

Last time

Classification of critical points:

$\lambda_{1,2}$ real

- distinct, same sign:
node

- equal $\begin{cases} \text{star} \\ \text{inflected node} \end{cases}$

stable if λ 's < 0

un - - - - - > 0

- different signs \rightarrow saddle

Complex conjugate:
pair

- $\text{Re } \lambda = 0$
 \rightarrow centre
(periodic, ellipses)

- $\text{Re } \lambda > 0$ unstable spiral
 < 0 stable

\rightarrow gives good picture near
critical points of non-linear
systems

Today:

How to draw phase diagrams?

Remark:

Curves where $X(x,y) = 0$
resp. $Y(x,y) = 0$

are the ONLY place where
trajectories can and will
become vertical resp. horizontal
as there we have

$$\dot{x}(t_0) = X(x(t_0), y(t_0)) = 0$$

resp

$$\dot{y}(t_0) = 0.$$

These curves are called nullclines,
these intersect at critical points.

Ex. 1:

$$\dot{x} = x - y = X(x, y)$$

$$\dot{y} = 1 - xy = Y(x, y)$$

critical points:

$$x = y \text{ and } 1 = xy$$

$$p_1 = (1, 1), \quad p_2 = (-1, -1).$$

$$M(x, y) = \begin{pmatrix} 1 & -1 \\ -y & -x \end{pmatrix}$$

$$M(1, 1) = \begin{pmatrix} 1 & -1 \\ -1 & -1 \end{pmatrix}, \quad \chi(\lambda) = (1-\lambda)(-1-\lambda) - 1 \\ = \lambda^2 - 2$$

$$\text{so } \lambda_1 = -\sqrt{2}, \quad \underline{z}_1 = \begin{pmatrix} 1 \\ 1+\sqrt{2} \end{pmatrix}$$

$$\lambda_2 = \sqrt{2}, \quad \underline{z}_2 = \begin{pmatrix} 1 \\ 1-\sqrt{2} \end{pmatrix}$$

saddle

$$M(-1, -1) = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

$$\chi(\lambda) = (1-\lambda)^2 + 1 = 0$$

$$\lambda_{1,2} = 1 \pm i, \quad \operatorname{Re}(\lambda_i) = 1 > 0 \text{ unstable spiral}$$

$$B = -1 < 0 \text{ anticlockwise}$$

Nullclines:

$$X(x, y) = 0 \quad \text{"vertical"}$$

$$\boxed{y = x}$$

$$Y(x, y) = 0 \quad \text{"horizontal"}$$

$$\boxed{y = \frac{1}{x}}$$

$p_1 = (1, 1)$ saddle

$p_2 = (-1, -1)$ spiral

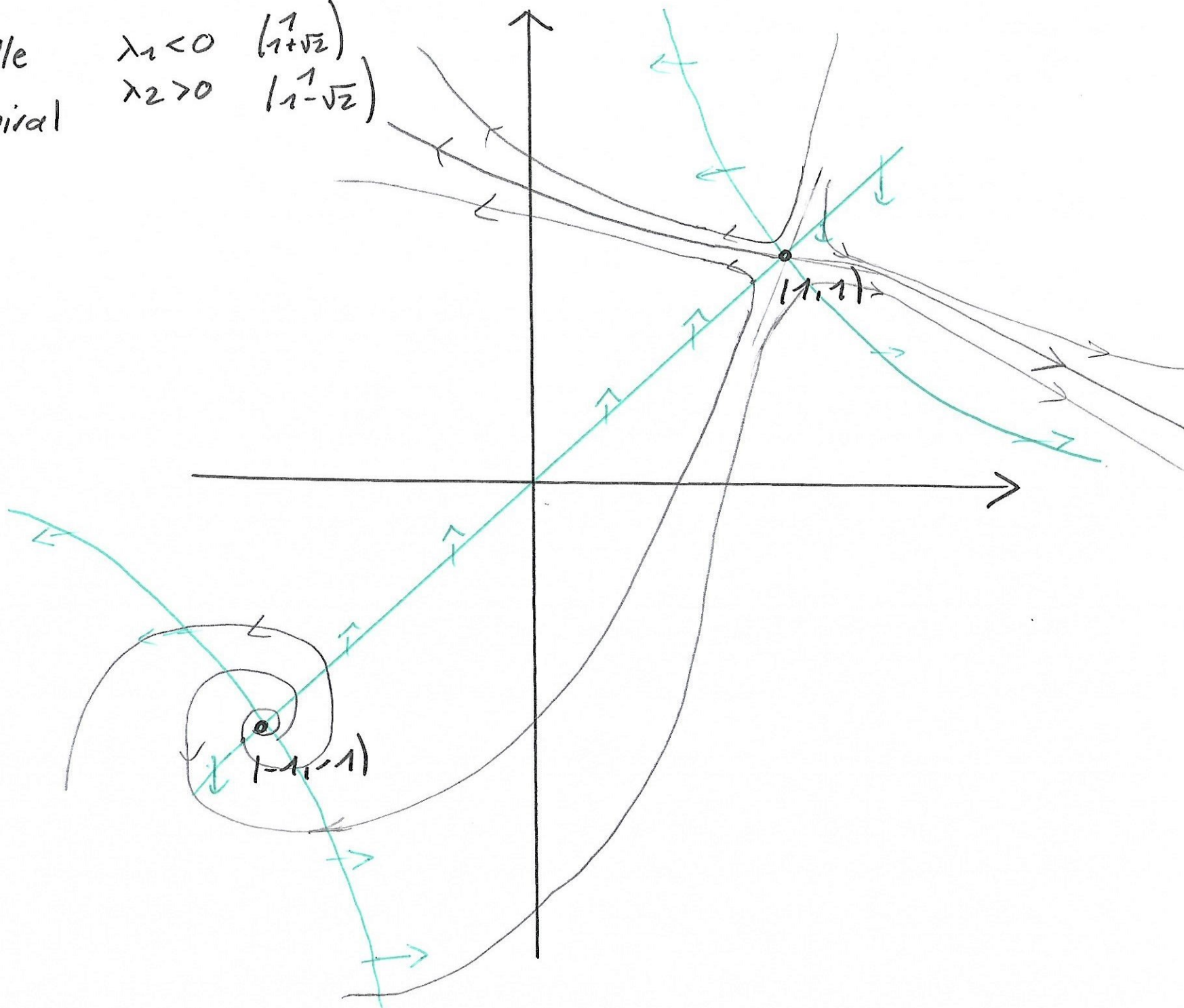
$$y = x \quad X = 0$$

$$y = \frac{1}{x} \quad Y = 0$$

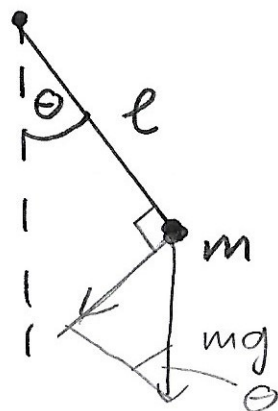
$$X(x, y) = x - y$$

$$Y(x, y) = 1 - xy$$

$$\lambda_1 < 0 \quad \begin{pmatrix} 1 \\ 1 + \sqrt{2} \end{pmatrix}$$
$$\lambda_2 > 0 \quad \begin{pmatrix} 1 \\ 1 - \sqrt{2} \end{pmatrix}$$



Ex 2 Damped pendulum:



$$m l \cdot \ddot{\theta} = -mg \cdot \sin \theta - mk l \dot{\theta}$$

$$k > 0$$

$$\text{Set } x = \theta, \quad y = \dot{x}$$

$$\begin{cases} \dot{x} = y \\ \dot{y} = -\frac{g}{l} \sin x - ky \end{cases}$$

crit. points: $y = 0, \quad x = \begin{cases} 2\pi n, & n \in \mathbb{Z} \\ 2\pi n + \pi, & n \in \mathbb{Z} \end{cases}$

$$M = \begin{pmatrix} 0 & 1 \\ -\frac{g}{l} \cos x & -k \end{pmatrix}$$

even mult. of π :

$$M = \begin{pmatrix} 0 & 1 \\ -\frac{g}{l} & -k \end{pmatrix}$$

For $k^2 < \frac{4g}{l}$ eigenval. are complex conjugates

As $\text{trace}(M) = -k < 0 \rightarrow$ stable spiral
 $1 > 0 \rightarrow$ clockwise

odd mult. of π : $M = \begin{pmatrix} 0 & 1 \\ \frac{g}{l} & -k \end{pmatrix}$

$\det(M) = -\frac{g}{l} < 0 \rightarrow$ saddle, $\lambda_1 < 0 < \lambda_2$

$$M - \lambda_1 I = \begin{pmatrix} + & + \\ - & - \end{pmatrix} \quad z_1 = \begin{pmatrix} + \\ - \end{pmatrix}, \quad M - \lambda_2 I = \begin{pmatrix} - & + \\ - & - \end{pmatrix}, \quad z_2 = \begin{pmatrix} + \\ + \end{pmatrix}$$

