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Units and nondimensionalization

$$\bullet [c^2] = \frac{[y_{tt}]}{[y_{xx}]} = \frac{m s^{-2}}{m m^{-2}} = m^2 s^{-2} \Rightarrow [c] = m s^{-1}$$

$$\text{Check: } [c^2] = \frac{[T]}{[\rho]} = \frac{N}{kg m^{-1}} = \frac{kg m s^{-2}}{kg m^{-1}} = m^2 s^{-2} \checkmark$$

- On what timescale does a displacement travel a distance L ?

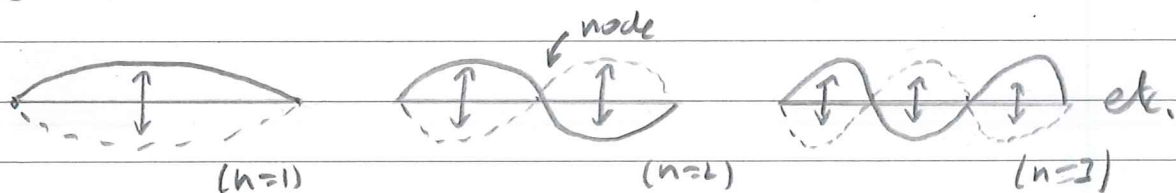
$$\text{Scale } x = L \hat{x}, t = t_0 \hat{t}, y = H \hat{y}$$

$$\Rightarrow \frac{H}{t_0^2} \hat{y}_{\hat{t}\hat{t}} = \frac{H c^2}{L^2} \hat{y}_{\hat{x}\hat{x}} \Rightarrow \hat{y}_{\hat{t}\hat{t}} = \hat{y}_{\hat{x}\hat{x}} \text{ provided } t_0 = \frac{L}{c}$$

Normal modes of vibration for a finite string

- Suppose string stretched between $x=0$ and $x=L$ and the ends held fixed.

- String experiment suggest \exists discrete modes of vibration:



- To analyze mathematically we seek separable solutions to
 - ① $y_{tt} = c^2 y_{xx}$ for $0 < x < L, t \in \mathbb{R}$;
 - ② $y(0,t) = 0, y(L,t) = 0, t \in \mathbb{R}$.

$$\bullet y = F(x)G(t) \text{ in } \textcircled{1} \Rightarrow F G'' = c^2 F'' G \Rightarrow \frac{F''(x)}{F(x)} = \frac{G''(t)}{c^2 G(t)} \quad (FG \neq 0)$$

- LHS ind. t & RHS ind. $x \Rightarrow$ LHS = RHS ind. x & t
 \Rightarrow LHS = RHS = $-\lambda \in \mathbb{R}$, say.

$$\bullet \text{Hence } -F'' = \lambda F \text{ for } 0 < x < L \text{ (I)}$$

$$\bullet \textcircled{2} \text{ & } G \text{ non-trivial} \Rightarrow F(0) = 0, F(L) = 0 \text{ (II)}$$

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• $\lambda \leq 0 \Rightarrow$ (I) - (II) have only the trivial solution $F=0$.

• Let $\lambda = \omega^2$, with $\omega > 0$ wlog.

• (I) $\Rightarrow F = A \cos(\omega x) + B \sin(\omega x)$ ($A, B \in \mathbb{R}$)

• (II) $\Rightarrow A = 0, B \sin(\omega L) = 0$

• F nontrivial $\Rightarrow B \neq 0 \Rightarrow \sin(\omega L) = 0 \Rightarrow \omega L = n\pi, n \in \mathbb{N} \setminus \{0\}$

• $\omega = \frac{n\pi}{L} \Rightarrow F(x) = B \sin\left(\frac{n\pi x}{L}\right), G(t) = C \cos\left(\frac{n\pi c t}{L}\right) + D \sin\left(\frac{n\pi c t}{L}\right)$
($C, D \in \mathbb{R}$)

• Combo \Rightarrow normal modes (nontrivial sep. sol^{ns} of ①-②) are

$$y_n(x, t) = \sin\left(\frac{n\pi x}{L}\right) \left(a_n \cos\left(\frac{n\pi c t}{L}\right) + b_n \sin\left(\frac{n\pi c t}{L}\right) \right)$$

$$\text{or } y_n(x, t) = c_n \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{n\pi c}{L}(t + \epsilon_n)\right),$$

where $a_n, b_n \in \mathbb{R}, c_n, \epsilon_n \in \mathbb{R}$ for each $n \in \mathbb{N} \setminus \{0\}$.

Remarks

(1) y_n periodic in t with prime period $p = \frac{2\pi}{n\pi c/L} = \frac{2L}{\pi c}$
and frequency (or pitch) $\frac{1}{p} = \frac{\pi c}{2L}$.

(2) y_1 is fundamental mode; $\frac{c}{2L}$ the fundamental frequency; all other modes have a frequency that is an integer multiple of $\frac{c}{2L}$.

(3) Consistent with slinky experiment.

(4) Normal modes are an example of a standing wave since $y = f^n(x) \times$ oscillatory function.

[Next time: use Fourier's method to solve IBVP obtained by imposing 2ICs.]

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IBVP for a finite string

- Find $y(x, t)$ s. t.
 - $y_{tt} = c^2 y_{xx}$ for $0 < x < L, t > 0$;
 - $y(0, t) = 0, y(L, t) = 0$ for $t > 0$;
 - $y(x, 0) = f(x), y_t(x, 0) = g(x)$ for $0 < x < L$.
- Use Fourier's method. [f, g = initial transverse displacement & velocity]

Step (I): Find all nontrivial sep. sol^{ns} of ①-②

- Last time we found that these (normal modes) are

$$y_n(x, t) = \sin\left(\frac{n\pi x}{L}\right) \left(a_n \cos\left(\frac{n\pi ct}{L}\right) + b_n \sin\left(\frac{n\pi ct}{L}\right) \right),$$

where $a_n, b_n \in \mathbb{R}$ and $n \in \mathbb{N} \setminus \{0\}$.

