

II. Linearised General Relativity

- 1) Einstein eqs with matter
- 2) Linearised gravity (weak grav. field)
- 3) Newtonian limit
- 4) Far field of isolated gravitational body
- 5) Gravitational waves

II.1. Einstein equations with matter

symmetric 2-covariant tensor field.

Continuum of matter described by stress-energy tensor T_{ab} . In flat space $\partial^a T_{ab} = 0$ expresses conservation laws (of energy, momentum, ...).
 ↗ (example sheet)

In curved spacetime $\Rightarrow \nabla^a T_{ab} = 0$.

Recall $G_{ab} := R_{ab} - \frac{1}{2} g_{ab} R$, Bianchi eq $\Rightarrow \nabla^a G_{ab} = 0$ (example sheet).

So Einstein tried

$$\underline{G_{ab} = \Lambda \cdot T_{ab}}, \quad \Lambda \text{ constant, to be determined by comparison with Newtonian theory.}$$

$$\begin{aligned} \text{From: } & \Lambda = 8\pi \quad \text{in geometrised units } G=c=1 \\ & \Lambda = \frac{8\pi G}{c^4} \quad \text{non-geometrised units} \end{aligned}$$

Example:

- a) Perfect fluid: Described by
- 4-velocity u , unit timelike vector field
 - \mathbf{g} mass-energy density in rest frame
 - p pressure in rest frame
 - equation of state $p = p(\mathbf{g})$
- } scalars

$$T_{ab} = (\mathbf{g} + p) u_a u_b + p g_{ab}$$

Choose orthonormal frame field e_0, \dots, e_3 with $e_0 = u$ (\Leftrightarrow rest frame), g_{ab} in M^4

$$\text{frame } \bar{T}_{ab} = \begin{pmatrix} \mathbf{g} & 0 \\ 0 & p \end{pmatrix}, \quad \text{i.e. interpretation of } \mathbf{g} \text{ & } p \text{ as given above.}$$

$$\nabla^a T_{ab} = 0 \quad \Leftrightarrow \quad \begin{cases} u^a \nabla_a \mathbf{g} + (\mathbf{g} + p) \nabla^a u_a = 0 \\ (p + \mathbf{g}) u^a \nabla_a u_b + (g_{ab} + u_a u_b) \nabla^a p = 0 \end{cases}$$

which, together with the equation of state, give the equations of motion for the fluid.

b) Dust : Perfect fluid with $\rho = 0$

$$\Rightarrow T_{ab} = \rho u_a u_b$$

c) Electromagnetic field : Faraday tensor F_{ab} , 2-form

$$T_{ab} = \frac{1}{4\pi} (F_{ac} F_{b}^c - \frac{1}{4} g_{ab} F_{de} F^{de})$$

$$\nabla^a T_{ab} = 0 \Leftrightarrow \begin{cases} dF = 0 \\ \nabla^a F_{ab} = 0 \end{cases} \quad (\text{example sheet})$$

(Remark: $\nabla^a T_{ab} = 0$ does not imply the Maxwell equations. see MTW, p 483)

Revisiting the Einstein equations

$$R_{ab} - \frac{1}{2} g_{ab} R = \lambda T_{ab} \quad \xrightarrow{\text{trace}} \quad R - 2R = \lambda T \quad \Rightarrow \quad R = -\lambda T$$

$$\text{EE are equivalent to } R_{ab} = \lambda (T_{ab} - \frac{1}{2} g_{ab} T)$$

In vacuum : $R_{ab} = 0$.

(Remark: The reason for revisiting the EE in this form is that the principal part of R_{ab} is not in harmonic gauge than that of G_{ab} . In linearized theory we thus obtain $R_{ab} \approx T_{ab}$, while $G_{ab} \approx \bar{G}_{ab}$, where $\bar{G}_{ab} = G_{ab} - \frac{1}{2} g_{ab} h$)

II.2 Linearizing the Einstein equations around Minkowski space

Start with Minkowski spacetime (\mathbb{R}^4, η) in inertial (Cartesian) coordinates x^μ . In the following, the Greek indices μ, ν, κ, \dots etc will not be abstract indices but always refer to the chosen coordinate system on \mathbb{R}^4 .

Looking for an approx. solution $(\mathbb{R}^4, g = \eta + \varepsilon h, T = \varepsilon T)$, h symmetric 2-cov. tensor field on \mathbb{R}^4 , ε small parameter, require that g satisfies the Einstein equations $R_{ab} = \lambda (T_{ab} - \frac{1}{2} g_{ab} T)$ to order ε . (Ignore higher orders of ε). \Rightarrow weak grav. field, small masses; linearized equations around η for h .) (Theory for sym. 2-cov. tensor field h on Minkowski spacetime)

Now: compute $R_{\mu\nu}(\eta + \varepsilon h)$ to order ε .

• Inverse of $g_{\mu\nu}$: Ansatz: $(\tilde{g}^{\mu\nu})^{\kappa\lambda} = \eta^{\nu\kappa} - \varepsilon s^{\nu\kappa}$, s symmetric 2-countervariant tensor

$$\text{Then } g_{\mu\nu}(\tilde{g}^{\mu\nu})^{\kappa\lambda} = (\eta_{\mu\nu} + \varepsilon h_{\mu\nu})(\eta^{\nu\kappa} - \varepsilon s^{\nu\kappa}) = \delta_\mu^\kappa - \varepsilon \eta_{\mu\nu} s^{\nu\kappa} + \varepsilon h_{\mu\nu} \eta^{\nu\kappa} + \mathcal{O}(\varepsilon^2)$$

$$\Rightarrow \eta_{\mu\nu} s^{\nu\kappa} = h_{\mu\nu} \eta^{\nu\kappa}$$

(24)

(Confusing: two metrics g & η , so not clear which need to raise indices)

Convention: Raise all indices with Minkowski metric $\eta_{\mu\nu}$, i.e. $h^{\mu\nu} = h_{\mu\nu} \eta^{\nu\kappa} \eta^{\mu\sigma}$

$$(\tilde{g}^\lambda)^{\nu\kappa} - \eta^{\nu\kappa} = \varepsilon h^{\nu\kappa} + \mathcal{O}(\varepsilon^2)$$

• Christoffel symbols: $T_{\nu\kappa}^M = \frac{1}{2} g^{\mu\sigma} (\partial_\nu g_{\mu\sigma} + \partial_\kappa g_{\nu\sigma} - \partial_\sigma g_{\nu\kappa})$

$$\stackrel{x^\mu \text{ are}}{\stackrel{\text{Cartesian}}{\stackrel{\text{coords.}}{\equiv}}} \varepsilon \frac{1}{2} \eta^{\mu\sigma} (\partial_\nu h_{\mu\sigma} + \partial_\kappa h_{\nu\sigma} - \partial_\sigma h_{\nu\kappa}) + \mathcal{O}(\varepsilon^2)$$

$$\bullet \underline{\text{Curvature:}} \quad R^M{}_{\kappa\mu\nu} = \partial_g T_{\nu\kappa}^M - \partial_\nu T_{\mu\kappa}^M + \underbrace{T_{\mu\sigma}^M T_{\nu\kappa}^\sigma}_{= \mathcal{O}(\varepsilon^2)} - T_{\nu\sigma}^M T_{\mu\kappa}^\sigma$$

$$= \varepsilon \frac{1}{2} \eta^{\mu\sigma} (\partial_g \partial_\nu h_{\mu\sigma} + \partial_g \partial_\kappa h_{\nu\sigma} - \partial_g \partial_\sigma h_{\nu\kappa})$$

$$- \varepsilon \frac{1}{2} \eta^{\mu\sigma} (\partial_\nu \partial_\kappa h_{\mu\sigma} + \partial_\nu \partial_\mu h_{\sigma\kappa} - \partial_\nu \partial_\sigma h_{\mu\kappa}) + \mathcal{O}(\varepsilon^2)$$

$$= \varepsilon \frac{1}{2} \eta^{\mu\sigma} (\partial_g \partial_\kappa h_{\nu\sigma} - \partial_g \partial_\sigma h_{\nu\kappa} - \partial_\nu \partial_\kappa h_{\mu\sigma} + \partial_\nu \partial_\sigma h_{\mu\kappa}) + \mathcal{O}(\varepsilon^2)$$

$$\bullet \underline{\text{Ricci curvature:}} \quad R_{\mu\nu} = R^M{}_{\mu\nu\kappa} = \varepsilon \frac{1}{2} (\partial_\kappa \partial_\mu h_{\nu\kappa} - \square h_{\mu\nu} - \partial_\nu \partial_\mu h + \partial_\nu \partial_\kappa h_{\mu\kappa}) + \mathcal{O}(\varepsilon^2)$$

$$\text{where } h = h_{\sigma\tau} \eta^{\sigma\tau} \quad (\text{trace}) \quad \text{and} \quad \square = \eta^{\mu\nu} \partial_\mu \partial_\nu \quad (\text{wave operator in Minkowski})$$

$$(\text{We now introduce } \bar{h}_{\mu\nu} = h_{\mu\nu} - \frac{1}{2} \eta_{\mu\nu} h)$$

$$\text{Compute } \underbrace{\partial_\kappa (\partial^\mu \bar{h}_{\mu\nu})}_T + \underbrace{\partial_\nu (\partial^\mu \bar{h}_{\mu\nu})}_T = \partial_\kappa \partial^\mu h_{\mu\nu} - \frac{1}{2} \partial_\kappa \partial_\nu h + \partial_\nu \partial^\mu h_{\mu\nu} - \frac{1}{2} \partial_\nu \partial_\kappa h$$

$$\stackrel{(1)}{=} \partial_\kappa \partial^\mu h_{\mu\nu} + \partial_\nu \partial^\mu h_{\mu\nu} - \partial_\kappa \partial_\nu h$$

$$\stackrel{(1)}{=} T_\nu \hookrightarrow T_\nu = \varepsilon \stackrel{(1)}{T}_\nu + \mathcal{O}(\varepsilon^2)$$

$$\text{Thus } R_{\mu\nu} (\eta + \varepsilon h) = \frac{1}{2} \varepsilon \left(-\square h_{\mu\nu} + \partial_\kappa (\partial^\mu \bar{h}_{\mu\nu}) + \partial_\nu (\partial^\mu \bar{h}_{\mu\nu}) \right) + \mathcal{O}(\varepsilon^2)$$

$$\text{Field equations } R_{ab} = \lambda (T_{ab} - \frac{1}{2} g_{ab} T) \quad \text{to order } \varepsilon \quad \text{are}$$

$$\frac{1}{2} (-\square h_{\mu\nu} + \partial_\kappa \partial^\mu \bar{h}_{\mu\nu} + \partial_\nu \partial^\mu \bar{h}_{\mu\nu}) = \lambda \left(\stackrel{(1)}{T}_{\mu\nu} - \frac{1}{2} \eta_{\mu\nu} \stackrel{(1)}{T} \right) \quad (*)$$

One can simplify these equations by choosing a suitable gauge.

