

Theorem $M \subset \mathbb{R}^n$ a ℓ -dimensional submanifold, locally given by
 $f \in C^1(\Omega, \mathbb{R}^{n-\ell})$ as $f^{-1}(0) = M \cap \Omega$, with $\text{rank } Df(x) = n-\ell$
for $x \in M \cap \Omega$. Then $\forall x \in M \cap \Omega$,

$$T_x M = \ker Df(x)$$

Proof $\subseteq \checkmark$

\exists We are going to use the Implicit Function Theorem.

After permutation of coordinates, we can assume $x = (z_0, y_0) \in \mathbb{R}^\ell \times \mathbb{R}^{n-\ell}$
and there exist open subsets $U \subset \mathbb{R}^\ell$, $V \subset \mathbb{R}^{n-\ell}$ and

$g \in C^1(U, V)$ such that ...

$$(*) \quad M_n(U \times V) = f^{-1}(0) = \{(z, g(z)) : z \in U\}$$

\mathbb{R}^n

A hand-drawn black arrow pointing upwards, indicating a positive direction or trend.

↑

implicitly

$$M = f^{-1}(0)$$

explicitly

$$M = \{(z, g(z))\}$$

This will allow us to write down some explicit tangent vectors.

lit

$$G: U \longrightarrow \mathbb{R}^n$$

$$z \mapsto (z, g(z))$$

For $\xi \in \mathbb{R}^k$, and small ϵ , set

$$g(t) = G(z_0 + t\xi)$$

Then $g: (-\epsilon, \epsilon) \rightarrow \mathbb{R}^n$

and by (*), $im(g) \subseteq M \cap (U \times V) \subseteq \mathbb{R}^n$, so we have a piece of a curve (C^1 image of open interval $(-\epsilon, \epsilon)$ inside M)

Then

$$g'(t) = DG(z_0 + t\xi) \xi \quad (\text{Chain Rule})$$

so

$$\boxed{g'(0) = DG(z_0) \xi}$$

Here $DG(z_0): \mathbb{R}^k \rightarrow \mathbb{R}^n$ is a linear map.

So we get

$$(\ast\ast) \quad \boxed{\text{im } DG(z_0) \subseteq T_x M \subseteq \ker Df(x)}$$

However, $DG(z_0) = \begin{pmatrix} I_{k_0} \\ Dg(z_0) \end{pmatrix}$ is injective.

$$\dim \text{im } DG(z_0) = k = n - \underbrace{\text{rank } Df(x)}_{n-k} = \dim Df(x)$$

So $(\ast\ast)$ must be = everywhere.

□

Example $\mathcal{O}(n) = \{X^t X = I\} \subseteq \mathbb{R}^{n^2}$ is a submanifold of dimension $\frac{n(n-1)}{2}$

$$I \in \mathcal{O}(n) \subseteq \mathbb{R}^{n^2}$$

$$f: \mathbb{R}^{n^2} \rightarrow \text{Sym}_n(\mathbb{R})$$

$$X \mapsto X^t X - I$$

$$T_I \mathcal{O}(n) \subseteq \mathbb{R}^{n^2} = \text{Mat}_n(\mathbb{R})$$

||

$$\ker Df(I)$$

||

$$Df(X)(H) = X^t H + H^t X$$

$$Df(I)(H) = H + H^t$$

$$\text{Skew}_n(\mathbb{R})$$

Note $\dim \text{Skew}_n(\mathbb{R}) = \frac{(n-1)n}{2} = \dim \mathcal{O}(n)$

Question $O(n)$ is - a submanifold of $M_{n,n}(\mathbb{R})$
- a group ("lie group") $O(n) \times O(n) \rightarrow O(n)$
 $(A, B) \longmapsto A \cdot B$

$Skew_n(\mathbb{R})$ is - tangent space at I to $O(n)$

- "Lie algebra" $[,]$ Lie bracket

$[,] : Skew_n(\mathbb{R}) \times Skew_n(\mathbb{R}) \rightarrow Skew_n(\mathbb{R})$

$(A, B) \longmapsto [A, B] = AB - BA$

(See later in Part B-C courses...)

Think about $SL(n, \mathbb{R})$ and its tangent space at I !

