

$$u_t + A u_x = 0$$

In general if $A = X \Lambda X^{-1}$

$$\text{with } \Lambda = \Lambda^- + \Lambda^+$$

$$\begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_p & 0 \\ & & & \ddots & \\ & & & & 0 \end{bmatrix} \begin{bmatrix} 0 & & \\ & \ddots & \\ & & \lambda_{p+1} & \\ & & & \ddots & \\ & & & & \lambda_p \end{bmatrix}$$

$$\lambda_1, \dots, \lambda_p < 0, \quad \lambda_{p+1}, \dots, \lambda_p > 0$$

$$\text{then if we write } A^- = X \Lambda^- X^{-1}$$

$$A^+ = X \Lambda^+ X^{-1}$$

the first order upwind scheme is

$$u_j^{n+1} = u_j^n - \frac{\Delta t}{\Delta x} \left[A^- (u_j^n - u_{j-1}^n) + A^+ (u_j^n - u_{j+1}^n) \right]$$

which is sometimes called the
Courant-Isaacson-Rees method

Clearly the eigenvalues take the place
of the wave speed, a , in the scalar
equation, so the (necessary) CFL
stability condition becomes

$$\max_j |\lambda_j| \frac{\Delta t}{\Delta x} \leq 1$$



An unfortunate property of most schemes
is that they are either

- 1) dissipative: wave amplitudes
decay as time increases
- 2) dispersive: different frequency
waves travel at different speeds

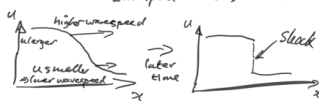
1) is often associated with leading local
truncation error terms which involve the
term u_{xx} associated with diffusion/delay
of solutions

2) often leads to Gibbs-like phenomenon

These issues arise for linear and nonlinear
wave problems. Associated only with
nonlinear problems can also be the
formation of shocks: discontinuities that
form as a solution evolves.

$$\text{e.g. Burgers Equation } u_t + u u_x = 0$$

$$\text{wave speed} = a(u) = u$$



Perhaps surprisingly finite difference
(and finite volume) methods remain the
most important and widely used methods
for such problems: we consider these now

Scalar nonlinear conservation laws

$$u_t + f(u)_x = 0$$

$$\text{or } u_t + a(u) u_x = 0, \quad a(u) = f'(u)$$

can be approximated by locally freezing
wave speeds:

$$\hat{a}_{j+\frac{1}{2}}^n = \begin{cases} \frac{f_j^n - f_{j-1}^n}{u_j^n - u_{j-1}^n}, & u_j^n \neq u_{j-1}^n \\ f'(u_j^n), & u_j^n = u_{j-1}^n \end{cases},$$

$$f_j^n = f(u_j^n), \dots \text{etc}$$

The e.g. 1st order upwind scheme is for

$$\hat{u}_{j+\frac{1}{2}}^n = \hat{a}_{j+\frac{1}{2}}^n \frac{\Delta t}{\Delta x} \text{ etc}$$

For $j=1, \dots, J$ (i.e. sweep from left to right
update u_j^n either once, twice or not at all
depending on local $\hat{a}$ values):

$$u_j^{n+1} = u_j^n - \frac{\Delta t}{\Delta x} \left\{ \begin{aligned} & \hat{a}_{j+\frac{1}{2}}^n (u_j^n - u_{j-1}^n) \text{ if } \hat{a}_{j+\frac{1}{2}}^n > 0 \\ & \hat{a}_{j-\frac{1}{2}}^n (u_j^n - u_{j-1}^n) \text{ if } \hat{a}_{j+\frac{1}{2}}^n < 0 \end{aligned} \right\}$$