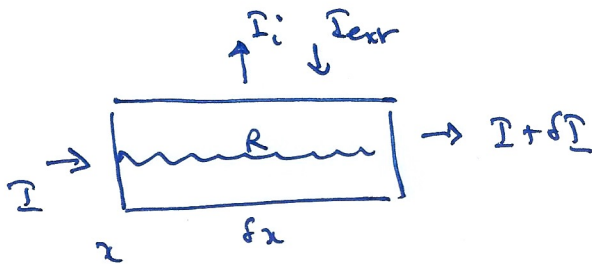


C5.12

Math Physiol 2018 21

C

(a)



Conservation of charge (density) $Q = CV$

$$\frac{\partial}{\partial t} Q \Delta x = I \Big|_x^{x+\Delta x} + (I_{\text{ext}} - I_i) \Delta x$$

$$\Rightarrow \frac{\partial}{\partial t} C \frac{\partial V}{\partial x} = - \frac{\partial I}{\partial x} + I_{\text{ext}} - I_i$$

Also Ohm's law with Resistance R / unit length

$$-\Delta V = R \Delta x I$$

$$\Rightarrow \frac{-\Delta V}{\Delta x} = R I$$

C capacitance (unit length)

R resistance (unit length)

$$(b) \quad I_i = g_1(V - V_1)n + g_2(V - V_2)(1-n) \quad V_1 < V_2$$

$$I_i \approx n = n_0(V) - n$$

(i) steady state $I_i = 0 \Rightarrow V = V_0, n = n_0(V_0) = n_0$

$$\Rightarrow 0 = g_1(V_0 - V_1)n_0 + g_2(V_0 - V_2)(1 - n_0) \quad \text{err } n = n(V_0)?$$

$$\Rightarrow V_0 = \frac{g_1 n_0 V_1 + g_2 (1 - n_0) V_2}{g_1 n_0 + g_2 (1 - n_0)} \in (V_1, V_2)$$

since $g_1 n_0 > 0$
 $g_2 (1 - n_0) > 0$

ii

(2)

$$\text{non-d } t \sim \tau \quad x \sim l \quad V = V_0 + V^* v$$

$$CV_t = \frac{1}{R} V_{xx} + \Gamma_{ext} - \Gamma_i$$

$$\begin{aligned} \dagger \Gamma_i &= g_1 [V_0 - V_1 + V^* v]_n + g_2 [V_0 - V_2 + V^* v]_{(1-n)m} \\ &= g_1 V^* \left[\frac{V_0 - V_1}{V^*} + v \right]_n + g_2 V^* \left[v - \frac{V_2 - V_0}{V^*} \right]_{(1-n)m} \end{aligned}$$

$$= g_2 V^* \Gamma_i^*$$

$$\Gamma_i^* = \frac{g_1}{g_2} \left[\frac{V_0 - V_1}{V^*} + v \right]_n + \left[v - \frac{V_2 - V_0}{V^*} \right]_{(1-n)m}$$

$$\text{choose } V^* \geq V_2 - V_0 > 0$$

$$\Rightarrow \Gamma_i^* = \gamma (v + v_1)_n + (v - 1)_{(1-n)m}$$

$$\gamma = \frac{g_1}{g_2}, \quad v_1 = \frac{V_0 - V_1}{V_2 - V_0} > 0$$

$$\text{and } \frac{CV^*}{\tau} v_t = \frac{V^*}{Rl^2} v_{xx} + g_2 V^* (\Gamma_{ext}^* - \Gamma_i^*)$$

$$\text{where also } \Gamma_{ext} = g_2 V^* \Gamma_{ext}^*$$

$$\Delta \quad \underline{n = n_0 - n}$$

$$\text{thus define } \varepsilon = \frac{CV^*}{\tau g_2 V^*} = \frac{C}{\tau g_2}$$

$$\dagger \varepsilon^2 = \frac{1}{g_2 R l^2} \quad \text{if } l = \frac{\tau g_2}{C \sqrt{g_2 R}} = \underline{\underline{\frac{\tau}{C} \sqrt{\frac{g_2}{R}}}}$$

(e)

$$\varepsilon_{V_T} = \Sigma_{\text{extr}}^k - \Sigma_i^k + \varepsilon^{-1} v_{\text{ext}}$$