Step (II): Formally apply the principle of superposition

- ① & ② linear so superimpose the normal modes (assuming convergence) to obtain the general series solution

$$y(x, t) = \sum_{n=1}^{\infty} y_n(x, t).$$

Step (III): Use theory of FS to satisfy the ICs

- ③ can only be satisfied if

$$f(x) = \sum_{n=1}^{\infty} a_n \sin\left(\frac{n\pi x}{L}\right) \text{ for } 0 < x < L,$$

$$g(x) = \sum_{n=1}^{\infty} b_n \frac{n\pi c}{L} \sin\left(\frac{n\pi x}{L}\right) \text{ for } 0 < x < L.$$

- Assuming $\{ \sum = \sum \}$, we deduce that

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$$\int_0^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx = \sum_{n=1}^{\infty} a_n \underbrace{\int_0^L \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{n\pi x}{L}\right) dx}_{= \frac{1}{2} \delta_{nm}} = \frac{L}{2} a_n$$

$$\Rightarrow a_n = \frac{2}{L} \int_0^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx, \text{ and similarly}$$

$$b_n \frac{n\pi c}{L} = \frac{2}{L} \int_0^L g(x) \sin\left(\frac{n\pi x}{L}\right) dx. \quad \square$$

Example 4.1: $f(x) = A \sin\left(\frac{\pi x}{L}\right) + B \sin\left(\frac{2\pi x}{L}\right) \Rightarrow a_1 = A, a_2 = B$
and rest 0.

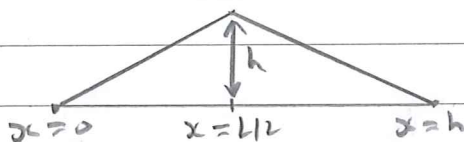
Example 4.2: $f(x) = 0, g(x) = \sin^3\left(\frac{\pi x}{L}\right) \Rightarrow a_n = 0 \forall n.$ □

Trick: $\sin^3\left(\frac{\pi x}{L}\right) = \frac{3}{4} \sin\left(\frac{\pi x}{L}\right) - \frac{1}{4} \sin\left(\frac{3\pi x}{L}\right)$

$$\Rightarrow \frac{n\pi c}{L} b_1 = \frac{3}{4}, b_2 = 0, \frac{3n\pi c}{L} b_3 = -\frac{1}{4} \text{ and rest } 0. \quad \square$$

Example 4.3 (Guitar string):

$$f(x) = \begin{cases} 2hx/L & \text{for } 0 \leq x \leq L/2, \\ 2h(L-x)/L & \text{for } L/2 \leq x \leq L, \end{cases} \quad g(x) = 0.$$



$$a_n = \frac{2}{L} \int_0^{L/2} \frac{2hx}{L} \sin\left(\frac{n\pi x}{L}\right) dx + \frac{2}{L} \int_{L/2}^L \frac{2h(L-x)}{L} \sin\left(\frac{n\pi x}{L}\right) dx = \frac{Ph}{n^2\pi^2} \sin\left(\frac{n\pi}{2}\right)$$

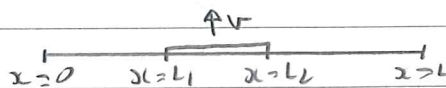
$$b_n = 0$$

(Since $\sin\left(\frac{n\pi}{2}\right) = \begin{cases} 0 & \text{for } n = 2m, m \in \mathbb{N} \setminus \{0\}, \\ (-1)^m & \text{for } n = 2m+1, m \in \mathbb{N} \end{cases}$)

we find $y(x,t) = \frac{Ph}{\pi^2} \sum_{m=0}^{\infty} \frac{(-1)^m}{(2m+1)^2} \sin\left(\frac{(2m+1)\pi x}{L}\right) \cos\left(\frac{(2m+1)\pi ct}{L}\right)$ □

Example 4.4 (Piano string):

$$f(x) = 0, \quad g(x) = \begin{cases} v & \text{for } L_1 \leq x \leq L_2, \\ 0 & \text{otherwise.} \end{cases}$$



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$$a_n = 0 \text{ and } b_n = \frac{L}{n\pi c} \frac{2}{L} \int_{L_1}^{L_2} v \sin\left(\frac{n\pi x}{L}\right)$$

$$\Rightarrow y(x,t) = \frac{2vL}{c\pi^2} \sum_{n=1}^{\infty} \frac{1}{n^2} \left(\cos\left(\frac{n\pi L_2}{L}\right) - \cos\left(\frac{n\pi L_1}{L}\right) \right) \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{n\pi ct}{L}\right)$$

Energy and uniqueness

• Consider IBVP ①-③.

• KE of string is $\int_0^L \frac{1}{2} \rho |y_t|^2 dx = \int_0^L \frac{1}{2} \rho y_t^2 dx$.

• Elastic PE of string is product of tension and extension, i.e.

$$T \left(\int_0^L |y_x| dx - L \right) = T \int_0^L (1 + y_x^2)^{\frac{1}{2}} - 1 dx.$$

• But $|y_x| \ll 1$, so $(1 + y_x^2)^{\frac{1}{2}} - 1 = \frac{1}{2} y_x^2 + \dots$, so to a first approximation (neglecting cubic and h.o.t.), the elastic PE is $\int_0^L \frac{1}{2} T y_x^2 dx$.

• Hence, energy of string $E(t) = \int_0^L \frac{1}{2} \rho y_t^2 + \frac{1}{2} T y_x^2 dx$.

Lemma(4.1): If y satisfies ①-②, then $E(t)$ is constant for $t > 0$.

$$\text{Pf: } \frac{dE}{dt} = \int_0^L \rho y_t y_{tt} + T y_x y_{xt} dx \quad (\text{by LIR})$$

$$= \int_0^L T y_t y_{xxt} + T y_{xt} y_{xt} dx \quad (\text{by ①})$$

$$= \int_0^L (T y_t y_x)_x dx$$

$$= [T y_t y_x]_{x=0}^{x=L}$$

$$= 0,$$

since ② $\Rightarrow y_t(0,t) = y_t(L,t) = 0$ for $t > 0$. \square

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Remarks

(1) Lemma e (3) $\Rightarrow E(t) = E(0) = \int_0^L \frac{1}{2} \rho (g(x))^2 + \frac{1}{2} T (f'(x))^2 dx$.

