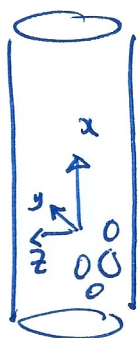


3(a)



The fluid consists of gas G & liquid L (subsets of $\mathbb{R}^3$)

The indicator function $\chi_G = 1$ if $\underline{x} \in G$
 $= 0$ if $\underline{x} \in L$

Mass of gas $\frac{\partial \rho_g}{\partial t} + \nabla \cdot [\rho_g \underline{v}] = 0$

$\times \chi_g$ integrate over cylindrical volume V :

$$\Rightarrow \int_V \left[\chi_g \frac{\partial \rho_g}{\partial t} + \chi_g \nabla \cdot [\rho_g \underline{v}] \right] dV = 0$$

$\Rightarrow \int_V \left[\frac{\partial}{\partial t} (\chi_g \rho_g) + \nabla \cdot [\chi_g \rho_g \underline{v}] \right] dV$
 $= - \int_V \left[\rho_g \frac{\partial \chi_g}{\partial t} + \rho_g \underline{v} \cdot \nabla \chi_g \right] dV$

treat χ_g as a generalized function

$$\Rightarrow \frac{\partial}{\partial t} \int_V \rho_g \chi_g dV + \frac{d}{dt} \left[\int_A \rho_g \chi_g \underline{v} \cdot \underline{n} dA \right] = - \int_V \rho_g \frac{d\chi_g}{dt} dV$$

where A is cross-section area $\underline{v} = \underline{v} \cdot \underline{n} = \underline{v} \cdot \underline{i}$ ($\underline{i}$ is x direction)
 (since $\underline{v} \cdot \underline{n} = 0$ on walls) $\left[\int_A \right]_+^+ = \text{jump from bottom to top}$

(2)

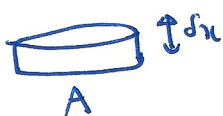
Now the definition of $\frac{dx_s}{dt} = \frac{\partial x_s}{\partial t} + \underline{v} \cdot \underline{\nabla} x_s$ is a generalised function is via integration over $\mathbb{R}^3 \times \mathbb{R}$ with a test function ϕ ($\rightarrow 0$ at ∞)

$$\begin{aligned}
 & \iint_{\mathbb{R}^3 \times \mathbb{R}} \phi \left[\frac{\partial x_s}{\partial t} + \underline{v} \cdot \underline{\nabla} x_s \right] dV dt \\
 &= - \iint x_s \left[\frac{\partial \phi}{\partial t} + \underline{\nabla} \cdot (\phi \underline{v}) \right] dV dt \\
 &= - \int_{-\infty}^{\infty} \int_G \left[\frac{\partial \phi}{\partial t} + \underline{\nabla} \cdot (\phi \underline{v}) \right] dV dt \\
 &= - \int_{-\infty}^{\infty} \left\{ \frac{d}{dt} \int_G \phi dV \right\} dt \quad \text{via Reynolds' transport theorem (material G)} \\
 &= - \int_G \phi dV \Big|_{t=-\infty}^{t=\infty} = 0 \quad \sim \phi \rightarrow 0 \text{ at } t \rightarrow \pm \infty.
 \end{aligned}$$

so $\frac{dx_s}{dt} = 0$ in the sense of generalised functions

Now let δ

$$V = A \delta x$$



$$\begin{aligned}
 & \frac{\partial}{\partial t} \int_A \rho_s x_s dA \delta x + \delta \int_A \rho_s x_s \underline{v} dA = 0 \\
 \Rightarrow & \frac{\partial}{\partial t} \int_A \rho_s x_s dA + \frac{\partial}{\partial x} \int_A \rho_s x_s \underline{v} dA = 0
 \end{aligned}$$

We define the gas volume fraction α , average cross-section gas density $\bar{\rho}_g$, average cross-section gas velocity $\bar{v}$, via

$$\alpha = \frac{1}{A} \int_A x_s dA$$

$$\alpha \bar{\rho}_g = \frac{1}{A} \int_A \rho_s x_s dA$$

$$\alpha \bar{\rho}_g \bar{v} = \frac{1}{A} \int_A \rho_s x_s \underline{v} dA$$

in other words

$$\bar{p}_s = \frac{\int_A p_s x_s dA}{\int_A x_s dA}$$

$$\bar{v} = \frac{\int p_s x_s v dA}{\int p_s x_s dA}$$

~~then~~

For liquid phase, x_l is indicator function $= 1$ if $\underline{x} \in L$ (liquid)
 $= 0$ if $\underline{x} \in G$

then
$$\bar{p}_l = \frac{\int_A p_l x_l dA}{\int_A x_l dA}$$

$$\bar{u} = \frac{\int p_l x_l v dA}{\int p_l x_l dA}$$

($v = \underline{v} \cdot \underline{i}$ as before)

$$\triangleright \frac{\partial}{\partial t} [\bar{p}_l (1-\alpha)] + \frac{\partial}{\partial x} [\bar{p}_l (1-\alpha) \bar{u}] = 0$$

~~(then)~~

(v)

(4)

