Numerical Solution of Differential Equations I

Endre Süli

Mathematical Institute University of Oxford 2019

Lecture 8

Absolute stability of linear multistep methods

We discussed the stability/accuracy properties of linear multistep methods in the limit of $h \rightarrow 0$, $n \rightarrow \infty$, nh fixed.

It is of practical significance to understand the performance of methods for h > 0 fixed and $n \to \infty$.

We must ensure that, when applied to an initial-value problem whose solution decays to zero as $x \to \infty$, the linear multistep method has a similar behaviour for h > 0 fixed, $x_n = x_0 + nh \to \infty$.

Our model problem with exponentially decaying solution is

$$y' = \lambda y, \quad x > 0, \qquad y(0) = y_0 \ (\neq 0),$$
 (1)

where $\lambda \in \mathbb{C}$, Re $\lambda < 0$. Indeed,

$$y(x) = y_0 \mathrm{e}^{\imath x \, \mathrm{Im} \, \lambda} \mathrm{e}^{x \, \mathrm{Re} \, \lambda},$$

and therefore,

$$|y(x)| \leq |y_0| \exp(-x|\operatorname{Re}\lambda|), \qquad x \geq 0,$$

yielding $\lim_{x\to\infty} y(x) = 0$.

Remark

We shall assume for simplicity that $\lambda \in \mathbb{R}_{<0}$, but everything extends straightforwardly to the case of $\lambda \in \mathbb{C}$ with $\operatorname{Re} \lambda < 0$.

By applying a linear *k*-step method to the model problem (1) with $\lambda \in \mathbb{R}_{<0}$, we have:

$$\sum_{j=0}^k \left(\alpha_j - h\lambda\beta_j\right) y_{n+j} = 0.$$

The general solution y_n to this homogeneous difference equation can be expressed as a linear combination of powers of roots of the associated characteristic polynomial

$$\pi(z;\bar{h}) = \rho(z) - \bar{h}\sigma(z), \qquad (\bar{h} = h\lambda). \tag{2}$$

Thus it follows that y_n will converge to zero for h > 0 fixed and $n \to \infty$ if, and only if, all roots of $\pi(z; \bar{h})$ have modulus < 1.

The *k*th degree polynomial $\pi(z; \bar{h})$ defined by (2) is called the **stability polynomial** of the linear *k*-step method with first and second characteristic polynomials $\rho(z)$ and $\sigma(z)$, respectively.

・ロト ・西ト ・ヨト ・ヨー うへぐ

Definition

A linear multistep method is called **absolutely stable** for a given \bar{h} if, and only if, for that \bar{h} all the roots $r_s = r_s(\bar{h})$ of the stability polynomial $\pi(z, \bar{h})$ defined by (2) satisfy $|r_s| < 1$, $s = 1, \ldots, k$. Otherwise, the method is said to be **absolutely unstable**.

An interval (α, β) of the real line is called the **interval of absolute stability** if the method is absolutely stable for all $\bar{h} \in (\alpha, \beta)$. If the method is absolutely unstable for all \bar{h} , it is said to have **no interval of absolute stability**.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

Since for $\lambda > 0$ the solution of (1) exhibits exponential growth, it is reasonable to expect that a consistent and zero-stable (and, therefore, convergent) linear multistep method will have a similar behaviour for h > 0 sufficiently small, and will be therefore absolutely unstable for small $\bar{h} = \lambda h$. This is indeed the case.

Theorem

Every consistent and zero-stable linear multistep method is absolutely unstable for small positive \bar{h} .

PROOF:

Because the method is consistent, there exists an integer $p \ge 1$ such that $C_0 = C_1 = \cdots = C_p = 0$ and $C_{p+1} \neq 0$. Consider $\pi(\mathbf{e}^{\bar{h}};\bar{h}) = \rho(\mathbf{e}^{\bar{h}}) - \bar{h}\sigma(\mathbf{e}^{\bar{h}}) = \sum_{i=1}^{n} \left[\alpha_{j}\mathbf{e}^{\bar{h}j} - \bar{h}\beta_{j}\mathbf{e}^{\bar{h}j} \right]$ $= \sum_{i=1}^{k} \left| \alpha_j \sum_{j=1}^{\infty} \frac{(\bar{h}j)^q}{q!} - \beta_j \sum_{j=1}^{\infty} \frac{\bar{h}^{q+1}j^q}{q!} \right|$ $= \sum_{i=1}^{k} \left[\alpha_j \sum_{j=1}^{\infty} \frac{(\bar{h}j)^q}{q!} - \beta_j \sum_{j=1}^{\infty} \frac{\bar{h}^q j^{q-1}}{(q-1)!} \right]$ $=\sum_{j=0}^{k} \alpha_j + \sum_{j=0}^{k} \left[\alpha_j \sum_{j=1}^{\infty} \frac{(\bar{h}j)^q}{q!} - \beta_j \sum_{j=1}^{\infty} \frac{\bar{h}^q j^{q-1}}{(q-1)!} \right]$ $= \sum_{i=0}^{k} \alpha_{j} + \sum_{q=1}^{\infty} \bar{h}^{q} \left[\sum_{i=0}^{k} \alpha_{j} \frac{j^{q}}{q!} - \sum_{i=0}^{k} \beta_{j} \frac{j^{q-1}}{(q-1)!} \right]$ $= C_0 + \sum^{\infty} \bar{h}^q C_q = \sum^{\infty} C_q \bar{h}^q = \mathcal{O}(\bar{h}^{p+1}).$ (3) 日本人間を入街を入街を一番

