

Introduction to SLE

Example Random Walk on $\mathbb{Z}^2 \rightarrow$ Brownian Motion in $\mathbb{R}^2$
 $\mathbb{R}^2 = \mathbb{C}$

Sketch of the proof

Levy characterization Z_t is a cont complex martingale
 s.t. $\langle Z_t, \bar{Z}_t \rangle = 2t$ then Z_t is a complex BM
 $Z_t = X_t + iY_t$, X_t, Y_t indep. 1-d BM

Complex Itô Z_t is a local complex mart.
 f is an analytic function

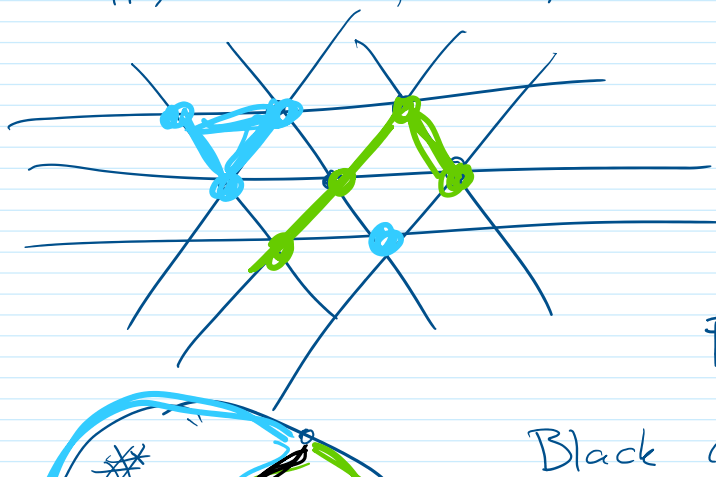
$$\text{the } f(Z_t) - f(Z_0) = \int_0^t f'(Z_s) dZ_s$$

$$\mathbb{E}_x \langle f(Z_t), \bar{f}(Z_t) \rangle = \int_0^t |f'(Z_s)|^2 d\langle Z_s, \bar{Z}_s \rangle$$

this is a positive increasing function.

After a time-change $f(Z_t)$ is a time-changed complex B.M

Other models Percolation, Ising model
 Potts model, O(n) model

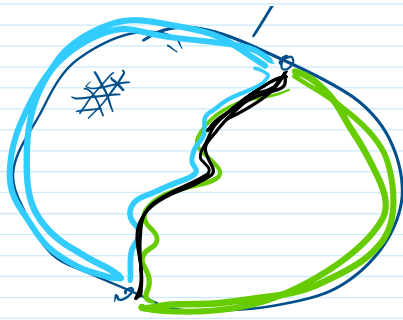


$P(\text{vertex is open}) = p$

$P(\text{closed}) = 1 - p$

$$p_c = \frac{1}{2}$$

Black curve is an interface

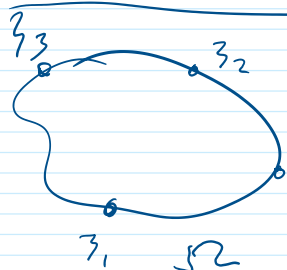


Black curve is an interface
between two clusters

Complex Analysis

Riemann mapping theorem Let Ω be a proper domain in $\mathbb{C}$, $z_0 \in \Omega$ then there is a unique conformal map $\varphi: \Omega \rightarrow \mathbb{D}$ s.t.
 $\varphi(z_0) = 0, \quad \varphi'(z_0) > 0 \quad (\arg \varphi'(z_0) = 0)$

Other normalizations



①

$\exists$

$$\varphi: \Omega \rightarrow \mathbb{H} \quad \text{////}$$

$\exists!$

$$\varphi: \Omega \rightarrow \mathbb{H} \text{ s.t. } \begin{aligned} \varphi(z_1) &= 0 \\ \varphi(z_2) &= 1 \\ \varphi(z_3) &= \infty \end{aligned}$$

② $\exists!$

$$\begin{aligned} \varphi(z_1) &= 0 \\ \varphi(z_2) &= \infty \\ |\varphi'(z_1)| &= 1 \end{aligned}$$