(2) Lemma \Rightarrow Energy in n th normal mode (given by)

$$E_n(t) = E_n(0) = \int_0^L \frac{1}{2} \rho (y_{nt}(x,0))^2 + \frac{1}{2} T (y_{nx}(x,0))^2 dx = \frac{\rho T \omega_n^2}{4L} (a_n^2 + b_n^2)$$

(3) Can then use Parseval's Identity for g and f' to show that $E(0) = \sum_{n=1}^{\infty} E_n(0)$, i.e. total energy is sum of energy in each normal mode (which are constant throughout motion and set by ICs by remark (2)).

Theorem (4.2, Uniqueness): The IBVP has at most one solution.

Pf: Let $w(x,t) = y - \tilde{y}$, where y, \tilde{y} are two solutions, then by linearity,

(1') $w_t = c^2 w_{xx}$ for $0 < x < L, t > 0$;

(2') $w(0,t) = 0, w(L,t) = 0$ for $t > 0$;

(3') $w(0,t) = 0, w_t(0,t) = 0$ for $0 < x < L$.

Lemma (4.1) applied to $w \Rightarrow$

$$\int_0^L \frac{\rho}{2} (w_t)^2 + \frac{T}{2} (w_x)^2 dx = E(t) = E(0) = 0 \text{ for } t \geq 0$$

(1') \uparrow (2') \uparrow (3')

$$\Rightarrow w_t = w_x = 0 \text{ for } 0 < x < L, t > 0 \text{ (assuming } w_t, w_x \text{ cts there)}$$

$$\Rightarrow w = \text{constant for } 0 < x < L, t > 0$$

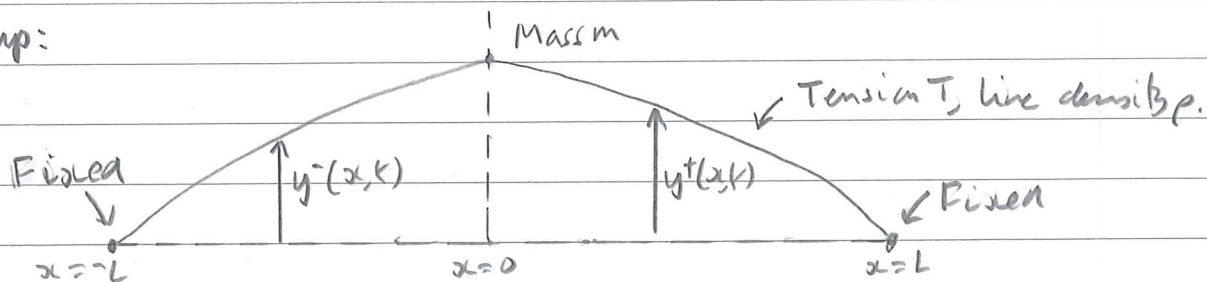
$$\Rightarrow w = 0 \text{ for } 0 \leq x \leq L, t \geq 0 \text{ (by (2') or (3'), assuming } w \text{ cts for } 0 \leq x \leq L, t \geq 0)$$

□

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Normal modes for a weighted string

• Setup:



• What are the normal modes?

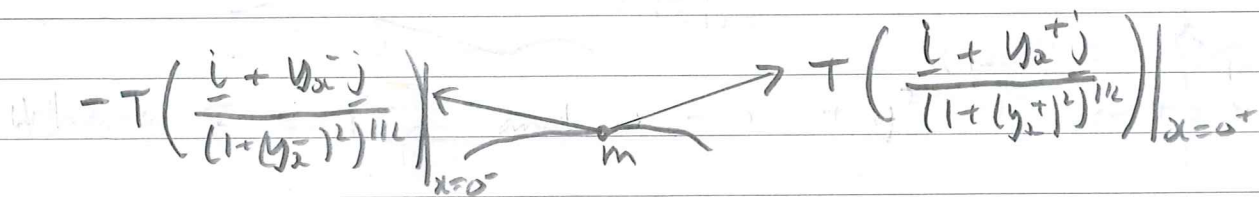
• PDEs: $\textcircled{1}^-$ $y^-_{tt} = c^2 y^-_{xx}$ for $-L < x < 0$
 $\textcircled{1}^+$ $y^+_{tt} = c^2 y^+_{xx}$ for $0 < x < L$

• BCs: $\textcircled{2}^-$ $y^-(-L, t) = 0$
 $\textcircled{2}^+$ $y^+(L, t) = 0$

$\textcircled{3}$ $y^-(0, t) = y^+(0, t) = \gamma(t)$ say.

• $\gamma(t)$ TBD so need a second BC at $x = 0$ via NII for the mass.

• Forces on mass (neglecting gravity and air resistance):



• Small transverse displacement $\Rightarrow |y^I_x| \ll 1 \Rightarrow (1 + (y^I_x)^2)^{3/2} = 1 + \text{h.o.t.} \Rightarrow$ to a first approximation mass remains on y -axis (because x -force components balance), while in y -direction

$\textcircled{4}$ $m \ddot{\gamma} = T (y^+_x|_{x=0^+} - y^-_x|_{x=0^-})$

• Separate variables: $y^I = F_{\pm}(x) G(t)$

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$$(1^\pm) \Rightarrow \frac{F_\pm''(x)}{F_\pm(x)} = \frac{G''(t)}{c^2 G} = -\lambda \in \mathbb{R} \text{ say } (F^\pm G \neq 0)$$

$$(2^\pm) \text{ e } G \neq 0 \Rightarrow F_-(-L) = 0, F_+(L) = 0 \quad (a^\pm)$$

$$(3) \text{ e } G \neq 0 \Rightarrow F_-(0) = F_+(0) \quad (b)$$

$$(4) \text{ e } G \neq 0 \Rightarrow m F_\pm(0) G''(t) = T(F_+'(0_+) - F_-'(0_-)) G(t)$$

$$\Rightarrow \underset{(c^2 = T/\rho)}{-\frac{\lambda m}{\rho} F_\pm(0)} = F_+'(0_+) - F_-'(0_-) \quad (c)$$

• Can show $\lambda \leq 0 \Rightarrow F_\pm = 0$. Let $\lambda = \omega^2$, $\omega > 0$ wlog.

