

# C4.3 Functional Analytic Methods for PDEs Lecture 11

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## In the last 6 lectures

Sobolev spaces and their properties

# This lecture

- Linear elliptic equations of second order
- Classical and weak solutions
- Energy estimates
- First existence theorem

# The equation of interest

We will consider the equation

$$Lu := -\partial_i(a_{ij}\partial_j u) + b_i\partial_i u + cu = f + \partial_i g_i \text{ in } \Omega$$
 (\*)

#### where

- $\star \Omega$  is a domain in  $\mathbb{R}^n$ , which frequently has Lipschitz regularity or better,
- $\star u: \Omega \to \mathbb{R}$  is the unknown,
- ★  $a_{ij}, b_i, c: \Omega \to \mathbb{R}$  are given coefficients,
- ★  $f, g_i : \Omega \to \mathbb{R}$  are given sources.
- Equation (\*) is said to be in divergence form. It can be written in more compact form:

$$Lu = -\operatorname{div}(a\nabla u) + b \cdot \nabla u + cu = f + \operatorname{div}g$$

#### where

- $\star$   $a=(a_{ij})$  is an  $n\times n$  matrix,
- $\star$   $b = (b_i)$  and  $g = (g_i)$  are (column) vectors.

# Divergence vs non-divergence form

 To dispel confusion, we note that we will not consider the equation

$$-a_{ij}\partial_i\partial_j u + b_i\partial_i u + cu = f + \partial_i g_i \text{ in } \Omega, \tag{**}$$

which is also of importance. The equation (\*\*) is said to be in non-divergence form.

To treat (\*\*), we will need some preparation different from what we have had so far.

# Structural assumptions

We make the following assumptions:

- The coefficients  $a_{ij}, b_i, c : \Omega \to \mathbb{R}$  belong to  $L^{\infty}(\Omega)$ .
- The coefficients  $a_{ij}$  is symmetric, i.e.  $a_{ij} = a_{ji}$ .
- The coefficients  $a_{ij}$  is *uniformly elliptic* this will be defined on the next slide.

# **Ellipticity**

#### **Definition**

Let  $a = (a_{ij}) : \Omega \to \mathbb{R}^{n \times n}$  be symmetric and have measurable entries.

• a is elliptic if

$$a_{ij}(x)\xi_i\,\xi_j\geq 0$$
 for all  $\xi\in\mathbb{R}^n$  and a.e.  $x\in\Omega$ .

(In other words, a is non-negative definite a.e. in  $\Omega$ .)

• a is strictly elliptic if there exists  $\lambda > 0$  such that

$$a_{ij}(x)\xi_i\,\xi_j\geq \lambda|\xi|^2$$
 for all  $\xi\in\mathbb{R}^n$  and a.e.  $x\in\Omega$ .

• a is uniformly elliptic if there exist  $0 < \lambda \le \Lambda < \infty$  such that

$$\lambda |\xi|^2 \leq a_{ij}(x)\xi_i \, \xi_j \leq \Lambda |\xi|^2$$
 for all  $\xi \in \mathbb{R}^n$  and a.e.  $x \in \Omega$ .

# Examples

Two simplistic but important examples:

- $a_{ij} = \delta_{ij}$  in all of  $\Omega$ .
- $a_{ij} = k(x)\delta_{ij}$  where  $k = k_1\chi_A + k_2\chi_{\Omega\setminus A}$  for some subset A of  $\Omega$  and some constants  $k_1, k_2 > 0$ .

# The Dirichlet boundary value problem

We will write  $L = -\partial_i(a_{ij}\partial_j) + b_i\partial_i + c$  to mean that

$$Lu = -\partial_i(a_{ij}\partial_j u) + b_i\partial_i u + cu.$$

The Dirichlet boundary value problem for L asks to find a function u satisfying

$$\begin{cases}
Lu = f + \partial_i g_i & \text{in } \Omega, \\
u = u_0 & \text{on } \partial\Omega.
\end{cases}$$
(BVP)

where

- $\star$  f and g are given sources,
- $\star$   $u_0$  is given boundary data.

# Classical solutions

$$L = -\partial_i(a_{ij}\partial_j) + b_i\partial_i + c.$$
 
$$\begin{cases} Lu &= f + \partial_i g_i & \text{in } \Omega, \\ u &= u_0 & \text{on } \partial\Omega. \end{cases}$$
 (BVP)

#### **Definition**

Suppose  $a \in C^1(\Omega)$ ,  $b, c \in C(\Omega)$ . For a given  $f \in C(\Omega)$ ,  $g \in C^1(\Omega)$  and  $u_0 \in C(\partial\Omega)$ , a function  $u \in C^2(\Omega) \cap C(\bar{\Omega})$  is called a *classical solution to* the Dirichlet boundary value problem (BVP) if it satisfies (BVP) in the usual sense.

