

# B7.2 ELECTROMAGNETISM

Chapter 6 : Electromagnetism and  
special relativity

Lecture 17  
(Last lecture !)

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## 6 Electromagnetism & special relativity

The forces of nature as they were understood at the end of 19th C were the following:

Newtonian mechanics (~1670)

$$\vec{F} = m \vec{a}$$

Newton's law of gravitation (~1670)  $\vec{F} = G m m' \frac{1}{r^2} \vec{r}$

Maxwell's theory of electromagnetism (~1864)

Einstein's theory of special relativity, proposed by Einstein in 1905, is a model for space time ( $\mathbb{R}^4$ ) and its symmetries, derived from two axioms.

It resolved an inconsistency that appeared at the end of the 19th century between Newtonian mechanics & Maxwell's laws of electromagnetism

↳ the inconsistency was due to Newtonian conceptions of space time

Special relativity describes the motion of particles and bodies (mechanics!) and replaces Newtonian mechanics. It

- ▶ reduces to Newtonian mechanics in the limit  $v \ll c$
- ▶ is experimentally confirmed
- ▶ is good up to large scales when gravitational effects become important  $\rightarrow$  general relativity
  - ↑ (e.g. gravitational field of a black hole causes spacetime to curve)



## Axiom 1

### Principle of <sup>special</sup> relativity

\* all laws of physics must be consistent with  
special relativity \*

in particular:

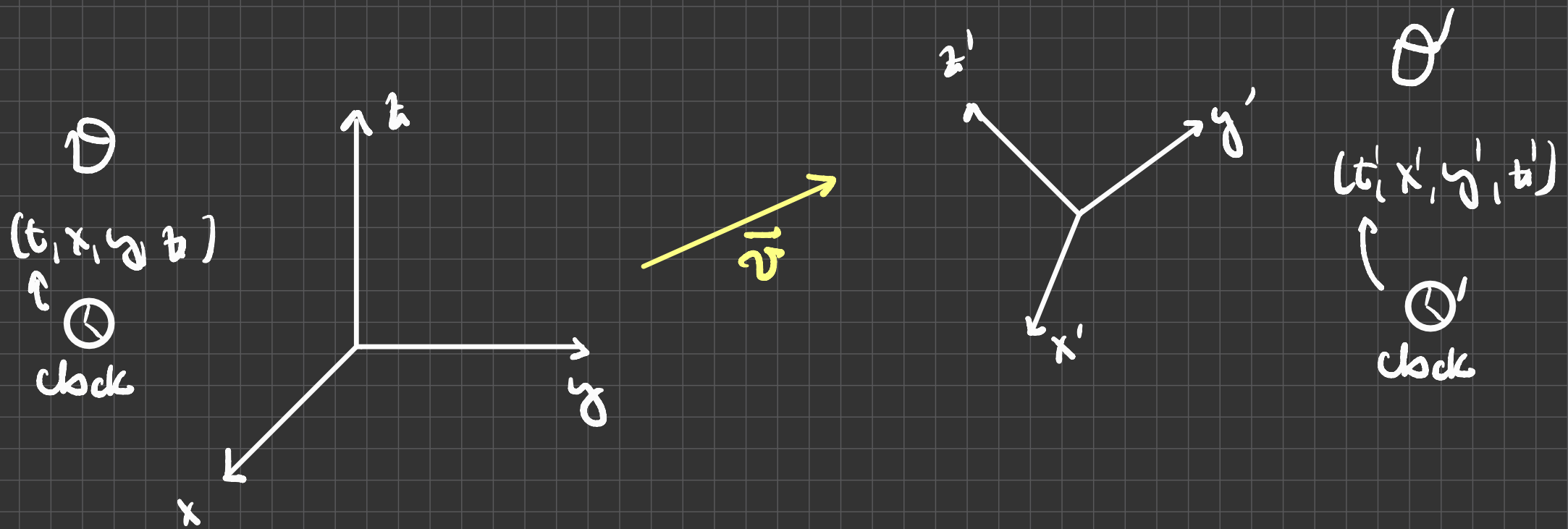
- Maxwell's equations are  
(and they unify electric & magnetic forces)
- Newtonian mechanics isn't!  
↑ but they under the Principle of Galilean  
relativity instead.

moving constant velocity  
relative to each other

Consider the reference frame of two inertial observers  $\mathcal{O}$  &  $\mathcal{O}'$

$\mathcal{O}$  sets up a coordinate system to make measurements  
 $(t, x, y, z)$

$\mathcal{O}'$  sets up a coordinate system to make measurements  
 $(t', x', y', z')$



how are these IRFs related?