Basic properties

$$S = \left\{ f \text{ s.t. } \begin{aligned} &f \text{ is univalent in } \mathbb{D} \\ &f(0) = 0, \quad f'(0) = 1 \\ &f(z) = z + a_2 z^2 + \dots \end{aligned} \right\}$$

$$f \longleftrightarrow f(\mathbb{D}) = \Omega$$

• Growth theorem $f \in S \quad z \in \mathbb{D}, |z| = r$

$$\frac{r}{(1+r)^2} \leq |f(z)| \leq \frac{r}{(1-r)^2}$$

equality for some $z \Rightarrow f = e^{i\theta} K(e^{-i\theta} z)$

$$K(z) = z + 2z^2 + 3z^3 + \dots \quad \text{Koebe function}$$

• Distortion theorem

$$\frac{1-r}{(1+r)^3} \leq |f'(z)| \leq \frac{1+r}{(1-r)^3}$$

$$(1+r)^3 - 1 - 3r - 3r^2 = (1-r)^3$$

• Schwarz lemma f is analytic in $\mathbb{D}$

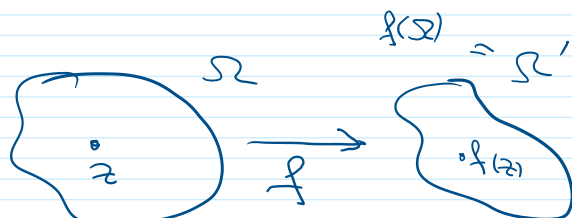
$$f(0) = 0, \quad |f| \leq 1$$

$$\text{then } |f(z)| \leq |z|, \quad |f'(0)| \leq 1$$

Equality for some $z \neq 0$, or $|f'(0)| = 1$

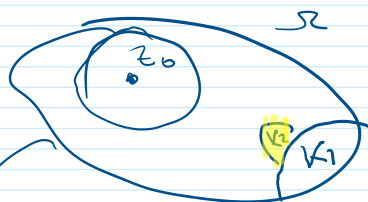
$$\text{then } f(z) = e^{i\theta} z$$

• Koebe distortion



$$\frac{1}{4} \leq |f'(z)| \frac{\text{dist}(z, \partial\Omega)}{\text{dist}(f(z), \partial\Omega')} \leq 4$$

Beurling estimate



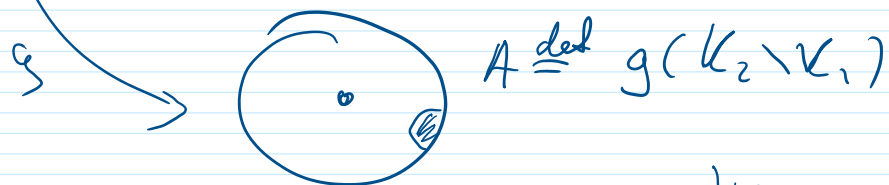
K_1 is a compact in Ω
s.t. $\Omega \setminus K_1$ is a s.c domain
containing z_0

K_2 comp in Ω
 $K_1 \subset K_2$

$$\textcircled{1} B(z_0, r_0) \subset \Omega \setminus K_2$$

$$\textcircled{2} \text{diam}(K_2 \setminus K_1) < \varepsilon < \frac{r_0}{10}$$

