B7.2 ELECTROMAGNETISM Chapter 3: Magnetostatics (Part2)

Lecture 10

	Magnetos tatics
√ [3.]]	Currents & construction of charge
	Biot-Savant Law & the magnetic field strength
	Differential equations for B
	Maznetic potential
[3.5]	Multipole expansion
3.6	Epilogue

13.4] The Magnetic potential A and the eqs of magnetostatics in torms of A

Recall eys for electrostatics: $\nabla^2 \vec{p} = -\frac{1}{60} \vec{p}$, $\vec{E} = -\nabla \vec{p}$ \vec{p} defined only up to a constant $\nabla \cdot \vec{E} = \frac{1}{\epsilon_0} \rho \quad \boldsymbol{\leftarrow}$ VNE=0 For may netos fatics we have $\nabla \cdot \vec{B} = 0$ 17 VNB=MJ

Connder J.B=0. Then there exists \vec{A} st \vec{B} = $\nabla_A \vec{A}$ À : magnetic vertis potential À is mt unique: "zange transformation" $\vec{A} \longrightarrow \vec{A}' = \vec{A} + \vec{\nabla} \vec{\nabla}$ Leans 3 machanged for and V. $\begin{bmatrix} \vec{B} = \vec{\nabla} \cdot \vec{A}' = \vec{\nabla} \cdot \vec{A} \quad (\vec{A} - \vec{A}) = \vec{O} \quad \vec{A} - \vec{A} = \vec{\nabla} \cdot \vec{A} \\ \text{(p) nome } \vec{K} \end{bmatrix}$

We will exphit this freedom to simplify resulting equation for A.

Now can viden $\nabla_{\Lambda}\vec{B} = M_{6}\vec{J}$ together with $\vec{B} = \nabla_{\Lambda}\vec{A}$ to find an equation $\vec{h}\vec{r}\vec{A}$ $\nabla \Lambda (\nabla \Lambda \vec{A}) = \nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A}$ $- O^{2}\vec{A} + \nabla(\nabla \cdot \vec{A}) = \mu_{0}\vec{J}$ Thm (+) let $\vec{A}' = A + \nabla N$. Then $\nabla \cdot \vec{A}' = \nabla \cdot \vec{A} + \nabla^2 \kappa$ mil (su) $iJ = -\nabla^2 \vec{A}' + \nabla (\nabla \cdot \vec{A}') = Mo \vec{J}$ VAB on can N such that $\nabla \cdot \tilde{A}' = 0$ Choox alar any do this $-\nabla^{2}\vec{A}' = M_{0}\vec{J}$ $\nabla\cdot\vec{A}' = 0$ Then

Drop the primes:

- $\nabla^2 \vec{A} = M_0 \vec{J} \in Poisson's eq ar each$ $<math>\nabla \cdot \vec{A} = 0$ PLOSENT Jamps (Lorentz)

Nerall : a solution of $\nabla \overline{\Phi} = \frac{1}{\epsilon_0} P$ which $\overline{\Phi} \to O(\frac{1}{\epsilon})$ os $1 \to \infty$

is
$$\oint (\vec{r}) = \int \int \rho(\vec{r}') \frac{1}{|\vec{r}-\vec{r}'|} dv'$$

It is not hand to see that for a current durvity $\tilde{i}(i)$

 $\vec{B} = \underbrace{M}_{utt} \int_{v} \vec{T}(\vec{r}') \wedge (\underbrace{\vec{r} - \vec{r}'}_{(\vec{r} - \vec{r}')} dV' = \nabla \wedge \vec{A}$ where $\vec{A} = \underbrace{M}_{utt} \int_{v} \vec{T}(\vec{r}') \underbrace{1}_{(\vec{r} - \vec{r}')} dV'$

but mu about $\nabla \cdot \vec{A} = 0$?

One can plove that $\nabla \cdot \vec{A} = 0$ if there are no anyonts at infinity: $\nabla \cdot \vec{A} = \frac{M_0}{n_{\overline{1}}} \int_{V} \nabla \cdot \left(\vec{T}(\vec{r}') \perp dV' \right)$ $= - \frac{\mu_0}{4\pi} \int_{V} \overline{J}(\overline{r'}) \cdot \nabla \left(\frac{1}{|\overline{r}-\overline{r'}|}\right) dV'$ $= -\frac{M_{0}}{4\pi} \int_{J} \left[\nabla' \left(\vec{J}(\vec{r}') \frac{1}{(\vec{r}-\vec{r}')} \right) - \frac{1}{(\vec{r}-\vec{r}')} \nabla' \cdot \vec{J}(\vec{r}') \vec{J} dV' \right] \\ = -\frac{M_{0}}{4\pi} \int_{J} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \\ = -\frac{M_{0}}{4\pi} \int_{S=\partial V} \frac{1}{(\vec{r}-\vec{r}')} \vec{J}(\vec{r}') \cdot d\vec{s}' \qquad \text{Sontinuity} \end{aligned}$ = 0 if there are no ano mits at infinity or in fact outside V including S= 2V if the arrivent is localited

