

SOLID MECHANICS

Lecture 13: Chapter 6: Isotropic Materials

Section 6.1: Objectivity

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6 Isotropic Materials

$$\dot{\rho} + \rho \operatorname{div} \mathbf{v} = 0, \quad \text{mass} \quad (1)$$

$$\operatorname{div} \mathbf{T} + \rho \mathbf{b} = \rho \dot{\mathbf{v}}, \quad \text{linear momentum} \quad (2)$$

$$\mathbf{T}^T = \mathbf{T}, \quad \text{angular momentum} \quad (3)$$

$$\mathbf{T} = J^{-1} \mathbf{F} \frac{\partial W}{\partial \mathbf{F}} - p \mathbf{1}. \quad \text{hyperelasticity} \quad (4)$$

where $J = 1$ for an incompressible material and $p = 0$ otherwise.

6.1 Objectivity

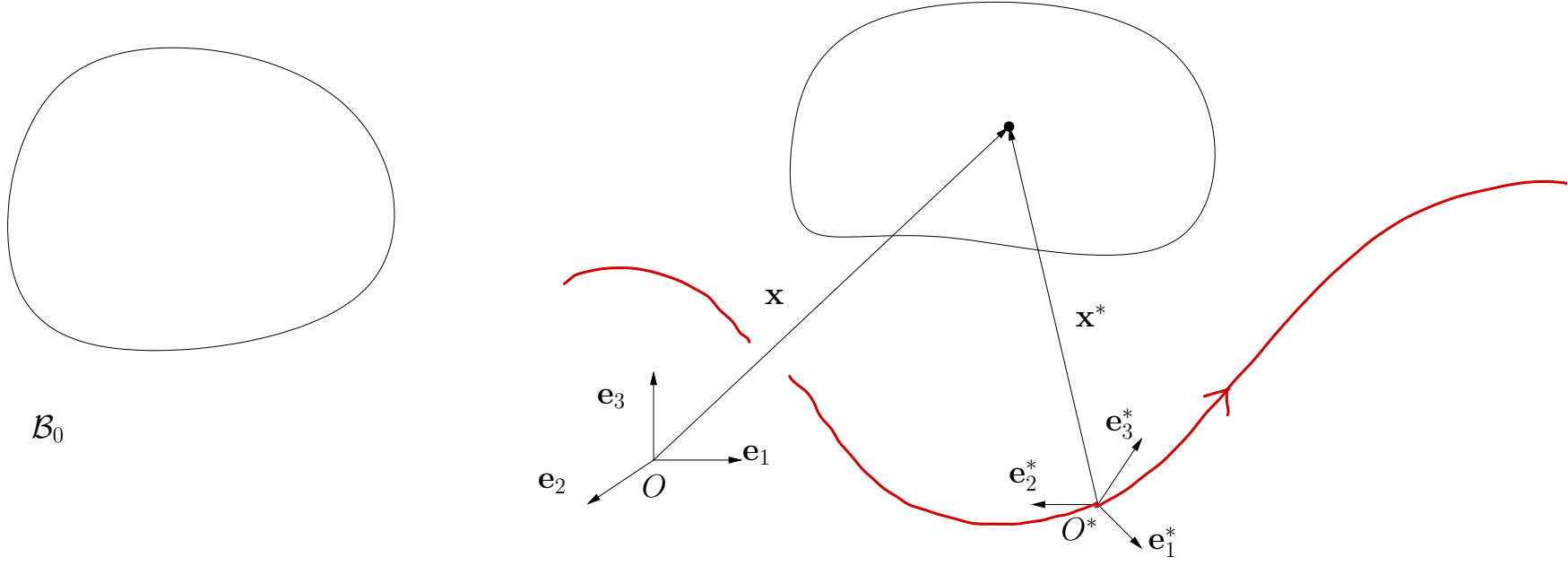
What are the constraints on $W = W(\mathbf{F})$?

Objectivity: Material properties and responses are independent of the frame in which they are observed (or the observer).

More precisely: “The constitutive laws governing the internal conditions of a physical system and the interactions between its parts should not depend on the external frame or reference used to describe them.”

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Change of observers:



$$\mathbf{x} = \chi(\mathbf{X}, t), \quad \mathbf{x}^* = \chi^*(\mathbf{X}, t), \quad t^* = t. \tag{5}$$

The two descriptions are related by

$$\mathbf{x}^* = \mathbf{Q}\mathbf{x} + \mathbf{c}, \tag{6}$$

where $\mathbf{Q} = \mathbf{Q}(t)$ is orthonormal and $\mathbf{c} = \mathbf{c}(t)$.