Let g be a conf. map $\Omega \setminus K_1 \rightarrow \mathbb{D}$
 $g(z_0) = 0$



Then $\exists c = c(r_0, \frac{1}{10})$ s.t.
 $\text{diam}(A) \leq c\varepsilon$

Carathéodory convergence $f_n : \mathbb{D} \rightarrow \Omega_n$

$f_n \rightarrow f$ if $f_n \rightarrow f$ unif on all compacts in $\mathbb{D}$

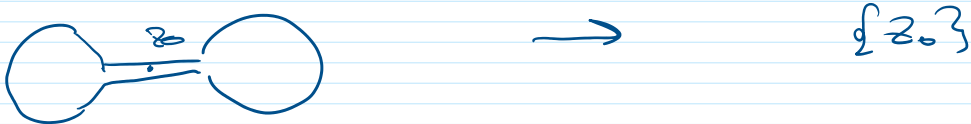
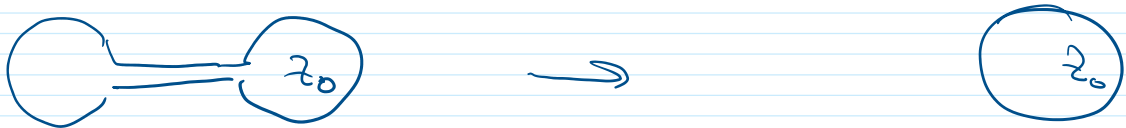
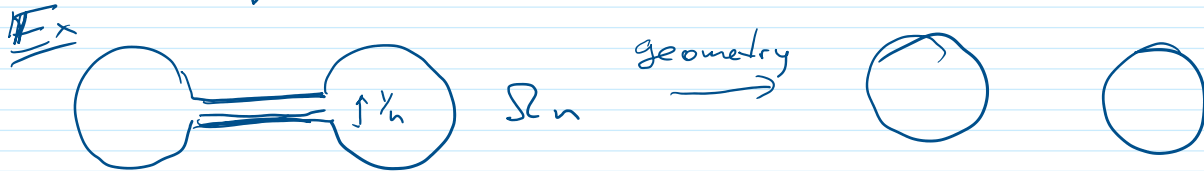
Th $f_n \rightarrow f$ ($\mathbb{D} \rightarrow \Omega$) $\Leftrightarrow \Omega_n \rightarrow \Omega$

$\{ \Omega_n \}_n \rightarrow \Omega \quad (\mathbb{D} \rightarrow \Omega) \Leftrightarrow \Omega_n \rightarrow \Omega$
in sense of kernels

Def $\{ \Omega_n \}_n$ Kernel w.r.t. z_0 is the largest s.c domain Ω s.t. $z_0 \in \Omega$ and every closed subset of Ω belongs to all but finitely many Ω_n

(if there is no such Ω then kernel = $\{z_0\}$)

$\Omega_n \rightarrow \Omega$ if Ω is the kernel of every subsequence



Poisson kernel

$\bullet \mathbb{D} \quad u(z) = \frac{1}{2\pi} \int_{\partial \mathbb{D}} u(\zeta) P(\zeta, z) |d\zeta|$

where $P_{\mathbb{D}}(\zeta, z) = \frac{1 - |z|^2}{|\zeta - z|^2} = \operatorname{Re} \frac{\zeta + z}{\zeta - z}$

Poisson kernel in $\mathbb{D}$

$\bullet \text{II}$ if $u \rightarrow 0$ as $|z| \rightarrow \infty$ (sufficiently fast)

• $\mathbb{H}$ if $u \rightarrow 0$ as $|z| \rightarrow \infty$ (sufficiently fast)

$$u(z) = \frac{1}{\pi} \int_{\mathbb{R}} u(t) \frac{y}{y^2 + (x-t)^2} dt = \int u(t) P(t, z) dt$$

$$P_H(t, z) = \frac{1}{\pi} \frac{y}{|z-t|^2} = \operatorname{Im} \left[\frac{1}{\pi(t-z)} \right] \quad \boxed{z = x+iy}$$

Complexity Schwarz kernels / integral formulas

$\mathbb{D}$ f is analytic in $\mathbb{D}$, cont in $\overline{\mathbb{D}}$ then

$$f(z) = \frac{1}{2\pi} \int_0^{2\pi} \frac{e^{i\theta} + z}{e^{i\theta} - z} \operatorname{Re} f(e^{i\theta}) d\theta + ic \quad [c = \operatorname{Im} f(0)]$$

$$= \frac{1}{2\pi} \int \frac{z+z}{z-z} \operatorname{Re} f(e^{i\theta}) |dz| + ic$$

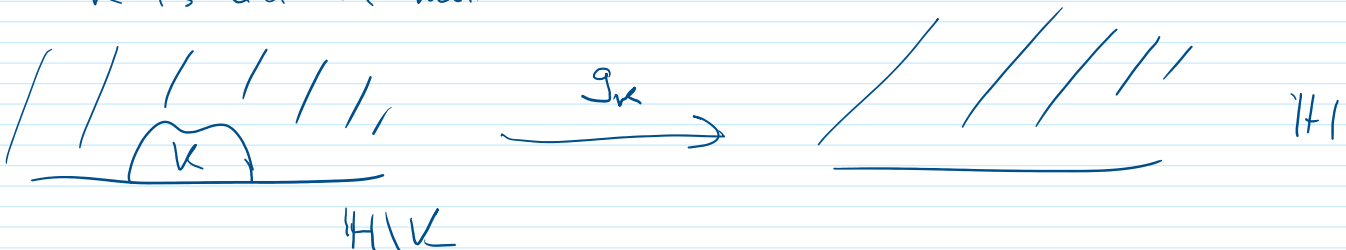
$\mathbb{H}$ f is analytic in $\mathbb{H}$, cont $\overline{\mathbb{H}}$, $f(z) = O(|z|^{-\alpha})$ as $z \rightarrow \infty$
 $\alpha > 0$ then

$$f(z) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{\operatorname{Im} f(t)}{t-z} dt$$