$S$  &  $S'$  develop laws of physics by making measurements in their own reference frames:  
how do these laws compare?

# Galileo says (Galilean relativity)

$$t' = t + t_0 \quad \leftarrow \text{constant}$$

$$\Rightarrow \Delta t' = \Delta t$$

time interval between two events is the same wrt  $\mathcal{O}$  &  $\mathcal{O}'$

Galilean transformation

$$\begin{pmatrix} x' \\ y' \\ t' \end{pmatrix} = R \begin{pmatrix} x \\ y \\ t \end{pmatrix} - \vec{v} t$$

rotation  
in  $\mathbb{R}^3$

position of the origin of  $\mathcal{O}$  at  $\vec{v} t$  wrt  $\mathcal{O}'$

- Newtonian mechanics is invariant under Galilean transformations ✓

eg  $\mathcal{O}$  would say  $\vec{F} = m\vec{a}$   
 $\mathcal{O}'$  would say  $\vec{F}' = m\vec{a}'$

- Lorentz says: Maxwell's equations **are not** invariant under Galilean transformations!

For example: the wave eq is not invariant under Galilean transformations

Suppose  $f'(t', \vec{r}')$  satisfies the wave eq wrt  $\Theta'$

$$\square' f' = -\frac{1}{c^2} \frac{\partial^2 f'}{\partial t'^2} + \nabla'^2 f' = 0$$

Then with respect to  $\Theta$ ,  $f(t, \vec{r}) = f'(t', \vec{r}')$  satisfies

$$\square f - \frac{2}{c^2} \vec{v} \cdot \nabla \frac{\partial f}{\partial t} + \frac{1}{c^2} (\vec{v} \cdot \nabla)(\vec{v} \cdot \nabla f) = 0$$

**Clearly a problem in electromagnetism.**

Instead Maxwell's equations are invariant under affine linear transformations of spacetime  $\mathbb{R}^4$

Lorentz transformation  
(see below)

$$\begin{pmatrix} t' \\ x' \\ y' \\ z' \end{pmatrix} = L \begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix} + C$$

$\uparrow$   
 $\mathbb{R}^4$

$\uparrow$   
constant  $4 \times 4$  matrix

$\uparrow$   
constant 4-vector

$\downarrow$   
 $\mathbb{R}^4$

# Postulates of special relativity:

- ▶ Laws of physics are the same in **all** inertial reference frames (IRF)

IRFs  $\rightarrow$  frames moving with constant velocity relative to each other

so for electromagnetism this means that laws on distributions of charges and currents are described by Maxwell's equations with  $\epsilon_0, \mu_0$  in **any** IRF