Recall: ϕ diffeomorphism, g solution of $R_{\mu\nu}(g) = \lambda(T_{\mu\nu} - \frac{1}{2}g_{\mu\nu}T)$

then ϕ^*g solution of $R_{\mu\nu}(\phi^*g) = \phi^*R_{\mu\nu}(g) = \lambda(\phi^*T_{\mu\nu} - \frac{1}{2}\phi^*_g\phi^*T)$

\Rightarrow solutions (g, T) and (ϕ^*g, ϕ^*T) are physically equivalent.

Now, let $\zeta \in \mathcal{X}^1(M)$ vector field and let ϕ_t denote the 1-parameter group of diffeomorphisms it generates.

$$\text{Then } (\phi_\varepsilon^*g)_{\mu\nu} = (\phi_\varepsilon^*g)_{\mu\nu} + \varepsilon(\phi_\varepsilon^*h)_{\mu\nu} = g_{\mu\nu} + \varepsilon \left. \frac{d}{dt} \right|_{t=0} (\phi_t^*g)_{\mu\nu} + \mathcal{O}(\varepsilon^2) + \varepsilon h_{\mu\nu} + \mathcal{O}(\varepsilon^2)$$

$$= g_{\mu\nu} + \varepsilon(h_{\mu\nu} + (\mathcal{L}_\zeta g)_{\mu\nu}) + \mathcal{O}(\varepsilon^2)$$

$$(\phi_\varepsilon^*T)_{\mu\nu} = (\phi_\varepsilon^*\varepsilon \overset{(n)}{\tilde{T}}_{\mu\nu}) = \varepsilon \overset{(n)}{\tilde{T}}_{\mu\nu} + \mathcal{O}(\varepsilon^2)$$

L gauge invariant at linear level.

Thus if $(\underbrace{g_{\mu\nu} + \varepsilon h_{\mu\nu}}_{= \tilde{g}_{\mu\nu}}, \varepsilon \overset{(n)}{\tilde{T}}_{\mu\nu})$ satisfy the Einstein equations $R_{\mu\nu} = \lambda(T_{\mu\nu} - \frac{1}{2}g_{\mu\nu}T)$

to order ε , then so does $(\underbrace{g_{\mu\nu} + \varepsilon(h_{\mu\nu} + (\mathcal{L}_\zeta g)_{\mu\nu})}_{= \tilde{g}_{\mu\nu}}, \varepsilon \overset{(n)}{\tilde{T}}_{\mu\nu})$ for any $\zeta \in \mathcal{X}^1(M)$

and one considers them as physically equivalent.

Often called "infinitesimal diffeomorphism"

\Rightarrow If $h_{\mu\nu}$ satisfies (*) then so does $\tilde{h}_{\mu\nu} := h_{\mu\nu} + (\mathcal{L}_\zeta g)_{\mu\nu} = h_{\mu\nu} + \partial_\mu s_\nu + \partial_\nu s_\mu$.

Choose gauge ζ by solving $\square s_\mu = -\partial^\nu \tilde{h}_{\mu\nu}$ (called wave gauge) || Just wave eq. with RHS in Minkowski, easily solvable, freedom of prescribing I.D. at $t=0$.

This determines ζ up to addition of solutions of

homogeneous wave equation $\square s_\mu = 0 \Rightarrow$ residual gauge freedom.

$$\begin{aligned} \text{Then } \partial^M \tilde{h}_{\mu\nu} &= \partial^M (\tilde{h}_{\mu\nu} - \frac{1}{2}g_{\mu\nu}\tilde{h}) = \partial^M (h_{\mu\nu} + \partial_\mu s_\nu + \partial_\nu s_\mu) - \frac{1}{2}\partial_\nu (\tilde{h} + 2\partial^M s_\mu) \\ &= \partial^M h_{\mu\nu} + \square s_\nu + \partial_\nu \partial^M s_\mu - \frac{1}{2}\partial_\nu h - \partial_\nu \partial^M s_\mu \\ &= \partial^M \tilde{h}_{\mu\nu} + \square s_\nu \\ &= 0 \end{aligned}$$

Thus $\tilde{h}_{\mu\nu}$ satisfies

$$\square \tilde{h}_{\mu\nu} = -2\lambda \left(\overset{(n)}{\tilde{T}}_{\mu\nu} - \frac{1}{2}g_{\mu\nu} \overset{(n)}{\tilde{T}} \right)$$

$$\underline{\underline{\partial^M \tilde{h}_{\mu\nu} = 0}}$$

Linearized Einstein equations
in wave gauge.
(LEW(5))

Remark (alternative formulation): (for quadrupole formula)

Sometimes convenient to rephrase first eq. also in terms of $\tilde{h}_{\mu\nu} = \hat{h}_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \hat{h}$

$$\Rightarrow \left. \begin{array}{l} \square \tilde{h}_{\mu\nu} = -2\lambda \overset{(as)}{\tilde{T}}_{\mu\nu} \\ \partial^\mu \tilde{h}_{\mu\nu} = 0 \end{array} \right\} \text{LEWh for } \tilde{h}_{\mu\nu}$$

Note that $\tilde{\tilde{h}}_{\mu\nu} = \overset{(as)}{h}_{\mu\nu}$.

Remark (why is it called wave gauge?):

$$(M, g) \text{ Lorentzian mfd} : \quad \square_g \psi := g^{st} \nabla_s \nabla_t \psi \quad \text{wave operator on } (M, g)$$

$$\Rightarrow \square = \square_{\eta} \quad \text{on } (\mathbb{R}^4, \eta)$$

Let x^M be coord. function on M , then $\square_g x^M = -g^{st} \nabla_s^M \nabla_t^M =: -T^M$

$$\text{Also } T_\nu := g_{\nu\mu} T^\mu.$$

Set of coords x^M satisfy wave eq. $\Leftrightarrow T_\nu = 0 \quad \forall \nu$.

In linearised gravity, Cartesian coords x^M satisfy $\square_g x^M = 0 + \mathcal{O}(\epsilon^2)$ (wave eq. to first order)

$$\text{iff } \mathcal{O}(\epsilon^1) T_\nu = g_{\nu\mu} g^{st} \nabla_s^M \nabla_t^M = 2\epsilon_{\mu\nu}^{\lambda} \epsilon_2^1 \eta^{st} (\partial_s \tilde{h}_{t\lambda} + \partial_\lambda \tilde{h}_{st} - \partial_t \tilde{h}_{s\lambda}) + \mathcal{O}(\epsilon^2)$$

$$= \epsilon_2^1 (\partial_s \tilde{h}_{t\lambda} + \partial_t \tilde{h}_{s\lambda} - \partial_\lambda \tilde{h}) + \mathcal{O}(\epsilon^2)$$

$$= \epsilon \partial^\lambda (\tilde{h}_{\nu\lambda} - \frac{1}{2} \eta_{\lambda\nu} \tilde{h}) + \mathcal{O}(\epsilon^2)$$

$$= \epsilon \partial^\lambda \tilde{h}_{\nu\lambda} + \mathcal{O}(\epsilon^2)$$

$$\text{i.e. iff } \partial^\lambda \tilde{h}_{\nu\lambda} = 0.$$

\tilde{F}_ν in $\tilde{h}_{\mu\nu}$ stands for "wave gauge" ...

Remark (analogy with gauge freedom in Maxwell's equations)

$$\text{Maxwell's equation in Minkowski} : \quad d\tilde{F} = 0 \quad \& \quad \partial^M \tilde{F}_{\mu\nu} = 4\pi \underset{\substack{\uparrow \\ \text{source}}}{J_\nu} \quad (\text{MTW convention})$$

$$\tilde{F} = dA \quad \text{A one-form, the electromagnetic potential.}$$

Then, $d\tilde{F} = ddA = 0$ is trivially satisfied and $\partial^M \tilde{F}_{\mu\nu} = \partial^M \partial_\mu A_\nu - \partial^M \partial_\nu A_\mu = J_\nu \Rightarrow \partial_\nu A_\mu - \partial_\mu A_\nu = \tilde{J}_\nu$ is second eq.

If A solves $\partial^M \tilde{F}_{\mu\nu} = 4\pi \tilde{J}_\nu$ with $\tilde{F} = dA$, and $x \in C^\infty(\mathbb{R}^4)$, then so does $\tilde{A} = A + dx$

(since $\tilde{F} = d\tilde{A} = dA + \underbrace{dx}_{=0} = F$). Here, addition of dx to A represents gauge freedom.

Fixing gauge: E.g. choose Lorentz gauge $\partial^M \tilde{A}_\mu = 0$. This can be arranged by

$$\text{solving } \square x = -\partial^M \tilde{A}_\mu.$$

$$\text{Since then } \partial^M \tilde{A}_\mu = \partial^M (A_\mu + \partial_\mu x) = \partial^M A_\mu + \partial x = 0.$$

In this gauge, second equation simplifies to $\square \tilde{A}_\nu = 4\pi \tilde{J}_\nu$. (inhomogeneous wave eq.)
 \Rightarrow residual gauge freedom $\tilde{A}_\mu = \tilde{A}_\mu + dy$ with $\square y = 0$.

Remark (Spin 2 particle)

Equations (LEW6) with $T \equiv 0$ describe a massless spin-2 field on Minkowski

Spacetime.

\Rightarrow "graviton"

Meaning only in linear approx. around Minkowski spacetime.

II.3 Newtonian limit:

Can we neglect the term $\tilde{T}_{\mu\nu} = \rho u_\mu u_\nu + p g_{\mu\nu}$?

Newtonian theory well verified if

i) gravity is weak \rightarrow Linearized theory

$$\text{Consider a perfect fluid } \stackrel{(a)}{\tilde{T}_{\mu\nu}} = (\bar{g} + p) u_\mu u_\nu + p g_{\mu\nu}$$

ii) relative motion of sources much slower than the speed of light $c=1$

$$\Rightarrow u^i \approx \partial_i$$

iii) material stresses much smaller than mass-energy density

$$\Rightarrow p \approx 0$$

$$\Rightarrow \stackrel{(a)}{\tilde{T}_{\mu\nu}} \approx g dt \otimes dt \quad (\text{pressureless dust at rest})$$

Since sources are slowly varying, also expect spacetime geometry to vary slowly

$$\Rightarrow \partial_t \tilde{h}_{\mu\nu}, \partial_t^2 \tilde{h}_{\mu\nu} \approx 0$$

$$(\text{LEWNG}) \Rightarrow \begin{cases} \Delta \tilde{h}_{00} = -2\lambda (g - \frac{1}{2}\dot{g}) = -\lambda g & (\text{use } \stackrel{(a)}{\tilde{T}} = -g) \\ \Delta \tilde{h}_{0i} = 0 & \text{for } i=1,2,3 \\ \Delta \tilde{h}_{ij} = -2\lambda (0 + \frac{1}{2}\dot{g}g_{ij}) = -\eta_{ij}\lambda g & \text{for } ij=1,2,3 \end{cases}$$

Unique solution of $\Delta \tilde{h}_{\mu\nu} = 0$ s.t. $\tilde{h}_{\mu\nu} \rightarrow 0$ for $r \rightarrow \infty$ is $\tilde{h}_{\mu\nu} \equiv 0$.

$$\Rightarrow \partial^M \tilde{h}_{\mu\nu} = 0 \quad \text{satisfied.} \quad \left(\begin{array}{l} \Delta \tilde{h}_{\mu\nu} = 0 \quad \text{for } (\mu\nu) \neq (0,0) \quad \Rightarrow \tilde{h}_{\mu\nu} = 0 \\ \Delta \tilde{h}_{00} = -2\lambda g \end{array} \right)$$

\Rightarrow whole content of gravity encoded in one scalar function $\tilde{h}_{00} = \tilde{h}_{ii}$ ($i=1,2,3$), which satisfies $\Delta \tilde{h}_{00} = -\lambda g$

Action on test body \rightarrow geodesic equation $\frac{d^2 x^\mu}{dr^2} + \tilde{T}^\mu_{\sigma\nu} \frac{dx^\sigma}{dr} \frac{dx^\nu}{dr} = 0$.