 We saw in the first lecture that the notion of classical solutions is insufficient for our need.

## An observation

• Suppose  $a \in C^1(\Omega)$ ,  $b, c \in C(\Omega)$ ,  $f \in C(\Omega)$  and  $g \in C^1(\Omega)$ . Suppose  $u \in C^2(\Omega)$  satisfies

$$Lu = -\partial_i(a_{ij}\partial_j u) + b_i\partial_i u + cu = f + \partial_i g_i \text{ in } \Omega.$$
 (\*)

• If  $\varphi \in C_c^{\infty}(\Omega)$  is a test function, then

$$\int_{\Omega} (Lu) \varphi \, dx = \int_{\Omega} \left[ a_{ij} \partial_j u \partial_i \varphi + b_i \partial_i u \varphi + c u \varphi \right] dx$$

and

$$\int_{\Omega} [f + \partial_i g_i] \varphi \, dx = \int_{\Omega} [f \varphi - g_i \partial_i \varphi] \, dx.$$

• Therefore, for all  $\varphi \in C_c^{\infty}(\Omega)$ ,

$$\int_{\Omega} \left[ a_{ij} \partial_j u \partial_i \varphi + b_i \partial_i u \varphi + c u \varphi \right] dx = \int_{\Omega} [f \varphi - g_i \partial_i \varphi] dx. \quad (\diamondsuit)$$

### An observation

• Conversely, if u is such that  $(\diamondsuit)$  holds for all  $\varphi \in C_c^{\infty}(\Omega)$ , then by reversing the argument, we have

$$\int_{\Omega} (Lu) \, \varphi \, dx = \int_{\Omega} [f + \partial_i g_i] \, \varphi \, dx \text{ for all } \varphi \in C_c^{\infty}(\Omega).$$

This implies  $Lu = f + \partial_i g_i$  in  $\Omega$ , i.e. u satisfies (\*).

• We conclude that  $u \in C^2(\Omega)$  satisfies

$$Lu = -\partial_i(a_{ij}\partial_j u) + b_i\partial_i u + cu = f + \partial_i g_i \text{ in } \Omega$$
 (\*)

if and only if u satisfies

$$\int_{\Omega} \left[ a_{ij} \partial_j u \partial_i \varphi + b_i \partial_i u \varphi + c u \varphi \right] dx = \int_{\Omega} [f \varphi - g_i \partial_i \varphi] dx \quad (\diamondsuit)$$

for all  $\varphi \in C_c^{\infty}(\Omega)$ .

### An observation

• We conclude that  $u \in C^2(\Omega)$  satisfies

$$Lu = -\partial_i(a_{ij}\partial_j u) + b_i\partial_i u + cu = f + \partial_i g_i \text{ in } \Omega$$
 (\*)

if and only if u satisfies

$$\int_{\Omega} \left[ a_{ij} \partial_j u \partial_i \varphi + b_i \partial_i u \varphi + c u \varphi \right] dx = \int_{\Omega} [f \varphi - g_i \partial_i \varphi] dx \quad (\diamondsuit)$$

for all  $\varphi \in C_c^{\infty}(\Omega)$ .

 Key: While the formulation (\*) requires u to be twice differentiable, the formulation (◊) requires u to be only once differentiable.

# Weak solutions

### Definition

Let  $a, b, c \in L^{\infty}(\Omega)$  and  $L = -\partial_i(a_{ij}\partial_j) + b_i\partial_i + c$ .

• Suppose  $f \in L^2(\Omega)$ ,  $g \in L^2(\Omega)$ . We say that  $u \in H^1(\Omega)$  is a weak solution (or generalized solution) to the equation

$$Lu = f + \partial_i g_i \text{ in } \Omega \tag{*}$$

if

$$\int_{\Omega} \left[ a_{ij} \partial_{j} u \partial_{i} \varphi + b_{i} \partial_{i} u \varphi + c u \varphi \right] dx = \int_{\Omega} [f \varphi - g_{i} \partial_{i} \varphi] dx \quad (\diamondsuit)$$

holds for all  $\varphi \in H_0^1(\Omega)$ .

When this holds, we also say that u satisfies (\*) in the weak sense.

# Weak solutions

#### **Definition**

Let  $a, b, c \in L^{\infty}(\Omega)$  and  $L = -\partial_i(a_{ij}\partial_j) + b_i\partial_i + c$ .