• Then $F_-'' + \omega^2 F_- = 0$ for $-L < x < 0$,
 $F_+'' + \omega^2 F_+ = 0$ for $0 < x < L$.

$$(a^\pm) \Rightarrow F_- = A \sin \omega(L+x), F_+ = B \sin \omega(L-x) \quad (A, B \in \mathbb{R})$$

$$(b) \text{ e } (c) \Rightarrow \underbrace{\begin{bmatrix} \sin(\omega L) & -\sin(\omega L) \\ \cos(\omega L) - \frac{m\omega}{\rho} \sin(\omega L) & \cos(\omega L) \end{bmatrix}}_M \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad (1)$$

• $\begin{bmatrix} A \\ B \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \det(M) = 0 \Rightarrow \sin(\omega L) \left(2\cos(\omega L) - \frac{m\omega}{\rho} \sin(\omega L) \right) = 0$

• Hence, either (i) $\sin(\omega L) = 0 \Rightarrow \omega = \frac{n\pi}{L}$, $n \in \mathbb{N} \setminus \{0\}$

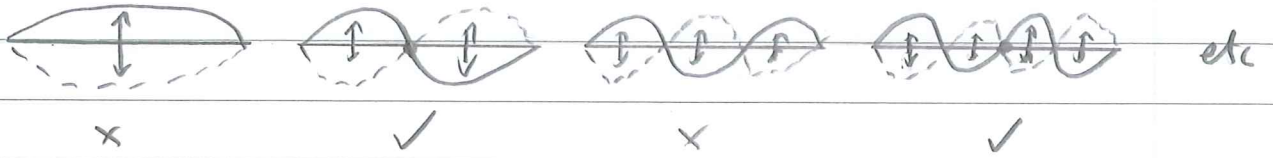
or (ii) $\cot(\omega L) = \frac{m\omega}{2\rho} \Rightarrow \cot \theta = \frac{m\theta}{2\rho L}$, where $\theta = \omega L$

• In each case, $G'' + \omega^2 c^2 G = 0 \Rightarrow G(t) = \underbrace{\cos(\omega c t + \epsilon)}_{\text{wlog}} \quad (c, \epsilon \in \mathbb{R})$

• In case (i), (1) $\Rightarrow A = -B \Rightarrow \begin{cases} y_- = A \sin \omega(L+x) \cos(\omega c t + \epsilon) \\ y_+ = -A \sin \omega(L-x) \cos(\omega c t + \epsilon) \end{cases}$

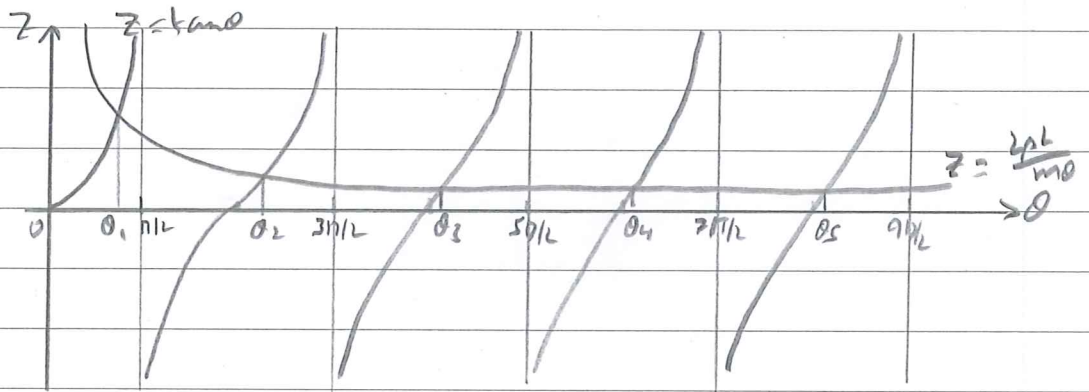
This means that the normal modes are the same as for a string of length $2L$ with a nod at $x=0$, i.e. mass stationary.

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In case (ii) there are infinitely many roots $\theta_1, \theta_2, \theta_3, \dots$

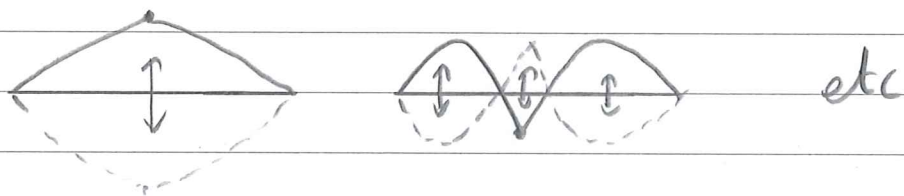
To see plot LHS & RHS of e.g. $\tan \theta = \frac{2\mu L}{m\omega}$



Hence, ∞ many normal modes $\omega_n = \frac{\theta_n}{L}$, $n \in \mathbb{N} \setminus \{0\}$.

Now $(1) \Rightarrow A = B \Rightarrow \begin{cases} y_- = A \sin \omega(L+x) \cos(\omega t + \epsilon) \\ y_+ = A \sin \omega(L-x) \cos(\omega t + \epsilon) \end{cases}$

This means that the normal modes are symmetric about $x=0$:



Try with slinky!

General solution of the wave equation

Remarkable fact: can write down all solutions of $y_{tt} = c^2 y_{xx}$!

