#### Numerical Solution of Differential Equations I

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Lecture 7

# Convergence

#### Linear *k*-step method:

$$\sum_{j=1}^{k} \alpha_j y_{n+j} = h \sum_{j=1}^{k} \beta_j f_{n+j}, \qquad n = 0, 1, \dots, N-k,$$

 $h := (X_M - x_0)/N, N \gg 1, f_n := f(x_n, y_n), \alpha_k \neq 0, \alpha_0^2 + \beta_0^2 \neq 0.$ 

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What matters most from the practical point of view is that the numerical approximation  $y_n$  at the mesh-point  $x_n$  is close to the value of the analytical solution  $y(x_n)$ , for n = 0, ..., N, and that the **global error**  $e_n = y(x_n) - y_n$  tends to 0 when  $h \rightarrow 0$ .

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In order to formalise the desired behaviour, we introduce the following definition.

#### Definition

A linear multi-step method is said to be **convergent** if, for all initial-value problems y' = f(x, y),  $y(x_0) = y_0$ , subject to the hypotheses of the Cauchy–Picard theorem, we have that

$$\lim_{\substack{h\to 0\\nh=x-x_0}} y_n = y(x) \tag{1}$$

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holds for all  $x \in [x_0, X_M]$  and for all solutions  $\{y_n\}_{n=0}^N$  generated by the *k*-step method with **consistent starting conditions**, i.e., with starting conditions  $y_s = \eta_s(h)$ , s = 0, 1, ..., k - 1, for which  $\lim_{h\to 0} \eta_s(h) = y_0$ , s = 0, 1, ..., k - 1. We shall investigate the interplay between

- zero-stability,
- consistency, and
- convergence.

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The key result is **Dahlquist's Equivalence Theorem**, which states that for a consistent linear multi-step method zero-stability is necessary and sufficient for convergence.

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Necessary conditions for convergence

We show that both zero-stability and consistency are necessary for convergence.

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# Necessary conditions for convergence

We show that both zero-stability and consistency are necessary for convergence.

#### Theorem

A necessary condition for the convergence of a linear multi-step method is that it be zero-stable.

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### **Proof**:

Suppose that a linear multi-step method is convergent; we wish to show that it is then zero-stable.

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We consider the initial-value problem y' = 0, y(0) = 0, on the interval  $[0, X_M]$ ,  $X_M > 0$ , whose solution is, trivially,  $y(x) \equiv 0$ .

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Applying the method to this problem yields the difference equation

$$\alpha_k y_{n+k} + \alpha_{k-1} y_{n+k-1} + \dots + \alpha_0 y_n = 0.$$
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As the method is assumed to be convergent, for any  $x \in [0, X_M]$  we have

$$\lim_{\substack{h\to 0\\bh=x}} y_n = 0, \tag{3}$$

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for all solutions of (2) s.t.  $y_s = \eta_s(h)$ ,  $s = 0, \ldots, k-1$ , where

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$$\lim_{h \to 0} \eta_s(h) = 0, \qquad s = 0, 1, \dots, k - 1.$$
 (4)

(1) Let  $z = r e^{i\phi}$ , be a root of the first characteristic polynomial  $\rho(z)$ ;  $r \ge 0$ ,  $0 \le \phi < 2\pi$ .

$$y_n = hr^n \cos n\phi$$

define a solution to (2) satisfying (4). [Hint:  $\operatorname{Re}(z^n \rho(z)) = 0$ .]

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**CASE 1.1** If  $\phi \neq 0$  and  $\phi \neq \pi$ , then

$$\frac{y_n^2 - y_{n+1}y_{n-1}}{\sin^2 \phi} = h^2 r^{2n}.$$

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Since the left-hand side of this converges to 0 as  $h \rightarrow 0$ ,  $n \rightarrow \infty$ , nh = x, the same must be true of the right-hand side; therefore,

$$\lim_{n\to\infty}\left(\frac{x}{n}\right)^2r^{2n}=0.$$

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$$\lim_{n\to\infty}\left(\frac{x}{n}\right)^2r^{2n}=0.$$

This implies that  $r \leq 1$ . Thus we have proved that  $|z| \leq 1$ .

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$$|y_n| = hr^n |\cos n\phi| = hr^n = \frac{x}{n}r^n.$$

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As  $y_n \to 0$  when  $h \to 0$  and  $n \to \infty$ , the same must be true of the right-hand side. Thus, again, necessarily  $r \le 1$ , i.e.,  $|z| \le 1$ .

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Assume, for contradiction, that  $z = re^{i\phi}$  is a *multiple* root of  $\rho(z)$ , with |z| = 1 (and therefore r = 1) and  $0 \le \phi < 2\pi$ .

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We shall prove below that this contradicts our assumption that the method (2) is convergent. It is easy to check that the numbers

$$y_n = h^{1/2} n r^n \cos n\phi \tag{5}$$

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define a solution to (2). [Hint:  $\operatorname{Re}(nz^n\rho(z) + z^{n+1}\rho'(z)) = 0.$ ]

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define a solution to (2). [Hint:  $\operatorname{Re}(nz^n\rho(z) + z^{n+1}\rho'(z)) = 0.$ ]

In addition, (4) holds because

$$|\eta_{s}(h)| = |y_{s}| \leq h^{1/2} s \leq h^{1/2} (k-1), \qquad s = 0, \ldots k-1.$$

$$\frac{z_n^2 - z_{n+1} z_{n-1}}{\sin^2 \phi} = r^{2n},$$
 (6)

where  $z_n = n^{-1}h^{-1/2}y_n = h^{1/2}x^{-1}y_n$ .

