## C6.2/B2. Continuous Optimization

## Problem Sheet 4

## Please hand-in for marking Problems 2, 3, 7 and 9. The remaining problems are optional.

1. The fundamental theorem of linear inequalities, also known as *Farkas' Lemma* states that: given any vectors  $b \in \mathbb{R}^n$  and  $a_i \in \mathbb{R}^n$ ,  $i \in \{1, \ldots, m\}$ , the set

$$\{s: b^T s < 0 \text{ and } a_i^T s \ge 0, i \in \{1, \dots, m\}\}$$

is empty if and only if

$$b \in C = \{\sum_{i=1}^{m} a_i y_i : y_i \ge 0, i \in \{1, \dots, m\}\}.$$

(In other words, a vector b lies in the cone C generated by the vectors  $a_i$  if and only if it cannot be separated from the vectors  $a_i$  by a separating hyperplane generated by s.) Use this lemma in the next part of the problem (for appropriate choices of b,  $a_i$  and m).

Suppose that  $f : \mathbb{R}^n \to \mathbb{R}$  and  $c : \mathbb{R}^n \to \mathbb{R}^p$  are  $\mathcal{C}^1$  functions. Let  $x^*$  be a local minimizer of

$$\min_{x} f(x) \quad c(x) \ge 0$$

Show that, provided a suitable first-order constraint qualification holds, there exists a vector  $\lambda_* \in \mathbb{R}^p$  of Lagrange multipliers such that

$$\nabla f(x^*) = J(x^*)^T \lambda^*, \quad c(x^*) \ge 0, \quad \lambda^* \ge 0, \quad \lambda_i^* c_i(x^*) = 0, \ i \in \{1, \dots, p\}.$$

(These are the KKT conditions for inequality-constrained problems. Use ideas and approaches from the proof of Theorem 16; note that we only need a first-order representation of the feasible path in the proof of Theorem 16. Recall that it is sufficient to consider the active constraints at  $x^*$ .)

2. Consider the following constrained optimization problem

$$\min_{(x_1, x_2) \in \mathbb{R}^2} \ \frac{1}{2} x_1^2 - x_2^2 \quad \text{subject to} \quad 1 - x_1^2 - x_2^2 \ge 0.$$
(1)

- (a) Write down the system of Karush-Kuhn-Tucker (KKT) conditions for problem (1). By solving this system as a function of x and the Lagrange multiplier, find (all) the KKT points  $\hat{x}$  of problem (1).
- (b) State the Slater constraint qualification for problem (1); does it hold for this problem? Conclude from this if each (local) minimizer of (1) is a KKT point (in other words, if first-order necessary optimality conditions hold for this problem).
- (c) Using (a) and (b), or otherwise, find a global minimizer of (1). Argue also that a global minimizer of (1) exists.
- (d) Is the constraint of problem (1) active at each (local or global) minimizer of (1)? Justify your answer.
- 3. Consider the problem

$$\min_{(x_1,x_2)\in\mathbb{R}^2} f(x_1,x_2) = -x_1 + x_2 \quad \text{subject to} \begin{cases} 0 \le x_1 \le a, \\ 0 \le x_2 \le 1, \\ x_2 \ge x_1^2, \end{cases}$$
(2)

where a > 0 is a fixed positive constant.

- (a) By drawing a diagram of the feasible region and the contours of f(x), or otherwise, determine the solution of problem (2).
- (b) Show that the set of active constraints at the solution differs according to whether or not a is greater than a certain fixed value  $\overline{a}$ , and determine  $\overline{a}$ . Obtain the value of the Lagrange multipliers of the active constraints at the solution in both cases, and verify that the KKT conditions are satisfied.
- 4. Consider the following quadratic programming problem.

minimize 
$$f(x) = (x_1 - 1)^2 + (x_2 - 4)^2$$
  
subject to  $-2x_1 - x_2 = -8$  (1)  
 $x_1 - x_2 \ge -2$  (2)  
 $x_1 \ge 0$  (3)  
 $x_2 \ge 0$  (4)

For the points  $x = (4 \ 0)^T$  and  $x = (2 \ 4)^T$ , compute the Lagrange multipliers and hence determine whether the KKT conditions are satisfied. If the KKT conditions cannot be satisfied then determine a feasible descent direction. If they are, determine whether the second order sufficient conditions are satisfied and deduce whether the vertex is a minimizer.

5. For the following problem,

minimize 
$$f(x) = x_1^2 + x_2^2$$
  
subject to  $c(x) = (x_1 - 1)^3 - x_2^2 = 0$ 

- (i) Sketch contours of f(x) and the points which satisfy c(x) = 0. Deduce the solution  $x^*$  of the problem.
- (ii) Use the constraint to eliminate  $x_2$  and show that the solution obtained in (i) is obtained. What happens if the problem is solved by eliminating  $x_1$ ?
- (iii) Attempt to solve the problem by the method of Lagrange multipliers. Show that either  $x_2 = 0$  or  $\lambda = -1$  and that both lead to a contradiction. Deduce that the stationary point condition for the Lagrangian function is not a necessary condition for a minimizer. What notable property does  $\nabla c(x^*)$  have?
- 6. Consider the problem

$$\min_{x \in \mathbb{R}^2} -x_1 - x_2 \quad \text{subject to} \quad 1 - x_1^2 - x_2^2 = 0.$$
(3)

- (a) Use the first-order necessary optimality (KKT) conditions to solve this problem.
- (b) Let  $x(\mu) = (x_1(\mu), x_2(\mu))$  be a local minimizer of the quadratic penalty function for (3). Show that  $x_1(\mu) = x_2(\mu)$  and  $2x_1(\mu)^3 x_1(\mu) \mu/2 = 0$ .
- (c) Among the two solutions for  $x(\mu)$ , pick the one for which  $x_1(\mu) > 0$ . Show that as  $\mu \to 0$ ,

$$x_1(\mu) = \frac{1}{\sqrt{2}} + a\mu + O(\mu^2).$$

Find the constant a.