$$n_T = n_a - n$$

$$\Sigma_i^k = g(n, v) = \gamma(v+v_1)n + (v-1)(1-n)m$$

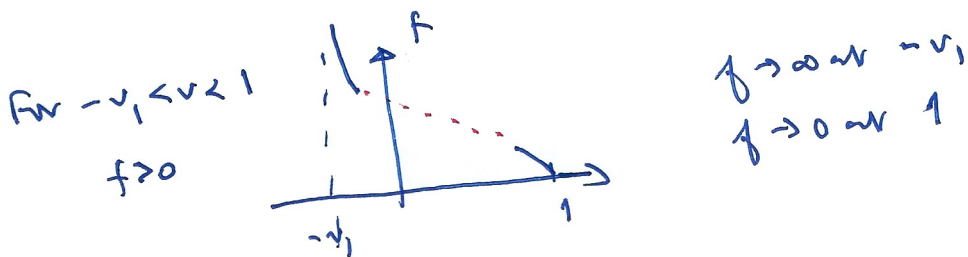
$$n = h(v) \iff g(n, v) = 0$$

explicitly $[\gamma(v+v_1) - (v-1)m]n + (v-1)m = 0$

$$n = \frac{(v-1)m(v)}{(\gamma(v+v_1) - (v-1)m)} = h(v) \quad m > 0, m' > 0$$

equilibrium: $v=0, n=n_0(0)$

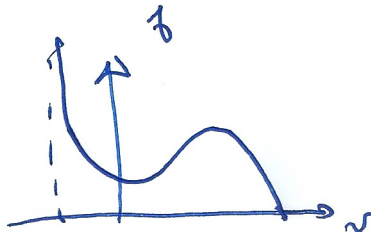
Consider the function $f(v) = \frac{(1-v)}{\gamma(v+v_1)} \quad (20 \text{ is } \frac{1}{f+1})$



so monotonically decreasing is possible

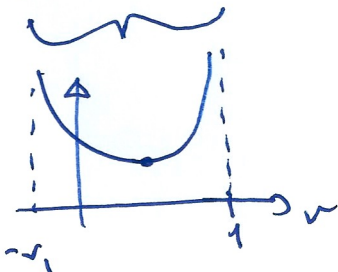
but clearly f will not be non-monotonic if

m' is large enough

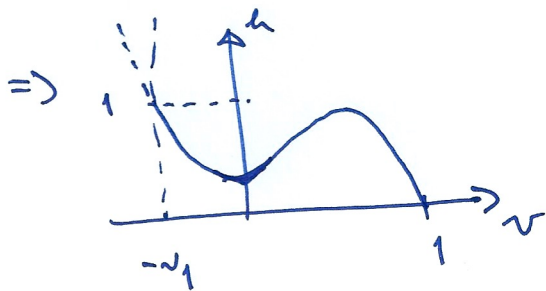
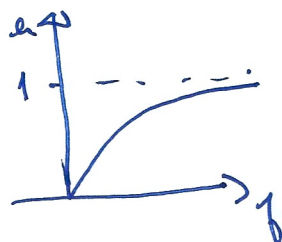
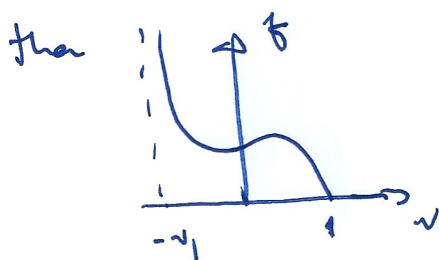


Explicitly $\frac{f(v)}{f(v_1)} = \frac{-1}{1-v} + \frac{m'}{m} - \frac{1}{v+v_1}$

$$= \frac{m'}{m} - \left[\frac{1}{1-v} + \frac{1}{v+v_1} \right]$$



> 0 if $\frac{m'}{m}$ larger than $\min_{-v_1 < v < 1} \left[\frac{1}{1-v} + \frac{1}{v+v_1} \right]$



(ii) obvious (clearly done) \cdot $h'(v) = h'(f) f'(v)$
 $= \frac{f}{(f+1)^2} \left[\frac{m'}{m} - \left\{ \frac{1}{1-v} + \frac{1}{v+v_1} \right\} \right]$

$\rightarrow -\infty$ as $v \rightarrow 1$
 $f < 0$ as $v \rightarrow v_1$
 $f \rightarrow \infty$

$$\left(h' = \frac{1}{f} \cdot -\frac{1}{(v+v_1)^2} \right)$$

$$\approx -\frac{\gamma}{(1+v_1)^2 m(-v_1)}$$

$$m = \exp[k(v-1)]$$

$$= \frac{m'}{m} = k$$

non-monotonic if $k > \min \left[\frac{1}{1-v} + \frac{1}{v+v_1} \right]$

which is at $\frac{1}{(1-v)^2} = \frac{1}{(v+v_1)^2}$

or $1-v = v+v_1$

$$v = \frac{1-v_1}{2}$$

$$\text{min is } \left[\frac{1}{1-\left(\frac{1-v_1}{2}\right)} + \frac{1}{\frac{1-v_1}{2}+v_1} \right]$$

$$= \frac{4}{1+v_1}$$

So if $k > \frac{4}{1+v_1}$

(iii) $n_\infty(v)$ increasing

~~At $v=0$, $f = \frac{n(0)}{2v_1}$~~

$$k'(v) = \frac{f}{(f+1)^2} \left[k - \left\{ \frac{1}{1-v} + \frac{1}{v+v_1} \right\} \right]$$

$$k'(0) > 0 \quad \text{if } [k(0) > 0] \text{ or } n(0) > 0$$

$$k > 1 + \frac{1}{v_1}$$

[Note: question suggests $h'(0) > 0$ or below. Skip if $h'(0) < 0$]

(6)