Ex $f(z) = z$ then on $\mathbb{R}$ $\operatorname{Im} f(t) = 0$

Mapping out functions

K is a compact in $\mathbb{H}$ s.t. $\mathbb{H} \setminus K$ is simply connected
 K is an $\mathbb{H}$ -hull



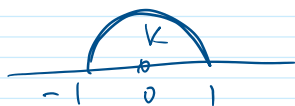
There is unique g s.t. $g: \mathbb{H} \setminus K \rightarrow \mathbb{H}$

$$g(\infty) \rightarrow \infty$$

$$g(z) = z + \frac{b_1}{z} + \frac{b_2}{z^2} + \dots \text{ as } z \rightarrow \infty$$

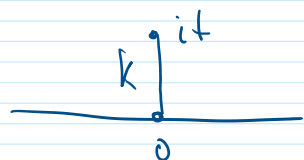
Def $\operatorname{hcap}(K) = b_1$ half-plane capacity

Ex



$$\text{hcap}(K) = 1$$

Ex



$$\text{hcap}(K) = \frac{t^2}{2}$$

Properties

- $\text{hcap}(\lambda K) = \lambda^2 \text{hcap}(K)$
- $\text{hcap}(K+x) = \text{hcap}(K)$
- hcap is cont w.r.t kernel convergence

Lemma

$$\Omega = \mathbb{H} \setminus K \quad f_K: \mathbb{H} \rightarrow \Omega \quad f_K = g_K^{-1}$$

Then ① $f_K(z) = z - \frac{\text{hcap}(K)}{z} + \dots$ and

$$\text{② } \text{hcap}(K) = \frac{1}{\pi} \int_{-\infty}^{\infty} \text{Im } f_K(x) dx$$

Proof

① follows from $g_K = z + \frac{\text{hcap}(K)}{z} + \dots$

② Consider $f_K(z) - z$ ($\rightarrow 0$ as $z \rightarrow \infty$)

Apply Schwarz formula

$$f_K(z) - z = \frac{1}{\pi} \int_{\mathbb{R}} \frac{\text{Im}(f_K(x) - x)}{x - z} dx = \frac{1}{\pi} \int \frac{\text{Im } f_K(x)}{x - z} dx$$

multiply by z and take the limit as $z \rightarrow \infty$

$$z(f_K(z) - z) = \frac{1}{\pi} \int \left(-1 + \frac{x}{x-z}\right) \text{Im } f_K(x) dx$$

$$\parallel$$

$$z\left(z - \frac{\text{hcap}(K)}{z} + \dots - z\right)$$

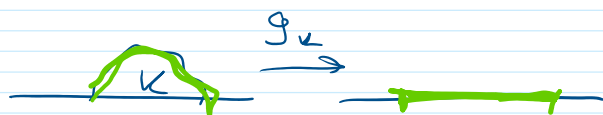
$$\downarrow z \rightarrow \infty$$

$$-\text{hcap}(K)$$

$$\downarrow z \rightarrow \infty$$

$$= -\frac{1}{\pi} \int \text{Im } f dx$$

$\text{Im } f_K(x) \neq 0$
only on a
compact set.

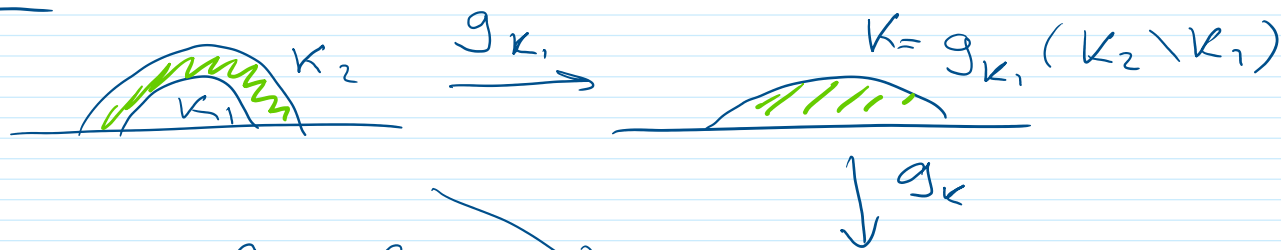


Corollary

- $\text{hcap}(K) > 0$ if K is non-trivial.

