

Numerical Solution of Differential Equations I

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Lecture 1

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The ODE (1) will be considered together with an **initial condition**: given two real numbers x_0 and y_0 , find a solution to (1) for $x > x_0$ such that

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The problem (1), (2) is called an **initial-value problem**.

Theorem (Picard's Theorem¹)

Suppose that $f(\cdot, \cdot)$ is a continuous function of its arguments in a region U of the (x, y) plane which contains the rectangle

$$R := \{(x, y) : x_0 \leq x \leq X_M, \quad |y - y_0| \leq Y_M\},$$

where $X_M > x_0$ and $Y_M > 0$ are constants.

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Suppose also, that there exists a positive constant L such that

$$|f(x, y) - f(x, z)| \leq L|y - z| \tag{3}$$

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suppose that $M(X_M - x_0) \leq Y_M$. Then, there exists a unique continuously differentiable function $x \mapsto y(x)$, defined on the closed interval $[x_0, X_M]$, which satisfies (1) and (2).

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$$\begin{aligned} y_0(x) &\equiv y_0, \\ y_n(x) &:= y_0 + \int_{x_0}^x f(\xi, y_{n-1}(\xi)) \, d\xi, \quad n = 1, 2, \dots, \end{aligned} \quad (4)$$

and show, using the conditions of the theorem, that $\{y_n\}_{n=0}^{\infty}$, as a sequence of continuous functions, converges uniformly on the interval $[x_0, X_M]$ to a continuous function y defined on $[x_0, X_M]$ s.t.

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$$y(x) = y_0 + \int_{x_0}^x f(\xi, y(\xi)) \, d\xi.$$

This implies that y is continuously differentiable on $[x_0, X_M]$ and it satisfies the differential equation (1) and the initial condition (2). The uniqueness of the solution follows from the Lipschitz condition.

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Picard's Theorem has a natural extension to an initial-value problem for a system of m differential equations of the form

$$\mathbf{y}' = \mathbf{f}(x, \mathbf{y}), \quad \mathbf{y}(x_0) = \mathbf{y}_0, \quad (5)$$

where $\mathbf{y}_0 \in \mathbb{R}^m$ and $\mathbf{f} : [x_0, X_M] \times \mathbb{R}^m \rightarrow \mathbb{R}^m$.

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Consider the Euclidean norm $\|\cdot\|$ on $\mathbb{R}^m$ defined by

$$\|v\| := \left(\sum_{i=1}^m |v_i|^2 \right)^{1/2}, \quad v \in \mathbb{R}^m.$$

We then have the following result.

Theorem (Picard's Theorem for systems)

Suppose that $\mathbf{f}(\cdot, \cdot)$ is a continuous function of its arguments in a region U of the $(x, \mathbf{y})$ space $\mathbb{R}^{1+m}$ containing the parallelepiped

$$R := \{(x, \mathbf{y}) : x_0 \leq x \leq X_M, \quad \|\mathbf{y} - \mathbf{y}_0\| \leq Y_M\},$$

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where $X_M > x_0$ and $Y_M > 0$ are constants.

Suppose also that there exists a positive constant L such that

$$\|\mathbf{f}(x, \mathbf{y}) - \mathbf{f}(x, \mathbf{z})\| \leq L\|\mathbf{y} - \mathbf{z}\| \quad (6)$$

holds whenever $(x, \mathbf{y})$ and $(x, \mathbf{z})$ lie in R . Finally, letting

$$M := \max\{\|\mathbf{f}(x, \mathbf{y})\| : (x, \mathbf{y}) \in R\},$$

suppose that $M(X_M - x_0) \leq Y_M$. Then, there exists a unique continuously differentiable function $x \mapsto \mathbf{y}(x)$, defined on the closed interval $[x_0, X_M]$, which satisfies (5).

We conclude by introducing the notion of *stability*.