Example consider a wire C with a line current distribution t $\vec{J} = \vec{J} + \vec{t} + \vec{t} \cdot \vec{t}$ constant $\vec{C} = \vec{J} + \vec{t} + \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot \vec{t} \cdot \vec{t} \cdot \vec{t}$ $\vec{t} \cdot$ 1_ Suppon the arrive C is powonnetrised by e Thus $\overline{A}(\overline{r}) = \frac{m}{4\pi} \int_{C} \frac{J de'}{|\overline{r}-\overline{r}'|} = \frac{msT}{4\pi} \int_{C} \frac{de'}{|\overline{r}-\overline{r}'|}$ $\vec{B}(\vec{r}) = \nabla A \vec{A}(\vec{r}) = \frac{M_0 T}{4 t \tau} \int_{e} \nabla A(\frac{1}{|\vec{r}-\vec{r}'|}) d\vec{L} = \frac{M_0 T}{4 t \tau} \int_{e} d\vec{L}' A \frac{\vec{r}-\vec{r}'}{|\vec{r}-\vec{r}'|}$ generaly hand to evaluate!

$\frac{\nabla comple}{dt}: compute the brue but we en two onto the provide with$ $<math display="block">C_{1} = \frac{1}{2} \frac{1}{dt}: \qquad C_{1} = \frac{1}{2} \frac{1}{dt}: \qquad C_{2} = \frac{1}{2} \frac{1}{dt}: \qquad C_{1} = \frac{1}{2} \frac{1}{2} \frac{1}{dt}: \qquad C_{2} = \frac{1}{2} \frac{1$

Consider an element of wire in C_2 at P_2 with tangent der. Then by the country force law $d\vec{F} = T_2 \vec{P}_2 \wedge \vec{B}$.

 $d\vec{F} = I_{d}\vec{e}_{x} \wedge \vec{B},$ is the force on the dumminer at P_{x} due to the magnetic field generated by I_{1} in \mathcal{C}_{1} . Intergraphing $\vec{F} = \int I_{x} d\vec{e}_{x} \wedge \vec{B}, = \frac{\mu_{0}}{4\pi} I_{1} I_{1} \int_{\mathcal{C}_{x}} \int_{\mathcal{C}_{x}} d\vec{e}_{x} \wedge d\vec{e}_{1} \wedge \frac{\vec{r}_{1} - \vec{r}_{1}}{(\vec{r}_{z} - \vec{r}_{1})}$ (total form on \mathcal{C}_{x} due to \vec{B}_{x} general \vec{P}_{x} on \mathcal{C}_{x}

[3.5] Multipole expansion

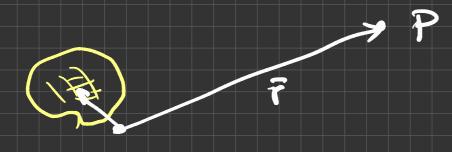
In this subsection we are intersted in studying the electrostatic β magnetostatic fields of a localized charry distribution $\rho(r)$ or current distribution T(r)

[What we are learning in this section applies in other areas, as for example the study of gravitational waves in GR] Consider the magnetic field B(F) due to a graval current distribution J(F) localited in a small region of space V

> L'small relative to the distance to the observation point

We know that the magnetostatic potential is $\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_{V} \frac{1}{\vec{r} - \vec{r}'} \vec{J}((\vec{r}')) dV'$

we want to evaluate the integral for IF1>>17'1



How? une Taylor miles expansion of $\frac{1}{(\vec{r}-\vec{r}')}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ $\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + O(r^{-3}) \quad \text{enervise ror'}$ C_{sum} of moments of $\overline{J}(\overline{r})$ We have then

 $\vec{A}(\vec{r}) = \frac{M_0}{u\pi} \int_{V} \left(\frac{1}{r} + \frac{1}{r^3} \vec{r} \cdot \vec{r}' + \Theta(r^3) \right) \vec{J}(\vec{r}') dV'$

 $= \frac{M_{0}}{4\pi} \int_{\tau} \frac{1}{7} \int_{\tau} \tilde{J}(\tilde{r}') dv' + \frac{1}{r^{3}} \int_{\tau} \tilde{r} \cdot \tilde{r}' \tilde{J}(\tilde{r}') dv' + \frac{1}{r^{3}} \int_{\tau} \tilde{r}' \tilde{J}(\tilde{r}') dv' + \frac{1$

