

$V/\mathbb{F}$ finite dimensional $\mathbb{F}$ -vector space

$$\begin{aligned}\mathbb{P}V &= \{ \text{one-dimensional vector subspaces of } V \} \\ &= V \setminus \{0\} / v \sim \lambda v, \lambda \in \mathbb{F}^\times\end{aligned}$$

Fix a basis of V $\{\underline{e}_0, \dots, \underline{e}_n\}$, $\underline{v} = \sum_{i=0}^n x_i \underline{e}_i$

$$\dim V = n+1, \dim \mathbb{P}V = n$$

$$\underline{v} \sim \lambda \underline{v} \rightsquigarrow (x_0, \dots, x_n) \sim (\lambda x_0, \dots, \lambda x_n)$$

Denote the equivalence class of this vector by $[x_0 : \dots : x_n]$

These are projective coordinates on $\mathbb{P}V = \mathbb{P}(\mathbb{F}^{n+1}) = \mathbb{F}\mathbb{P}^n$

Rules • $[x_0 : \dots : x_n] = [\lambda x_0 : \dots : \lambda x_n] \quad \lambda \in \mathbb{F}^*$

• Not all x_i are 0.

• $x_i \in \mathbb{F}$

Take $n=1$: $\mathbb{F}P^1 = \mathbb{P}(\mathbb{F}^2)$.

A point $p \in \mathbb{F}P^1$ has coordinates $[x_0 : x_1]$

Case 1 $x_0 \neq 0$. Then $p = [x_0 : x_1] = [1 : x_1/x_0]$ $\xleftrightarrow{\quad} \mathbb{F}$
 $\mathbb{F} \xleftarrow{\quad} [1 : x]$
 $\mathbb{F} \xleftarrow{\quad} \text{determined by } p$

Case 2 $x_0 = 0$, then $x_1 \neq 0$. $p = [0 : x_1] = [0 : 1]$. $\xleftrightarrow{\quad}$ one extra point " ∞ "

Conclusion $\mathbb{F}P^1 = \mathbb{F} \sqcup \{\infty\}$

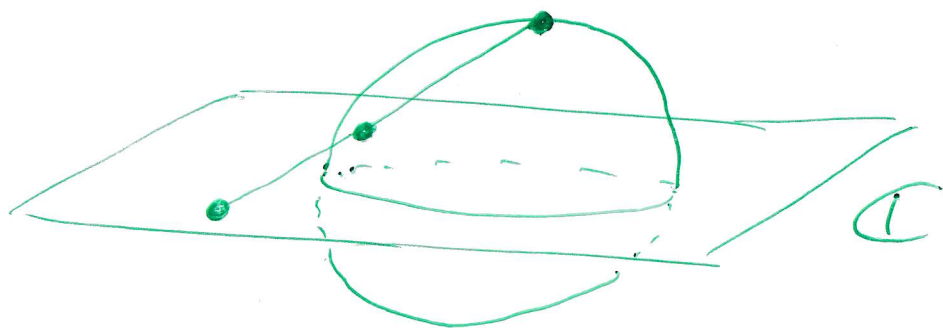
$\uparrow$ decomposition depends on choice of coordinates
and choice of x_0

Sub-example Take $F = \mathbb{C}$, then $\boxed{\mathbb{C}P^1 = \mathbb{C} \cup \{\infty\}}$

Riemann sphere

Aside:

- $\mathbb{C}P^1$ is a line, so dimension 1, as projective space over $\mathbb{C}$
- $\mathbb{C}P^1$ is a sphere, so dimension 2, in $\mathbb{R}$ coordinates
(Re z , Im z , and stereographic projection)



Take $n=2$, $\mathbb{A}P^2 = \mathbb{P}(\mathbb{F}^3)$

$$p = [x_0 : x_1 : x_2]$$

$$[1 : \alpha : \beta] \longleftrightarrow (\alpha, \beta)$$

finite
point

Case 1 $x_0 \neq 0$, $p = [x_0 : x_1 : x_2] = [1 : \frac{x_1}{x_0} : \frac{x_2}{x_0}] \longleftrightarrow \mathbb{F}^2$

Case 2 $x_0 = 0$, $p = [0 : x_1 : x_2]$

- one of them nonzero
- up to scale

$$\longleftrightarrow \mathbb{A}P^1 = \mathbb{P}(\mathbb{F}^2)$$



directions in $\mathbb{F}^2$

ideal points, one
for each direction

We get: $\mathbb{A}P^2 = \mathbb{F}^2 \coprod \mathbb{A}P^1$

~~$\mathbb{A}P^2$~~
= $\mathbb{F}$ -plane $\coprod$ (ideal points)

decomposition depends on
choices

Arbitrary n

$$\mathbb{A}^n(\mathbb{F}) = \mathbb{P}^n(\mathbb{F}) \setminus \mathbb{H}^n(\mathbb{F})$$