Corollary • $\text{hcap}(K) > 0$ if K is non-trivial.
 • $K_1 \subsetneq K_2$ then $\text{hcap}(K_1) < \text{hcap}(K_2)$

Proof



$$g_{K_2} = g_K \circ g_{K_1}$$

expand at infinity
compare $\frac{1}{z}$ terms

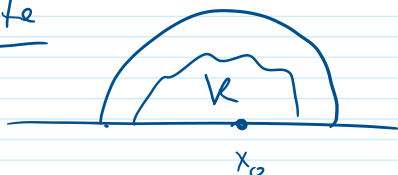
hcap is additive

$$\Rightarrow \text{hcap}(K_2) = \text{hcap}(K_1) + \underbrace{\text{hcap}(K)}_{> 0}$$

$$\text{hcap}(K_2) > \text{hcap}(K_1)$$



Note



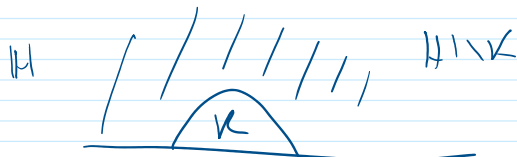
$$K \subset \{z: z \in H, |z - x_0| \leq R\}$$

$$\text{hcap} K \leq \text{hcap}(\text{half disc}) = R^2$$

No lower bound



$$\text{hcap}(K_\alpha) = \frac{1}{2} \alpha^{1-2\alpha} (1-\alpha)^{2\alpha-1} \rightarrow 0 \text{ as } \alpha \rightarrow 0 \text{ or } \alpha \rightarrow 1$$



$$g_K(z) = z + \frac{\text{hcap}(K)}{z} + \dots$$

thermodynamical normalization.

Lemma



Let $x \in \mathbb{R}$ be to the right

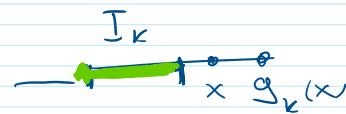
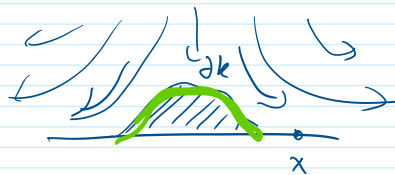
Lemma



Let $x \in \mathbb{R}$ be to the right of K

Then

$$g_K(x) > x$$



Proof

Schwarz formula for $f_K(z) - z$

$$f_K(x) - x = \frac{1}{\pi i} \int_{I_K} \frac{\operatorname{Im} f_K(t)}{t - x} dt$$