Let $y(x,t) = \gamma(\xi, \eta)$, $\xi = x - ct$, $\eta = x + ct$ (as in Intro. Calculus)

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$$\Rightarrow y_x = \gamma_3 z_x + \gamma_m m_x = \gamma_3 + \gamma_m$$

$$y_{xx} = (\gamma_3 + \gamma_m) z_{xx} + (\gamma_3 + \gamma_m) m_{xx} = \gamma_3 z_{xx} + 2\gamma_3 m_x + \gamma_m m_{xx}$$

$$y_t = \gamma_3 z_t + \gamma_m m_t = -c(\gamma_3 + c\gamma_m)$$

$$y_{tt} = (-c\gamma_3 + c\gamma_m) z_{tt} + (-c\gamma_3 + c\gamma_m) m_{tt} = c^2(\gamma_3 z_{tt} - 2\gamma_3 m_x + \gamma_m m_{tt})$$

where we assumed $\gamma_3 m = \gamma_m z$.

Hence, $y_{tt} - c^2 y_{xx} = -4c^2 \gamma_3 m$

Wave equation, $c > 0 \Rightarrow \gamma_3 m = 0$

$$\Rightarrow \gamma_3 = F'(z) \text{ say}$$

$$\Rightarrow (\gamma - F'(z))_z = 0$$

$$\Rightarrow \gamma - F'(z) = G(m) \text{ say}$$

$$\Rightarrow y = F(x-ct) + G(x+ct)$$

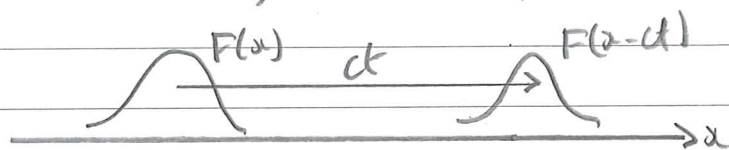
where F, G are arbitrary twice contly diff. functions.

Remarks

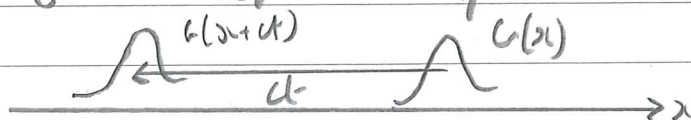
(1) cf. # arb. constants in general solution to a 2nd order ODE.

(2) Easy to verify this is a solution (see online notes): we've shown that all solutions must be of this form.

(4) $F(x-ct)$ is a (travelling) wave of constant shape moving to the right with speed c :



$G(x+ct)$ is a (travelling) wave of constant shape moving to the left with speed c :



(41)

Waves on infinite strings: D'Alembert's formula

- Consider the IVP $\textcircled{1}$ $y_{tt} = c^2 y_{xx}$ for $-\infty < x < \infty, t > 0$;
 $\textcircled{2}$ $y(x, 0) = f(x), y_t(x, 0) = g(x)$ for $-\infty < x < \infty$,

where initial transverse displacement f and velocity g are given.

- The general solution of $\textcircled{1}$ is $y(x, t) = F(x-ct) + G(x+ct)$.
- ICs $\textcircled{2} \Rightarrow F(x) + G(x) \stackrel{\textcircled{a}}{=} f(x), -cF'(x) + cG'(x) = g(x)$ for $x \in \mathbb{R}$.

The latter implies $-F(x) + G(x) \stackrel{\textcircled{b}}{=} \frac{1}{c} \int_0^x g(s) ds + a$ ($a \in \mathbb{R}$)

$$\textcircled{a} - \textcircled{b} \Rightarrow F(x) = \frac{1}{2} f(x) - \frac{1}{2c} \int_0^x g(s) ds - \frac{1}{2} a$$

$$\textcircled{a} + \textcircled{b} \Rightarrow G(x) = \frac{1}{2} f(x) + \frac{1}{2c} \int_0^x g(s) ds + \frac{1}{2} a$$

$$\text{Hence, } y(x, t) = \frac{1}{2} f(x-ct) + \frac{1}{2c} \int_{x-ct}^0 g(s) ds - \frac{1}{2} a \\ + \frac{1}{2} f(x+ct) + \frac{1}{2c} \int_0^{x+ct} g(s) ds + \frac{1}{2} a$$

$$\Rightarrow y(x, t) = \frac{1}{2} (f(x-ct) + f(x+ct)) + \frac{1}{2c} \int_{x-ct}^{x+ct} g(s) ds$$

D'Alembert's formula

Remarks

(1) Don't forget the constant a !

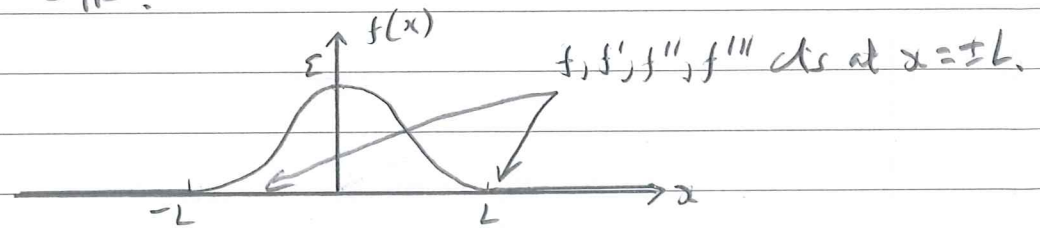
(2) Argument shows $\exists!$ solⁿ of IVP $\textcircled{1} - \textcircled{2}$.

(3) Can also prove uniqueness via energy conservation under the additional assumption that $y_t, y_x \rightarrow 0$ suff. rapidly as $x \rightarrow \pm\infty$ that the energy $E(t) = \int_{-\infty}^{\infty} \frac{1}{2} y_t^2 + \frac{1}{2} y_x^2 dx$ exists.

(42)

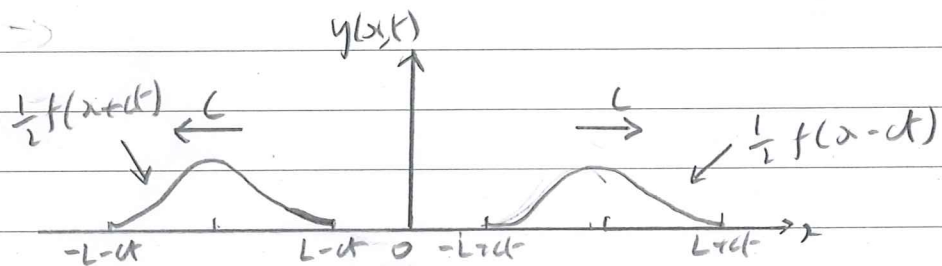
Example: $f(x) = \begin{cases} \varepsilon \cos^4\left(\frac{\pi x}{2L}\right) & \text{for } |x| \leq L \\ 0 & \text{otherwise,} \end{cases}$ $g(x) = 0,$

where $\varepsilon, L \in \mathbb{R}^+$.