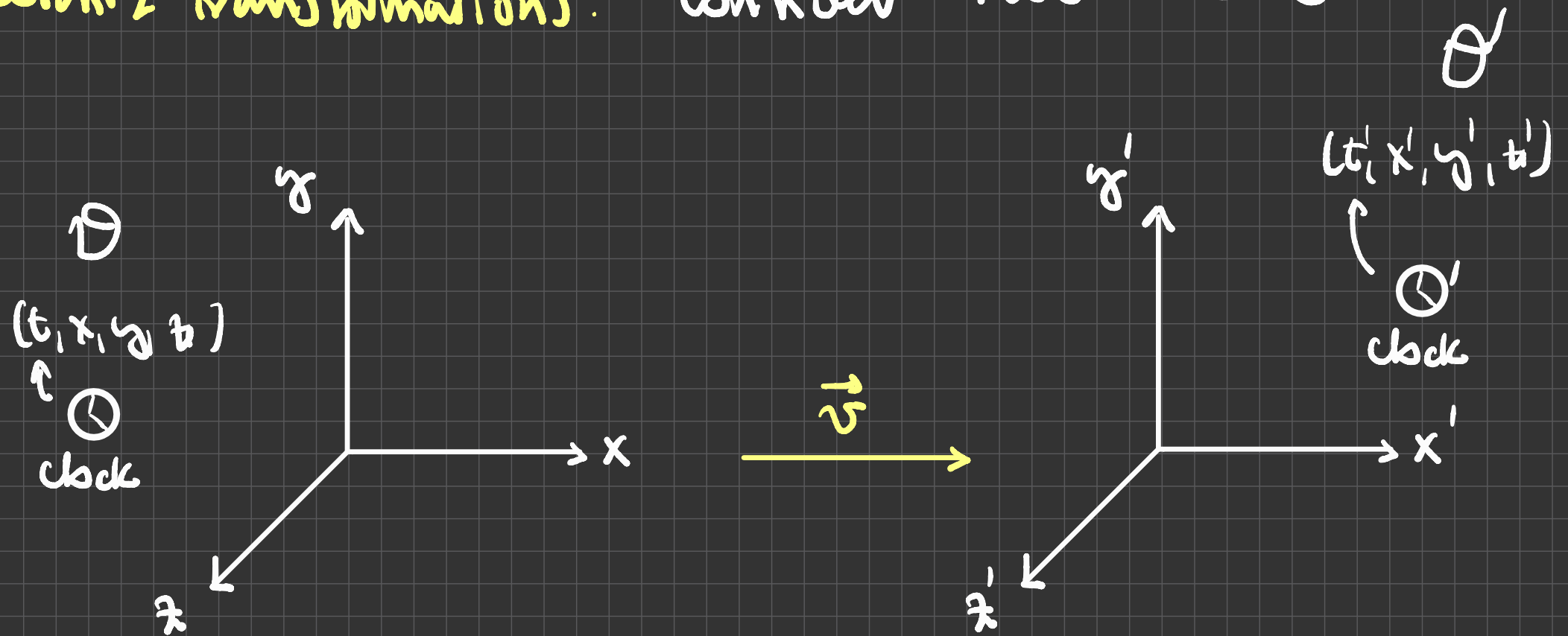
- ▶ The speed of light  $c = (\epsilon_0 \mu_0)^{-1/2}$  is the **same** in all IRFs.

Einstein proved that Lorentz transformations follow from these postulates

- ▶ replace Newtonian mechanics by special relativity
- ▶ Maxwell's equations already invariant  
In particular electromagnetic waves in vacuum move with velocity  $c$  in any IZF



Lorentz transformations: Consider two IZFs:



assume: at  $t = t' = 0$  the origin of  $O$  coincides  
with the origin of  $O'$   
and suppose that at this moment a flash light  
is sent.

This flash of light expands spherically with velocity  $c$  with respect to both IZFs

with respect to  $\mathcal{O}$ : at a time  $t$  in their clock this sphere has equation

$$x^2 + y^2 + z^2 = (\underbrace{ct}_{\text{distance traveled}})^2$$

↑ distance traveled

with respect to  $\mathcal{O}'$ : at a time  $t'$  in their clock this sphere has equation

$$x'^2 + y'^2 + z'^2 = (\underbrace{ct'}_{\text{distance traveled}})^2$$

↑ distance traveled

Galileo would have said that these observations are related by

$$t' = t$$

$$x' = x - vt$$

$$y' = y$$

$$z' = z$$

Hence

$$x'^2 + y'^2 + z'^2 = (x - vt)^2 + y^2 + z^2$$

$$(ct')^2 = (ct)^2$$

which is inconsistent with the predictions of  
electromagnetism

On the other hand Lorentz, Poincaré, Einstein would have said that the linear transformation

$$X' = LX, \quad X' = \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} \quad X = \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} \quad (\text{on } \mathbb{R}^4)$$

which leaves the equation

$$-(ct)^2 + x^2 + y^2 + z^2 = X^T \eta X, \quad \eta = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$= 0$

invariant is :

$$ct' = \frac{1}{\sqrt{1-v^2/c^2}} (ct - \frac{v}{c}x)$$

$$x' = \frac{1}{\sqrt{1-v^2/c^2}} (x - vt)$$

$$y' = y$$

$$z' = z$$

$$\text{ie } L = \begin{pmatrix} \gamma & -\gamma \frac{v}{c} & 0 & 0 \\ -\frac{v}{c}\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\gamma = \frac{1}{\sqrt{1-v^2/c^2}} > 1$$

