

# C3.3 Differentiable Manifolds

## Problem Sheet 0

Michaelmas Term 2020–2021

- For a smooth map  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  (or between open subsets of  $\mathbb{R}^n$  and  $\mathbb{R}^m$ ) we let  $df_p : \mathbb{R}^n \rightarrow \mathbb{R}^m$  denote the differential of  $f$  at  $p \in \mathbb{R}^n$ . Since  $df_p$  is a linear map, we can identify it with a matrix: if we write  $f = (f_1, \dots, f_m)$  and let  $(x_1, \dots, x_n)$  denote coordinates on  $\mathbb{R}^n$ , then the matrix is  $(\frac{\partial f_i}{\partial x_j})$ .
  - Let  $f : \mathbb{R} \rightarrow \mathbb{R}^2$  be given by  $f(t) = (t^2, t^3)$ .  
Calculate  $df_t$  for any  $t \in \mathbb{R}$  and show that  $df_t$  is injective except at  $t = 0$ . Sketch the image of  $f$  in  $\mathbb{R}^2$ .
  - Let  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  be given by  $f(x_1, x_2, x_3) = x_1^2 + x_2^2 - x_3$ .  
Calculate  $df_x$  for any  $x \in \mathbb{R}^3$  and show that  $df_x$  is surjective for all  $x \in \mathbb{R}^3$ .
  - Let  $f : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be given by  $f(x_1, x_2, x_3) = (x_2x_3, x_3x_1, x_1x_2)$ .  
Calculate  $df_x$  for any  $x \in \mathbb{R}^3$  and determine for which  $x \in \mathbb{R}^3$  we have that  $df_x$  is an isomorphism.
  - Let  $M_n(\mathbb{R})$  be the  $n \times n$  real matrices and let  $GL(n, \mathbb{R})$  be the set of invertible  $n \times n$  real matrices. Let  $f : GL(n, \mathbb{R}) \rightarrow \mathbb{R}$  be given by  $f(A) = \det A$ .  
Calculate  $df_A$  for any  $A \in GL(n, \mathbb{R})$  as a map from  $M_n(\mathbb{R})$  to  $\mathbb{R}$  and show that it is surjective for all  $A \in GL(n, \mathbb{R})$ .
- Show that  $\mathbb{R}^n$  and  $\mathcal{S}^n = \{(x_1, \dots, x_{n+1}) \in \mathbb{R}^{n+1} : x_1^2 + \dots + x_{n+1}^2 = 1\}$  are second countable and Hausdorff with respect to their natural topologies.
- Let  $N = (0, 0, 1) \in \mathcal{S}^2$  and  $S = (0, 0, -1) \in \mathcal{S}^2$  and define  $U_N = \mathcal{S}^2 \setminus \{N\}$  and  $U_S = \mathcal{S}^2 \setminus \{S\}$ .  
Let  $\varphi_N : U_N \rightarrow \mathbb{R}^2$  and  $\varphi_S : U_S \rightarrow \mathbb{R}^2$  be given by
$$\varphi_N(x_1, x_2, x_3) = \frac{(x_1, x_2)}{1 - x_3} \quad \text{and} \quad \varphi_S(x_1, x_2, x_3) = \frac{(x_1, x_2)}{1 + x_3}.$$
  - By constructing explicit inverses, or otherwise, show that  $\varphi_N$  and  $\varphi_S$  are homeomorphisms (i.e. continuous bijections with continuous inverses).Let  $f = \varphi_S \circ \varphi_N^{-1}$  defined on  $\varphi_N(U_N \cap U_S)$ .
  - Calculate  $f$  and show that it defines a diffeomorphism of  $\mathbb{R}^2 \setminus \{0\}$  (i.e. it is a smooth map with smooth inverse).
  - Calculate the differential  $df_y$  at any point  $y \in \mathbb{R}^2 \setminus \{0\}$ . Calculate  $\det df_y$  when  $df_y$  is viewed as a matrix, and show that it is never zero.
- Define  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by  $f(x_1, x_2) = (e^{x_1} \cos x_2, e^{x_1} \sin x_2)$ .  
Show that  $f$  is a local diffeomorphism (i.e. given any point  $x \in \mathbb{R}^2$  there is an open set  $U \ni x$  and  $V \ni f(x)$  so that  $f : U \rightarrow V$  is a diffeomorphism). Is  $f$  a diffeomorphism?
  - Define  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  by  $f(x_1, x_2) = x_1^3 + x_2^3 + e^{x_1+x_2}$ .  
Show that there is a smooth function  $g(x_1)$  so that  $f(x_1, x_2) = 0$  if and only if  $x_2 = g(x_1)$ .  
Deduce that  $f^{-1}(0)$  is a manifold.