ELECRROMAGMETISM (PART B)

Chapter 1: Electrostatics (B)

Lecture 3

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[] Electrostatics electric phinomena involving <u>time independent</u> distributions of charges and fields

[Contents] (so far) [1.1) Gulombis Law [1.2] The electrostatic scalow potential (〒=-∇₫) [1.3] The Dirac delta Sumction (1.4) Gauss' law and Poisson's equation

Summying: lost lecture

$\nabla \cdot \vec{E} = \frac{1}{\epsilon_0} Q$ $\nabla \cdot \vec{E} = 0$ $\nabla \cdot \vec{E} = 0$ $\vec{E} = -\nabla \vec{E}$

Combining these into a single eq

$$\nabla^2 \Phi = - \frac{1}{\epsilon_0} e$$

 $\varepsilon_0 = - \frac{1}{\epsilon_0} e$
for $\overline{\Phi}$

Any volution give E by $E = - \nabla \Phi$ Also: $\vec{F} = q \vec{E}$ is the force on a test particle of charge q in the presence of the field $\vec{F} = q \vec{m}$ in the presence of $P(\vec{r})$

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[1.1) Coulomb's Law [1.2] The electrostatic scalow potential (〒=-∇∮) [1.3] The Dirac delta Sumption [1.4] Gauss' law and Poisson's equation (1.5) An important example , this lecture [I.L] Comductors and inmlators [1.7] Energy stored in the electric field

[1.5] An important example

illustratu

- . Gauss' law
- complications we find when trying to
 compute € or € when there are boundaring
 between regions in space

We have seen that for a continuous distribution of change Q(7) in a bounded region V we have

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di it's bution,

 $Q(\vec{r}) = \sum_{i=1}^{2} q_i \delta(\vec{r} - \vec{r}_i)$

 $\oint (\vec{r}) = \frac{1}{4\pi\epsilon_0} \int Q(\vec{r}') \frac{1}{(\vec{r}-\vec{r}')} dV'$ $\vec{r} \in V$ solves Poissoner. $\nabla^2 \overline{\Phi} = -\frac{1}{60} \rho$

 $\int More one: \Phi(\vec{x}) \sim \frac{C}{C} \quad \text{as} \quad r \to \infty$ $\int (Com you prove this?)$

OS COUNT: $\vec{E}(\vec{r}) = -\vec{\nabla} \vec{\Phi}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int Q(\vec{r}') \frac{\vec{r} - \vec{r}'}{(\vec{r} - \vec{r}')^2} dV$

BUT: what happens when there are changed surfaces in a region V?

Suppose there is a surface $\Sigma \subset \mathbb{R}^3$ which has a surface change density \mathcal{T} . (Σ :eq thin metal surface)

This configuration annountes an electric field $\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \sigma(\vec{r}) \frac{\vec{r} - \vec{r}'}{(\vec{r} - \vec{r}')} ds' \qquad smooth if \sigma is re z$ at all points $\vec{r} \in \mathbb{R}^3 \setminus \mathbb{Z}$.

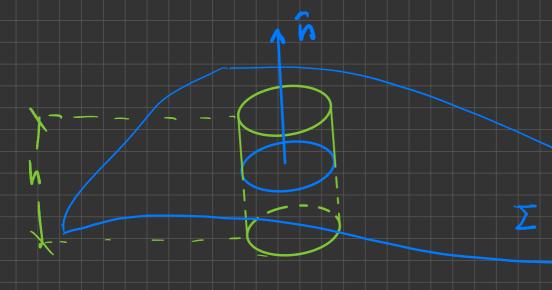
However: there is discontinuity in $\tilde{E}(\tilde{r})$ on one crosses Σ

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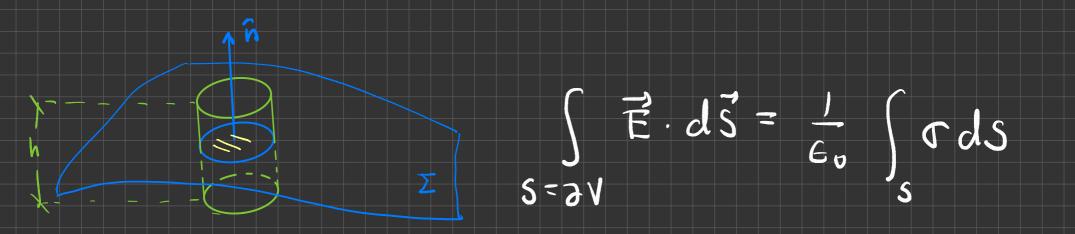
n = normal to Z in the direction of E in region 2