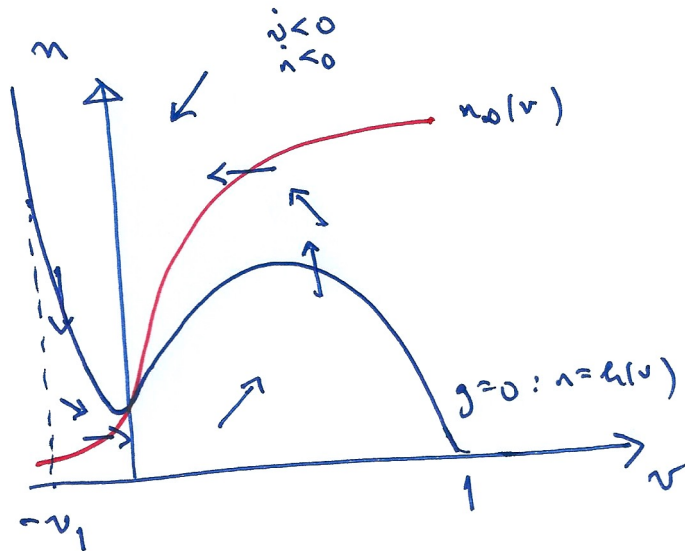
$$\epsilon \dot{v} = -g(v, n)$$

$$\dot{n} = n_0 - n$$

Note for $-v_1 < v < 1, n > 0$

$$g \rightarrow \infty \text{ as } n \rightarrow \infty$$

$$\Rightarrow \dot{v} < 0 \text{ for } n > h(v)$$



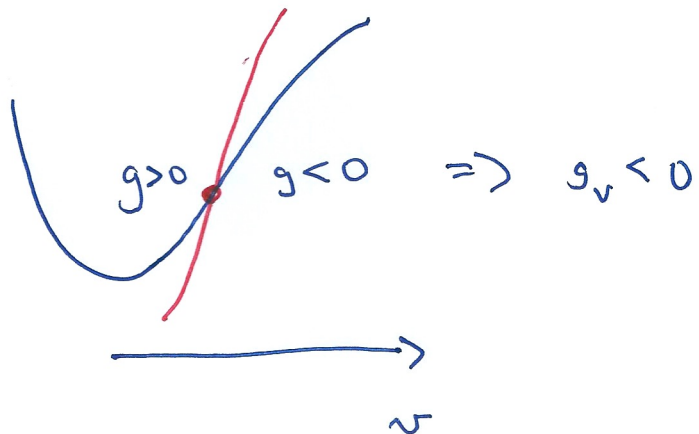
↓
trajectory direction
as shown
⇒ fixed point
is node or spiral

⇒ stable if $\text{tr} M < 0$ where $M = \begin{pmatrix} -\frac{1}{\epsilon} g_v & \frac{1}{\epsilon} g_n \\ n_0' & -1 \end{pmatrix}$

$$\text{tr} M = -\frac{1}{\epsilon} g_v - 1$$

$$< 0 \text{ if } g_v > -\epsilon$$

Now need $h'(0) > 0$



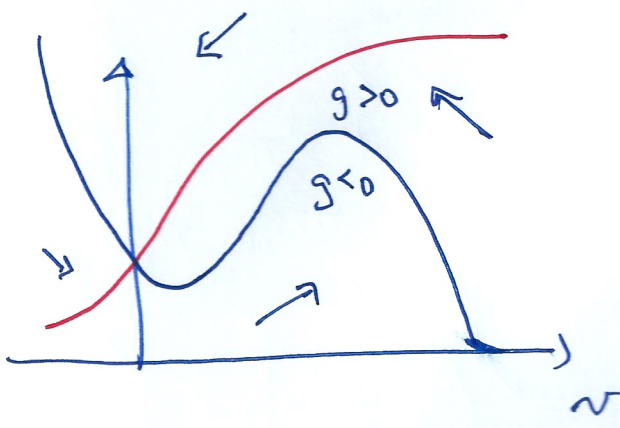
and the steady state is unstable !?

[The question is not specific, but the implication to me is that we should have $h'(0) < 0$]

[I think the question ought to read:

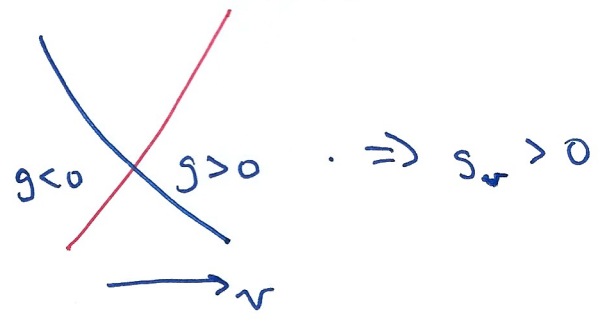
determine the conditions such that $h'(v_0) < 0$. Assuming this,

we...]



Steady state is stable if $g_v > -\epsilon$

Always i.e. if $g_v \geq 0$ ($\epsilon < 1$)



Threshold phenomenon: increase v