Non-relativistic motion $\left| \frac{dx^i}{dr} \right| \ll \frac{dt}{dr} \approx 1$, $\Rightarrow t \approx r$. $i=1,2,3$

Hence leading order contribution $\frac{d^2 x^i}{dt^2} \approx \frac{d^2 x^i}{dr^2} \approx -\tilde{T}^i_{00}(x^r(t))$

Also $T^{i0}_{00} = \frac{1}{2} \gamma^{i0} (2\partial_0 \tilde{h}_{00} - \partial_0 \tilde{h}_{00}) = -\frac{1}{2} \partial_0 \tilde{h}_{00}$ no only \tilde{h}_{00} enters.

$$\Rightarrow \frac{d^2 x^i}{dt^2} \approx \frac{1}{2} \partial_0 \tilde{h}_{00}$$

if we hadn't assumed that \tilde{h}_{0i} negligible, would get contribution here.
see next

Compare with Newtonian theory:

$$\left\{ \begin{array}{l} \Delta \phi = 4\pi g \\ \vec{F} = -\vec{\nabla} \phi \end{array} \right. \quad \text{Poisson's equation } (G=1) \quad \sim \quad \frac{d^2 x^i}{dt^2} = -\partial_i \phi$$

(Compare with (1)) $\Rightarrow \phi = -\frac{1}{2} \tilde{h}_{00}$

(Compare with (2)) $-\lambda g = \Delta \tilde{h}_{00} = -2 \Delta \phi \Rightarrow \lambda = 8\pi$

Thus Einstein field equations $G_{ab} = 8\pi \tilde{T}_{ab}$

(Perhaps remark on geodesic hypothesis coming from 2nd order approximation
(aspects of higher orders as well ~ Wald, p. 78)

In Newtonian theory space & time
a priori given by coords.
Einstein: have to determine light and
time gravitationally
Can identify Minkowski space $\mathbb{R} \times \mathbb{R}^3$
(Newton's limit mass)
Now introduce small areas, in
harmonic coords., computation
of orbits etc. (grav. exp.) reduce
to Newtonian computations.
Moreover, the "heat" coords are
Laplace, m/s², with θ four grav. fields
 $(= O(\epsilon^2))$, so we are "close".

II.4 Far field of isolated gravitational body in linear approximation

Recall: Linearized Einstein equations in wave gauge:

$$(1) \quad \square \tilde{h}_{\mu\nu} = -16\pi \left(\overset{(a)}{T}_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \overset{(a)}{T} \right) =: -16\pi \overset{(a)}{\tilde{T}}_{\mu\nu}$$

$$\partial^\mu \tilde{h}_{\mu\nu} = 0 \quad , \quad \overset{(a)}{\tilde{h}}_{\mu\nu} := \tilde{h}_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \tilde{h}$$

Here, looking for solution with $\partial^\mu \overset{(a)}{T}_{\mu\nu} = 0$ (of course!)

- $\overset{(a)}{T}_{\mu\nu}(+, \cdot)$ compact support in \mathbb{R}^3 for all $t > 0$ (isolated gravitational body)
- $\partial_t \overset{(a)}{T}_{\mu\nu} = 0 = \partial_t \tilde{h}_{\mu\nu}$ (time independent (stationary \Leftrightarrow KVF) solution)
- $\Rightarrow (1)$ becomes $\Delta \tilde{h}_{\mu\nu} = -16\pi \overset{(a)}{\tilde{T}}_{\mu\nu}$ where $\Delta = \eta^{ij} \partial_i \partial_j$ indices running from 1 to 3

Interested in the asymptotics $\tilde{h}_{\mu\nu}(x)$ for $|x| \rightarrow \infty$, $x = (x^1, x^2, x^3) \in \mathbb{R}^3$

Recall: Poisson's equation $\Delta \phi = f$ in \mathbb{R}^3 , then $\phi(x) = - \int_{\mathbb{R}^3} \frac{f(x')}{4\pi|x-x'|} dx'$

Thus $\tilde{h}_{\mu\nu}(x) = 4 \int_{\mathbb{R}^3} \frac{\overset{(a)}{\tilde{T}}_{\mu\nu}(x')}{|x-x'|} dx'$

Cliché wave gauge is satisfied: $\tilde{h}_{\mu\nu}(x) = 4 \int_{\mathbb{R}^3} \frac{1}{|x-x'|} \left(\overset{(a)}{\tilde{T}}_{\mu\nu}(x') - \frac{1}{2} g_{\mu\nu} \overset{(a)}{\tilde{T}}(x') \right) dx' = 4 \int_{\mathbb{R}^3} \frac{1}{|x-x'|} \overset{(a)}{\tilde{T}}_{\mu\nu}(x') dx'$

(Formally) Thus $\partial^\mu \tilde{h}_{\mu\nu}(x) = 4 \int_{\mathbb{R}^3} \left(\frac{1}{|x-x'|} \overset{(a)}{\tilde{T}}_{\mu\nu}(x') dx' \right) = -4 \int_{\mathbb{R}^3} \partial_x^\mu \left(\frac{1}{|x-x'|} \right) \overset{(a)}{\tilde{T}}_{\mu\nu}(x') dx' = 4 \int_{\mathbb{R}^3} \frac{1}{|x-x'|} \partial_x^\mu \overset{(a)}{\tilde{T}}_{\mu\nu}(x') dx' = 0$

Now: Asymptotics \sim expand $\tilde{h}_{\mu\nu}(x)$ in powers of $\frac{1}{r}$.

Use following identities (2nd problem sheet, problem 7)

- 1) $\frac{1}{|\underline{x} - \underline{x}'|} = \frac{1}{r} + \frac{1}{r^3} \underline{x} \cdot \underline{x}' + \mathcal{O}\left(\frac{1}{r^3}\right)$ as a function of \underline{x} , uniformly for bounded \underline{x}' .
- 2) $\int_{\mathbb{R}^3} T^{ij}(1, \underline{x}) d\underline{x}' = 0$
- 3) $\int_{\mathbb{R}^3} T_{0j}^{ij} d\underline{x}' = 0$
- 4) $\int_{\mathbb{R}^3} T_{;i}^{ij}(1, \underline{x}) d\underline{x}' = 0$
- 5) $\int_{\mathbb{R}^3} (T^{0j}_{x^k} + T^{0k}_{x^j})(1, \underline{x}) d\underline{x}' = 0$
- 6) $\int_{\mathbb{R}^3} T_{;i}^{ij}(1, \underline{x}) x^j d\underline{x}' = 0$

$$\bullet \quad \tilde{h}_{00}(\underline{x}) : \quad \overset{(1)}{\hat{T}}_{00} = \overset{(1)}{T}_{00} + \frac{1}{2} \overset{(1)}{\bar{T}} = \overset{(1)}{T}_{00} + \frac{1}{2} \left(-\overset{(1)}{T}_{00} + \overset{(1)}{\bar{T}}_i \right) = \frac{1}{2} \left(\overset{(1)}{T}_{00} + \overset{(1)}{\bar{T}}_i \right)$$

thus

$$\begin{aligned} \tilde{h}_{00}(\underline{x}) &= 4 \int_{\mathbb{R}^3} \left(1 + \frac{\underline{x} \cdot \underline{x}'}{r^2} + \mathcal{O}\left(\frac{1}{r^2}\right) \right) \frac{1}{2} \left(\overset{(1)}{T}_{00} + \overset{(1)}{\bar{T}}_i \right) (\underline{x}') d\underline{x}' \\ &= \frac{2M}{r} \int_{\mathbb{R}^3} \left(\overset{(1)}{T}_{00} + \overset{(1)}{\bar{T}}_i + \frac{\underline{x}_j(\underline{x}')}{r^2} \left(\overset{(1)}{T}_{00}(\underline{x}') + \overset{(1)}{\bar{T}}_i(\underline{x}') \right) + \mathcal{O}\left(\frac{1}{r^2}\right) \right) d\underline{x}' \\ &= \frac{2M}{r} + \mathcal{O}\left(\frac{1}{r^3}\right) \end{aligned}$$

where $M := \int_{\mathbb{R}^3} \overset{(1)}{T}_{00}(\underline{x}') d\underline{x}'$ total mass

and we have used $(*) \quad \int_{\mathbb{R}^3} (\underline{x}')^j \overset{(1)}{T}_{00}(\underline{x}') d\underline{x}' = 0$ by closing ...

the Cartesian coords. s.t. the origin is the centre of mass, i.e. exactly the above is true.

$$\bullet \quad \tilde{h}_{0i}(\underline{x}) : \quad \overset{(1)}{\hat{T}}_{0i} = \overset{(1)}{T}_{0i}$$

thus $\tilde{h}_{0i}(\underline{x}) = 4 \int_{\mathbb{R}^3} \left(1 + \frac{\underline{x} \cdot \underline{x}'}{r^2} + \mathcal{O}\left(\frac{1}{r^2}\right) \right) \overset{(1)}{T}_{0i}(\underline{x}') d\underline{x}'$

$$\text{use (3)} \Rightarrow = \frac{4}{r^3} \underline{x}^i \int_{\mathbb{R}^3} (\underline{x}_j^i) \overset{(1)}{T}_{0i}(\underline{x}') d\underline{x}' + \mathcal{O}\left(\frac{1}{r^3}\right)$$

$$\begin{aligned} \overset{(1)}{T}_{0i} \underline{x}_j^i &= \overset{(1)}{T}_{00} \underline{x}_{0j}^i + \overset{(1)}{T}_{0i} \underline{x}_{jj}^i \\ &\stackrel{=0}{\underset{\text{by 5)}}{=} \frac{4}{r^3} \underline{x}^i \int_{\mathbb{R}^3} \overset{(1)}{T}_{0i} \underline{x}_{jj}^i d\underline{x}' + \mathcal{O}\left(\frac{1}{r^3}\right) \end{aligned}$$