~~$x_0 \neq 0$~~ $[x_0 : \dots : x_n] = [1 : \underbrace{x_1/x_0 : \dots : x_n/x_0}_{\substack{\text{affine coordinates} \\ (x_1, \dots, x_n)}}] \longleftrightarrow \mathbb{F}^n$

finite
pts

$$x_0 = 0 \quad [x_0 : \dots : x_n] = [0 : x_1 : \dots : x_n] \longleftrightarrow \mathbb{H}^n(\mathbb{F})$$

ideal
pts

↑
directions in $\mathbb{F}^n$

Recall projective linear subspaces in $\mathbb{P}V$ are $\mathbb{P}U$, for $U \leq V$ linear subspace. One way to view these is as 0-locus linear, homogeneous equations



$$U = \{ \underline{v} : \sum_{i=0}^n \alpha_{ji} x_i = 0, j=1, \dots, m \} = \ker(T)$$

with $T: V \rightarrow \mathbb{F}^m$
given by (α_{ji})

Can write directly

$$\mathbb{P}U = \{ [x_i] : \underbrace{\sum_{i=0}^n \alpha_{ji} x_i = 0}_{\text{makes sense up to scale}}, j=1, \dots, m \} \subseteq \mathbb{P}V$$

makes sense up to scale

Example start with plane $\mathbb{F}^2$

$$\mathbb{F}P^2 = \mathbb{F}^2 \perp \mathbb{F}P^1$$

$$[1:x:y] \leftarrow (x,y)$$

$$[0:x_1:x_2] \leftarrow [x_1:x_2]$$

$$\begin{aligned} [x_0:x_1:x_2] &\xrightarrow{\quad} [1:\frac{x_1}{x_0}:\frac{x_2}{x_0}] & x_0 \neq 0 \\ &\searrow & x_0 = 0 \\ & [x_1:x_2] \end{aligned}$$

Consider line $\{y=2x\} \subseteq \mathbb{F}^2$

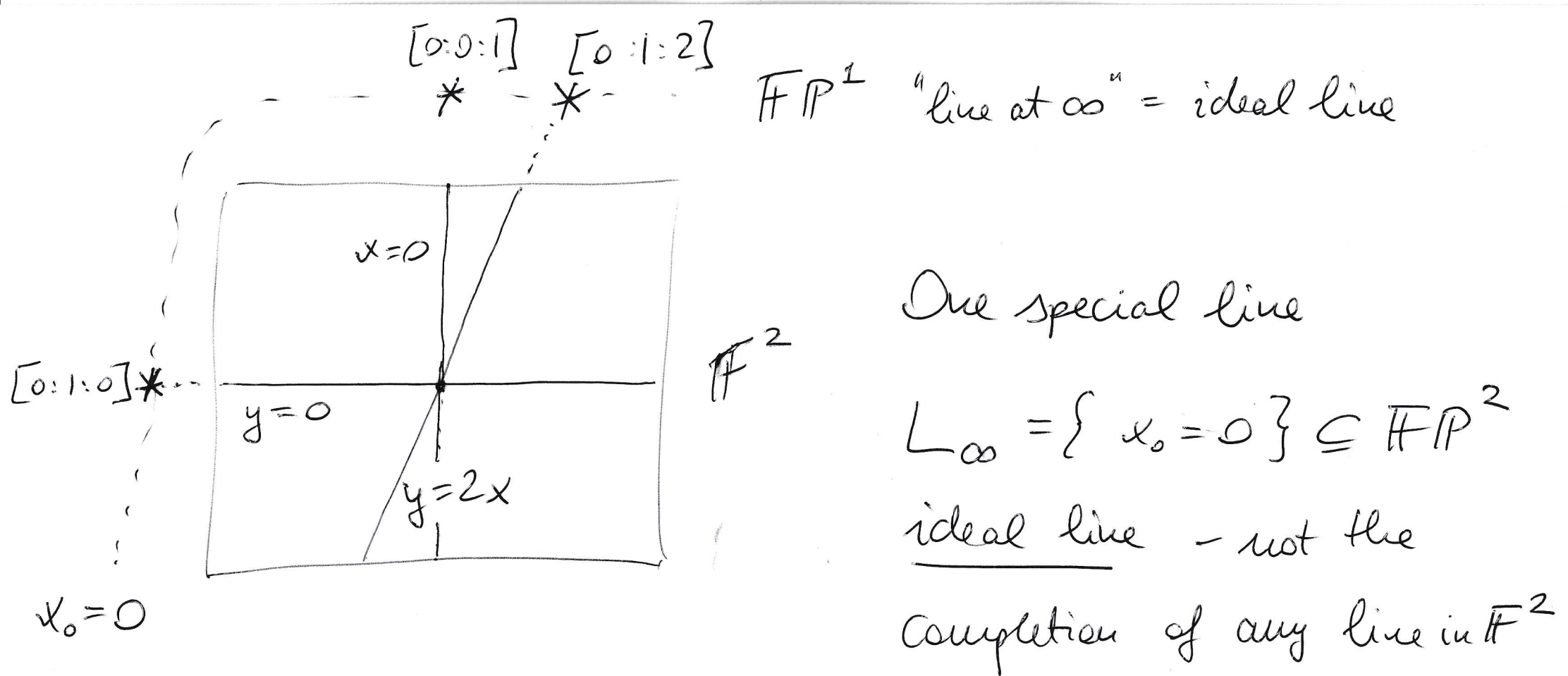
To get the corresponding projective line, use projective coordinates

