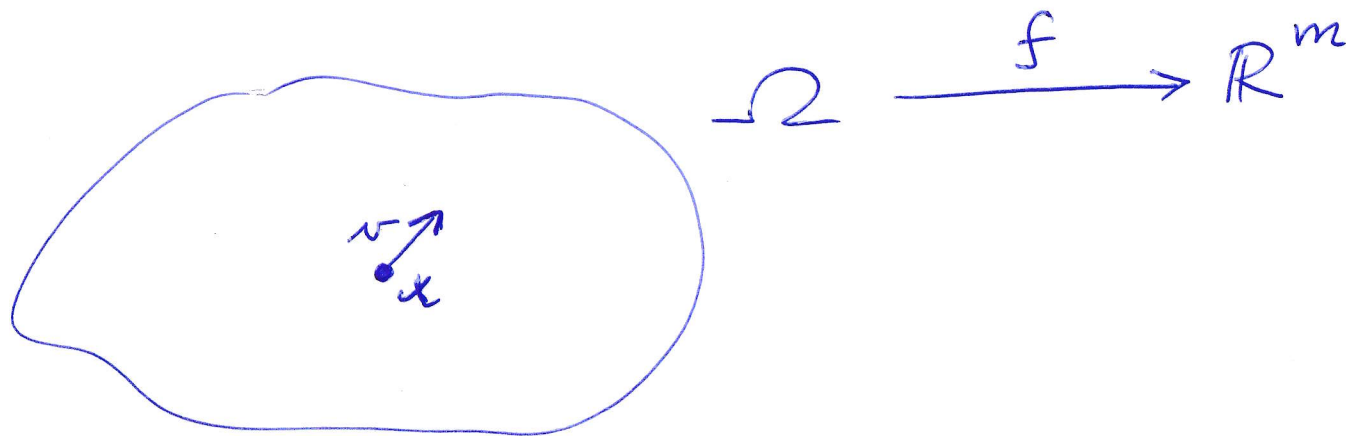


Definition Let $f: \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$, and $v \in \mathbb{R}^n \setminus \{0\}$.

The directional derivative of f at $x \in \mathbb{R}^n$ in direction v is

$$\partial_v f(x) = \lim_{t \rightarrow 0} \frac{f(x+tv) - f(x)}{t}$$

if the limit exists.



Note that with $v = e_i$, we recover $\partial_i f(x) = \partial_{e_i} f(x)$.

Ex $f(x) = |x| \quad f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\partial_v f(x) = \left. \frac{d}{dt} |x + tv| \right|_{t=0} = \left\langle \frac{x}{|x|}, v \right\rangle \text{ if } x \neq 0.$$

Calculation in
printed lecture notes

Remark: think about what this says for $n=1$.

Definition $f: \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$, assume all partials exist

at $x \in \Omega$, then

$$\nabla f(x) = \begin{pmatrix} \partial_1 f(x) \\ \vdots \\ \partial_n f(x) \end{pmatrix}$$

Note that we have

$$\partial_v f(x) = \langle \nabla f(x), v \rangle$$

and so, for example, for $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $\nabla f(x) = \frac{x}{|x|}$.
 $x \mapsto |x|$

Definition For general $f: \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that all partial derivatives $\partial_i f_j$ at x exist for $x \in \Omega$, then define the Jacobian matrix

$$Df(x) = \begin{pmatrix} \partial_1 f_1(x) & \partial_2 f_1(x) & \dots & \partial_n f_1(x) \\ \vdots & \vdots & \ddots & \vdots \\ \partial_1 f_m(x) & \dots & \dots & \partial_n f_m(x) \end{pmatrix}$$

If $n = m$, then we have the Jacobian determinant

$$J_f(x) = \det(Df(x))$$

Function spaces $C^k(\Omega, \mathbb{R}^m)$ Given a domain $\Omega \subset \mathbb{R}^n$.

We are looking at functions $f: \Omega \rightarrow \mathbb{R}^n$

k^{th} partial derivatives for an index set $i_1, \dots, i_k \in \{1, \dots, n\}$: let

$$x \in \Omega, \quad \partial_{i_1, i_2, \dots, i_k} f := \partial_{i_1} (\partial_{i_2} (\partial_{i_3} \dots \partial_{i_k} f) \dots) (x)$$

if all relevant limits exist.

$f \in C^k(\Omega, \mathbb{R}^n)$ if for all $x \in \Omega$, and all possible index sets, k^{th} derivatives exist and are continuous at x .

Theorem of Schwarz \blacksquare If $f \in C^2(\Omega, \mathbb{R}^m)$, then $\forall 1 \leq i, j \leq n$
and $x \in \Omega$,

$$\partial_{i,j} f(x) = \partial_{j,i} f(x)$$

i.e. order of differentiation can be exchanged.

Corollary If $f \in C^k(\Omega, \mathbb{R}^m)$ then for every index set $\blacksquare i_1, \dots, i_k$,
the order of the partial differentiations can be taken arbitrarily.