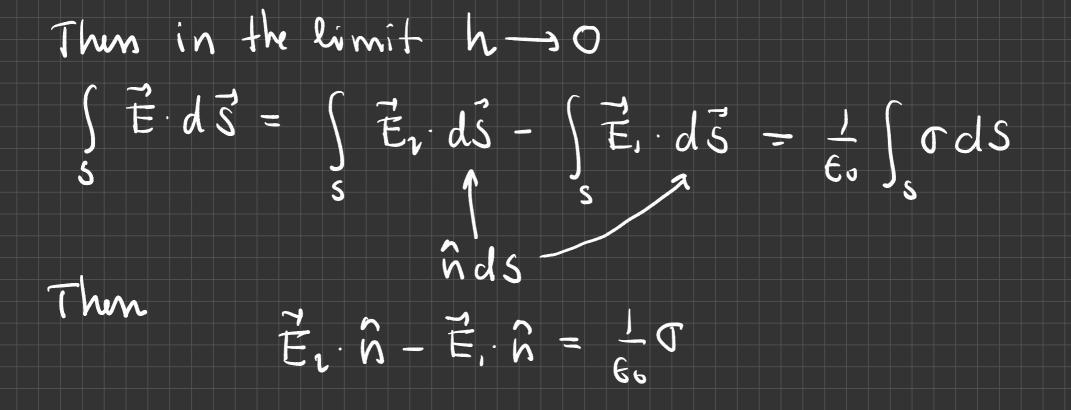
Proof of the claim: une Gauss' law



Convider a region V which is a cylinder of height h and cross sectional area SS

 $\begin{array}{l} Gomss'(aw) \Rightarrow \int \vec{E} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{E} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{E} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d\vec{s} = \frac{1}{\epsilon_0} \int \sigma ds \\ \int \vec{S} \cdot d$





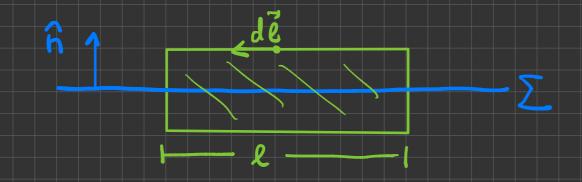
connidur instead a rectangular bop C = 3Abounding a rectangle A of hight h and length C $\hat{h} = \frac{d\hat{e}}{d\hat{e}}$

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Necule also \nabla A \vec{E} = 0. Thun

O = \int (\nabla A \vec{E}) \cdot dA = \int \vec{E} \cdot d\vec{e}

A notional \int C = \partial A

to \vec{A} stoke's theorem
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Thus
$$O = \int \vec{E} \cdot d\vec{e} = \int \vec{E}_1 \cdot d\vec{e} - \int \vec{E}_1 \cdot d\vec{e}$$

 $\vec{E} = \partial \vec{A} - \int \vec{C}_1 \cdot d\vec{e} - \int \vec{E}_1 \cdot d\vec{e}$

where $d\vec{e} = \hat{f} dl$, \hat{f} unif tangent vector along e $\vec{E}_2 \cdot \hat{f} = \hat{E}_1 \cdot \hat{f}$

or equivalently:
$$(\vec{E}_2 - \vec{E}_1) \cdot \vec{n} = 0$$

[1.6] Comductors and inmlators

A conductor is an object with a lawye number of size electrons (change corriers).

Conductors respond to extirnal electric fiels: the wee changes more around the material as brog as they experience a brue until they reach equilibrium

Two important con sequences

(1) In an static situation, inside a conductor $\vec{E} = 0$

becaux if it weren't thus by Contomb's laws the were elistions would continue to move 3 Suppose a conductor is placed in a region where there is an electric field \vec{E}_{ext} .

> -, Е=0

E_{ext}

Then the eletrops actorced to move until they reach the surface of the electric field invide reaches its apprilibrium and vanishes

One then hinds electrons very dose to the misace producing a musical change dimity I and they generate an electric field which precisely cancels First

More over: as $\vec{E}_{inide} = 0 = -\nabla \vec{\Phi}_{inide} \implies \vec{\Phi} = constant everywhere$ in the conductor is a conductor is an equipotential region of space An insulator, or dielectric material, on the other hand is an object with charged particles strongly bounded to molecules.