On the other hand, the polynomial $\pi(z; \bar{h})$ can be written in the factorised form

$$\pi(z,\bar{h})=(\alpha_k-\bar{h}\beta_k)(z-r_1)\cdots(z-r_k)$$

where $r_s = r_s(\bar{h})$, s = 1, ..., k, are the roots of $\pi(\cdot; \bar{h})$. Hence,

$$\pi(\mathrm{e}^{\bar{h}};\bar{h}) = (\alpha_k - \bar{h}\beta_k)(\mathrm{e}^{\bar{h}} - r_1(\bar{h}))\cdots(\mathrm{e}^{\bar{h}} - r_k(\bar{h})).$$
(4)

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

As $\bar{h} \to 0$, we have $\alpha_k - \bar{h}\beta_k \to \alpha_k \neq 0$, and thanks to the continuous dependence of the roots of a polynomial on the coefficients of the polynomial,

$$lpha_k - ar{h}eta_k o lpha_k
eq 0$$
 and $r_s(ar{h}) o \zeta_s$, $s = 1, \dots, k$,

where ζ_s , $s = 1, \ldots, k$, are the roots of $\rho(z)$.

Since, by assumption, the method is consistent, 1 is a root of $\rho(z)$; furthermore, by zero-stability 1 is a simple root of $\rho(z)$.

Suppose for definiteness that it is ζ_1 that is equal to 1. Then, $\zeta_s \neq 1$ for $s \neq 1$ and therefore

$$\lim_{\bar{h}\to 0} (\mathrm{e}^h - r_s(\bar{h})) = (1-\zeta_s) \neq 0, \qquad s\neq 1.$$

Thus, by (4), the only factor of $\pi(e^{\bar{h}}; \bar{h})$ that converges to 0 as $\bar{h} \to 0$ is $e^{\bar{h}} - r_1(\bar{h})$ (the other factors tend to nonzero constants).

Now, by (3),
$$\pi(e^{\bar{h}}; \bar{h}) = \mathcal{O}(\bar{h}^{p+1})$$
, so it follows that
 $e^{\bar{h}} - r_1(\bar{h}) = \mathcal{O}(\bar{h}^{p+1}).$

Thus we have shown that

$$r_1(\bar{h}) = \mathrm{e}^{\bar{h}} + \mathcal{O}(\bar{h}^{p+1}).$$

Hence

$$r_1(\bar{h}) > 1 + \frac{1}{2}\bar{h}$$
 for small positive \bar{h} .

How to locate the interval of absolute stability?

We describe two methods for finding the endpoints of the interval of absolute stability.



(10 January 1875, Mogilev, Belarus – 10 January 1941, Tel Aviv, Israel)

▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @

How to locate the interval of absolute stability?

We describe two methods for finding the endpoints of the interval of absolute stability.

The Schur criterion. A polynomial

$$\phi(r)=c_kr^k+\cdots+c_1r+c_0,\qquad c_k
eq 0,\quad c_0
eq 0,$$

with complex coefficients is said to be a **Schur polynomial** if each of its roots, r_s , satisfies $|r_s| < 1$, s = 1, ..., k. Let

$$\hat{\phi}(r) := \bar{c}_0 r^k + \bar{c}_1 r^{k-1} + \cdots + \bar{c}_{k-1} r + \bar{c}_k,$$

where \bar{c}_j denotes the complex conjugate of c_j , $j = 1, \ldots, k$. Further, let us define

$$\phi_1(r) = rac{1}{r} \left[\hat{\phi}(0) \phi(r) - \phi(0) \hat{\phi}(r)
ight].$$

Clearly ϕ_1 has degree $\leq k - 1$.

(ロ)、

The following key result is stated without proof.

Theorem (Schur's criterion)

The polynomial ϕ is a Schur polynomial if, and only if:

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

- $|\hat{\phi}(0)| > |\phi(0)|$, and
- $\blacktriangleright \phi_1$ is a Schur polynomial.