Now use $J_k = \int_{\mathbb{R}^3} \epsilon_{emk}(x')^{(1)} T^{0m}(x') dx'$ total angular momentum around x^k axis.

$$\therefore \tilde{\epsilon}_{ijk} J^k = \int_{\mathbb{R}^3} [(x')^i T^{0j}(x') - (x')^j T^{0i}(x')] dx' = 2 \int_{\mathbb{R}^3} T_0^{ij} x'_{ij} dx' \quad (\text{minus sign from lowering index})$$

$$\therefore \tilde{h}_{0i}(x) = \frac{2}{r^3} \tilde{\epsilon}_{ijk} x^j J^k + O(\frac{1}{r^3}) \left(\frac{2}{r^3} (\vec{x} \times \vec{J})_i + O(\frac{1}{r^3}) \right)$$

↑
cross-product in \mathbb{R}^3

$$\therefore \tilde{h}_{ij}(x) : \frac{\tilde{T}^{ij}}{T_{ij}} = \frac{(1)}{T_{ij}} - \frac{1}{2} m_{ij} \left(-\frac{(1)}{T_{00}} + \frac{(1)}{T_{kk}} \right)$$

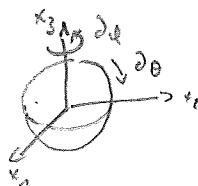
Thus

$$\begin{aligned} \tilde{h}_{ij}(x) &= 4 \int_{\mathbb{R}^3} \left(\frac{1}{r} \left(1 + O(\frac{1}{r}) \right) \right) \left(\frac{(1)}{T_{ij}} - \frac{1}{2} m_{ij} \left(-\frac{(1)}{T_{00}} + \frac{(1)}{T_{kk}} \right) \right) (x')^i dx' \\ &= \frac{4}{r} \int_{\mathbb{R}^3} \left[\frac{(1)}{T_{ij}} + \frac{1}{2} m_{ij} \left(\frac{(1)}{T_{00}} - \frac{(1)}{T_{kk}} \right) (x')^i + O(\frac{1}{r^2}) \right] (dx') \\ &= \frac{2}{r} M m_{ij} + O(\frac{1}{r^2}) \end{aligned}$$

Thus obtain the asymptotic form of metric

$$\boxed{\begin{aligned} g &\approx (g_{\mu\nu} + \varepsilon \tilde{h}_{\mu\nu}) dx^\mu \otimes dx^\nu \\ &= -\left(1 - \frac{2EM}{r} + O(\frac{1}{r^2})\right) dt^2 + \left(\frac{2}{r^3} \tilde{\epsilon}_{ijk} x^j \varepsilon J^k + O(\frac{1}{r^3})\right) (dt \otimes dx^i + dx^i \otimes dt) \\ &\quad + \left(\left(1 + \frac{2EM}{r}\right) m_{ij} + O(\frac{1}{r^2})\right) dx^i \otimes dx^j \end{aligned}}$$

Wlog can assume that $\vec{J} = J \hat{x}_3$ (rotate coordinate system) and introduce (r, θ, ϕ)
Spherical polar coords (r, θ, ϕ)



$$\text{Then } \tilde{\epsilon}_{ijk} x^j J^k dx^i = J(x^2 dx^1 - x^1 dx^2) = -J r^2 \sin^2 \theta d\phi$$

$$\begin{aligned} x^1 &= r \cos \theta \sin \phi \\ x^2 &= r \sin \theta \sin \phi \\ x^3 &= r \cos \theta \end{aligned} \quad \Rightarrow \quad \begin{aligned} x^1 dx^1 &= r^2 \cos \theta \sin \theta \sin^2 \phi d\theta \\ x^2 dx^2 &= r^2 \sin^2 \theta \sin \theta \sin^2 \phi d\theta \\ x^3 dx^3 &= -r^2 \cos \theta \sin \theta \sin^2 \phi d\theta \\ &= -r^2 \sin^2 \theta d\phi \end{aligned}$$

and thus

$$g \approx -\left(1 - \frac{2\varepsilon M}{r} + \mathcal{O}\left(\frac{1}{r^3}\right)\right) dt^2 - \frac{2}{r} \varepsilon J \sin^2\theta (dt \otimes d\varphi + d\varphi \otimes dt) + \mathcal{O}\left(\frac{1}{r^3}\right)(dt \otimes dx^i + dx^i \otimes dt) \\ + \left(1 + \frac{2\varepsilon M}{r}\right) \left(dt^2 + r^2(d\theta^2 + \sin^2\theta d\varphi^2)\right) + \mathcal{O}\left(\frac{1}{r^3}\right)(dx^i \otimes dx^j + dx^j \otimes dx^i)$$

εM total mass of body, εJ total angular momentum of body.

Remark: - Compare with last section on Newtonian limit, $\phi = -\frac{1}{2}\tilde{h}_{00} = -\frac{1}{2}\tilde{h}_{ii} = -\frac{\varepsilon M}{r}$ → Newtonian grav. potential of body with mass εM .

- In contrast to last section we allowed relative motion of sources to be comparable to the speed of light ($T_{0i} \neq 0$), which gives us the \tilde{h}_{0i} terms (problem: effect on (allows rotations, comparable with disturbance/distribution of mass-energy, geodesic motion? of sources, of momentum does not change) → is it static? When is it static?)
- We allowed material stresses to be comparable to mass energy density ($T_{ij} \neq 0$) .
- We restricted to M for field.
- The same asymptotic form of the metric can be derived for a stationary strongly gravitating isolated body in the fully nonlinear theory.
↳ Now, it doesn't in general hold anymore that $\int_{\mathbb{R}^3} T_{00} d^3x = \varepsilon M$ and $\varepsilon J_k = \int_{\mathbb{R}^3} \varepsilon \epsilon_{ijk} (\mathbf{x}) T^{0i} (\mathbf{x}) dx^i$ but still define the parameters εM & εJ appearing in the asymptotic form of the metric above to be mass & angular momentum of the spacetime. (another approach of defining M & J by Bronwt, Deser, Helder using Hamiltonian formulation of GR)

↳ M can be measured by looking at trajectory of test particles:

$$\text{As in Newtonian limit but } \frac{d\mathbf{v}}{dt} \approx \frac{1}{2} \partial_i \tilde{h}_{00} = \partial_i \left(\frac{\varepsilon M}{r} \right) + \mathcal{O}\left(\frac{1}{r^3}\right)$$

For large r Newton's laws are still valid and can measure M e.g. from

$$\text{Kepler's third law } M \approx \omega^2 a^3 \quad \begin{matrix} \uparrow \\ \text{orbital period} \end{matrix} \quad \begin{matrix} \rightarrow \\ \text{semi-major axis of elliptic orbit.} \end{matrix}$$

no good "definition" of M .

↳ Can measure J from precession of gyroscope, see MTW p. 451

Example:

Example: Schwarzschild $g = -\left(1 - \frac{2M}{r}\right)dt^2 + \frac{1}{1-\frac{2M}{r}}dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2)$

To bring into above form, find $g(r)$ new coordinate s.t.

$$g = -A(g)^2 dt^2 + B(g)^2 [dr^2 + g^2(d\theta^2 + \sin^2\theta d\phi^2)]$$

\downarrow

with $x = g \sin\theta \cos\phi$

$$\Rightarrow B(g)^2 g^2 = r^2 \quad \& \quad B(g)^2 dg^2 = \frac{1}{1-\frac{2M}{r}} dr^2 \quad \& \quad A(g)^2 = 1 - \frac{2M}{r}$$

$$\begin{aligned} \left(\frac{dg}{dr}\right)^2 &= \frac{1}{(1-\frac{2M}{r})B(g)^2} = \frac{r^2}{(1-\frac{2M}{r})} \\ \Rightarrow \frac{dg}{dr} &= \pm \frac{r}{(1-\frac{2M}{r})^{1/2}} \quad \Rightarrow \log g = \pm \int \frac{1}{r(1-\frac{2M}{r})^{1/2}} dr \end{aligned}$$

We use $\int \frac{dy}{\sqrt{y^2-a^2}} = \ln(y + \sqrt{y^2-a^2}) + \text{const}$ (check or derive with trigonometric substitution)

$$\Rightarrow \log g = \pm \int \frac{1}{\sqrt{r^2-2Mr}} dr = \pm \int \frac{1}{\sqrt{(r-M)^2-M^2}} dr$$

$$= \pm \log \left(r - M + \sqrt{(r-M)^2 - M^2} \right) + \text{const}$$

$$= \pm \log \left(r - M + r(1 - \frac{2M}{r})^{1/2} \right) + \text{const}$$

Use '+' sign s.t. $g \rightarrow +\infty$ for $r \rightarrow +\infty$

Then $\underline{g = C \left(r - M + r(1 - \frac{2M}{r})^{1/2} \right)}$ $C > 0$ constant

Solve for $r(g)$: $g - C(r-M) = rC(1 - \frac{2M}{r})^{1/2}$

(to get $B(g)^2 = \frac{r^2}{g^2}$) $\Rightarrow (g + CM - Cr)^2 = r^2 C^2 (1 - \frac{2M}{r})$

$$\Leftrightarrow (g + CM)^2 - 2(g + CM)Cr + C^2 r^2 = r^2 C^2 - 2MrC^2$$

$$\Leftrightarrow (g + CM)^2 - 2gCr = 0$$

$$\Rightarrow r = \frac{(g + CM)^2}{2gC} = \frac{g}{2C} \left(1 + \frac{CM}{g} \right)^2$$

This gives $B(g)^2 = \frac{r^2}{g^2} = \frac{1}{4C^2} \left(1 + \frac{CM}{g} \right)^4$

Choose $C = \frac{1}{2}$ s.t. $B(g) \rightarrow 1$ for $g \rightarrow +\infty$

(32 additional) i.e. g is of the previous form to leading order.

$$\Rightarrow r = s \left(1 + \frac{M}{2s}\right)^2 \quad \text{and} \quad \underline{B(g)^2 = \left(1 + \frac{M}{2s}\right)^4}$$

$$\begin{aligned} & \text{& } A(g)^2 = \underline{1 - \frac{2M}{r}} = 1 - \frac{2M}{s\left(1 + \frac{M}{2s}\right)^2} = \frac{s\left(1 + \frac{M}{2s}\right)^2 - 2M}{s\left(1 + \frac{M}{2s}\right)^2} \\ & = \frac{s + M + \frac{M^2}{4s} - 2M}{s\left(1 + \frac{M}{2s}\right)^2} = \frac{s - M + \frac{M^2}{4s}}{s\left(1 + \frac{M}{2s}\right)^2} = \frac{\left(1 - \frac{M}{2s}\right)^2}{\left(1 + \frac{M}{2s}\right)^2} \end{aligned}$$

$$\Rightarrow g = - \frac{\left(1 - \frac{M}{2s}\right)^2}{\left(1 + \frac{M}{2s}\right)^2} dt^2 + \underbrace{\left(1 + \frac{M}{2s}\right)^4 \left(dx^2 + g^2 (d\phi^2 + \sin^2 \phi d\psi^2) \right)}_{= dx^2 + dy^2 + dz^2}$$

$(+, s, \theta, \psi)$ called isotropic coordinates for Schwarzschild.

$$\text{Taylor expanding in } \frac{1}{s} \text{ gives} \quad \left(1 - \frac{M}{2s}\right)^2 = 1 - \frac{M}{s} + \dots$$

$$\frac{1}{\left(1 + \frac{M}{2s}\right)^2} = 1 - \frac{M}{s} + \dots$$

$$\left| \left(\frac{1}{1 + \frac{M}{2s}} \right) \right|_{s=0}^1 = \frac{2 \cdot M}{1} = M$$

$$\Rightarrow g = - \left(1 - \frac{2M}{s} + \mathcal{O}\left(\frac{1}{s^2}\right)\right) dt^2 + \left(1 + \frac{2M}{s} + \mathcal{O}\left(\frac{1}{s^2}\right)\right) [dx^2 + dy^2 + dz^2]$$

Compared thus M indeed the total mass and $\vec{J} = 0$.