Objectivity of a scalar field ϕ :

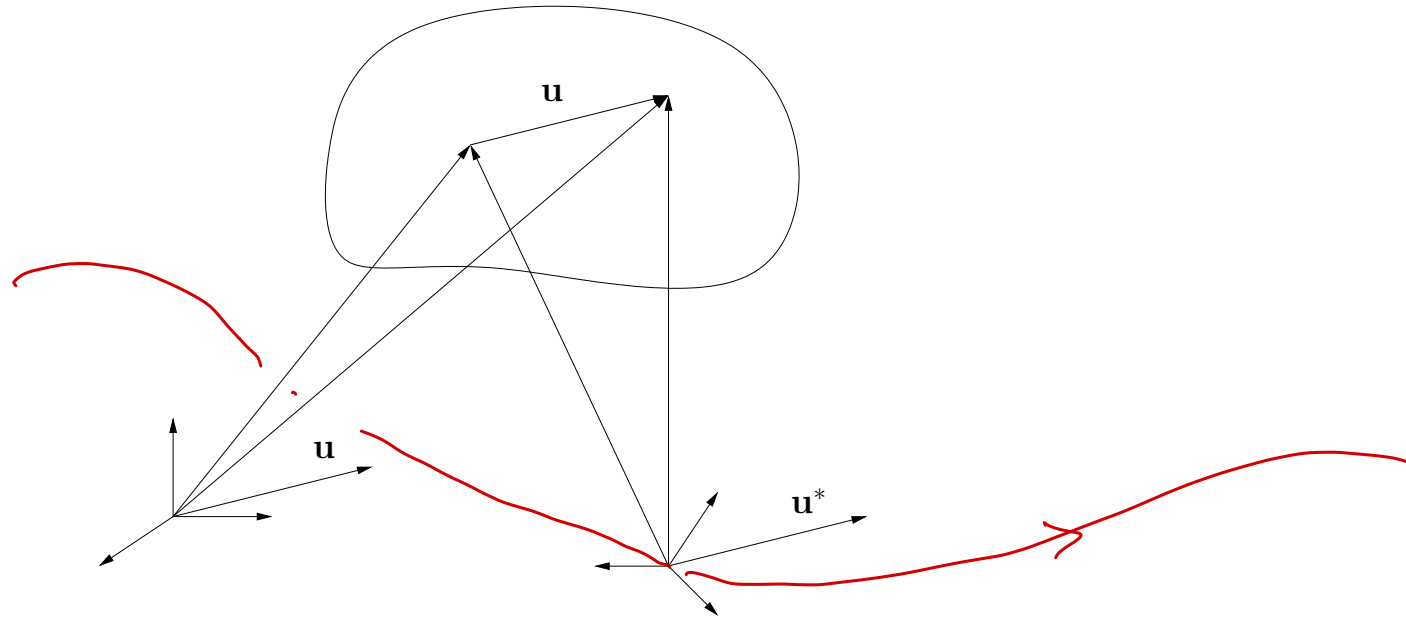
scalar field $\phi(\mathbf{x})$ viewed from one observer.

scalar field $\phi^*(\mathbf{x}^*)$ viewed from the other observer.

Then ϕ is objective if independent of the observer $\phi(\mathbf{x}) = \phi^*(\mathbf{x}^*) = \phi^*(\mathbf{Q}\mathbf{x} + \mathbf{c})$

e.g.: mass density, temperature, energy are objective

e.g.: coordinate, angle with respect to an axis are not objective.

Objectivity of a vector:

$$\mathbf{u} = \mathbf{y} - \mathbf{x}, \quad \mathbf{u}^* = \mathbf{y}^* - \mathbf{x}^* = \mathbf{Q}(\mathbf{y} - \mathbf{x}) = \mathbf{Q}\mathbf{u} \quad (7)$$

Therefore

$$\boxed{\mathbf{u} \text{ is objective if } \mathbf{u}^* = \mathbf{Q}\mathbf{u}.} \quad (8)$$

e.g.: traction vector, forces are objective BUT velocity vector and acceleration vector are not objective

Velocity

$$\vec{x}^* = Q \vec{x} + C$$

$$\Rightarrow \vec{v}^* = \frac{\partial \vec{x}^*}{\partial t} = Q \vec{v} + \dot{Q} \vec{x} + \dot{C}$$

$$\Rightarrow \vec{v}^* \neq Q \vec{v} \quad \text{in general}$$

\Rightarrow velocity not objective

2/ Acceleration

$$\vec{a}^* = Q \vec{a} + \underbrace{2 \dot{Q} \vec{v}}_{\text{coriolis}} + \underbrace{\ddot{Q} \vec{x}}_{\text{centrifugal}} + \ddot{\vec{c}}$$

$\Rightarrow \vec{a}^* \neq Q \vec{a}$ in general

\vec{a}^* is not objective

3/ Gradient of an objective fn.

