

LU decomposition

$$Ax = b$$

$$x = A^{-1}b$$

bad idea in practice!

Let $A \in \mathbb{R}^{n \times n}$. Suppose we can decompose (or factorise)

$$P A = \begin{bmatrix} * & * & * & * & * \\ * & * & * & * & * \\ * & * & * & * & * \\ * & * & * & * & * \\ * & * & * & * & * \end{bmatrix} = \begin{bmatrix} * & & & & \\ * & * & & & \\ * & * & * & & \\ * & * & * & * & \\ * & * & * & * & * \end{bmatrix} \begin{bmatrix} * & * & * & * & * \\ & * & * & * & * \\ & & * & * & * \\ & & & * & * \\ & & & & * \end{bmatrix} = \underline{LU}$$

$x = A^{-1}b$
(great)

L : lower triangular, U : upper triangular. How to find L, U ?

$$\underbrace{L_n \dots L_1}_{L^{-1}} A \rightarrow U \Leftrightarrow A = \underbrace{L}_{L^{-1}} U$$

$L^{-1} = (\text{low. tri.})$

$(\dots \dots \dots)$

$(\dots \dots \dots)$

$(\dots \dots \dots)$

LU decomposition

Let $A \in \mathbb{R}^{n \times n}$. Suppose we can decompose (or factorise)

$$A = \begin{bmatrix} * & * & * & * & * \\ * & * & * & * & * \\ * & * & * & * & * \\ * & * & * & * & * \\ * & * & * & * & * \end{bmatrix} = \underbrace{\begin{bmatrix} * & & & & \\ * & * & & & \\ * & * & * & & \\ * & * & * & * & \\ * & * & * & * & * \end{bmatrix}}_{L} \underbrace{\begin{bmatrix} * & * & * & * & * \\ & * & * & * & * \\ & & * & * & * \\ & & & * & * \\ & & & & * \end{bmatrix}}_{U} = \underline{LU}$$

L : lower triangular, U : upper triangular. How to find L, U ?

equal to A 's.

$$A = \begin{bmatrix} * & & & & \\ * & * & & & \\ * & * & * & & \\ * & * & * & * & \\ * & * & * & * & * \end{bmatrix} = \underbrace{\begin{bmatrix} * & & & & \\ * & * & & & \\ * & * & * & & \\ * & * & * & * & \\ * & * & * & * & * \end{bmatrix}}_{L_1 U_1} + \begin{bmatrix} * & * & * & * & * \\ & * & * & * & * \\ & & * & * & * \\ & & & * & * \\ & & & & * \end{bmatrix} = \dots \underbrace{\begin{bmatrix} * & * & * & * & * \\ & * & * & * & * \\ & & * & * & * \\ & & & * & * \\ & & & & * \end{bmatrix}}_{L_n U_n}$$

LU decomposition cont'd

First step:

$$A = \underbrace{\begin{bmatrix} * \\ * \\ * \\ * \\ * \end{bmatrix} \begin{bmatrix} * & * & * & * & * \end{bmatrix}}_{L_1 U_1} + \begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix}$$

algorithm:

$$\begin{bmatrix} A_{11} & A_{12} & A_{13} & A_{14} & A_{15} \\ A_{21} \\ A_{31} \\ A_{41} \\ A_{51} \end{bmatrix} = \begin{bmatrix} L_{11} \\ L_{21} \\ L_{31} \\ L_{41} \\ L_{51} \end{bmatrix} \begin{bmatrix} U_{11} & U_{12} & U_{13} & U_{14} & U_{15} \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{bmatrix} + \begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} 1 \\ A_{21}/a \\ A_{31}/a \\ A_{41}/a \\ A_{51}/a \end{bmatrix} \begin{bmatrix} A_{11} & A_{12} & A_{13} & A_{14} & A_{15} \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{bmatrix}}_{= L_1 U_1} + \begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix}$$

$a = A_{11}$

Solving $Ax = b$ via LU

\downarrow \leftarrow $+$ \downarrow \sim \downarrow

L U

$$A = LU \in \mathbb{R}^{n \times n}$$

$$\boxed{LU}x = b$$

easy to solve!

L : lower triangular, U : upper triangular

▶ Cost $\frac{2}{3}n^3$ flops

▶ For $Ax = b$,

▶ first solve $Ly = b$, then $Ux = y$.

▶ triangular solve is always backward stable: e.g. $(L + \Delta L)\hat{y} = b$ (see Higham's book)

▶ **Pivoting** crucial for numerical stability: $PA = LU$, where P : permutation matrix

Then stability means $\hat{L}\hat{U} = PA + \Delta A$

▶ Even with pivoting, unstable examples exist, but still always stable in practice and used everywhere!