$$\text{and } x = \frac{x_1}{x_0}, \quad y = \frac{x_2}{x_0}$$

Then we get the equation $\{x_2 = 2x_1\} \subseteq \mathbb{F}P^2$

What solutions are there to this equation? $x_0 \neq 0$: get $(\frac{x_1}{x_0}, \frac{x_2}{x_0})$ on $\{y=2x\}$

$$x_0 = 0: \text{ get } [0:1:2] \in \mathbb{F}P^2$$



$$y = mx + b \quad \text{or} \quad x = c$$

$\uparrow$ slope $\in \mathbb{F}$ $\uparrow$ slope ∞

Aside: let $\mathbb{F} = \mathbb{R}$

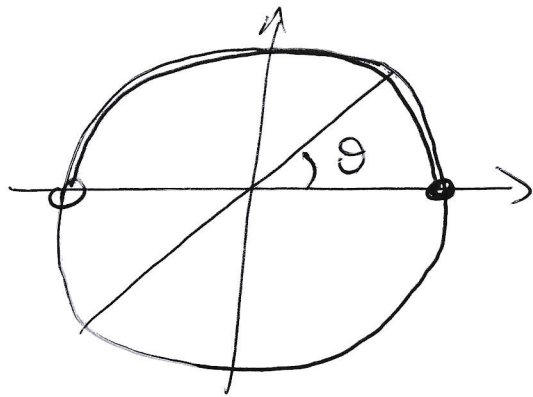
$$\begin{aligned}\mathbb{R}P^n &= \mathbb{P}(\mathbb{R}^{n+1}) = \underline{v} \in \mathbb{R}^{n+1} \setminus \{0\} / (\underline{v} \sim \lambda \underline{v}, \lambda \in \mathbb{R}^*) \\ &= v \in S^n / (v \sim \pm v)\end{aligned}$$

where $S^n = \{v \in \mathbb{R}^{n+1}, |v| = 1\}$ is the unit n -sphere in $\mathbb{R}^{n+1}$.

Slogan: $\mathbb{R}P^n = S^n$ with antipodal points identified.

Fact $\mathbb{RP}^n = S^n / (\underline{v} \sim -\underline{v}) = S^n / C_2$ acting by $\underline{v} \mapsto -\underline{v}$

Example 1 $n=1$ $\mathbb{RP}^1 = S^1 / (\pm 1)$

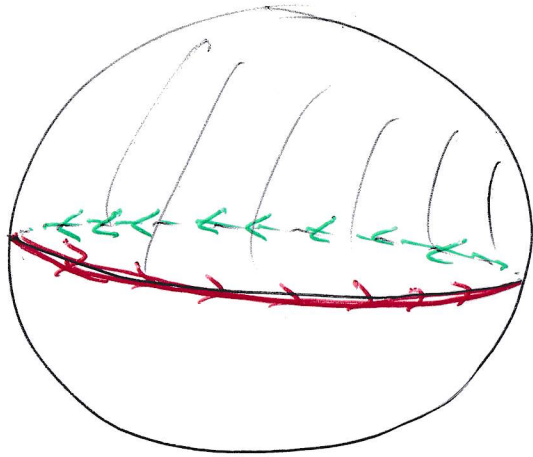


θ and $\theta + \pi$ are different points of S^1
but correspond to the same direction

Actually $\mathbb{RP}^1 \sim S^1$

Proposition S^n is compact (closed and bounded in $\mathbb{R}^{n+1}$), so $\mathbb{RP}^n$ is also compact, as the surjective image of S^n .

Example 2 get $\mathbb{R}P^2 = S^2/(\pm 1) = \overset{\substack{\text{"upper"} \\ \text{hemisphere} \\ z \geq 0}}{U S^2} / (\text{identification } \underline{v} \mapsto -\underline{v} \text{ on the boundary})$



identification on boundary as indicated

Note Key point for equations of linear subspaces was that we used linear, homogeneous equations.

We can define interesting subspaces of $\mathbb{P}^n$ by using ~~linear~~ homogeneous polynomial equations of (x_i) : total degree of each term is the same.

$$\begin{array}{ll} \underline{\text{Ex:}} & x_1^2 + x_2^2 + 3x_3^2 + x_1x_2 + x_2x_3 : \text{homogeneous of degree 2} \\ & x_0^3 + x_1^3 + x_2^3 + x_0x_1x_2 : \text{homogeneous of degree 3} \end{array}$$

Setting these to 0 makes sense in projective space.

$$\begin{array}{ll} x_0 + x_1^2 + x_2^3 & \times \text{ not homogeneous.} \\ x_0x_1 + x_2^3 & \times \end{array}$$