Exercise

Use Schur's criterion to determine the interval of absolute stability of the linear multistep method

$$y_{n+2} - y_n = \frac{h}{2} (f_{n+1} + 3f_n).$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ □臣 ○のへ⊙

SOLUTION: The first and second characteristic polynomials of the method are

$$\rho(z) = z^2 - 1, \qquad \sigma(z) = \frac{1}{2}(z+3).$$

Therefore the stability polynomial is

$$\pi(r;\bar{h})=\rho(r)-\bar{h}\sigma(r)=r^2-\frac{1}{2}\bar{h}r-\left(1+\frac{3}{2}\bar{h}\right).$$

Now,

$$\hat{\pi}(r;\bar{h})=-\left(1+\frac{3}{2}\bar{h}\right)r^2-\frac{1}{2}\bar{h}r+1.$$

Clearly, $|\hat{\pi}(0;\bar{h})| > |\pi(0,\bar{h})|$ if, and only if, $\bar{h} \in (-\frac{4}{3},0)$. As

$$\pi_1(r,\hat{h}) = -\frac{1}{2}\bar{h}(2+\frac{3}{2}\bar{h})(3r+1)$$

has the unique root $-\frac{1}{3}$ and is, therefore, a Schur polynomial, we deduce from Schur's criterion that $\pi(r; \bar{h})$ is a Schur polynomial if, and only if, $\bar{h} \in (-\frac{4}{3}, 0)$. Therefore the interval of absolute stability is $(-\frac{4}{3}, 0)$.





Edward John Routh

Adolf Hurwitz 20 January 1831, Quebec – 7 June 1907 Cambridge 26 March 1859 Hildesheim – 18 November 1919 Zürich

<□▶ <□▶ < □▶ < □▶ < □▶ < □▶ = のへぐ

The Routh–Hurwitz criterion.

Consider the mapping

$$\mathsf{z} = \frac{r-1}{r+1}$$

of the open unit disc |r| < 1 of the complex *r*-plane to the left open complex half-plane Re z < 0 of the complex *z*-plane.

The inverse of this mapping is

$$r=\frac{1+z}{1-z}.$$

Under this transformation $\pi(r, \bar{h}) = \rho(r) - \bar{h}\sigma(r)$ becomes

$$\rho\left(\frac{1+z}{1-z}\right) - \bar{h}\sigma\left(\frac{1+z}{1-z}\right).$$

Multiplying this by $(1-z)^k$ we obtain a polynomial of the form

$$a_0 z^k + a_1 z^{k-1} + \dots + a_k.$$
 (5)

The roots of $\pi(r, \bar{h})$ lie inside the open unit disk |r| < 1 if, and only if, the roots of (5) lie in the left open complex half-plane Re z < 0.

Theorem (Routh–Hurwitz criterion)

The roots of (5) lie in the left open complex half-plane if, and only if, all the leading principal minors of the $k \times k$ matrix

$$Q = \begin{bmatrix} a_1 & a_3 & a_5 & \cdots & a_{2k-1} \\ a_0 & a_2 & a_4 & \cdots & a_{2k-2} \\ 0 & a_1 & a_3 & \cdots & a_{2k-3} \\ 0 & a_0 & a_2 & \cdots & a_{2k-4} \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ 0 & 0 & 0 & \cdots & a_k \end{bmatrix}$$

are positive and a₀ > 0; we assume that a_j = 0 if j > k. E.g.:
a) for k = 2: a₀ > 0, a₁ > 0, a₂ > 0;
b) for k = 3: a₀ > 0, a₁ > 0, a₂ > 0, a₃ > 0, a₁a₂ - a₃a₀ > 0;
c) for k = 4: a₀ > 0, a₁ > 0, a₂ > 0, a₃ > 0, a₄ > 0, a₁a₂a₃ - a₀a₃² - a₄a₁² > 0;

represent the necessary and sufficient conditions for ensuring that all roots of (5) lie in the left open complex half-plane.

Exercise

Use the Routh–Hurwitz criterion to find the interval of absolute stability of the linear multistep method from the previous exercise.

SOLUTION: By applying the substitution

$$r = \frac{1+z}{1-z}$$

in the stability polynomial

$$\pi(r,ar{h})=r^2-rac{1}{2}ar{h}r-\left(1+rac{3}{2}ar{h}
ight)$$

and multiplying the resulting function by $(1-z)^2$, we get

$$(1-z)^{2}\left[\left(\frac{1+z}{1-z}\right)^{2}-\frac{1}{2}\bar{h}\left(\frac{1+z}{1-z}\right)-\left(1+\frac{3}{2}\bar{h}\right)\right]=a_{0}z^{2}+a_{1}z+a_{2}z^{2}$$

with

$$a_0=-\bar{h}, \qquad a_1=4+3\bar{h}, \qquad a_2=-2\bar{h}.$$

Applying part a) of the theorem (Routh–Hurwitz criterion) we deduce that the method is zero-stable if, and only if, $\bar{h} \in (-\frac{4}{3}, 0)$; hence the interval of absolute stability is $(-\frac{4}{3}, 0)$. \diamond