Proof of Corollary: interchange orders one step at a time, using
Theorem of Schwarz. 2-cycles generate all permutations.

Example / Exercise

$$f(x, y) = \begin{cases} xy \frac{x^2 - y^2}{x^2 + y^2} & \text{for } (x, y) \neq (0, 0) \\ 0 & \text{at } (0, 0) \end{cases}$$

Check a., $f \in C^1(\mathbb{R}^2)$ [for $m=1$, write $C^k(\mathcal{L}) = C^k(\mathcal{L}, \mathbb{R})$]

b., $\partial_x \partial_y f(0, 0) = 1$

$$\partial_y \partial_x f(0, 0) = -1$$

So existence of the limits defining $\partial_x \partial_y$, $\partial_y \partial_x$ is not sufficient for their equality.

Definition *** $f: \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ is differentiable at $x \in \Omega$

if there exists a linear map $L_x: \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that

$$\lim_{h \rightarrow 0} \frac{f(x+h) - f(x) - L_x(h)}{|h|} = 0$$

We say f is differentiable on Ω if it is so $\forall x \in \Omega$.

Alternatively, we require $L_x: \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that

$$f(x+h) = f(x) + L_x(h) + R_f(h)$$

Constant term
at x

linear term

remainder term
"small compared
to h "

such that

$$\lim_{h \rightarrow 0} \frac{R_f(h)}{|h|} = 0.$$

Note : for $n = m = 1$, we are back to the interpretation of $f'(x)$ as the slope of the tangent line!

Linear and quadratic cases

Let A be an $n \times m$ matrix, $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$b \in \mathbb{R}^m$$

$$x \mapsto Ax + b$$

$$f(x+h) - f(x) = Ah$$

So can take $L_x(h) = Ah$, $R_f(h) = 0$.

In other words, $L_x = A$

Linear maps stay themselves as derivatives

Quadratic case: quadratic forms. Take $C \in \text{Sym}_n(\mathbb{R})$

and let $f(x) = x^t C x$, this defines $f: \mathbb{R}^n \rightarrow \mathbb{R}$.
 $= \langle x, Cx \rangle$

$$\begin{aligned} f(x+h) - f(x) &= \langle x+h, C(x+h) \rangle - \langle x, Cx \rangle \\ &= \langle x, Ch \rangle + \langle h, Cx \rangle + \langle h, Ch \rangle \end{aligned}$$

\langle, \rangle symmetric. $\xrightarrow{\hspace{2cm}}$

$$= \langle Ch, x \rangle + \langle h, Cx \rangle + \langle h, Ch \rangle$$

$$C = C^t$$

$$\xrightarrow{\hspace{2cm}} = \underbrace{2\langle h, Cx \rangle}_{\text{candidate for } L_x(h)} + \langle h, Ch \rangle$$

Indeed, this is correct, since ...

$$\frac{|f(x+h) - f(x) - L_x(h)|}{|h|} = \frac{|\langle h, Ch \rangle|}{|h|} \leq \frac{|h| \|Ch\|}{|h|} \leq \|C\| |h|$$

So indeed, $\frac{R_f(h)}{|h|} \rightarrow 0$ as $h \rightarrow 0$.

Hence indeed, f is differentiable at every $x \in \mathbb{R}^n$ and

$$L_x(h) = 2 \langle h, Cx \rangle$$

Last example

$$\begin{array}{ccc} f: \mathbb{R}^{u^2} & \longrightarrow & \mathbb{R}^{u^2} \\ \parallel & & \parallel \\ \text{Mat}_{u \times u}(\mathbb{R}) & & \text{Mat}_{u \times u}(\mathbb{R}) \end{array}$$

$$A \longmapsto A^2$$

For $H \in \mathbb{R}^{u^2}$ (small)

$$f(A+H) - f(A) = (A+H)^2 - A^2$$

$$= \underbrace{AH + HA}_{\text{linear}} + H^2$$

constant

remainder
"higher order"

So, with $L_A(H) = AH + HA$, get

$$\frac{\|f(A+H) - f(A) - L_A(H)\|}{\|H\|} = \frac{\|H^2\|}{\|H\|} \leq \frac{\|H\|^2}{\|H\|} \rightarrow 0$$

as $H \rightarrow 0$.

Denote $df(x) = L_x : \mathbb{R}^n \rightarrow \mathbb{R}^m$ (if exists)

Theorem A If $f: \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ is differentiable at $x \in \Omega$ then f is continuous, all partial derivatives exist at x and

$$\underbrace{df(x)(h)}_{\substack{\text{linear map} \\ \mathbb{R}^n \rightarrow \mathbb{R}^m}} = \underbrace{Df(x)}_{\text{matrix}} \cdot \underbrace{h}_{\substack{\uparrow \\ \text{matrix multiplication}}}$$

Theorem B If $f: \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ has continuous partial derivatives at $x \in \Omega$, then f is differentiable at $x \in \Omega$.