Tool to compute this: (Jackson)

 $\int_{V} \left[f(\vec{r}') \ \vec{J}(\vec{r}') \cdot \vec{V}' q(\vec{r}') + q(\vec{r}') \ \vec{J}(\vec{r}') \cdot \vec{V}' f(\vec{r}') \ \vec{J}(\vec{V}') + q(\vec{r}') \ \vec{J}(\vec{r}') \cdot \vec{V}' f(\vec{r}') \ \vec{J}(\vec{V}') + q(\vec{r}') \ \vec{J}(\vec{r}') \cdot \vec{V}' f(\vec{r}') \ \vec{J}(\vec{V}') + q(\vec{r}') \ \vec{J}(\vec{r}') \cdot \vec{V}' f(\vec{r}') \ \vec{J}(\vec{V}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \ \vec{J}(\vec{V}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \ \vec{J}(\vec{V}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \ \vec{J}(\vec{V}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' q(\vec{r}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \ \vec{J}(\vec{r}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' q(\vec{r}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' q(\vec{r}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' q(\vec{r}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' q(\vec{r}') + q(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' f(\vec{r}') \cdot \vec{V}' q(\vec{r}') \cdot \vec{V}' q(\vec{r}') + q(\vec{r}') \cdot \vec{V}' q(\vec{r}') \cdot \vec{V} q(\vec{r}') \cdot \vec{V} q(\vec{r}') \cdot \vec{V}' q(\vec{r}') \cdot \vec{V} q(\vec{r}')$

► For f = 1 and $g = x_i$ $\int_{V} \overline{f(z')} \cdot \nabla' x_i' = \int_{V} \overline{f(z')} dV = 0$ $\implies \int_{V} \overline{f(z')} dV' = 0$ as expected. For $f = x_i$ & $\Im = x_j$ $\int x'_i \overline{T(r')} \cdot \overline{D'x'_j} + x'_j \overline{T(r')} \cdot \overline{D'x_j}$ $= \int (x'_i \overline{J_j}(r') + x'_i \overline{T_i(r')}] = 0$

So $\int \vec{F} \cdot \vec{F} \cdot \vec{f}(\vec{F}') dV' = \sum_{i,j} x_i \left(\int_{V} x_i' T_j(\vec{F}') dV' \right) \hat{e}_i$ $= \frac{1}{a} \sum_{i,j} X_i \int (X_i J_j (\vec{r}') - X_j' J_i (\vec{r}') dv' \hat{e}_j'$ $= -\frac{1}{a} \vec{r} \wedge \int_{V} \vec{r}' \wedge \vec{J}(\vec{r}') dv'$ $\vec{a} \cdot (\vec{b} \cdot \vec{c}) = -(\vec{a} \cdot \vec{b})\vec{c} + (\vec{a} \cdot \vec{c})\vec{b}$

Aming this in A(r) $A(\vec{r}) = \frac{M_0}{4\pi} \left\{ \frac{1}{r} \int_{\tau} \vec{J}(\vec{r}') dv' + \frac{1}{r^3} \int_{\tau} \vec{F} \cdot \vec{r}' \vec{J}(\vec{r}') dv' + \cdots \right\}$ $= 0 + \frac{M_0}{4\pi} \left(-\frac{1}{2}\right) \vec{r} \wedge \int_V \vec{r}' \wedge \vec{f}(\vec{r}') dV' + \cdots$ no monopoles dipole moment of J moments of J $\vec{A}(\vec{r}) = 0 + \frac{u_0}{u_{\overline{1}\overline{1}}} \frac{1}{r^3} \vec{m}_{1}\vec{r} + \cdots$ which we can write as magnetic dipole vector potential J, řn J(ř)dV magnetic, moment of J magnetitation dipole (magnetitation denity) where $\tilde{m} = \frac{1}{a} \int_{V} \tilde{r}' n \tilde{J}(\tilde{r}') dV'$

