } \nabla^2 \left\{ \frac{m_j}{4\pi} \left[\delta_{ij} \nabla^2 - \frac{\partial^2}{\partial x_i \partial x_j} \right] G(r) \right\} = -\frac{m_j}{4\pi} \left(\delta_{ij} \nabla^2 - \frac{\partial^2}{\partial x_i \partial x_j} \right) \left(\frac{1}{r} \right)$$

$$\therefore \text{Let } u_i = +\frac{1}{\mu} \frac{m_j}{4\pi} \left(\delta_{ij} \nabla^2 - \frac{\partial^2}{\partial x_i \partial x_j} \right) G.$$

Solve $\frac{1}{r} (rG)'' = -\frac{1}{r} \quad \therefore (rG)'' = +1 \quad \therefore (rG) = +r^2/2 + Ar + B$

$$\therefore G = +r/2 + A + B/r$$

↑
Wiped out by derivatives.

$$\therefore G = -r/2.$$

$$\therefore u_i = \frac{1}{8\pi\mu} m_j \left(\delta_{ij} \nabla^2 - \frac{\partial^2}{\partial x_i \partial x_j} \right) r$$

$$= \frac{m_j}{8\pi\mu} \left(\frac{\delta_{ij}}{r} + \frac{r_i r_j}{r^3} \right) = \frac{G_{ijm_j}}{8\pi\mu}$$

Dim of r^2 ... no constant to make this up.
(either r^2 or $\frac{p}{|m|} \propto 1/r^2$).

To reinstate x_0 dependence use $r_i = (x - x_0)_i$ and $r = |x - x_0|$

Differentiating this solution, and other singularity solutions, w.r.t x_0 generates many more solutions.

Derivatives wrt $\underline{x}_0$ also generate solutions to Stokes' equations, with singular forcings.

Superposition of such solutions provides an easy means of solving Stokes flow problems.

Potential Dipole Solution

Firstly $p = \text{const}$

$$u_i = - \frac{\partial}{\partial x_i} \frac{1}{|\underline{x} - \underline{x}_0|} = \frac{(\underline{x} - \underline{x}_0)_i}{r^3}$$

$$r = |\underline{x} - \underline{x}_0|$$

is a solution of Stokes' Equation. Hence $\nabla^2 u = 0$, $\nabla \cdot u = 0$

Hence with

$$D_{ij} = \frac{\partial}{(\partial x_0)_j} \left(\frac{x_i - (x_0)_i}{|\underline{x} - \underline{x}_0|^3} \right) = -\frac{\delta_{ij}}{r^3} + \frac{3\hat{x}_i \hat{x}_j}{r^5}$$

where $r = |\underline{x} - \underline{x}_0|$ $\hat{\underline{x}} = \underline{x} - \underline{x}_0$.

Thus $u_i = D_{ij} q_j$

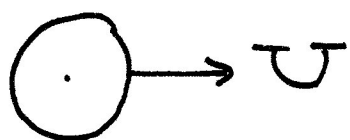
for $\underline{q}$ a constant vector
is a solution of Stokes
equation

$$W_i = \frac{\partial u_i}{\partial x_{0j}} q_j$$

$$\frac{\partial W_i}{\partial x_i} = \frac{\partial}{\partial x_{0j}} \left(\frac{\partial u_i}{\partial x_i} \right) q_j = 0 \quad \text{as } \nabla \cdot \underline{u} = 0$$

$$\nabla^2 W_i = \nabla^2 \left(\frac{\partial u_i}{\partial x_{0j}} \right) q_j = \frac{\partial (\nabla^2 u_i)}{\partial x_{0j}} q_j = 0 \quad \text{as } \nabla^2 \underline{u} = 0$$

Solution for translating sphere



$$\left. \begin{aligned} -\nabla p + \mu \nabla^2 \underline{u} &= 0 \\ \nabla \cdot \underline{u} &= 0 \end{aligned} \right\} \quad |\underline{x} - \underline{x}_0| > a$$

At instantaneous
time point, sphere
centre at ~~origin~~ $\underline{x}_0$

$$\underline{u} = \underline{U} = U \underline{e}_{x_0} \quad \text{on } |\underline{x} - \underline{x}_0| = a.$$

Consider $u_i = u_i^{(1)} + u_i^{(2)}$

$$u_i^{(1)} = G_{ij} g_j$$

$$u_i^{(2)} = D_{ij} q_j$$

65

$\therefore$ On $r = a$

$$u_i = u_i = \left(\delta_{ij}/a + \frac{\hat{x}_i \hat{x}_j}{a^3} \right) q_j + \left(-\delta_{ij}/a^3 + \frac{3\hat{x}_i \hat{x}_j}{a^5} \right) q_j$$

$$= \left(q_i/a - q_i/a^3 \right) + \frac{\hat{x}_i \hat{x}_j}{a^3} \left(q_j + \frac{3}{a^2} q_j \right)$$

$$\therefore \text{Let } \underline{q} = -\frac{a^2}{3} \underline{g}$$

$$\therefore \underline{u} = \frac{1}{a} \left(\underline{g} - \frac{1}{a^2} \left(-\frac{a^2}{3} \underline{g} \right) \right) = \frac{4}{3a} \underline{g} \therefore \underline{g} = \frac{3a}{4} \underline{u}$$

$$\therefore \boxed{\underline{g} = \frac{1}{8\pi\mu} (6\pi\mu a \underline{u}) = -3/a^2 \underline{q}}$$

$\therefore$ We have the solution for the translating sphere

Drag Force

Potential Dipole does not contribute to the force

$$\therefore D_{ij} q_j \sim O(1/r^3) \quad \bigcirc$$

$$\int_{\text{Sphere}} \sigma_{ij} n_j dS = \int_{S_a} \sigma_{ij} n_j dS \sim O(1/r^4 \cdot r^2) \sim O(1/r^2) \rightarrow 0.$$