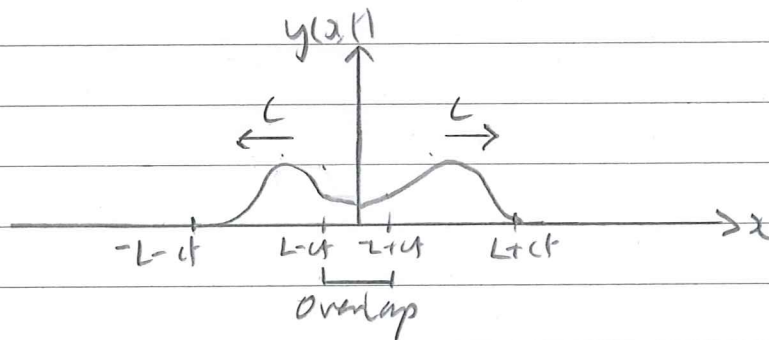


DF $\Rightarrow y(x,t) = \frac{1}{2}f(x-ct) + \frac{1}{2}f(x+ct)$

$ct > L$



$0 < ct < L$



Explicit formulae for these graphs requires some careful book keeping - much easier to use a...

Characteristic diagram

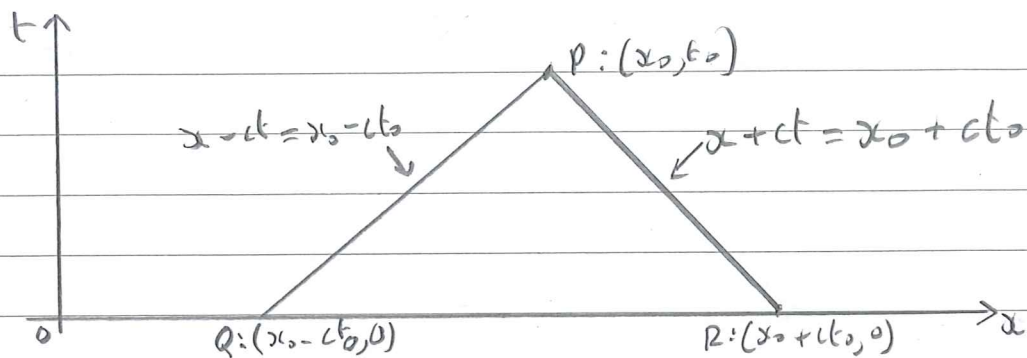
• Let $P = (x_0, t_0) \in \mathbb{R} \times \mathbb{R}^+$. How does $y(P)$ depend on f, g ?

• DF $\Rightarrow y(x_0, t_0) = \frac{1}{2}(f(x_0 - ct_0) + f(x_0 + ct_0)) + \frac{1}{2c} \int_{x_0 - ct_0}^{x_0 + ct_0} g(s) ds$ (#)

$\Rightarrow y(P) = \frac{1}{2}(f(Q) + f(R)) + \frac{1}{2c} \int_Q^R g(s) ds,$ (#)

where Q and R are points on the x -axis as shown.

(43)