$L$  is not well defined when  $v > c$

(Lorentz found this from Maxwell's eqs)

no real valued  
transformations  
when  $v > c$  between  
 $\mathcal{O}$  &  $\mathcal{O}'$

Sketch of the proof:

let  $X' = LX$  for some  $4 \times 4$  matrix  $L$

$$\underbrace{X'^T \eta X'}_{\text{"0"}} = X^T \underbrace{(L^T \eta L)}_{\text{"0"}} X = \underbrace{X^T \eta X}_{\text{"0"}}$$

Hence  $L^T \eta L = \mu \eta$  for some  $\mu \in \mathbb{R}$

[  $\mu = 1$  because  $\underbrace{(L^{-1})^0}_{\text{"0"}} = \mu^{-1} \underbrace{L^0}_{\text{"0"}}$  ] non symmetric

Then  $L$   $4 \times 4$  matrices having  $\eta$  invariant  
[  $(L \in SO(1,3))$  ]  $L^T \eta L = \eta$

## Remarks:

11 For  $v \ll c$   $c = 300\,000 \text{ km/sec}$

$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}} = 1 + \frac{1}{2} \left(\frac{v}{c}\right)^2 + \dots$$

Then: Lorentz transformation  $\rightarrow$  Galilean transformation

compare for example: a car with  $v = 100 \text{ km/hr}$

$$v = 100 \frac{\text{km}}{\text{hr}} = \frac{1}{36} \text{ km/sec} \Rightarrow \left(\frac{v}{c}\right)^2 \sim (10^{-7})^2$$

2

►  $\mathcal{O}$  measures the length of a stationary bar and finds  $l$

$\mathcal{O}'$  says  $l'$

One can show :  $l' = \frac{1}{\gamma} l$  so  $l' < l$

►  $\mathcal{O}$  says that  $\Delta t$  is the time interval between two events at the same place in space

$\mathcal{O}'$  says  $\Delta t'$

Then :  $\Delta t' = \gamma \Delta t$  ie " $\mathcal{O}'$  is slower than  $\mathcal{O}$ "



### 3 Schrödinger equation in quantum mechanics

Let  $\psi(t, \vec{r})$ , respectively  $\psi'(t', \vec{r}')$ , be the wave function of a particle relative to  $\mathcal{O}$  and respectively  $\mathcal{O}'$ . Schrödinger's equation

$$-\frac{\hbar^2}{2m} \nabla^2 \psi + V \psi = i\hbar \frac{\partial \psi}{\partial t}$$

is invariant under Galilean transformations as long as  $V$  is and the wave function changes by a factor (so  $|\psi|^2 = |\psi'|^2$ )

Need to correct this  $\rightarrow$  relativistic quantum mechanics

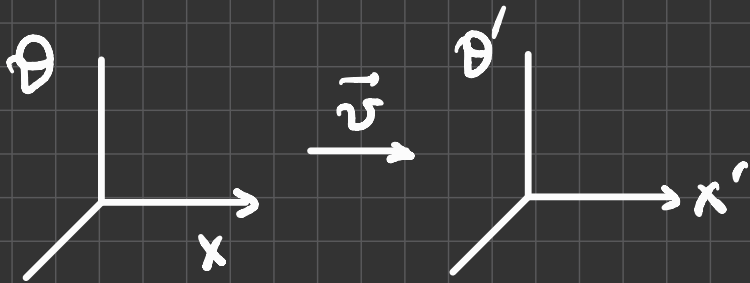
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Exercise: Under a Lorentz transformation

$$X' = LX$$

$$L = \begin{pmatrix} \gamma & -\gamma \frac{v}{c} & 0 & 0 \\ -\gamma \frac{v}{c} & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}} > 1$$