We can now compute the magnetic field outside a localised burge

$$\vec{B} = \nabla_{\Lambda} \vec{A} - \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \nabla_{\Lambda} (\vec{M}_{\Lambda} + \vec{f}) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \left\{ \left(\nabla \cdot (\vec{f} \cdot \vec{r}) \right) \vec{M} - \vec{M} \cdot \nabla (\vec{f} \cdot \vec{r}) \right\} + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \frac{1}{f_{3}} \left(-\vec{M} + \frac{2}{f_{3}^{2}} (\vec{M} \cdot \vec{r}) \vec{r} \right) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \frac{1}{f_{3}^{3}} \left(-\vec{M} + \frac{2}{f_{3}^{2}} (\vec{M} \cdot \vec{r}) \vec{r} \right) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \frac{1}{f_{3}^{3}} \left(-\vec{M} + \frac{2}{f_{3}^{2}} (\vec{M} \cdot \vec{r}) \vec{r} \right) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \frac{1}{f_{3}^{3}} \left(-\vec{M} + \frac{2}{f_{3}^{2}} (\vec{M} \cdot \vec{r}) \vec{r} \right) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \frac{1}{f_{3}^{3}} \left(-\vec{M} + \frac{2}{f_{3}^{2}} (\vec{M} \cdot \vec{r}) \vec{r} \right) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \frac{1}{f_{3}^{3}} \left(-\vec{M} + \frac{2}{f_{3}^{2}} (\vec{M} \cdot \vec{r}) \vec{r} \right) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \frac{1}{f_{3}^{3}} \left(-\vec{M} + \frac{2}{f_{3}^{2}} (\vec{M} \cdot \vec{r}) \vec{r} \right) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \frac{1}{f_{3}^{3}} \left(-\vec{M} + \frac{2}{f_{3}^{2}} (\vec{M} \cdot \vec{r}) \vec{r} \right) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}}{\mathcal{M}_{\Pi}} \frac{1}{f_{3}^{3}} \left(-\vec{M} + \frac{2}{f_{3}^{2}} (\vec{M} \cdot \vec{r}) \vec{r} \right) + \cdots$$

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$$= O + \underbrace{\mathcal{M}_{0}} \frac{1}{f_{3}^{3}} \left(-\vec{M} + \frac{2}{f_{3}} (\vec{M} \cdot \vec{r}) \right) + \cdots$$

$$= O + \underbrace{\mathcal{M}_{0}} \frac{1}{f_{3}} \left(-\vec{M}$$

Field lines of \vec{B}_{diple} (some as for \vec{E}_{diple} with $\vec{m} \in \vec{D}$, $\mu_0 \in \vec{T}_0$)

Company with the electric field È due to a Budited change distribution P

 $\frac{1}{\Psi}\left(\vec{r}\right) = \frac{1}{4\pi\epsilon_0} \int_{V} \frac{1}{\left(\vec{r} - \vec{r}\right)} \frac{1}{\varphi(\vec{r}')} dV'$ for for mong the distribution " boks hille a a point change g a dipole with dipole mommt p lez p=qē -1) -q ē

Example: Suppon the same of contract is a distant airmit le cuvizing a contant avvant I

The potential is

 $A(\vec{r}) = \frac{M \circ I}{4 \tau \tau} \int_{e} \frac{1}{(r-\hat{r})} d\ell'$ hand

 $= \underbrace{M_{0}}_{4\pi r^{3}} \qquad \widehat{M}_{\Lambda} \vec{r} + \cdots$

magnetic dipole

Sav anon it needs more "looks" like a details about details about the grometry of C

C

Convecalarlate m?

$\vec{m} = \frac{1}{a} \int_{V} \vec{r}' \cdot \vec{j}(\vec{r}') dV' = \frac{1}{a} \oint_{C} \vec{r}' \cdot d\vec{r}$

Assume the wire liss on a plane.

Thus mis promotional to the plane of the wire Now note That

 $\frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular element} \\ \frac{1}{a} |\vec{F} \wedge d\vec{e}| = da \qquad \text{triangular ele$

⇒ (m) = I. Area regardless of the shape of the circuit Higher moments of J need more detailed knowledge of the zometrus of C



The magnetic field of a magnet excerts a force on certain material as for example "furromagnetic" materials eg iron

A maynet has a magnetic field maint due to its manutic dipole moment Compare the magnitudes of magnetic fields of different objects: ~10° Tesla repriserator magnet • Superconducting magnets in CERN (diffe magnets) ~ 8 Tesla 25-65 10° Tesla on the surface Earth's magnetic field
 p (~ magnetic dipole) of eiguid 110n · grenated by Zanth's core · shields acconnot radiation Worm the sun by deficiting cosmic rays and changed particles in solar wind (stream of changed pandicles icleand from the sun) • anioias

· MRI

~1.5-3 Teslas

~ 2x Bcarth • Sum I not weid; plasma, send conductor How do we know? For example: Reeman effect to measure magnetic fields L splitting of eight into "nonnporments" in the presence of a static field

10⁴-10¹¹ Îosla - Neutron stans I some of the most fascinating objects in the universe wy small m~1.5 MsvN r~10 km smallest densest stavs, almost entitles composed of neutrons (neutral particles in the nucleans of atoms with Mneuwon ~ Mproton) new newtron stars lotate - 100 times on sec (linear mi face speed c/4) C=300000 km/sc (compare : the Jun votation priod ~ 25 days at its equator)

Next: time vanjang Q & J and Maxuell's equations