x to the right of K
 $\Rightarrow g_K(x)$ is to the right of I_K

Take x to the right of I_K

$$\Rightarrow f_K(x) - x < 0 \Rightarrow x > f_K(x) \quad (\text{apply } g_K)$$

$$\Rightarrow g_K(x) > x$$

Lemma

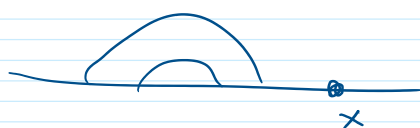


$K_1 \subset K_2$ x to the right of K_2

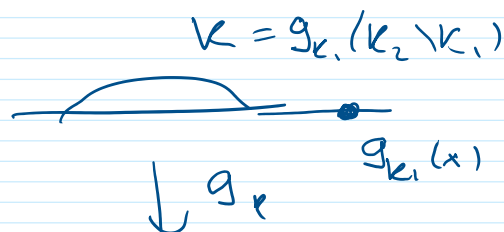
then

$$g_{K_1}(x) < g_{K_2}(x)$$

Proof



g_{K_1}



g_K

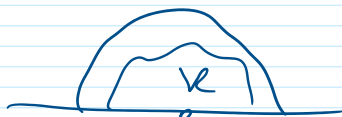
g_{K_2}



$$g_{K_2}(x) = g_K(g_{K_1}(x)) \Rightarrow g_{K_1}(x)$$

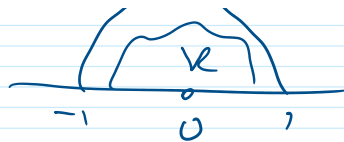


Lemma



$K \subset \mathbb{D}$ then $x > 1$

Lemma



$K \subset \mathbb{D}$ then if $x > 1$

then $x < g_K(x) < x + \frac{1}{x}$

Proof $K_1 = K$, $K_2 = \overline{\mathbb{D}} \cap \mathbb{H}$

$$g_{K_2} = z + \frac{1}{z}$$

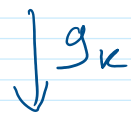
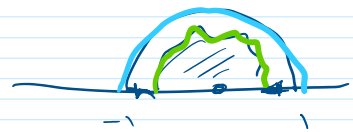
$$g_{K_2}(x) = x + \frac{1}{x} > g_K(x) > x$$



Lemma $\mathbb{H} \setminus K \xrightarrow{g_K} \mathbb{H}$ then

$$|g_K(z) - z| \leq 3 \text{rad}(K)$$

Proof Assume that $K \subset \mathbb{D}$



Previous lemmas $\Rightarrow$

$$[x^-, x^+] \subset [-2, 2]$$

• if $x > 1$ then

$$0 \leq g_K(x) - x \leq \frac{1}{x} \leq 1$$

$$\Rightarrow |g_K(x) - x| \leq 1 \Rightarrow |f_K(x) - x| \leq 1 \text{ if } x > 2$$

$$\bullet f_K((2, 2)) \subset \mathbb{D} \Rightarrow |f_K(x) - x| \leq 3 \text{ on } [-2, 2]$$

$$\bullet \text{ if } x < 1 \dots \Rightarrow \text{ if } x < -2 \Rightarrow |f_K(x) - x| \leq 1$$

$$\bullet |f_K(z) - z| \rightarrow 0 \text{ as } z \rightarrow \infty$$

$$\text{Maximum modulus} \Rightarrow |f_K(z) - z| \leq 3 \text{ in } \mathbb{H}$$

$$\Rightarrow |g_K(z) - z| \leq 3 \text{ in } \mathbb{H} \setminus K$$

Lemma Let us assume $K \subset \{ |z| \leq R \}$

$$z \in \mathbb{H}, |z| \geq 10R$$

Then

$$\left| g_K(z) - z - \frac{\text{hcap } K}{z} \right| \leq \frac{10R \text{hcap}(K)}{|z|^2}$$

Proof

$$\text{hcap } K = \int_{\partial K} \frac{1}{z} dz = 0$$

Proof $g_k(z) - z - \frac{\log k}{z} = \frac{1}{\pi} \int_{\mathbb{R}} \underbrace{\operatorname{Im} f_k}_{\substack{\text{if } |x| \leq 2R \\ = 0 \text{ outside of } [-2R, 2R]}} \left(\frac{1}{g_k(z) - x} - \frac{1}{z} \right) dx$

Since $|z| > 10R$

$$|g_k(z) - z| \leq 3R$$

$$\left| \frac{1}{g_k(z) - x} - \frac{1}{z} \right| = \frac{|g_k(z) - x - z|}{|z| |g_k(z) - x|} \leq \frac{5R}{|z| |z - 5R|} \leq \frac{10R}{|z|^2}$$

if $|x| \leq 2R$

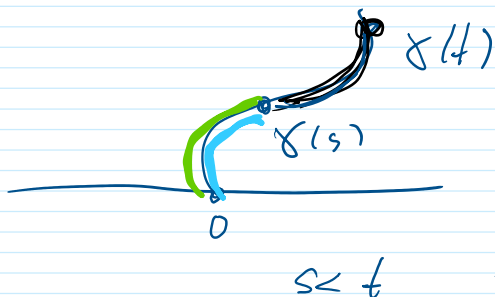
Since $K \subset \{ |z| \leq R \} \Rightarrow \operatorname{Im} f_k = 0$ outside of $[-2R, 2R]$

Then $|g_k(z) - z - \frac{\log k}{z}| \leq \frac{10R}{|z|^2} \frac{1}{\pi} \int_{\mathbb{R}} \operatorname{Im} f_k = \frac{10R \log k}{|z|^2}$