(drop the bars) , p_s, p_t constant

$$\Rightarrow \alpha_t + (\alpha v)_n = 0$$

$$-\alpha_t + [(1-\alpha)u]_n = 0$$

$$\Delta \text{ then } p_s \propto (v_t + v v_n) = -\alpha p_n - \frac{F_{st}}{A}$$

$$p_e \left[(1-\alpha)(u_t + u u_n) + (\alpha-1) \{ (1-\alpha)u^2 \}_n \right] \\ = - (1-\alpha) p_n \quad \left(\frac{F_{st} + F_{en}}{A} \right) \\ - \frac{(F_{en} - F_{se})}{A}$$

$$\text{Scale } \alpha = 1 - B\beta, \quad B = \frac{f_{en}}{f_{se}}$$

$$u \sim U, v \sim V, p - p_a \sim P$$

$$V = \alpha_0 v_0, \quad P = p_s V^2, \quad U = \epsilon V, \quad \epsilon = \left(\frac{p_s f_{se}}{p_e f_{en}} \right)^{1/2}$$

$$n \sim \frac{R}{f_{se}}, \quad t \sim \frac{A}{f_{se} U}, \quad \text{note } t \sim \frac{x}{U}$$

$$\Delta \quad F_{se} = 2\pi R f_{se} p_s f_{se} |v-u|(v-u)$$

$$= 2\pi R p_s f_{se} V^2 \Phi_{se}, \quad \Phi_{se} = (1-B\beta)^{1/2} |v-\epsilon u|(v-\epsilon u)$$

$\uparrow$
non-1

$$F_{en} = 2\pi R p_e f_{en} U^2 |u|u$$

$$= 2\pi R p_e f_{en} V^2 \epsilon^2 \Phi_{en}, \quad \Phi_{en} = |u|u$$

$\leftarrow \text{non-1}$

So we get $(t \sim \frac{x}{U})$

(5)

$$\underline{-\varepsilon B \beta_t + [(1-B\beta)v]_x = 0}$$

$$B\beta_t + [B\beta u]_x = 0$$

$$\Rightarrow \underline{\beta_t + (\beta u)_x = 0}$$

After (note $l = \frac{R}{f_{se}} \sim x$) so $t \sim \frac{l}{U}$

$$p_s [1-B\beta] \left[\frac{UV}{l} v_t + \frac{V^2}{l} v v_x \right] = -(1-B\beta) \frac{p_s V^2}{l} p_x$$

$$- \frac{2\pi R p_s b_{se} V^2 \bar{I}_{se}}{A}$$

(where $A = \pi R^2$)

$$\div \frac{p_s V}{l} \Rightarrow (1-B\beta) [\varepsilon v_t + v v_x] = -(1-B\beta) p_x$$

$$- \frac{\frac{R}{f_{se}} p_s V^2 \cdot \frac{2\pi R p_s b_{se} V^2 \bar{I}_{se}}{\pi R^2}}{2}$$

$$\text{or } \underline{(1-B\beta) (\varepsilon v_t + v v_x) = -(1-B\beta) p_x - 2(1-B\beta)^2 |v - \varepsilon u| (v - \varepsilon u)}$$

and finally

$$\begin{aligned}
 p_e \left[B \beta \frac{V^2}{l} (u_t + u u_x) + \frac{V^2}{l} (D_x - 1) \{ B \beta u^2 \}_x \right] \\
 = - B \beta \frac{p_s V^2}{l} p_x \\
 - \frac{[2 \pi R \gamma \frac{p_s V^2}{l} \epsilon^2 \bar{\Phi}_{ew} - 2 \pi R p_s b_{se} V^2 \bar{\Phi}_{se}]}{\pi R^2}
 \end{aligned}$$

note $\epsilon^2 = \frac{p_s b_{se}}{p_e b_{ew}}$

$$- \frac{2}{R} p_s b_{se} V^2 (\bar{\Phi}_{ew} - \bar{\Phi}_{se})$$

$$\begin{aligned}
 \div \frac{p_e V^2}{l} : \quad B \beta (u_t + u u_x) + (D_x - 1) \{ B \beta u^2 \}_x \\
 = - B \beta \frac{p_s}{p_e \epsilon^2} p_x - \frac{2}{R} \frac{p_s b_{se} V^2}{p_e V^2 b_{se}} (\bar{\Phi}_{ew} - \bar{\Phi}_{se})
 \end{aligned}$$

note $B = \frac{b_{ew}}{b_{se}}$

$$\begin{aligned}
 \div B \Rightarrow \beta (u_t + u u_x) + (D_x - 1) (\beta u^2)_x \\
 = - \frac{p_s}{p_e \epsilon^2} \beta p_x - \frac{2 p_s b_{se}}{p_e b_{se} \epsilon^2} (\bar{\Phi}_{ew} - \bar{\Phi}_{se})
 \end{aligned}$$

$$\epsilon^2 = \frac{p_s}{p_e B} \Rightarrow = - B \beta p_x - 2 B (\bar{\Phi}_{ew} - \bar{\Phi}_{se})$$

we

$$\beta(u_t + uu_x) + (D_x - 1)(\beta u^2)_x$$

$$= -B \left[\beta p_x + 2 \left\{ |u|u - (1-B\beta)^{1/2} |v-\varepsilon u|(v-\varepsilon u) \right\} \right]$$

initial values

(*) $1 - B\beta_0 = \alpha_0, \quad Uu_0 = \bar{u}_0, \quad Vv_0 = \bar{v}_0, \quad p_0 + p_{t_0} = \bar{p}_0$

(c) $D_x - 1 \ll 1, \quad B \ll 1, \quad \varepsilon \ll 1$

$$\Rightarrow u_t + uu_x \approx 0$$

$$vv_x = -p_x - 2|v|v$$

$$v_x = 0$$

$$p_t + (\beta u)_x = 0$$

$$x=0 \quad \beta = \beta_0, \quad v=1, \quad u=u_0 \quad \Rightarrow \quad v=1$$

$$(p_x = -2 \quad p = p_0 - 2x)$$

By inspection, or using characteristics, $u \equiv u_0 \quad \beta \equiv \beta_0$