$$E'_x = E_x$$

$$B'_x = B_x$$

$$E'_y = \gamma(E_y - v B_z)$$

$$B'_y = \gamma\left(B_y + \frac{v}{c^2} E_z\right)$$

$$E'_z = \gamma(E_z + v B_y)$$

$$B'_z = \gamma\left(B_z - \frac{v}{c^2} E_y\right)$$

components along relative motion are the same

Then one can show that if  $\vec{E}$  &  $\vec{B}$  satisfy  
Maxwell's equations with respect to  $\mathcal{V}$  then so do  
 $\vec{E}'$  &  $\vec{B}'$  with respect to  $\mathcal{V}'$

$$\nabla' \cdot \vec{E}' = \frac{1}{\epsilon_0} \rho' \quad \dots \quad \nabla' \cdot \vec{B}' = 0 \quad \text{etc.}$$

$$\nabla \wedge \vec{E} + \frac{\partial}{\partial t} \vec{B} = 0$$

↖

Example Suppose that w/ a charge  $q$  is moving with constant velocity  $\vec{v} = v \hat{i}$

$$\text{so } \rho(t, \vec{r}) = q \delta(\vec{r} - \vec{r}_0(t))$$

↳ position of  $q$  at  $t$   
(eq of trajectory)

$$\vec{J}(t, \vec{r}) = q \vec{v} \delta(\vec{r} - \vec{r}_0(t)), \quad \vec{v} = \frac{d}{dt} \vec{r}_0(t)$$

↑  
constant

Chapter 4:

$$\Phi(t, \vec{r}) = \frac{q}{4\pi\epsilon_0} \int dt' \frac{1}{|\vec{r} - \vec{r}_0(t')|} \delta(t - t' - \frac{1}{c} |\vec{r} - \vec{r}_0(t')|)$$

$$\vec{A}(t, \vec{r}) = \dots$$

← etc.

Alternatively, in the particles' reference frame  $\Theta'$

$$\vec{E}' = \frac{q}{4\pi\epsilon_0} \frac{1}{r'^3} \vec{r}' \quad \& \quad \vec{B}' = 0$$

Using Lorentz transformations

$$\vec{r}' = \gamma(x - vt)\hat{i} + y\hat{j} + z\hat{k}$$

$$r'^2 = \gamma^2(x - vt)^2 + y^2 + z^2$$

$$0 = B'_x = B_x$$

$$B_x = 0$$

$$0 = B'_y = \gamma \left( B_y + \frac{v}{c^2} E_z \right) \Rightarrow B_y = -\frac{v}{c^2} E_z \iff \underline{\underline{\vec{B} = -\frac{v}{c^2} \hat{i} \wedge \vec{E}}}$$

$$0 = B'_z = \gamma \left( B_z - \frac{v}{c^2} E_y \right) \quad B_z = \frac{v}{c^2} E_y$$

$$E'_x = E_x \Rightarrow E_x = E'_x$$

$$E'_y = \gamma (E_y - v B_z) \Rightarrow E'_y = \gamma E_y \left( 1 - \frac{v^2}{c^2} \right) = \gamma^{-1} E_y \Rightarrow E_y = \gamma E'_y$$

$$E'_z = \gamma (E_z + v B_y) \Rightarrow E'_z = \gamma E_z \left( 1 - \frac{v^2}{c^2} \right) = \gamma^{-1} E_z \Rightarrow E_z = \gamma E'_z$$

$$\text{ie } \vec{E} = E'_x \hat{i} + \gamma E'_y \hat{j} + \gamma E'_z \hat{k}$$

using  $\vec{E}' = \frac{q}{4\pi\epsilon_0} \frac{1}{r'^3} \vec{r}'$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1}{r'^3} (x' \hat{i} + y' \hat{j} + z' \hat{k})$$

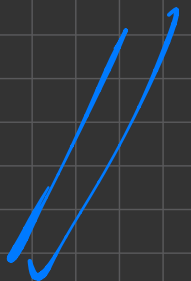
$$= \frac{q}{4\pi\epsilon_0} \frac{\gamma}{r'^3} ((x-vt) \hat{i} + y \hat{j} + z \hat{k})$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\gamma}{r'^3} (\vec{r} - \vec{v}t)$$

$$\vec{B} = -\frac{\gamma}{c^2} \vec{v} \times \vec{E}$$

where

$$r'^2 = \gamma^2 (x-vt)^2 + y^2 + z^2$$



End of the lecture course

Thank you !