II.5 Gravitational waves

Now vacuum $T_{\mu\nu} = 0$.

Recall linearized Einstein equations in wave gauge in vacuum

$$\left\{ \begin{array}{l} \square \tilde{h}_{\mu\nu} = 0 \\ \partial^M \tilde{h}_{\mu\nu} = 0 \end{array} \right.$$

Recall we have residual gauge freedom of choosing linearized diffeomorphism γ_μ that satisfies $\square \gamma_\mu = 0$,

then can go over to $\hat{h}_{\mu\nu} := \tilde{h}_{\mu\nu} + \partial_\mu \gamma_\nu + \partial_\nu \gamma_\mu$ which is physically equivalent to $\tilde{h}_{\mu\nu}$ and still in wave gauge $\square \hat{h}_{\mu\nu} = 0$.

Show: Can choose γ (depending on $\tilde{h}_{\mu\nu}$) s.t. $\hat{h}_{\mu\nu} = 0 = \hat{h}$, $\mu = 0, 1, 2, 3$.
 [This requires $T_{\mu\nu} = 0$!]

Idea illustrated by Maxwell's equations:

Maxwell's eq. in Lorentz gauge

$$\left\{ \begin{array}{l} \square \tilde{A}_\mu = 0 \\ \partial^M \tilde{A}_\mu = 0 \end{array} \right.$$

and recall residual gauge freedom $\hat{A}_\mu = \tilde{A}_\mu + \partial_\mu \gamma$ with $\square \gamma = 0$
 (since then $\partial^\mu \hat{A}_\mu = \partial^\mu \tilde{A}_\mu + \square \gamma = 0$.)

Can use this freedom to set $\hat{A}_0 = 0$ (Coulomb or radiation gauge):

On $\{t=0\}$ solve Poisson's eq. $\Delta \gamma_0|_{t=0} = -\partial^i \tilde{A}_i|_{t=0}$ ($= -\text{div}(\tilde{A}_1^1 \partial_1 + \tilde{A}_2^2 \partial_2 + \tilde{A}_3^3 \partial_3)$)

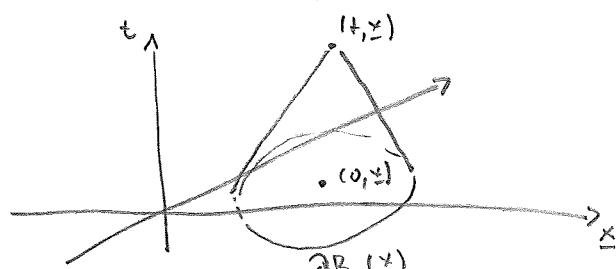
Then γ ... \Rightarrow get solution γ_0

Then solve wave equation $\square \gamma = 0$ with initial data $\left\{ \begin{array}{l} \gamma|_{t=0} = \gamma_0 \\ \partial_t \gamma|_{t=0} = \gamma_1 = -\tilde{A}_0 \end{array} \right.$

There exists a unique such solution. Indeed, it is given by Kirchhoff's formula \Rightarrow

$$\gamma(t, \mathbf{x}) = \frac{1}{4\pi t^2} \int_{\partial B_t(\mathbf{x})} (\gamma_0(\mathbf{y}) + \nabla \gamma_0(\mathbf{y}) \cdot (\mathbf{y} - \mathbf{x}) + t \gamma_1(\mathbf{y})) d\sigma(\mathbf{y})$$

(Non-examinable)



Then $f := \tilde{A}_0 + \partial_t \gamma$ satisfies $\Delta f = \Delta \tilde{A}_0 + \partial_t \Delta \gamma = 0$

$$\text{and we have } f|_{t=0} = 0 \quad \& \quad \partial_t f|_{t=0} = (\partial_0 \tilde{A}_0 + \partial_t^2 \gamma)|_{t=0}$$

$$= (\partial^i \tilde{A}_i + \Delta \gamma)|_{t=0}$$

$$\partial^i \tilde{A}_i = 0$$

$$\Delta = -\partial_t^2 + \Delta$$

$$= 0$$

Thus $f \equiv 0$ by Kirchhoff's formula and thus $\hat{A}_0 = \tilde{A}_0 + \partial_t \gamma = 0$.

Now for linearised gravity:

Solve on $\{t=0\}$

$$2(-\partial_t \gamma_0 + \partial^i \gamma_i) = -\tilde{h} \quad \left. \begin{array}{l} (1) \\ (2) \end{array} \right\}$$

$$2[-\Delta \gamma_0 + \partial^i \partial_t \gamma_i] = -\partial_t \tilde{h} \quad \left. \begin{array}{l} (2) \\ (3) \end{array} \right\}$$

$$\partial_t \gamma_i + \partial_i \gamma_0 = -\tilde{h}_{0i} \quad \left. \begin{array}{l} (3) \\ (4) \end{array} \right\}$$

$$\Delta \gamma_i + \partial_i \partial_t \gamma_0 = -\partial_t \tilde{h}_{0i} \quad \left. \begin{array}{l} (4) \end{array} \right\}$$

To obtain $\gamma_\mu|_{t=0}, \partial_t \gamma_\mu|_{t=0}$.

Exercise: Show that one can indeed solve the above system to obtain $\gamma_\mu|_{t=0}, \partial_t \gamma_\mu|_{t=0}$ in terms of $\tilde{h}_{\mu\nu}$.

Solution: Put (3) into (2) to obtain $2[-\Delta \gamma_0 + \partial^i (-\partial_i \gamma_0 - \tilde{h}_{0i})] = -\partial_t \tilde{h}$
 $\Leftrightarrow 2[-2\Delta \gamma_0 - \partial^i \tilde{h}_{0i}] = -\partial_t \tilde{h}$
 $\Rightarrow \text{gives } \gamma_0|_{t=0}$

Use $\gamma_0|_{t=0}$ in (3) to obtain $\partial_t \gamma_i|_{t=0}$. Then $\partial_t \gamma_i|_{t=0}$ & $\gamma_0|_{t=0}$ satisfy (2) & (3).

Similarly use (1) to eliminate $\partial_t \gamma_0$ from (4) to get Poisson eq for γ_i . Then use

(1) to get $\partial_t \gamma_0|_{t=0}$.

Now solve $\square \tilde{h}_{\mu\nu} = 0$ with determined initial data and it follows as before

that

$$\hat{h}_{\mu\nu} = \tilde{h}_{\mu\nu} + \partial_{\mu}\tilde{q}_{\nu} + \partial_{\nu}\tilde{q}_{\mu}$$

satisfies

$$\square \hat{h}_{\mu\nu} = 0$$

and

$$\hat{h}|_{t=0} = 0 = \partial_t \hat{h}|_{t=0} \quad (\text{from } \textcircled{1} \text{ & } \textcircled{2})$$

$$\text{and } \hat{h}_{0i}|_{t=0} = 0 = \partial_t \hat{h}_{0i}|_{t=0} \quad (\text{from } \textcircled{3} \text{ & } \textcircled{4})$$

$$\Rightarrow \hat{h} = 0 = \hat{h}_{0i}$$

In order to see that also $\hat{h}_{00} = 0$, we observe that since $\hat{h} = 0$, we have $\hat{h}_{\mu\nu} = \tilde{h}_{\mu\nu}$.

$$\Rightarrow 0 = \underset{\substack{\text{wave} \\ \text{gauge}}}{\partial^M \tilde{h}_{\mu 0}} = \underset{\substack{\text{wave} \\ \text{gauge}}}{\partial^M \hat{h}_{\mu 0}} = \underset{\substack{\text{wave} \\ \text{gauge}}}{\partial^0 \hat{h}_{00}} \Rightarrow \partial_t \hat{h}_{00} = 0$$

Then use inverted EE in wave gauge $0 = \square \hat{h}_{00} = \Delta \hat{h}_{00}$.

$$\Rightarrow \hat{h}_{00} = 0 \quad (\hat{h}_{00} = \text{const.} \text{ is ruled out since we have very large enough } \partial_t \hat{h}_{00} \rightarrow 0 \text{ for } t \rightarrow \infty \text{ and all our gauge choices respect this condition})$$

Example: Consider plane wave solutions $\hat{h}_{\mu\nu}(x) = \hat{H}_{\mu\nu}(k) e^{ik \cdot x}$, $k = (k_0, \dots, k_3) \in \mathbb{R}^4$

(Note that $(\hat{h}_{\mu\nu})^2 \neq 0$ for $t \rightarrow \infty$), but the actual solution will be a superposition

of real part of plane wave solutions which will satisfy the usual theory ...

$$\square \hat{h}_{\mu\nu} = 0 \Leftrightarrow \underbrace{\eta^{\alpha\beta} k_{\alpha} k_{\beta}}_{\text{k null vector}} = 0 \Rightarrow \text{k null vector}$$

$$\Rightarrow \partial^M \tilde{h}_{\mu\nu} = \partial^M \hat{h}_{\mu\nu} = 0 \Leftrightarrow \underbrace{k^M \hat{H}_{\mu\nu}(k)}_{\text{3 cond.}} = 0, \quad k^M \hat{H}_{\mu 0}(k) = 0 \text{ implied by}$$

$$\hat{h}_{0\mu} = 0 \Leftrightarrow \underbrace{\hat{H}_{0\mu}(k)}_{\text{4 cond.}} = 0$$

$$\hat{h} = 0 \Leftrightarrow \underbrace{\hat{H}_{\mu\nu}(k)}_{\text{1 cond.}} = 0 \quad \Rightarrow \text{2 degrees of freedom.}$$

e.g. if $k = \omega(\partial_t + \partial_3)$ (grav. wave propagating in z-direction)

$$\text{then } \hat{H}_{\mu\nu}(k) = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & A(k) & B(k) & 0 \\ 0 & B(k) & -A(k) & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

\Rightarrow distortion of spacetime geometry is transverse to the direction of propagation.