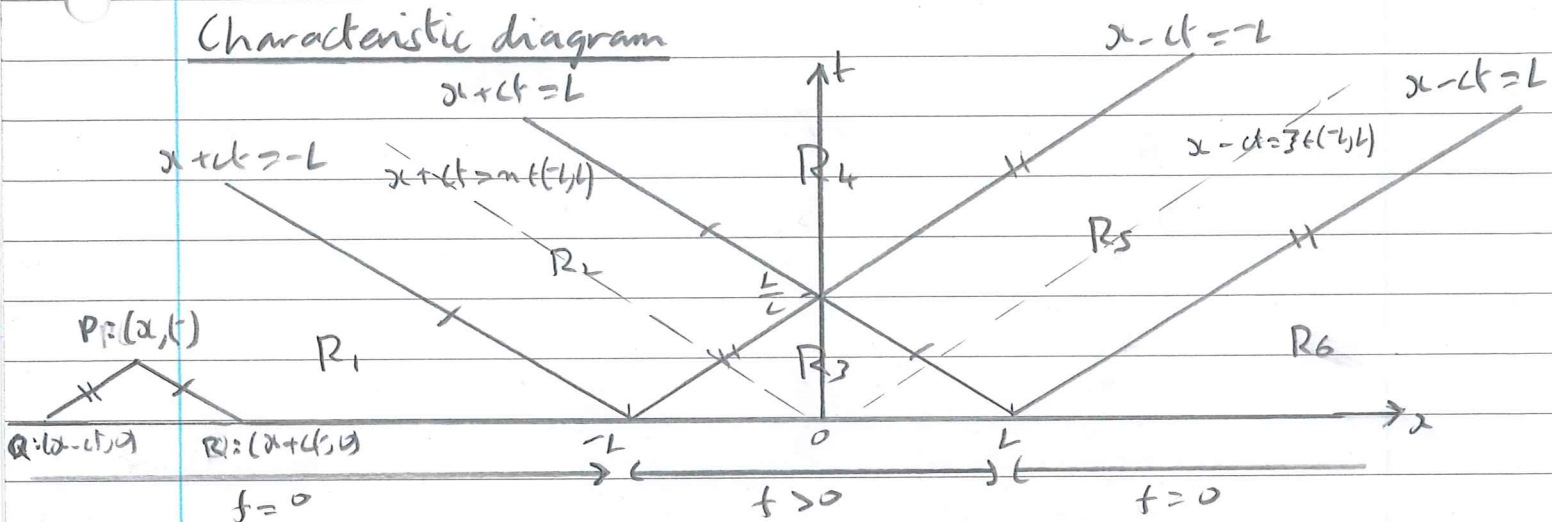


- Note deliberate abuse of notation in (H) to aid geometric interpretation of (†).
- Defⁿ: $x \pm ct = x_0 \pm ct_0$ called characteristic lines through P.
- (H) \Rightarrow $y(P)$ depends only on
 - (i) f through the values f takes at Q and R;
 - (ii) g through the values g takes on x -axis between Q and R.
- Defⁿ: The interval $[x_0 - ct_0, x_0 + ct_0]$ of the x -axis between Q and R is called the domain of dependence of P: (x_0, t_0) .
- If f or g modified outside the domain of dependence of P, then $y(P)$ is unchanged.
- Explicit geometric interpretation (H) of VF (†) to construct explicit formulae for the solution: contribution to $y(P)$ from f and g change at points on x -axis where f and g change their analytic behaviour.
- Hence, given a particular f and g , first task is to identify these points on x -axis and sketch the characteristic lines $x \pm ct = \text{constant}$ through each of them - this is the characteristic diagram.
- This divides the (x, t) -plane, with $t > 0$, into regions in which the contributions from f and g may be different.

(44)

Back to earlier example...

Characteristic diagram



• DF $\Rightarrow y(P) = \frac{1}{2}(f(Q) + f(R))$, where P, Q, R are points shown.

• PQ $\parallel x-ct = \pm L$ and PR $\parallel x+ct = \pm L$, so solution as follows.

• $P \in R_1 \Rightarrow y = \frac{1}{2}[0 + 0]$

• $P \in R_2 \Rightarrow y = \frac{1}{2}\left[0 + \varepsilon \cos^2\left(\frac{\pi}{2L}(x+t)\right)\right]$

• $P \in R_3 \Rightarrow -y = \frac{1}{2}\left[\varepsilon \cos^2\left(\frac{\pi}{2L}(x-t)\right) + \varepsilon \cos^2\left(\frac{\pi}{2L}(x+t)\right)\right]$

• $P \in R_4 \Rightarrow y = \frac{1}{2}[0 + 0]$

• $P \in R_5 \Rightarrow y = \frac{1}{2}\left[\varepsilon \cos^2\left(\frac{\pi}{2L}(x-t)\right) + 0\right]$

• $P \in R_6 \Rightarrow y = \frac{1}{2}[0 + 0]$

• Since y is continuous on characteristic bounding regions, it does not matter to which region each belongs, e.g.

could pick $R_1: x+ct < -L, t > 0;$

$R_2: -L \leq x+ct \leq L, x-ct \leq L;$

$R_3: -L < x+ct < L, -L < x-ct < L, t > 0;$

etc.

(45)

Example 4.6: Suppose $y(x,t)$ s.t. ① $y_{tt} = c^2 y_{xx}$ for $-\infty < x < \infty, t > 0$;

② $y(x,0) = f(x), y_x(x,0) = g(x)$ for $-\infty < x < \infty$.

Find $y(x,t)$ when $f(x) = 0$ and $g(x) = \begin{cases} vx/L & \text{for } |x| \leq L \\ 0 & \text{otherwise,} \end{cases}$

where $L, v \in \mathbb{R}^+$.

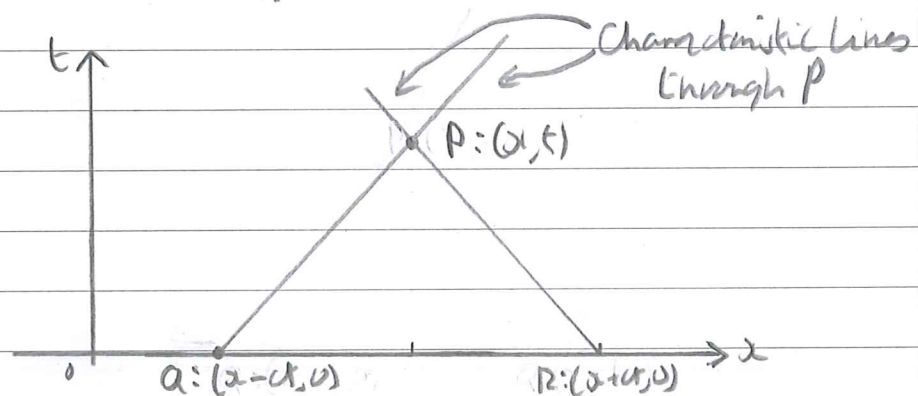
• Recall D'Alembert's Formulae (DF) for the solution of ①-②:

$$y(x,t) = \frac{1}{2} (f(x-ct) + f(x+ct)) + \frac{1}{2c} \int_{x-ct}^{x+ct} g(s) ds$$