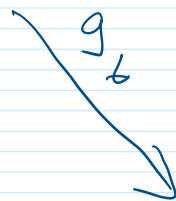


Loewner's Evolution

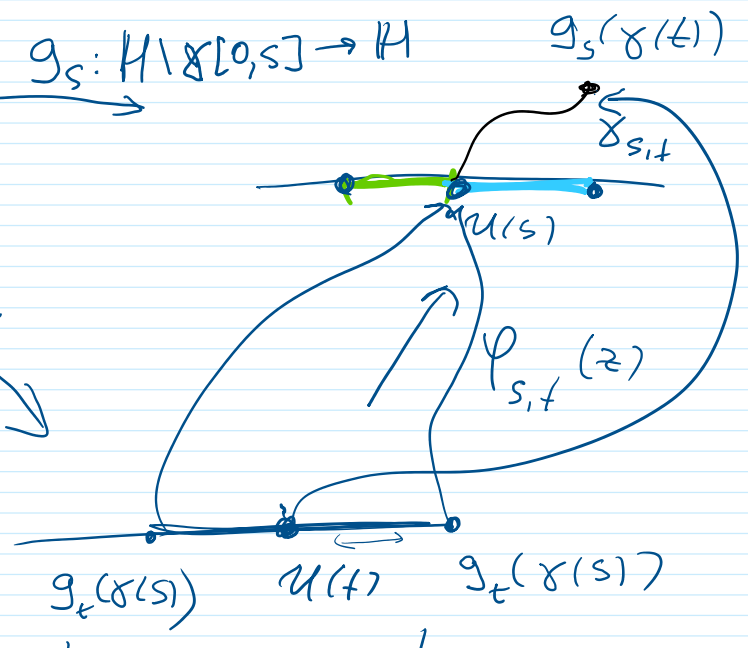
Chordal version $\gamma(t)$ is a simple curve in $\mathbb{H}$
s.t. $\gamma(0) = 0$, $\gamma(t) \neq \infty$ for $t > 0$



$$g_s: \mathbb{H} \setminus \gamma[0, s] \rightarrow \mathbb{H}$$



Def $\varphi_{s,t} = g_s \circ g_t^{-1}$



$g_t(\gamma(s))$ $u(t)$ $g_t(\gamma(s))$
Claim: $u(t)$ is continuous in t
 Fix T large $0 < s < t < T$
 $\forall \varepsilon > 0 \quad \exists \delta$ s.t. $|s - t| < \delta$ then
 $\text{diam } \gamma([s, t]) < \varepsilon$

By Beurling estimate

$$\text{diam}(\gamma_{s,t}) = \text{diam}(g_s(\gamma([s, t]))) \leq c\sqrt{\varepsilon}$$

$$\Rightarrow |\varphi_{s,t}(z) - z| \leq c\sqrt{\varepsilon}$$

$$\Rightarrow |u(t) - u(s)| = \underbrace{|u(t) - g_t(\gamma(s))|}_{\leq c\sqrt{\varepsilon}} + \underbrace{|g_t(\gamma(s)) - u(s)|}_{\leq c\sqrt{\varepsilon}} \leq c\sqrt{\varepsilon}$$

Claim g_t satisfies a certain D.E

$$\varphi_{s,t}(z) - z = \frac{1}{\pi} \int \frac{1}{x - z} \text{Im } \varphi_{s,t}(x) dx$$

$g_s = \varphi_{s,t}(g_t)$, plug in $g_t(z)$ instead of z

$$g_s(z) - g_t(z) = \frac{1}{\pi} \int \frac{1}{x - g_t(z)} \text{Im } \varphi_{s,t}(x) dx$$