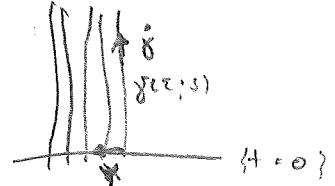
Detection of gravitational waves via gravitational tidal forces.

If $\gamma(\tau; s)$ is a one parameter family of timelike geodesics $\tau \mapsto \gamma(\tau; s)$ and

let $\Upsilon^M(\gamma(\tau; s)) = \frac{\partial}{\partial s} \gamma^M(\tau; s)$ be the deviation vector.

Then $D_\tau^2 \Upsilon^M = R(\dot{\gamma}, \Upsilon) \dot{\gamma}$

$$\left((\nabla_{\dot{\gamma}} (\nabla_{\dot{\gamma}} \Upsilon))^M = R^M_{\nu \sigma \rho} \dot{\gamma}^\nu \dot{\gamma}^\sigma \Upsilon^\rho \right) \quad (*)$$



Set up s.t. $s \mapsto \gamma(0; s) \equiv \{t=0\}$ and

Assume that test particles are nearly at rest w.r.t. Minkowski coords $x^\mu \rightsquigarrow \dot{\gamma} = \partial_x$ + lower order terms
and thus $\tau \approx t$. Also to highest order $D_\tau^2 \approx \left(\frac{d}{dt}\right)^2 \approx \left(\frac{d}{dt}\right)^2$ and thus

(*) becomes

$$\frac{d^2 \Upsilon^M}{dt^2} \approx R^M_{00\nu} \Upsilon^\nu$$

Moreover, $\Upsilon^0(0; s) = \partial_s \gamma^0(0; s) = 0$ & $\frac{d}{dt} \Upsilon^0(0; s) \approx \frac{\partial}{\partial s} \frac{\partial}{\partial t} \gamma^0(0; s) \approx \frac{\partial}{\partial t} \gamma^0(0; s) = 0$. Since $R^0_{00\nu} = 0$, $\Rightarrow \Upsilon^0 = 0$

$$\text{Recall } R^M_{\nu \sigma \rho} \approx \varepsilon \frac{1}{2} \eta^{M\sigma} (\partial_\rho \partial_\nu \hat{h}_{\sigma\rho} - \partial_\rho \partial_\sigma \hat{h}_{\nu\rho} - \partial_\nu \partial_\sigma \hat{h}_{\rho\rho} + \partial_\nu \partial_\sigma \hat{h}_{\rho\rho})$$

$$\text{and thus } R^M_{00\nu} \approx \left(\varepsilon \frac{1}{2} \eta^{M\sigma} (\partial_\rho \partial_\nu \hat{h}_{\sigma\rho} - \partial_\rho \partial_\sigma \hat{h}_{\nu\rho} - \partial_\nu \partial_\sigma \hat{h}_{\rho\rho} + \partial_\nu \partial_\sigma \hat{h}_{\rho\rho}) \right)$$

$$\approx \varepsilon \frac{1}{2} \eta^{M\sigma} \partial_\rho \partial_\nu \hat{h}_{\sigma\rho}$$

using radiation gauge
 $\hat{h}_{\rho 0} = 0$.

$$\Rightarrow \left| \frac{d^2}{dt^2} \Upsilon^i \approx \frac{1}{2} \varepsilon (\partial_t^2 \hat{h}_{ij}) \cdot \Upsilon^j \right|$$

Now $\frac{d}{dt} \Upsilon^i(0) = 0$ (test particles at rest initially) and since ε very small get

$$\Upsilon^i(t) \approx \Upsilon^i(0) + \text{small}$$

To get leading order of correction: $\frac{d^2}{dt^2} \Upsilon^i(0) \approx \frac{1}{2} \varepsilon \partial_t^2 \hat{h}_{ij} \cdot \Upsilon^j(0)$

$$\frac{d}{dt} \Upsilon^i(0) = 0 \quad \boxed{\Upsilon^i(t) \approx \Upsilon^i(0) + \frac{\varepsilon}{2} \hat{h}_{ij}(t) \Upsilon^j(0)}$$

Ex: Evaluate for plane wave solution $\hat{h}_{\nu\sigma}(x) = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & B & B & 0 \\ 0 & B & -B & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \text{Re} \left(e^{-i\omega(t-x_3)} \right) = \cos(\omega t - x_3)$
(but of course ignore not linear harmonic dependence)

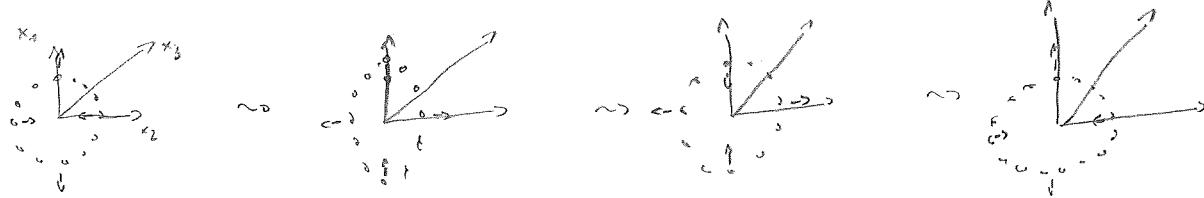
Linear polarisations:

i) $B = 0$, " + " polarisation

$$Y^1(t) \approx Y^1(0) + \frac{\epsilon}{2} A \cos(\omega(t - x_3)) Y^1(0)$$

$$Y^2(t) \approx Y^2(0) - \frac{\epsilon}{2} A \cos(\omega(t - x_3)) Y^2(0)$$

$$Y^3(t) = Y^3(0)$$



Distances in x & y directions oscillate \Rightarrow can be measured with lasers in interferometer (LIGO)

(Don't mix position in absolute space...)

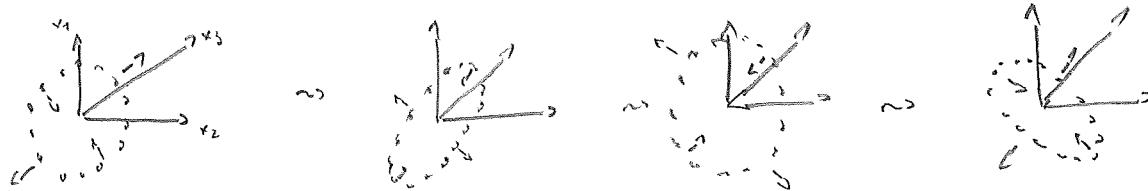
ii) $B = 0$, " x " polarisation

$$Y^1(t) \approx Y^1(0) + \frac{\epsilon}{2} B \cos(\omega(t - x_3)) Y^2(0)$$

$$Y^2(t) \approx Y^2(0) + \frac{\epsilon}{2} B \cos(\omega(t - x_3)) Y^1(0)$$

$$Y^3(t) = Y^3(0)$$

$$\left. \begin{aligned} (Y^1 + Y^2)(t) &= Y^1(0) + Y^2(0) + \frac{\epsilon}{2} B \cos(\dots) (Y^1(0) + Y^2(0)) \\ (Y^1 - Y^2)(t) &= Y^1(0) - Y^2(0) - \frac{\epsilon}{2} B \cos(\dots) (Y^1(0) - Y^2(0)) \end{aligned} \right\}$$



\Rightarrow circular polarisations (MTW) p. 952)

Remark: Very weak effect : LIGO : $\frac{1}{1000}$ diameter of proton over 4 km
 $\approx 10^{-15} \text{ m}$
 $\approx 10^{-18} \text{ m}$

Generation of gravitational waves

- Gravitational waves produced by collision of two BH's \Rightarrow outside validity of linear approximation
- Here, derive formula for generation of grav. waves by weak non-self-gravitating sources in the linear approximation (spinning rods, rotating inhomogeneous stars) in the far field

Moreover assume: • $T_{\mu\nu}^{(1)}(t, x)$ compactly supported w.r.t. time t , coords s.t. $T_{\mu\nu}(t, x)$ centred around $x = 0$.

- Source time over which source varies small compared to spatial extent of source.

(e.g. rotation slow) (say as: typical wavelength of radiation much larger than extent of source)

$$\text{Recall} \quad \left\{ \begin{array}{l} \square \tilde{h}_{\mu\nu} = -16\pi \overset{(n)}{T}_{\mu\nu} \\ \partial^\mu \tilde{h}_{\mu\nu} = 0 \end{array} \right.$$

$$\tilde{h}_{\mu\nu} = \tilde{h}_{\mu\nu} - \frac{1}{2}\eta_{\mu\nu}\tilde{h}$$

Retarded solution (no incoming radiation)

$$\tilde{h}_{\mu\nu}(t, \mathbf{x}) = 4 \int_{\mathbb{R}^3} \frac{\overset{(n)}{T}_{\mu\nu}(t - |\mathbf{x}' - \mathbf{x}|, \mathbf{x}')}{|\mathbf{x}' - \mathbf{x}|} d\mathbf{x}'$$

Ex: show that gauge condition $\partial^\mu \tilde{h}_{\mu\nu} = 0$ is satisfied by virtue of $\partial^\mu \overset{(n)}{T}_{\mu\nu} = 0$. 77

$$\partial^\mu \tilde{h}_{\mu\nu}(t, \mathbf{x}) = 4 \int_{\mathbb{R}^3} \frac{\partial^\mu \overset{(n)}{T}_{\mu\nu}(t - |\mathbf{x}' - \mathbf{x}|, \mathbf{x}')}{|\mathbf{x}' - \mathbf{x}|} d\mathbf{x}'$$

$$\partial_i \tilde{h}_{iv}(t, \mathbf{x}) = 4 \int_{\mathbb{R}^3} \left[\frac{\partial_i [\overset{(n)}{T}_{\mu\nu}(t - |\mathbf{x}' - \mathbf{x}|, \mathbf{x}')] }{|\mathbf{x}' - \mathbf{x}|} + \frac{\overset{(n)}{T}_{iv}(t - |\mathbf{x}' - \mathbf{x}|, \mathbf{x}')}{|\mathbf{x}' - \mathbf{x}|} \partial_i \left(\frac{1}{|\mathbf{x}' - \mathbf{x}|} \right) \right] d\mathbf{x}'$$

$$= -\partial_i^! \left(\frac{1}{|\mathbf{x}' - \mathbf{x}|} \right)$$

1.P. since
 $T_{\mu\nu}$ is conserved
sufficient on
light cone

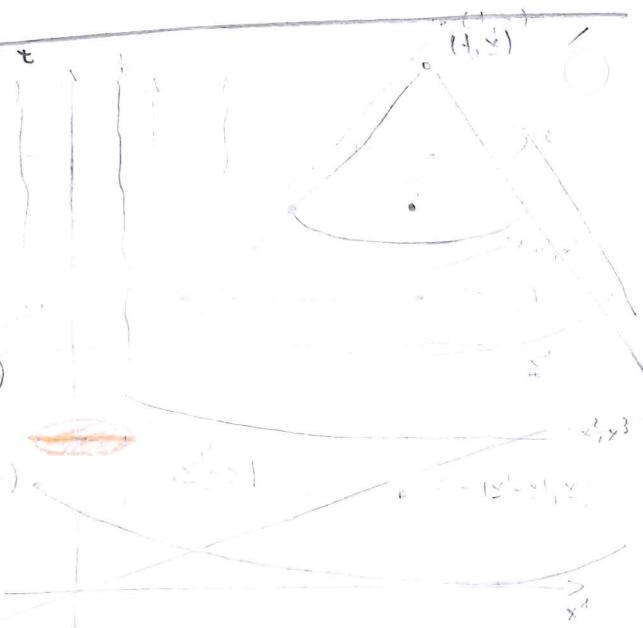
$$\stackrel{?}{=} 4 \int_{\mathbb{R}^3} \frac{(\partial_i + \partial_i^!) [\overset{(n)}{T}_{iv}(t - |\mathbf{x}' - \mathbf{x}|, \mathbf{x}')] }{|\mathbf{x}' - \mathbf{x}|} d\mathbf{x}'$$

$$\partial_i |\mathbf{x}' - \mathbf{x}| = -\partial_i^! |\mathbf{x}' - \mathbf{x}| \stackrel{?}{=} 4 \int_{\mathbb{R}^3} \frac{(\partial_i^! \overset{(n)}{T}_{iv})(t - |\mathbf{x}' - \mathbf{x}|, \mathbf{x}')}{|\mathbf{x}' - \mathbf{x}|} d\mathbf{x}'$$