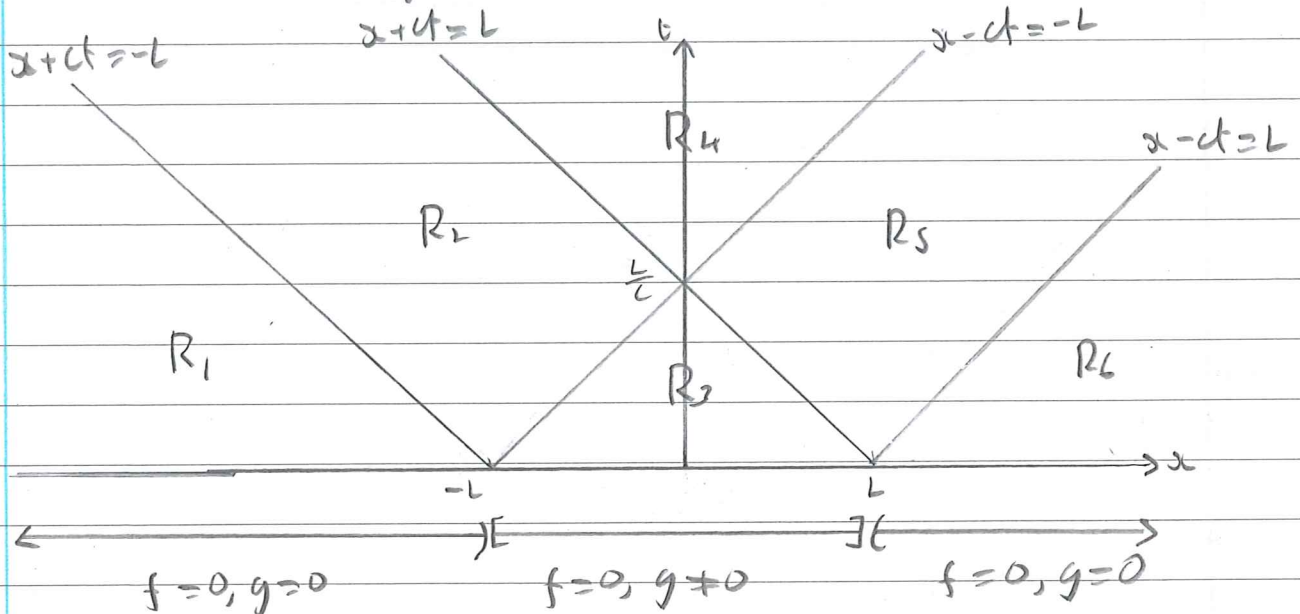
• Thus,

$$y(P) = \frac{1}{2c} \int_Q^R g(s) ds,$$

where P, Q, R are the points shown



Characteristic diagram



46

• PQ // $x-ct = \pm L$ and PR // $x+ct = \pm L$, so solution as follows:

$$R_1: y = \frac{1}{2c} \int_{x-ct}^{x+ct} 0 ds = 0$$

$$R_2: y = \frac{1}{2c} \int_{x-ct}^{-L} 0 ds + \frac{1}{2c} \int_{-L}^{x+ct} \frac{vs}{L} ds = \frac{v}{4Lc} ((x+ct)^2 - L^2)$$

$$R_3: y = \frac{1}{2c} \int_{x-ct}^{x+ct} \frac{vs}{L} ds = \frac{v}{4Lc} ((x+ct)^2 - (x-ct)^2) = \frac{vxt}{L}$$

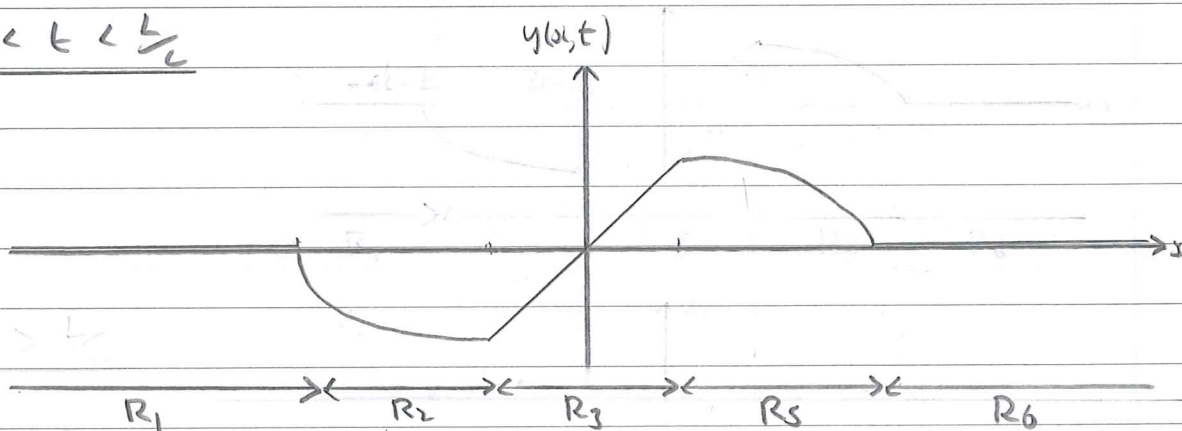
$$R_4: y = \frac{1}{2c} \int_{x-ct}^{-L} 0 ds + \frac{1}{2c} \int_{-L}^L \frac{vs}{L} ds + \frac{1}{2c} \int_L^{x+ct} 0 ds = 0$$

$$R_5: y = \frac{1}{2c} \int_{x-ct}^L \frac{vs}{L} ds + \frac{1}{2c} \int_L^{x+ct} 0 ds = \frac{v}{4Lc} (L^2 - (x-ct)^2)$$

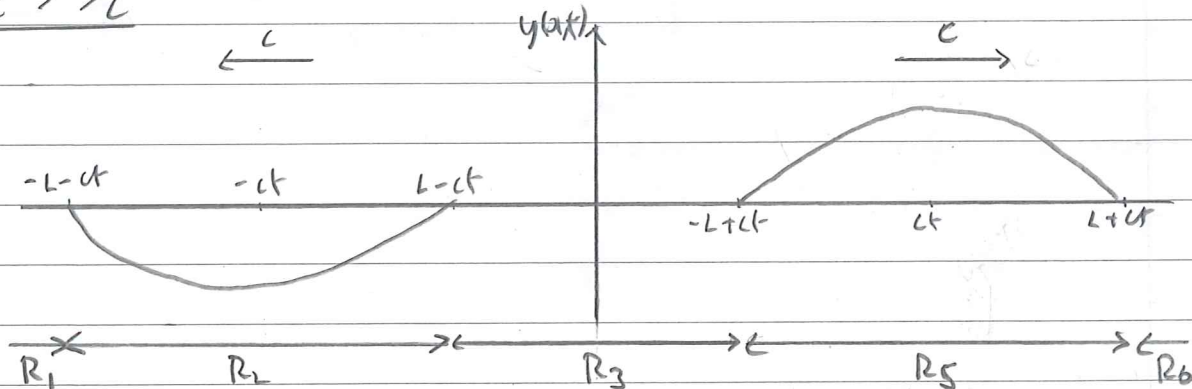
$$R_6: y = \frac{1}{2c} \int_{x-ct}^{x+ct} 0 ds = 0$$

• Note solution ds across borders between regions.

$0 < t < \frac{L}{c}$



$t > \frac{L}{c}$



• Note \exists corners \Rightarrow not a classical (twice ds diff.) solution!