

Lecture 4: Sci. Comp. for DPhil Students

Nick Trefethen, Thursday 24.10.19

Today

- I.8 The definition of numerical analysis
- I.9 Overview of matrix iterations
- I.10 Lanczos iteration
- I.11 Numerical software tools and information sources

Handouts

- “Distracting digits”
- Quiz 3 (Matlab syntax)
- `m06_lanczos.m` and `lanczos.m`
- Essay “Numerical Analysis” from *Princeton Companion to Mathematics*
- Numerical software tools and information sources
- List of students in the course

Announcements

- Assignment 1 returned at end of lecture
- Assignment 2 posted online tomorrow
- Please do the quiz

I.8 The definition of Numerical Analysis

Definition of Numerical analysis/scientific computing:

The study of algorithms for the problems of continuous mathematics.

Our PCG discussion touches upon one of the fascinating aspects of these algorithms nowadays. The best algorithms for large problems are often iterative, even when there exists a noniterative algorithm that in principle would get the exact answer in a finite number of steps. For other examples and discussion, see the appendix to Trefethen & Bau, “The definition of numerical analysis”. Also see this essay “Numerical Analysis” from the *Princeton Companion to Mathematics*.

In particular, see Section 7 of the *PCAM* essay, especially its final paragraph.

The essay is a decade years old. The biggest thing that strikes me that has happened since then is the rise of randomness: new questions with a random aspect to them; and new algorithms for very large problems exploiting randomness.

I.9 Overview of matrix iterations

Good reading: Trefethen & Bau Lecture 32

The two biggest problems in large-scale matrix computation are:

$Ax = b$ (linear system of equations)

$Ax = \lambda x$ (eigenvalue problem)

And there are two big classes of matrices: symmetric or nonsymmetric. Here's an outline of the famous methods for these problems:

	$Ax = b$	$Ax = \lambda x$
$A^T = A$	CG (if SPD)	Lanczos
	MINRES	Implicitly restarted L.
	SYMLQ	J-D (Jacobi-Davidson)
$A^T \neq A$	CGN / LSQR / LSMR	Arnoldi
	GMRES	Implicitly restarted A.
	QMR, BiCG, CGS, BiCGSTAB, ...	J-D
	see Saad 2 & Templates 2	see Saad 1 & Templates 1

For $Ax = b$, the crucial thing is getting a good preconditioner. If you've got one, all methods are good. If you don't...

Maybe BiCGSTAB is the best? The 1992 BiCGSTAB paper by van der Vorst was the most heavily cited maths paper in the 1990s! — 5936 hits on Google Scholar as of today.

But CGN is the simplest: convert $Ax = b$ to $A^T Ax = A^T b$ and use CG. A bonus is that this also works for least-squares (rectangular A).

$Ax = b$ in MATLAB: PCG, MINRES, SYMLQ, LSQR, GMRES, QMR, BICG, CGS, BICGSTAB

$Ax = \lambda x$ in MATLAB: EIGS

I.10 Lanczos iteration

Read: Trefethen & Bau Lec. 36.

History

- Lanczos 1950.
- Closely related to CG, though people didn't fully see that at first. "Rediscovery" - Paige 1971.

Given: symmetric matrix A . Whether A is SPD doesn't matter — the eigenvalue problems for A and $A + cI$ are equivalent.

What Lanczos does is construct an orthogonal similarity transformation of A to a tridiagonal matrix $T = QAQ^T$:

$$T = \begin{pmatrix} \alpha_1 & \beta_1 & & \\ \beta_1 & \alpha_2 & \beta_2 & \\ & \beta_2 & \alpha_3 & \beta_3 \\ & & \ddots & \ddots \end{pmatrix}$$

Instead of going all the way (which wouldn't be accurate anyway because of rounding errors) we stop after a smallish number of rows and columns n and find that the eigenvalues of T_n are often good approximations of some of those of A .

Watch out: there are often some spurious repeats — “ghosts”.

As with CG, we will state the iteration but not derive it. Also as with CG, A enters only via a matrix-vector multiplication at each step, so the method takes advantage of sparsity.

For a vector x , $\|x\|$ denotes the **norm** or **2-norm** defined by

$$\|x\| = (x^T x)^{1/2} = \left(\sum_j x_j^2\right)^{1/2}.$$

$\beta_0 = 0, \quad q_0 = 0, \quad b = \text{arbitrary}, \quad q_1 = b/\|b\|$

for $n = 1, 2, 3, \dots$

$$v = Aq_n$$

$$\alpha_n = q_n^T v$$

$$v = v - \beta_{n-1}q_{n-1} - \alpha_n q_n$$

$$\beta_n = \|v\|$$

$$q_{n+1} = v/\beta_n$$

Compute the eigenvalues of the $n \times n$ matrix

$$T_n = \text{tridiag}(\alpha_1, \dots, \alpha_n; \beta_1, \dots, \beta_{n-1})$$

end

In MATLAB the `eigs` code does this and more:

“implicitly restarted Lanczos/Arnoldi” (from Fortran package ARPACK).

[`lanczos.m` and `m06_lanczos.m`]

There are some video interviews of Cornelius Lanczos (1893–1974) on YouTube. You might enjoy watching a few minutes to get a sense of a remarkable man.

I.11 Numerical software tools and information sources

An online tour of the offerings at our course Web page under “Numerical Software Tools and Information Sources”

This site is a valuable resource. I recommend that you explore it in your browser, and read over the hardcopy sheet at leisure.

[handout: `people.maths.ox.ac.uk/trefethen/tools.html`]