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$$= \frac{4}{r} \int_{\mathbb{R}^3} \overset{(n)}{T}_{\mu\nu}(t - |\mathbf{x}' - \mathbf{x}|, \mathbf{x}') d\mathbf{x}' + \mathcal{O}\left(\frac{1}{r^2}\right) \quad (\text{for field approx, } \frac{1}{|\mathbf{x}' - \mathbf{x}|} = \frac{1}{r} + \mathcal{O}(\frac{1}{r^2}))$$

$$= \frac{4}{r} \int_{\mathbb{R}^3} \overset{(n)}{T}_{\mu\nu}(t - |\mathbf{x}' - \mathbf{x}|, \mathbf{x}') d\mathbf{x}'$$



replace integral over retarded cone with source by retarded $(t' - t > 0)$ with source

now depends by source. The new value

We want expand the integrand using the slow motion approximation, more precisely assuming that if ω is a characteristic frequency of change of $T_{\mu\nu}$ and R_0 is the radius of the support, then $R_0 \ll \lambda$.

Let $f(x') = t - |x' - x|$. Then

$$\partial_i f(x') = -\frac{x'_i - x_i}{\sqrt{\sum_j (x'_j - x_j)^2}}, \quad \partial_i f(0) = \frac{x'_i}{r} = \mathcal{O}(1)$$

$$\partial_k \partial_i f(x') = -\frac{\delta_{ik}}{|x' - x|} + \frac{(x'_i - x_i)(x'_{ik} - x_{ik})}{|x' - x|^3}, \quad \partial_k \partial_i f(0) = -\frac{\delta_{ik}}{r} + \frac{x_i x_{ik}}{r^3} = \mathcal{O}\left(\frac{1}{r}\right)$$

$$\partial_k \partial_l \partial_i f(x') = \mathcal{O}\left(\frac{1}{r^2}\right) \text{ for } |x'| \leq R_0.$$

$$\text{Also } \partial_i T_{\mu\nu}^{(n)}(f(x'), y') = \partial_0 T_{\mu\nu}^{(n)}(t(x'), y') \cdot \partial_i f(y), \quad \partial_k \partial_i T_{\mu\nu}^{(n)}(f(x'), y') = \partial_0^2 T^{(n)}(t(x'), y') \partial_i f(y) \partial_i f(y) + \partial_0 T^{(n)}(t(x'), y) \partial_k \partial_i f(y)$$

$$\begin{aligned} \text{Then } \overset{(n)}{T}_{\mu\nu}(f(x'), y') &= \overset{(n)}{T}_{\mu\nu}(f(0), y') + \partial_0 \overset{(n)}{T}_{\mu\nu}(f(0), y') \partial_i f(0) \cdot x'_i \\ &\quad + \frac{1}{2} \left[\partial_0^2 \overset{(n)}{T}_{\mu\nu}(f(0), y') \partial_i f(0) \partial_i f(0) + \partial_0 \overset{(n)}{T}_{\mu\nu}(f(0), y') \partial_k \partial_i f(0) \right] x'_i x_{ik} \\ &\quad + \frac{1}{6} \left[\partial_0^3 \overset{(n)}{T}(f(0), y') \partial_i f(0) \partial_i f(0) \partial_i f(0) + \mathcal{O}\left(\frac{1}{r^2}\right) \right] x'_i x_{ik} x_{il} \end{aligned}$$

$$\text{Assume now } \overset{(n)}{T}_{\mu\nu}(t', x') = E_{\mu\nu}(x') \cos(\omega t') \quad \text{then } |\partial_0 \overset{(n)}{T}_{\mu\nu}(t', x')| \approx \omega^k \quad \text{for } k \geq 1$$

Thus we obtain

$$\begin{aligned} \overset{(n)}{T}_{\mu\nu}(t - |x' - x|, x') &= \overset{(n)}{T}_{\mu\nu}(t - r, x') + \underbrace{\partial_0 \overset{(n)}{T}_{\mu\nu}(t - r, x') \frac{x_i x'_i}{r}}_{\mathcal{O}(\omega R_0)} \\ &\quad + \frac{1}{2} \partial_0^2 \overset{(n)}{T}_{\mu\nu}(t - r, x') \frac{x_i x_{ik}}{r} x'_i x_{ik} + \mathcal{O}\left(\frac{1}{r^2}\right) + \mathcal{O}(\omega^3 R_0^3 |E_{\mu\nu}|) \\ &\quad \in \mathcal{O}(\omega^2 R_0^2) \end{aligned}$$

Now compute metric to leading order in $\frac{1}{r}$ and ωR_0 :

$$\partial_i \tilde{h}_{ij}(t, x) \approx \frac{1}{r} \int_{\mathbb{R}^3} \overset{(n)}{T}_{ij}(t - r, x') dx' + \text{higher order terms.}$$

$$\underset{\mathcal{O}(R_0^3 R_0^2)}{\rightarrow} \frac{2}{r} \frac{d^2}{dt^2} Q_{ij}(t - r)$$

radial propagation (33)

$$\text{where } Q_{ij}(t) = \int_{\mathbb{R}^3} T_{00}(t, x') x'_i x'_j dx'$$

quadrupole moment

$\sim R_0^2$

$$\tilde{h}_{oi}(t, \mathbf{x}) = \underbrace{\frac{4}{r} \int_{\mathbb{R}^3} {}^{(n)}T_{oi}(t-r, \mathbf{x}') d\mathbf{x}'}_{= -\frac{4}{r} \dot{q}^i(t-r) = 0} + \frac{4}{r} \sum_i \int_{\mathbb{R}^3} \partial_o {}^{(n)}T_{oi}(t-r, \mathbf{x}') \mathbf{x}_i^i d\mathbf{x}' + \text{higher order terms}$$

By Problem sheet 2 $\dot{q}^i = \text{const}$,
can choose s.t. $\dot{q}^i = 0$

$$\begin{aligned} \partial_o {}^{(n)}T_{oi} &= 0 \\ &\Rightarrow \frac{4}{r} \sum_i \int_{\mathbb{R}^3} \partial_o {}^{(n)}T_{ki}(t-r, \mathbf{x}') \mathbf{x}_j^i d\mathbf{x}' + \text{higher order terms} \\ &= \frac{4}{r} \sum_i \int_{\mathbb{R}^3} {}^{(n)}Q_{ij}(t-r, \mathbf{x}') d\mathbf{x}' + \dots \\ &= -\frac{2}{r} \sum_i \frac{d^2}{dt^2} Q_{ij}(t-r) + \text{higher order terms} \\ &\quad \underbrace{\sim \mathcal{O}(\omega^2 R_0^2)} \end{aligned}$$

$$\begin{aligned} \tilde{h}_{oo}(t, \mathbf{x}) &= \underbrace{\frac{4}{r} \int_{\mathbb{R}^3} {}^{(n)}T_{oo}(t-r, \mathbf{x}') d\mathbf{x}'}_{= \frac{4M}{r} \text{ time indep., non-radiating contribution}} + \underbrace{\frac{4}{r} \sum_i \int_{\mathbb{R}^3} \partial_o {}^{(n)}T_{oo}(t-r, \mathbf{x}') \mathbf{x}_i^i d\mathbf{x}'}_{\sim \frac{d}{dt} D^i = \dot{p}^i = 0} \\ &+ \frac{4}{r} \cdot \frac{1}{2} \sum_i \frac{x_i x_k}{r} \int_{\mathbb{R}^3} \partial_o^2 {}^{(n)}T_{oo}(t-r, \mathbf{x}') \mathbf{x}_i^i \mathbf{x}_k^k d\mathbf{x}' + \text{h.o.t} \\ &= \frac{4M}{r} + \frac{2}{r} \sum_i \frac{x_i x_k}{r} \frac{d^2}{dt^2} Q_{ik}(t-r) + \text{h.o.t} \\ &\quad \underbrace{\sim \mathcal{O}(\omega^2 R_0^2)} \end{aligned}$$

$$\left. \begin{aligned} \tilde{h}_{oo}(t, \mathbf{x}) &\approx \frac{4M}{r} + \frac{2}{r} \sum_i \frac{x_i x_k}{r} \frac{d^2}{dt^2} Q_{ik}(t-r) \\ \tilde{h}_{oi}(t, \mathbf{x}) &\approx -\frac{2}{r} \sum_i \frac{d^2}{dt^2} Q_{ij}(t-r) \\ \tilde{h}_{ij}(t, \mathbf{x}) &\approx \frac{2}{r} \frac{d^2}{dt^2} Q_{ij}(t-r) \end{aligned} \right\}$$

Often called the
quadrupole formula
 \rightarrow $\tilde{h}_{ij} \propto \tilde{Q}_{ij}$

Check: wave gauge is satisfied to highest order: use $\partial_i r = \frac{x_i}{r}$, then

$$\begin{aligned} \partial_i \tilde{h}_{ij} &\approx -\frac{2}{r} \sum_i \frac{d^3}{dt^3} Q_{ij}(t-r) \\ \partial^0 \tilde{h}_{oj} &\approx \frac{2}{r} \sum_i \frac{d^3}{dt^3} Q_{ij}(t-r) \\ \partial^0 \tilde{h}_{oj} &\approx \frac{2}{r} \sum_i \frac{x_i}{r} \frac{d^3}{dt^3} Q_{ij}(t-r) \\ \partial^0 \tilde{h}_{oo} &\approx -\frac{2}{r} \sum_i \frac{x_i}{r} \frac{d^2}{dt^2} Q_{ij}(t-r) \end{aligned}$$

Remarks:

- Monopole moment $\int_{\mathbb{R}^3} {}^{(n)}T_{oo}(t, \mathbf{x}') d\mathbf{x}' = M$ indep. of the

- Dipole moment $\int_{\mathbb{R}^3} {}^{(n)}T_{oo}(t, \mathbf{x}') \mathbf{x}_i^i d\mathbf{x}' = D^i(t)$ - centre of mass ($= 0$ wlog.)