Definition

A solution $\mathbf{y} = \mathbf{y}(x)$ to (5) is said to be **stable** on the interval $[x_0, X_M]$ if:

$$\forall \varepsilon > 0 \quad \exists \delta > 0 \quad \text{s.t.} \quad \forall \mathbf{z}_0 \in \mathbb{R}^m \quad \text{satisfying} \quad \|\mathbf{y}_0 - \mathbf{z}_0\| < \delta$$

the solution $\mathbf{z} = \mathbf{z}(x)$ to the differential equation $\mathbf{z}' = \mathbf{f}(x, \mathbf{z})$ satisfying the initial condition $\mathbf{z}(x_0) = \mathbf{z}_0$ is defined for all $x \in [x_0, X_M]$ and satisfies

$$\|\mathbf{y}(x) - \mathbf{z}(x)\| < \varepsilon \quad \text{for all } x \text{ in } [x_0, X_M].$$

Using this definition, we can state the following theorem.

Theorem

Under the hypotheses of Picard's Theorem, the (unique) solution $\mathbf{y} = \mathbf{y}(x)$ to the initial-value problem (5) is stable on the interval $[x_0, X_M]$, (where we assume that $-\infty < x_0 < X_M < \infty$).

PROOF: Since

$$\mathbf{y}(x) = \mathbf{y}_0 + \int_{x_0}^x \mathbf{f}(\xi, \mathbf{y}(\xi)) \, d\xi$$

and

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it follows that

$$\begin{aligned} \|\mathbf{y}(x) - \mathbf{z}(x)\| &\leq \|\mathbf{y}_0 - \mathbf{z}_0\| + \int_{x_0}^x \|\mathbf{f}(\xi, \mathbf{y}(\xi)) - \mathbf{f}(\xi, \mathbf{z}(\xi))\| \, d\xi \\ &\leq \|\mathbf{y}_0 - \mathbf{z}_0\| + L \int_{x_0}^x \|\mathbf{y}(\xi) - \mathbf{z}(\xi)\| \, d\xi. \end{aligned} \quad (7)$$

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Now put $A(x) := \|\mathbf{y}(x) - \mathbf{z}(x)\|$ and $a := \|\mathbf{y}_0 - \mathbf{z}_0\|$; then, (7) can be written as

$$A(x) \leq a + L \int_{x_0}^x A(\xi) \, d\xi, \quad x_0 \leq x \leq X_M. \quad (8)$$

Multiplying (8) by $\exp(-Lx)$, we find that

$$\frac{d}{dx} \left[e^{-Lx} \int_{x_0}^x A(\xi) d\xi \right] \leq a e^{-Lx}. \quad (9)$$

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Integrating the inequality (9), we deduce that

$$e^{-Lx} \int_{x_0}^x A(\xi) d\xi \leq \frac{a}{L} \left(e^{-Lx_0} - e^{-Lx} \right),$$

that is

$$L \int_{x_0}^x A(\xi) d\xi \leq a \left(e^{L(x-x_0)} - 1 \right). \quad (10)$$

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Now substituting (10) into (8) gives

$$A(x) \leq a e^{L(x-x_0)}, \quad x_0 \leq x \leq X_M. \quad (11)$$

[The implication “(8) $\Rightarrow$ (11)” is called **Gronwall's Lemma**.]

Returning to our original notation, we deduce from (11) that

$$\|\mathbf{y}(x) - \mathbf{z}(x)\| \leq \|\mathbf{y}_0 - \mathbf{z}_0\| e^{L(x-x_0)}, \quad x_0 \leq x \leq X_M. \quad (12)$$

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Thus, given $\varepsilon > 0$ as in Definition 3, we choose

$$\delta = \varepsilon e^{-L(X_M-x_0)}.$$

Then, if $\|\mathbf{y}_0 - \mathbf{z}_0\| < \delta$, it follows from (12) that

$$\|\mathbf{y}(x) - \mathbf{z}(x)\| < \varepsilon e^{-L(X_M-x_0)} e^{L(x-x_0)} \leq \varepsilon, \quad x_0 \leq x \leq X_M.$$

Therefore, the solution $\mathbf{y}$ is stable, as has been asserted. $\diamond$

Remark

A solution which is stable on $[x_0, \infty)$ (i.e. stable on $[x_0, X_M]$ for each X_M and with δ independent of X_M) is said to be **stable in the sense of Lyapunov**.

Moreover, if

$$\lim_{x \rightarrow \infty} \|\mathbf{y}(x) - \mathbf{z}(x)\| = 0,$$

then the solution $\mathbf{y} = \mathbf{y}(x)$ is called **asymptotically stable**.