ϕ objective

$$\Rightarrow (\text{grad}^* \phi^*)_i = \frac{\partial \phi^*}{\partial x_i^*} = \frac{\partial \phi}{\partial x_i^*} = \frac{\partial x_b}{\partial x_i^*} \frac{\partial \phi}{\partial x_b}$$

$$= \Phi_{ik} (\text{grad } \phi)_k$$

$$\Rightarrow (\text{grad } \phi)^* = \Phi \text{grad } \phi \quad \forall \Phi \in \text{SO}(3)$$

$\Rightarrow \text{grad } \phi$ is objective.

Objectivity of a tensor:

Let \mathbf{t} be the traction vector and \mathbf{n} normal vector to a surface $\Gamma \subset \mathcal{B}$. We have: \mathbf{n} is objective: $\mathbf{n}^* = \mathbf{Q}\mathbf{n}$

$$\mathbf{t} = \mathbf{T} = \mathbf{T}\mathbf{n}, \quad \mathbf{t}^* = \mathbf{T}^* = \mathbf{T}^*\mathbf{n}^*, \quad (9)$$

So

$$\mathbf{t}^* = \mathbf{T}^*\mathbf{n}^* = \mathbf{T}^*\mathbf{Q}\mathbf{n} \quad (10)$$

but also

$$\mathbf{t}^* = \mathbf{Q}\mathbf{t} = \mathbf{Q}\mathbf{T}\mathbf{n} \quad (11)$$

So

$$\mathbf{Q}\mathbf{T}\mathbf{n} = \mathbf{T}^*\mathbf{Q}\mathbf{n} \quad (12)$$

This is true $\forall \mathbf{n}$, which implies $\mathbf{T}^*\mathbf{Q} = \mathbf{Q}\mathbf{T}$,

$$\mathbf{T}^* = \mathbf{Q}\mathbf{T}\mathbf{Q}^\top \quad (13)$$

More generally a tensor \mathbf{T} is objective if

$$\boxed{\mathbf{T}^* = \mathbf{Q}\mathbf{T}\mathbf{Q}^\top} \quad (14)$$

1. Deformation gradient

$$\mathbf{F}^* = \frac{\partial \mathbf{x}^*}{\partial \mathbf{X}} = \frac{\partial \mathbf{x}^*}{\partial \mathbf{x}} \frac{\partial \mathbf{x}}{\partial \mathbf{X}} = \mathbf{QF}. \quad (15)$$

So \mathbf{F} is NOT objective.

2. Left Cauchy-Green tensor \mathbf{B}

$$\mathbf{B}^* = \mathbf{F}^*(\mathbf{F}^*)^T = \mathbf{QFF}^T\mathbf{Q}^T \quad (16)$$

So \mathbf{B} is objective.

3. Right Cauchy-Green tensor \mathbf{C}

$$\mathbf{C}^* = (\mathbf{F}^*)^T\mathbf{F}^* = \mathbf{F}^T\mathbf{Q}^T\mathbf{QF} = \mathbf{C} \quad (17)$$

So \mathbf{C} is NOT objective.

4. Exercise: \mathbf{L} is not objective but the Eulerian strain \mathbf{D} rate is objective.

Back to Navier-Stokes:

$$\mathcal{C}[\mathbf{L}] = 2\mu\mathbf{D}, \quad \mathbf{D} = \frac{1}{2}(\mathbf{L} + \mathbf{L}^T), \quad (18)$$

Conclusion: ϕ , \mathbf{u} , \mathbf{T} are objective if

$$\phi = \phi^*, \quad \mathbf{u}^* = \mathbf{Q}\mathbf{u}, \quad \mathbf{T}^* = \mathbf{Q}\mathbf{T}\mathbf{Q}^\top. \quad (19)$$

Objectivity of the strain-energy density function W

$$W \text{ scalar} \implies W^* = W. \quad (20)$$

$$\mathbf{F} \text{ gradient} \implies \mathbf{F}^* = \mathbf{Q}\mathbf{F}. \quad (21)$$

$$\implies W^*(\mathbf{F}^*) = W(\mathbf{Q}\mathbf{F}) = W(\mathbf{F}) \quad (22)$$

$$W(\mathbf{Q}\mathbf{F}) = W(\mathbf{F}), \quad \forall \mathbf{Q} \in SO(3), \quad (23)$$

But, polar decomposition theorem states $\mathbf{F} = \mathbf{R}\mathbf{U}$, so

$$W(\mathbf{Q}\mathbf{F}) = W(\mathbf{Q}\mathbf{R}\mathbf{U}) \quad (24)$$

Choose $\mathbf{Q} = \mathbf{R}^\top$ and

$$\boxed{W(\mathbf{F}) = W(\mathbf{U})} \quad (25)$$

The principle of objectivity implies that W only depends on \mathbf{F} through $\mathbf{C} = \mathbf{U}^2$

We can write $W(\mathbf{F}) = \bar{W}(\mathbf{C})$.