Lowest moment that radiates in GR is quadrupole moment (in contrast to electromagnetism, where dipole moment gives leading order (40) of radiation (see problem sheet 2))

$\left. \begin{aligned} \text{since momentum } \frac{d}{dt} D^i(t) = P^i(t) \text{ is} \\ \text{conserved and} \\ \text{wlog. } \omega = 0 \end{aligned} \right\}$

Using $\tilde{h}_{\mu\nu} = \bar{h}_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \bar{h}$ we can now compute $\tilde{h}_{\mu\nu}$ from (4) and then
 find R_{00j} of the metric $\tilde{g}_{\mu\nu} = g_{\mu\nu} + \varepsilon \tilde{h}_{\mu\nu}$ to leading order in ε and $(\frac{1}{r})$. We
 find (problem sheet 3)

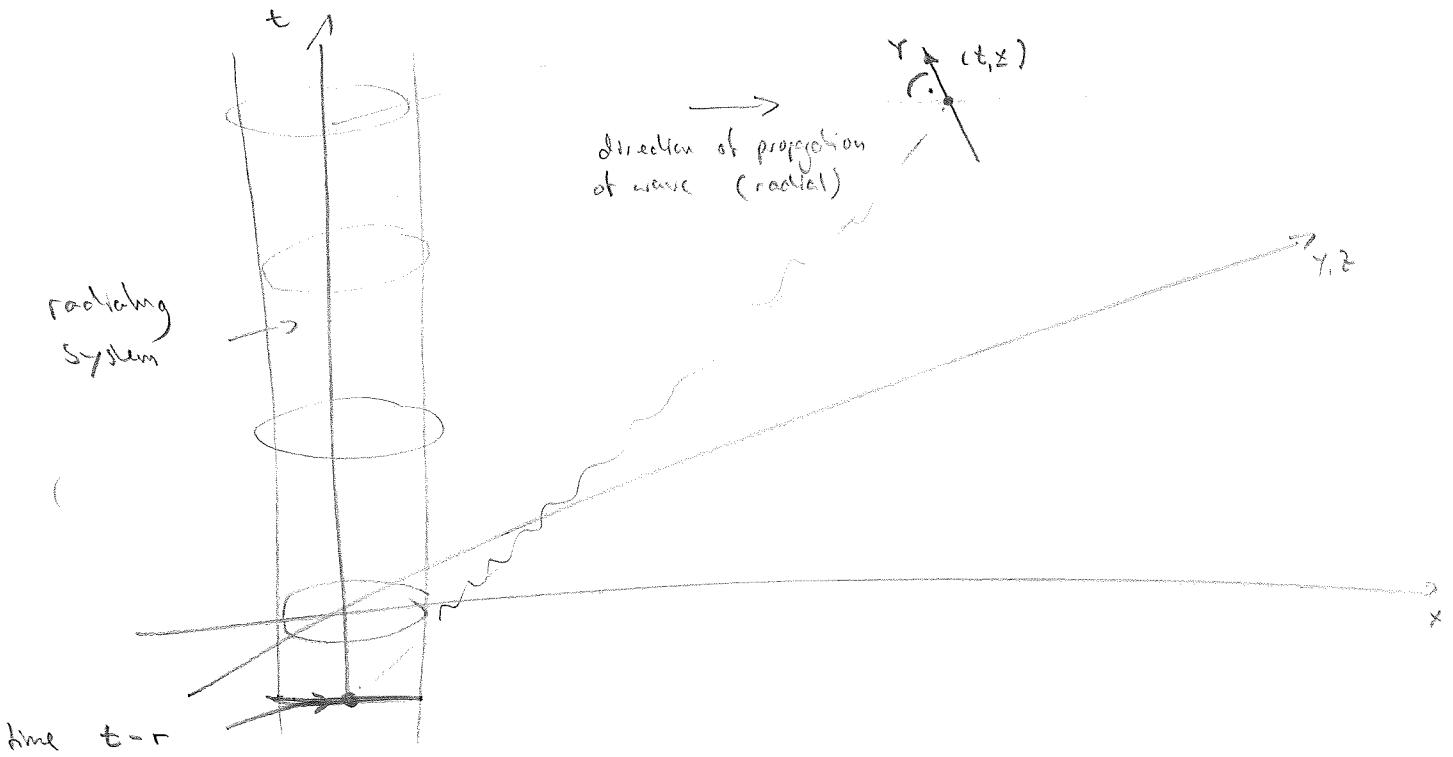
$$(**) R_{00j}^i \approx \frac{\varepsilon}{r} \left[\bar{\pi}_i^m \bar{\pi}_j^n - \frac{1}{2} \bar{\pi}^{mn} \bar{\pi}_{ij} \right] \frac{d^4}{dt^4} Q_{mn}(t-r) \quad \text{where } \bar{\pi}^{mn} = \delta^{mn} - \frac{x^m x^n}{r^2}$$



projection on 2-space orthogonal to $x \in \mathbb{R}^3$
 For detection of gravitational waves set up one-parameter family of metric geometries as before,
 with Jacobi field γ

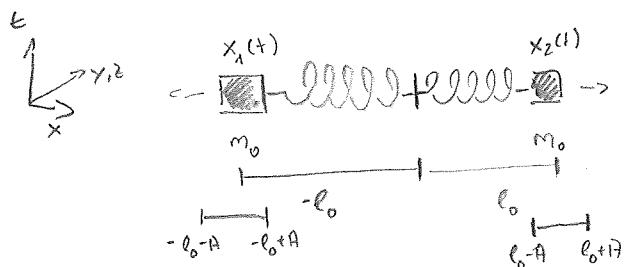
$$\Rightarrow \frac{d^2}{dt^2} \gamma^i \approx R_{00j}^i \gamma^j \approx \frac{\varepsilon}{r} \left[\bar{\pi}_i^m \bar{\pi}_j^n - \frac{1}{2} \bar{\pi}^{mn} \bar{\pi}_{ij} \right] \frac{d^4}{dt^4} Q_{mn}(t-r) \gamma^j$$

$$(\text{as before} \Rightarrow \boxed{\gamma^i(t) \approx \gamma^i(0) + \frac{\varepsilon}{r} \left[\bar{\pi}_i^m \bar{\pi}_j^n - \frac{1}{2} \bar{\pi}^{mn} \bar{\pi}_{ij} \right] \frac{d^2}{dt^2} Q_{mn}(t-r) \gamma^j(0)})$$



Remarks. Oscillation of test masses only in directions in \mathbb{R}^3 orthogonal to propagation
 direction of wave ($\bar{\pi}_{ij} x^j = 0$)

Example: Laboratory gravitational wave generator



Two masses with mass m_0 oscillating with angular frequency ω and amplitude A around positions $\pm l_0$ on $x = \alpha x^3$.

$$\Rightarrow x_1(t) = -l_0 - A \cos(\omega t)$$

$$x_2(t) = l_0 + A \cos(\omega t)$$

$$\frac{\partial}{\partial t} T_{00}(t, x, y, z) \approx m_0 \delta^3(x - x_1(t)) + m_0 \delta^3(x - x_2(t))$$

movement slow
compared to speed of light.

$$\begin{aligned} \Rightarrow Q_{xx}(t) &= \int_{\mathbb{R}^3} T^{(1)}(t, x, y, z) x^1 x^1 dx^1 dy^1 dz^1 = m_0 [x_1^2(t) + x_2^2(t)] \\ &= 2m_0 [l_0 + A \cos(\omega t)]^2 \\ &= 2m_0 [l_0^2 + 2l_0 A \cos(\omega t) + A^2 \cos^2(\omega t)] \end{aligned}$$

All other components $Q_{ij} = 0$. It follows from $T^{ij}(x, 0, 0) = 0$ that there is no radiation in the x -direction. (But radiation in y & z -direction.)

$$\Rightarrow \frac{d^2}{dt^2} Q_{xx}(t) \sim m_0 l_0 A \omega^2 + m_0 A^2 \omega^2$$

$$\text{Take } m_0 = 10^3 \text{ kg} = 10^6 \text{ g}, \quad l_0 = 1 \text{ m} = 100 \text{ cm}, \quad A = 10^{-1} \text{ cm} = 10^{-4} \text{ m}, \quad \omega = 10^4 \text{ s}^{-1}$$

$$\text{Use } c = 3 \cdot 10^{10} \frac{\text{cm}}{\text{s}}, \quad G = 6.67 \cdot 10^{-8} \frac{\text{cm}^3}{\text{g s}^2}$$

$$\Rightarrow m_0 = 10^6 \text{ g} \cdot 6.67 \cdot 10^{-8} \frac{\text{cm}^3}{\text{g s}^2} \cdot \frac{1}{(3 \cdot 10^{10} \frac{\text{cm}}{\text{s}})^2} \simeq 0.75 \cdot 10^{-22} \text{ cm}$$

$$l_0 = 10^2 \text{ cm}$$

$$A = 10^{-1} \text{ cm}$$

$$\omega \simeq 0.3 \cdot 10^{-6} \text{ cm}^{-1}$$

$$\Rightarrow \text{First term leading order } (l_0 \gg A) \quad \Rightarrow \frac{d^2}{dt^2} Q_{xx}(t) \sim 0.0675 \cdot 10^{-22} \frac{10^2 \cdot 10^{-1} \cdot 10^{-12}}{10^{-23}} \text{ cm} = 6.75 \cdot 10^{-35} \text{ cm}$$

$$\Rightarrow \Delta Y^i \simeq 6.75 \cdot 10^{-35} \cdot Y^i(0) \text{ cm}$$

If test masses are $1 \text{ cm} = 10^3 \text{ cm}$ apart, this gives change in amplitude of order $\frac{1}{10^3} \cdot 6.75 \cdot 10^{-32} \text{ cm}$ with c in cm.

\Rightarrow too small to be detectable.

Remark: Derivation of Quadrupole formula only valid for non-self-gravitating systems because we used $\partial_\mu T^{\mu\nu} = 0$. However, it is expected that it still is a good approximation for example for orbiting binaries. Indeed Hulse & Taylor observed in 1975 the increase of orbiting frequency of a binary system which contains a pulsar at a rate compatible with the loss of energy due to emission of gravitational waves predicted by the quadrupole formula.

First indirect observation of gravitational waves, Nobel prize for physics 1993.

Remark: Alfred Eddington noted that on small scales (quantum scales) one has to worry GR because otherwise an atom would be unstable due to emission of gravitational radiation.