Extremization with constraints: the simplest case

Suppose $f, g: C^1(\mathcal{Q}, \mathbb{R}), \mathcal{Q} \subset \mathbb{R}^2$

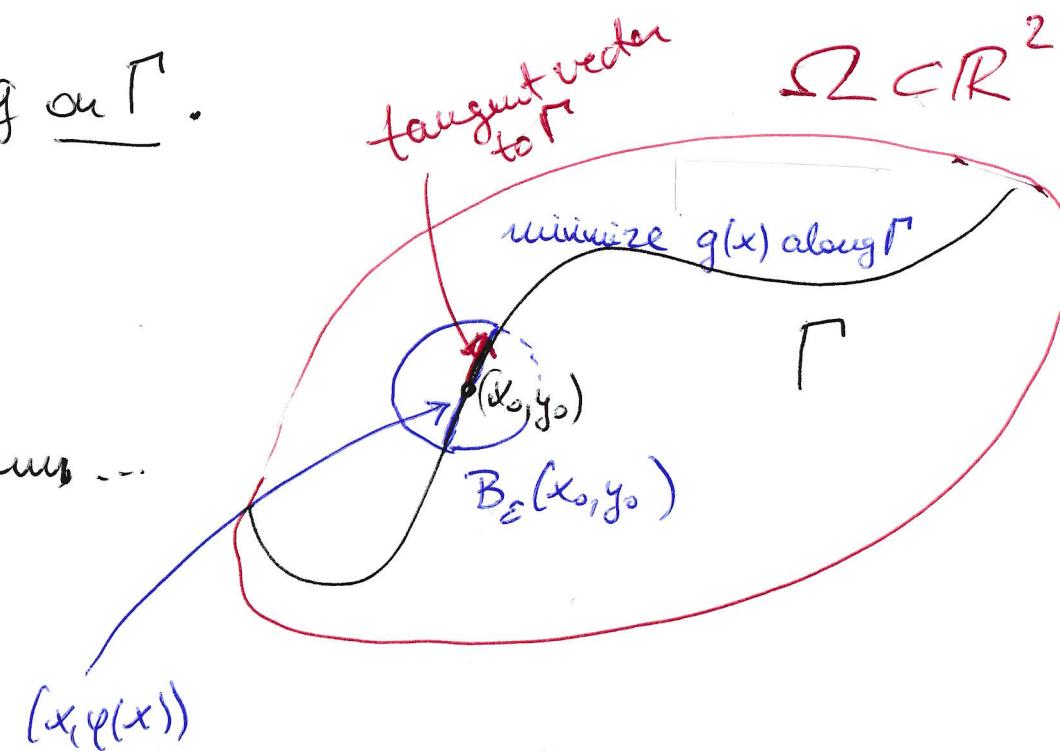
Consider $\Gamma = \{(x, y) \in \mathcal{Q} : f(x, y) = 0\} = f^{-1}(0) \subset \mathcal{Q} \subset \mathbb{R}^2$

Pick $(x_0, y_0) \in \Gamma$ such that $Df(x_0, y_0) \neq 0$, then $\Gamma \cap \mathcal{Q}$ is a one-dimensional submanifold of \mathbb{R}^2 near (x_0, y_0) .

We want to minimize g on Γ .

Assume $\partial_y f(x_0, y_0) \neq 0$.

By Implicit Function Thm ...



$$\Gamma \cap B_\varepsilon(x_0, y_0) = \{ (x, \varphi(x)) \} \text{ where } \begin{aligned} \varphi: I &\rightarrow \mathbb{R} \\ x_0 &\mapsto y_0 \end{aligned}$$

Assume that for $(x, y) \in \Gamma \cap B_\varepsilon(x_0, y_0)$, we have $g(x, y) \geq g(x_0, y_0)$ (*)

(graph of g looks like along the curve)

Tangent vector to Γ at x is given by $(1, \varphi'(x))^t$ and we know

$$(1, \varphi'(x))^t \perp \nabla f(x, \varphi(x))$$

$G(x) = (x, g(x))$, then (*) tells us

$$0 = G'(x) = \underset{\substack{\uparrow \\ \text{by } (x)}}{\partial_x} g(x_0, y_0) + \underset{\substack{\uparrow \\ \text{chain rule}}}{\partial_y g(x_0, y_0)} \cdot \varphi'(x_0)$$

$$= \left\langle \nabla g(x_0, y_0), \begin{pmatrix} 1 \\ \varphi'(x_0) \end{pmatrix} \right\rangle$$

$$\Rightarrow \nabla g(x_0, y_0) \perp \begin{pmatrix} 1 \\ \varphi'(x_0) \end{pmatrix}$$

Conclusion $\nabla f(x_0, y_0)$ and $\nabla g(x_0, y_0)$ are proportional at all stationary points, in particular minima/maxima, of g along Γ .

Constant of proportionality: "Lagrange multiplier"

Theorem (Lagrange multipliers)

Let $\Omega \subset \mathbb{R}^n$ domain, $f: \Omega \rightarrow \mathbb{R}^{n-k}$, $g \in C^1(\Omega, \mathbb{R})$

- Assume
- $x_0 \in f^{-1}(0)$ is a local extremum of g on $f^{-1}(0)$
(ie. \exists open ball around x_0 such that if $f(x)=0$ in the ball, then $g(x) \geq g(x_0)$ for a fixed choice of inequality)
 - $\nabla f(x_0)$ is of maximal rank ($n-k$).

Then $\nabla g(x_0) \subseteq \text{Span } (\nabla f_i(x_0)) = \text{Tan } (\nabla f(x_0))$

ie: $\exists \lambda_1, \dots, \lambda_{n-k} \in \mathbb{R}$ "the Lagrange multipliers"

such that
$$\boxed{\nabla g(x_0) = \sum_{i=1}^{n-k} \lambda_i \nabla f_i(x_0)}$$

Summary

Analysis

- $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$
- differentiability: good linear approximation
 $df(x): \mathbb{R}^n \rightarrow \mathbb{R}^m$ linear map
- $df(x) = Df(x)$ Jacobian matrix
 given by partial derivatives
 of components
- $f \in C^1(\Omega, \mathbb{R}^m)$: all first
 partials exist & are continuous
 \Leftrightarrow differentiability of f

Geometry

- $\{f=0\} \subset \mathbb{R}^n$, $f \in C^1(\Omega, \mathbb{R}^{n-s})$
 maximal rank assumption
- Implicit Function Thm
 $\{f=0\} =$ graph(g) \uparrow implicit and
 explicit descriptions
- Inverse Function Thm
 differentiable
- Submanifolds of \mathbb{R}^n
 conics/quadratics
 matrix groups

- Chain Rule
- Versions of Intermediate Value Theorem
- Tangent spaces: linear approximation at each point