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Thus we have reached a contradiction.

CASE 2.2 If, on the other hand,  $\phi = 0$  or  $\phi = \pi$ , it follows from (5) with h = x/n that

$$|y_n| = x^{1/2} n^{1/2} r^n.$$
(7)

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Since, by assumption, |z| = 1 (and therefore r = 1), we deduce from (7) that  $\lim_{n\to\infty} |y_n| = \infty$ , which again contradicts (3).

#### Theorem

A necessary condition for the convergence of a linear multi-step method is that it be consistent.

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Remark. In other words, we need to show that if a linear multi-step method is convergent, then

$$C_0=\sum_{j=0}^k\alpha_j=\rho(1)=0,$$

and

$$C_1 = \sum_{j=1}^k j\alpha_j - \sum_{j=0}^k \beta_j = \rho'(1) - \sigma(1) = 0.$$

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### **Proof**:

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Applying the method to this gives:

$$\alpha_k y_{n+k} + \alpha_{k-1} y_{n+k-1} + \dots + \alpha_0 y_n = 0.$$
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We supply "exact" starting values for the numerical method; i.e., we choose  $y_s = 1$ , s = 0, ..., k - 1. As, by hypothesis, the method is convergent, we deduce that

$$\lim_{\substack{h \to 0 \\ nh = x}} y_n = 1. \tag{9}$$

Since in the present case  $y_n$  is independent of the choice of h, (9) is equivalent to saying that

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Passing to the limit  $n \to \infty$  in (8), we deduce that

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By the definition of  $C_0$ , (11) is equivalent to  $C_0 = 0$ .

To show that  $C_1 = 0$ , we consider the initial-value problem y' = 1, y(0) = 0, on the interval  $[0, X_M]$ ,  $X_M > 0$ ; hence, y(x) = x.

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The method applied to this now becomes

 $\alpha_k y_{n+k} + \alpha_{k-1} y_{n+k-1} + \dots + \alpha_0 y_n = h(\beta_k + \beta_{k-1} + \dots + \beta_0), \quad (12)$ 

where  $X_M - x_0 = X_M - 0 = Nh$  and  $1 \le n \le N - k$ .

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$$\alpha_{k}y_{n+k} + \alpha_{k-1}y_{n+k-1} + \dots + \alpha_{0}y_{n} = h(\beta_{k} + \beta_{k-1} + \dots + \beta_{0}), (12)$$
  
where  $X_{M} - x_{0} = X_{M} - 0 = Nh$  and  $1 \le n \le N - k$ .

For a convergent method every solution of (12) satisfying

$$\lim_{h \to 0} \eta_{s}(h) = 0, \qquad s = 0, 1, \dots, k - 1,$$
(13)

where  $y_s = \eta_s(h)$ , s = 0, 1, ..., k - 1, must also satisfy

$$\lim_{\substack{h \to 0 \\ nh = x}} y_n = x.$$
(14)

By the previous theorem zero-stability is necessary for convergence; so the first characteristic polynomial  $\rho(z)$  of the method does not have a multiple root on the unit circle |z| = 1; therefore

$$\rho'(1) = k\alpha_k + \cdots + 2\alpha_2 + \alpha_1 \neq 0.$$

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Let the sequence  $\{y_n\}_{n=0}^N$  be defined by  $y_n = Knh$ , where

$$K = \frac{\beta_k + \dots + \beta_1 + \beta_0}{k\alpha_k + \dots + 2\alpha_2 + \alpha_1} = \frac{\sigma(1)}{\rho'(1)};$$
(15)

this sequence clearly satisfies (13) and is the solution of (12).

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this sequence clearly satisfies (13) and is the solution of (12).

Furthermore, (14) implies that

$$x = y(x) = \lim_{\substack{h \to 0 \\ nh = x}} y_n = \lim_{\substack{h \to 0 \\ nh = x}} Knh = Kx,$$

and therefore K = 1. Hence, from (15),

$$C_1 = (k\alpha_k + \dots + 2\alpha_2 + \alpha_1) - (\beta_k + \dots + \beta_1 + \beta_0) = 0.$$

# Sufficient conditions for convergence

## Theorem

For a linear multi-step method that is consistent with the ordinary differential equation y' = f(x, y), where f is assumed to satisfy a Lipschitz condition, and starting with consistent starting conditions, zero-stability is sufficient for convergence.

[Proof (optional): See the Lecture Notes.]

By combining the last three theorems we arrive at the following important result.



Germund Dahlquist (16 January 1925 - 8 February 2005)

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Germund Dahlquist (16 January 1925 – 8 February 2005)

# Theorem (Dahlquist's Theorem)

For a linear multi-step method that is consistent with the ordinary differential equation y' = f(x, y) where f satisfies the Lipschitz condition, and starting with consistent initial data, zero-stability is necessary and sufficient for convergence. Moreover if the solution y(x) has continuous derivative of order (p + 1) and consistency error  $\mathcal{O}(h^p)$ , then the global error  $e_n = y(x_n) - y_n$  is also  $\mathcal{O}(h^p)$ .

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In fact, if the root condition is violated then there exists a solution to the linear multi-step method which will grow by an arbitrarily large factor in a fixed interval of x, however accurate the starting conditions are. This highlights the importance of zero-stability in practical computations.

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