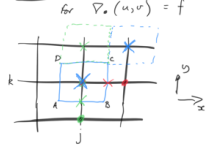


Finite Volume Method
for $\nabla \cdot (u, v) = f$



$$\iint_{\text{box}} \nabla \cdot (u, v) = \iint_{\text{box}} f$$

$$\int_{\partial \text{box}} (u, v) \cdot \Delta \, dS$$

approximated by

$$\int_A^B -v + \int_C^D u + \int_E^F v + \int_G^H -u = \iint_{\Omega} f$$

approximated by

$$-h \left(\frac{v_{j,k} + v_{j,l}}{2} \right) + h \left(\frac{u_{j,i} + u_{j,m}}{2} \right) + h \left(\frac{v_{j,k} + v_{j,l}}{2} \right) - h \left(\frac{u_{j,i} + u_{j,m}}{2} \right) = h^2 f_j$$

Numerical Methods for Hyperbolic Conservation Laws

Conservation Laws are of the form

$$\frac{\partial u}{\partial t} + \nabla \cdot f(u) = 0$$

where f is the flux.

So called because in any region Ω with boundary $\partial \Omega$, by integration we get

$$\frac{d}{dt} \iint_{\Omega} u \, dV + \iint_{\partial \Omega} f(u) \cdot \Delta \, dS = 0$$

so: rate of change of u in Ω = flux of u into Ω across $\partial \Omega$ (i.e. in the direction $-\Delta$)

for 1 spatial dimension

$$u_t + f(u)_x = 0$$

$$\Rightarrow \frac{d}{dt} \int_a^b u \, dx = -f(b) + f(a)$$

so the total amount of u is conserved if $a(u) = f'(u)$ then $u_x + a(u)u_x = 0$ and we have that for the shock $u(x,t)$

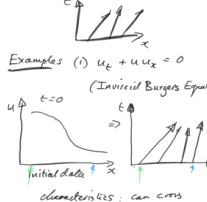
$$\frac{d}{dt} (u(x(t), t)) = \frac{du}{dx} \frac{dx}{dt} + \frac{du}{dt}$$

Chain Rule

$$= \left[\frac{dx}{dt} - a(u) \right] \frac{du}{dx} = 0$$

so u is constant on $\frac{dx}{dt} = a(u)$: characteristic curves and $a(u)$ constant on characteristic curves \Rightarrow characteristic curves are straight lines determined by initial data

Examples (1) $u_t + u u_x = 0$ (Inviscid Burgers Equation)

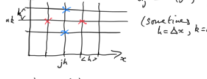


characteristics can cross \Rightarrow solution discontinuities or 'shocks'

(2) $u_t + \alpha u_x = 0$, $\alpha \neq 0$ constant
1D linear wave equation: characteristics are lines of slope $\frac{1}{\alpha}$ in $x-t$ space
This equation is also called the advection equation

We will initially concentrate on the linear wave equation and assume $\alpha > 0$ for definiteness
(\Rightarrow right moving wave solution)

Finite Difference Schemes



Simplest (A)

$$\frac{u_j^{n+1} - u_j^n}{\Delta t} + \alpha \frac{u_j^n - u_{j-1}^n}{\Delta x} = 0$$

or $u_j^{n+1} = u_j^n - \alpha \frac{u_j^n - u_{j-1}^n}{\Delta x}$

$\alpha \frac{\Delta x}{\Delta t} = \frac{\Delta x}{\Delta t}$ (Leapfrog) scheme

(A) 3 level scheme since 3 time levels involved

or (B)

$$u_j^{n+1} = u_j^n - \frac{\alpha}{2} (u_{j+1}^n - u_{j-1}^n)$$

turns out to be unstable, so not useful
but $u_j^{n+1} = u_j^n - \frac{\alpha}{2} (u_{j+1}^n - u_{j-1}^n)$

the 'Backward Euler' scheme is implicit

(C) Lax-Friedrichs scheme

$$u_j^{n+1} = \frac{1}{2} (u_{j+1}^n + u_{j-1}^n) - \frac{\alpha \Delta t}{2} (u_{j+1}^n - u_{j-1}^n)$$