• Suppose that  $f \in L^2(\Omega)$ ,  $g \in L^2(\Omega)$  and  $u_0 \in H^1(\Omega)$ . We say that  $u \in H^1(\Omega)$  is a weak solution (or generalized solution) to the Dirichlet boundary value problem

$$\begin{cases}
Lu = f + \partial_i g_i & \text{in } \Omega, \\
u = u_0 & \text{on } \partial\Omega.
\end{cases}$$
(BVP)

if  $Lu = f + \partial_i g_i$  in  $\Omega$  in the weak sense and if  $u - u_0 \in H_0^1(\Omega)$ .

### Weak solutions

• It is convenient to introduce the bilinear form  $B(\cdot, \cdot)$ :

$$B(u,v) = \int_{\Omega} [a_{ij}\partial_j u \partial_i v + b_i \partial_i u v + c u v] dx \qquad u,v \in H^1(\Omega).$$

B is called the bilinear form associated with the operator L.

• Then  $u \in H^1(\Omega)$  satisfies (\*) in the weak sense if

$$B(u,\varphi) = \langle f, \varphi \rangle - \langle g_i, \partial_i \varphi \rangle$$
 for all  $\varphi \in H_0^1(\Omega)$ ,

where  $\langle \cdot, \cdot \rangle$  denotes the inner product of  $L^2(\Omega)$ .

# Theorem (Energy estimates)

Suppose that  $a,b,c\in L^\infty(\Omega)$ , a is uniformly elliptic,  $L=-\partial_i(a_{ij}\partial_j)+b_i\partial_i+c$  and B is its associated bilinear form. Then there exists some large constant C>0 such that

$$|B(u,v)| \le C||u||_{H^1(\Omega)}||v||_{H^1(\Omega)},$$
  
 $\frac{\lambda}{2}||u||_{H_1(\Omega)}^2 \le B[u,u] + C||u||_{L^2(\Omega)}^2.$ 

Here  $\lambda$  is the constant appearing in the definition of ellipticity of a.

#### Proof

 The first estimate is clear from the definition of B and Cauchy-Schwarz's inequality:

$$|B(u,v)| \leq \int_{\Omega} \left[ |a_{ij}| |\partial_{j}u| |\partial_{i}v| + |b_{i}| |\partial_{i}u| |v| + |c||u||v| \right] dx$$

$$\leq ||a||_{L^{\infty}} ||\nabla u||_{L^{2}} ||\nabla v||_{L^{2}} + ||b||_{L^{\infty}} ||\nabla u||_{L^{2}} ||v||_{L^{2}}$$

$$+ ||c||_{L^{\infty}} ||u||_{L^{2}} ||v||_{L^{2}}$$

$$\leq C ||u||_{H^{1}} ||v||_{H^{1}}.$$

#### Proof

 For the second estimate, we start by estimating the lower order term in the same fashion while leaving the highest order term untouched:

$$\begin{split} B(u,u) &\geq \int_{\Omega} \left[ a_{ij} \partial_j u \partial_i u + |b_i| |\partial_i u| |u| + |c| |u|^2 \right] dx \\ &\geq \int_{\Omega} a_{ij} \partial_j u \partial_i u \, dx \\ &- \|b\|_{L^{\infty}} \|\nabla u\|_{L^2} \|u\|_{L^2} - \|c\|_{L^{\infty}} \|u\|_{L^2}^2. \end{split}$$

• The leading term is treated using the ellipticity condition:

$$a_{ij}\partial_j u\partial_i u \geq \lambda |\nabla u|^2$$
.

#### Proof

We thus have

$$B(u,u) \geq \lambda \|\nabla u\|_{L^{2}}^{2} - \|b\|_{L^{\infty}} \|\nabla u\|_{L^{2}} \|u\|_{L^{2}} - \|c\|_{L^{\infty}} \|u\|_{L^{2}}^{2}.$$

• Using the inequality  $xy \leq \frac{\lambda}{2}x^2 + \frac{1}{2\lambda}y^2$ , we can absorb the quantity  $\|\nabla u\|_{L^2}$  in the second term on the right hand side to the first term:

$$B(u, u) \ge \lambda \|\nabla u\|_{L^{2}}^{2} - \frac{\lambda}{2} \|\nabla u\|_{L^{2}}^{2} - \frac{1}{2\lambda} \|b\|_{L^{\infty}}^{2} \|u\|_{L^{2}}^{2} - \|c\|_{L^{\infty}} \|u\|_{L^{2}}^{2}$$

$$= \frac{\lambda}{2} \|\nabla u\|_{L^{2}}^{2} - C \|u\|_{L^{2}}^{2}.$$

# L as an operator on $H^1(\Omega)$

## Corollary

Suppose that  $a, b, c \in L^{\infty}(\Omega)$ , a is uniformly elliptic,

$$L = -\partial_i(a_{ij}\partial_i) + b_i\partial_i + c.$$

For every  $u \in H^1(\Omega)$ , define a map  $Lu : H^1_0(\Omega) \to \mathbb{R}$  by

$$(Lu)(\varphi) = B(u, \varphi)$$
 for all  $\varphi \in H_0^1(\Omega)$ .