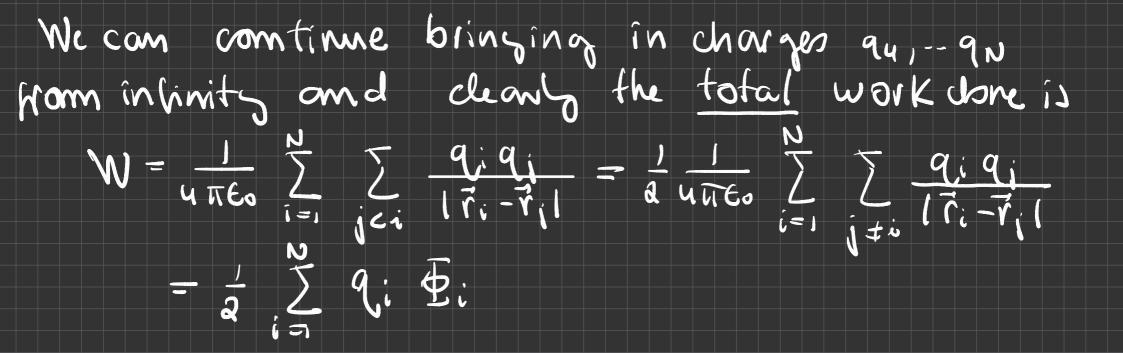
In the presence of an external electric field, charged powficles shift portions in repronse

changed ponnticles shift poritions in response but do not leave the vicinity of their molecules

[1.7] Energy stored in the electric field

Let q, be a point change at Ý. . The electrostatic potential $\phi_{1}(\vec{r})$ due to this charge's $\overline{\Phi}_{1}(\overline{r}) = \frac{q_{1}}{4\overline{n}6_{0}} \frac{1}{|\overline{r}-\overline{r}_{1}|} \quad \text{at} \quad \overline{r} \neq \overline{r}_{1}$ Considur mus another point charge q2 at infinity. In moving this charge from infinity to a point ?, we find that the work done in maxing the charge against the cluthic field \vec{E} , due to q, is $W_2 = q_1 \overline{P}_1(\overline{r}_1) = \frac{q_2}{u_{\pi 60}} \frac{q_1}{|\overline{r}_1 - \overline{r}_1|}$

Now move another change qo from infinity to B.



For a combinuous distribution $Q(\vec{r})$, the wolk done is $W = \frac{1}{a} \int_{V} Q(\vec{r}) \vec{\Phi}(\vec{r}) d^{3}x$ $\sum_{rotential energy} pre-unit charge stored$ $in the electric field <math>\vec{E} = -\nabla \vec{\Phi}$ We can write this retratial energy in turns of \vec{E} . And Gauss' (and to eliminate \vec{P} : $\vec{P} = \vec{E} \cdot \vec{\Phi} \cdot \vec{\nabla} \cdot \vec{E} = \vec{E} \cdot \vec{E} \cdot \vec{\nabla} \cdot \vec{E} = \vec{E} \cdot \vec{\nabla} \cdot \vec{E} \cdot \vec{E} \cdot \vec{E} \cdot \vec{E}$ $= \vec{E} \cdot \vec{\nabla} \cdot \vec{\nabla} \cdot \vec{E} = \vec{E} \cdot \vec{\nabla} \cdot \vec{E} \cdot \vec{E} \cdot \vec{E} \cdot \vec{E}$ $= \vec{E} \cdot \vec{\nabla} \cdot \vec{E} \cdot \vec{E} \cdot \vec{E} \cdot \vec{E} \cdot \vec{E} \cdot \vec{E}$

Thun $W = \frac{60}{a} \left\{ \int_{\partial V} \overline{\Phi} \vec{E} \cdot d\vec{S} + \int_{V} |\vec{E}|^2 dV \right\}$

Taking $V = \alpha$ very large ball of radius r and $\partial V = \alpha$ sphere \Rightarrow first turns vanishes when $\overline{\Phi} \sim \frac{c}{r}$ as $r \rightarrow \infty$



 $W = \frac{6}{a} \int_{R^3} \left[\vec{E} \right]^1 dV$