▶ Special case where $A \succ 0$ positive definite: $A = R^T R$, **Cholesky** factorization, ALWAYS stable, $\frac{1}{3}n^3$ flops

$$Ax = b \Leftrightarrow \boxed{LU}x = b$$

1st: $L_{11}y_1 = b_1 \Rightarrow y_1 = \frac{b_1}{L_{11}}$

2nd: $L_{12}y_1 + L_{22}y_2 = b_2 \Rightarrow y_2 = \dots$

forward subst.

$$\cancel{LU}x = b$$

$$\text{upper: } \boxed{U}x = y$$

$$U_{11}x_1 = y_1$$

Symmetric
 $\Leftrightarrow x^T A x > 0 \forall x \neq 0$
 C-F minmax

$$O(n^2)$$

LU decomposition with pivots

$$\begin{bmatrix} A_{11} & A_{12} & A_{13} & A_{14} & A_{15} \\ A_{21} & & & & \\ A_{31} & & & & \\ A_{41} & & & & \\ A_{51} & & & & \end{bmatrix} = \begin{bmatrix} 1 & & & & \\ A_{21}/a & & & & \\ A_{31}/a & & & & \\ A_{41}/a & & & & \\ A_{51}/a & & & & \end{bmatrix} \begin{bmatrix} A_{11} & A_{12} & A_{13} & A_{14} & A_{15} \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{bmatrix} + \begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix}$$

Trouble if $a = A_{11} = 0!$ e.g. no LU for $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ solution: **pivot**, permute rows s.t. largest entry of first (active) column is at top. $\Rightarrow PA = LU$, P : permutation matrix

- ▶ $PA = LU$ exists for any nonsingular A (exercise)
- ▶ for $Ax = b$, solve $LUx = P^T b$
- ▶ cost still $\frac{2}{3}n^3 + O(n^2)$

$$PAx = Pb \Rightarrow LUx = Pb$$

$$PAx = b \Rightarrow \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} x = b$$

permutation $\begin{bmatrix} 1 & & \\ & 1 & \\ & & \ddots \end{bmatrix}$

Cholesky factorisation for $A \succ 0$

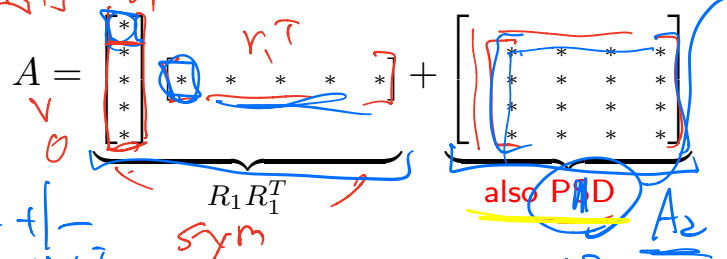
SPSD $\lambda_i(A) \geq 0$

If $A \succ 0$ (symmetric positive definite (S)PD $\Leftrightarrow \lambda_i(A) > 0$), two simplifications:

- ▶ We can take $U_i = L_i^T =: R_i$ by symmetry $\Rightarrow \frac{1}{3}n^3$ flops
- ▶ No pivot needed

$A = LU = R^T R$ (not 1's)

Suppose $A_2 V = \lambda V$
 $\lambda \leq 0$
 $V^T A_2 V = \lambda V^T V < 0$



Notes:

- ▶ $\text{diag}(R)$ no longer 1's
- ▶ A can be written as $A = R^T R$ for some $R \in \mathbb{R}^{n \times n}$ iff $A \succeq 0$ ($\lambda_i(A) \geq 0$)
- ▶ Indefinite case: when $A = A^*$ but A not PSD, $\exists A = LDL^*$ where D diagonal (when $A \in \mathbb{R}^{n \times n}$, D can have 2×2 diagonal blocks), L has 1's on diagonal

$A = LDL^T$

cont. $x^T A x > 0 \iff A \text{ PD}$
 $x = \begin{bmatrix} 0 \\ 0 \\ a \end{bmatrix} \implies x^T A x = A_{11} > 0$

$\begin{bmatrix} \alpha \\ v \end{bmatrix}^T \begin{bmatrix} \alpha & \\ & A_2 \end{bmatrix} \begin{bmatrix} \alpha \\ v \end{bmatrix} < 0$
 choose α s.t. $R^T \begin{bmatrix} \alpha \\ v \end{bmatrix} = 0$