Then Lu :  $H_0^1(\Omega) \to \mathbb{R}$  is bounded linear, i.e.

$$Lu \in (H_0^1(\Omega))^* =: H^{-1}(\Omega).$$

Furthermore, L is a bounded linear map from  $H^1(\Omega)$  into  $H^{-1}(\Omega)$ .

# L as an operator on $H^1(\Omega)$

#### Proof

- Linearity if clear. By the energy estimate,  $|(Lu)(\varphi)| \leq C||u||_{H^1}||\varphi||_{H^1}$  and so Lu belongs to  $H^{-1}(\Omega)$ .
- Furthermore, we have

$$||Lu||_{H^{-1}(\Omega)} = \sup_{\varphi \in H_0^1(\Omega), ||\varphi||_{H^1} \le 1} |Lu(\varphi)| \le C||u||_{H^1}.$$

This means  $L \in \mathcal{L}(H^1(\Omega), H^{-1}(\Omega))$ .

# Weak sense vs $H^{-1}$ sense

## Corollary

u is a weak solution to (\*) if and only if  $Lu = f + \partial_i g_i$  as elements of  $H^{-1}(\Omega)$ .

Here  $f + \partial_i g_i$  is viewed as an element of  $H^{-1}(\Omega)$  by letting

$$(f + \partial_i g_i)(\varphi) = \int_{\Omega} [f\varphi - g_i \partial_i \varphi] dx.$$

# $W^{1,p}$ solutions

#### Remark

One can similarly define a notion of  $W^{1,p}$  solutions to (\*) and (BVP) using  $p \neq 2$ . The treatment for these type of solutions is beyond the scope of this course.

### An existence theorem

#### Theorem

Suppose that  $a, c \in L^{\infty}(\Omega)$ , a is uniformly elliptic,  $c \geq 0$  a.e. in  $\Omega$ , and  $L = -\partial_i(a_{ij}\partial_j) + c$  (i.e.  $b \equiv 0$ ). Then for every  $f \in L^2(\Omega)$ ,  $g \in L^2(\Omega)$  and  $u_0 \in H^1(\Omega)$ , the Dirichlet boundary value problem

$$\begin{cases}
Lu = f + \partial_i g_i & \text{in } \Omega, \\
u = u_0 & \text{on } \partial\Omega
\end{cases}$$
(BVP)

has a unique weak solution  $u \in H^1(\Omega)$ .

### An existence theorem

The above theorem is a consequence of the following statement:

#### **Theorem**

Suppose that  $a, c \in L^{\infty}(\Omega)$ , a is uniformly elliptic,  $c \geq 0$  a.e. in  $\Omega$ , and  $L = -\partial_i(a_{ij}\partial_j) + c$  (i.e.  $b \equiv 0$ ). Then  $L|_{H^1_0(\Omega)}$  is a bijection from  $H^1_0(\Omega)$  into  $H^{-1}(\Omega)$ .

Indeed, if we let  $L^{-1}: H^{-1}(\Omega) \to H^1_0(\Omega)$  be the inverse of  $L|_{H^1_0(\Omega)}$ , then the unique solution to (BVP) is given by

$$u = u_0 + L^{-1}(-Lu_0 + f + \partial_i g_i).$$

### An existence theorem

### First proof

• Observe that the bilinear form associated with L is positive in  $H_0^1(\Omega)$ :

$$B(u,u) = \int_{\Omega} \left[ a_{ij} \partial_j u \partial_i u + c u^2 \right] dx$$
  
 
$$\geq \lambda \| \nabla u \|_{L^2}^2 \geq \frac{1}{C} \| u \|_{H^1} \text{ for all } u \in H_0^1(\Omega).$$

Hence  $B(\cdot, \cdot)$  defines an inner product on  $H_0^1(\Omega)$ , which is equivalent to the standard inner product of  $H_0^1(\Omega)$ .

• Thus, by the Riesz representation theorem, for every  $T \in H^{-1}(\Omega)$  there exists a unique  $u \in H^1_0(\Omega)$  such that

$$B(u, v) = Tv$$
 for all  $v \in H_0^1(\Omega)$ .

But this means precisely that Lu = T. We conclude that  $L|_{H_0^1(\Omega)}$  is a bijection from  $H_0^1(\Omega)$  into  $H^{-1}(\Omega)$ .