(d) Now consider the problem

$$\min - x_1 - x_2$$
  
s.t.  $1 - x_1^2 - x_2^2 = 0$ ,  
 $x_2 - x_1^2 \ge 0$ .

Show how the penalty function may be modified to solve this problem. Show that there is a range of values of  $\mu$  for which the minimisers of the two penalty functions agree.

7. Consider the problem

$$\min - x_1 x_2 x_3 \tag{4}$$
  
s.t.  $72 - x_1 - 2x_2 - 2x_3 = 0.$ 

(i) For  $x^* = (24\ 12\ 12)^T$  verify that there exists a Lagrange multiplier  $\lambda^*$  such that  $(x^*, \lambda^*)$  is a KKT point.

(ii) Now let

$$x(\mu) := \arg\min_{x \in \mathbb{R}^2} Q(x,\mu),$$

where  $Q(x,\mu)$  is the quadratic penalty function for (4). Verify that the explicit expression for  $x(\mu)$  given by

$$x_1(\mu) = 2x_2(\mu), \quad x_2(\mu) = x_3(\mu) = \frac{24}{1 + \sqrt{1 - 8\mu}}$$

satisfies  $\nabla_x Q(x(\mu), \mu) = 0$ , and verify that  $x(\mu) \to x^*$  as  $\mu \to 0$ .

- (iii) Let  $\mu = 1/9$ . Find  $x(\mu)$  and verify that  $\nabla^2_{xx}Q(x(\mu),\mu)$  is positive definite, so that  $x(\mu)$  is a local minimizer of  $Q(x,\mu)$ .
- (iv) Show that  $-c(x(\mu))/\mu \to \lambda^*$ , where c is the equality constraint function in (4).
- 8. (a) Show that the logarithmic barrier function for the problem of minimizing  $1/(1+x^2)$  subject to  $x \ge 1$  is unbounded from below for all  $\mu$ .

Comment: Thus the barrier function approach will not always work.

(b) Find the minimizer  $x(\mu)$ , and its related Lagrange multiplier estimate  $\lambda(\mu)$ , of the logarithmic barrier function for the problem of minimizing  $\frac{1}{2}x^2$  subject to  $x \ge 2a$  where a > 0. What is the rate of convergence of  $x(\mu)$  to  $x_*$  as a function of  $\mu$ ? And the rate of convergence of  $\lambda(\mu)$  to  $\lambda_*$  as a function of  $\mu$ ?

Comment: Problems with strictly complementary solutions (for which  $\lambda_i^* > 0$  whenever  $c_i(x^*) = 0$ ) generally have  $x(\mu) - x_* = \mathcal{O}(\mu)$  and  $\lambda(\mu) - \lambda_* = \mathcal{O}(\mu)$  as  $\mu \to 0$ .

(c) Find the minimizer  $x(\mu)$ , and its related Lagrange multiplier estimate  $\lambda(\mu)$ , of the logarithmic barrier function for the problem of minimizing  $\frac{1}{2}x^2$  subject to  $x \ge 0$ . How do the errors  $x(\mu) - x_*$  and  $\lambda(\mu) - \lambda_*$  behave as a function of  $\mu$ ?

Comment: Without strict complementarity, the errors  $x(\mu) - x_*$  and  $\lambda(x(\mu)) - \lambda_*$  are generally larger than in the strictly complementary case.

9. Apply the augmented Lagrangian function to minimize

$$f(x) = 2x_1^2 - x_2^2$$
 subject to  $c(x) = x_1 + x_2 - 1 = 0$ .

The estimate of the Lagrange multiplier of the constraint is revised by the formula

$$\lambda^{k+1} = \lambda^k - \frac{c(x(\lambda^k))}{\sigma}$$

where  $x(\lambda^k)$  is a minimizer of the augmented Lagrangian function. Show that the sequence of values of  $\lambda^k$  converges if  $\sigma > 0$  is sufficiently small. Find the value of  $\sigma$  such that each iteration reduces the difference between  $\lambda^k$  and the optimal multiplier  $\lambda^*$  by a factor of 10.

10. Suppose that an algorithm for unconstrained minimization fails if the ratio of the largest to the smallest eigenvalue of the Hessian matrix exceeds  $10^{10}$  at the required solution. It is used to find an approximate solution of the problem

$$f(x) = x_1^2 + 2x_2^2$$
 subject to  $x_1 + x_2 - 1 \ge 0$ 

in two ways. Specifically, the functions

$$x_1^2 + 2x_2^2 + r(x_1 + x_2 - 1)^2$$
 and  $x_1^2 + 2x_2^2 - r\log(x_1 + x_2 - 1)$ 

are minimized over  $\mathbb{R}^2$  using a large and a small value of r, respectively. Estimate the accuracy of the approximate solution in each case when r is close to a value that causes failure.