$\text{Im } \varphi_{s,t} = 0$ outside of an interval around $u(t)$, which shrinks as $s \nearrow t$

$$\partial_t g_t(z) = \lim_{s \rightarrow t} \frac{g_s(z) - g_t(z)}{s - t} = \frac{1}{u(t) - g_t(z)} \lim_{s \rightarrow t} \frac{1}{s - t} \int \frac{1}{\pi} \text{Im } \varphi_{s,t}(x) dx$$

$$\text{hcap } \gamma[0, t] = \text{hcap } \gamma_{s,t} - \text{hcap } \gamma[0, s]$$

$$= \frac{1}{g_t(z) - u(t)} \partial_t \text{hcap } \gamma[0, t]$$

$$= \frac{1}{g_t(z) - u(t)} \partial_t \text{hcap } \gamma[0, t]$$

Loewner Evolution or Loewner D.E

$$\dot{g}_t(z) = \frac{\partial_t \text{hcap } \gamma[0, t]}{g_t(z) - u(t)}$$

Consider $f_t(z) = g_t^{-1}(z)$

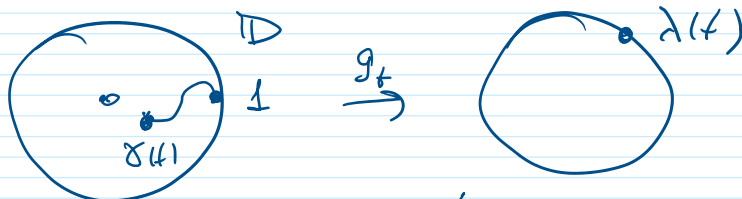
$f_t(g_t(z)) = z$, differentiate w.r.t t

$$\dot{f}_t(z) = -f'_t(z) \frac{\partial_t \text{hcap } \gamma[0, t]}{z - u(t)}$$

Note We assumed that $\partial_t \text{hcap } \gamma[0, t]$ exists

Def If γ is parametrized s.t $\text{hcap } \gamma[0, t] = 2t$
then we say that γ is parametrized by capacity

Radial version

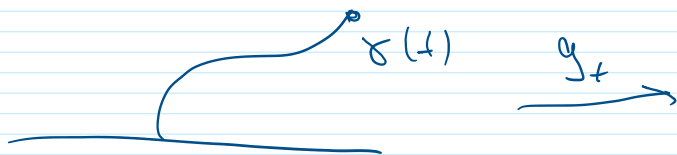


Parametrize γ s.t $g_t(z) = e^t z + \dots$

$$\dot{g}_t(z) = g_t(z) \frac{\lambda(t) + g_t(z)}{\lambda(t) - g_t(z)}$$

$$\dot{f}_t(z) = -z f'_t(z) \frac{\lambda(t) + z}{\lambda(t) - z}$$

Solving Loewner D.E



$$\begin{cases} \partial_t g_t(z) = \frac{2}{g_t(z) - u(t)} & \left[\begin{array}{l} \gamma \text{ is param.} \\ \text{by cap} \end{array} \right] \\ g_0(z) = z \end{cases}$$

$$\text{Given } \gamma \longrightarrow \{g_t\} \rightsquigarrow u(\cdot)$$

?

$$\longleftarrow$$

Th Let μ_t be a family of non-negative Borel measures on $\mathbb{R}$ s.t. $\forall T \exists R(T)$ s.t. $\forall t \in [0, T]$

- $\text{supp } \mu_t \subset [-R, R]$
- $\mu_t(\mathbb{R}) < R$

Assume that μ_t is cont. in t w.r.t. weak topology. For each $z \in \mathbb{H}$ let $g_t(z)$ be the solution

$$g_t(z) = \int_{\mathbb{R}} \frac{\mu_t(dx)}{g_t(z) - x}, \quad g_0(z) = z$$

Define $T(z)$ to be the supremum of t s.t. $g_t(z)$ exists and $g_t(z) \in \mathbb{H}$ for all $s < t$

$$K_t \stackrel{\text{def}}{=} \{z \in \mathbb{H} \text{ s.t. } T(z) \leq t\}$$

$$\mathbb{H}_t = \{z : T(z) > t\} = \mathbb{H} \setminus K_t$$

$$H_t = \{z: T(z) > t\} = H \cap K_t$$

Then g_t is the conformal map $H_t \rightarrow H$ with the thermodynamical norm.

$$g_t(z) = z + \frac{b(t)}{z} + \dots \quad \text{at } \infty$$

$$b(t) = \int_0^t \mu_s(\mathbb{R}) ds$$

Note if $\mu_t = 2S_{u(t)}$ then

$$\int \frac{\mu_t(dx)}{g_t(z) - x} = \frac{2}{g_t(z) - u(t)}$$

$u(t)$ is the driving function

$\{\mu_t\}$ is the driving family of measures

Proof $\partial_t (\operatorname{Im} g_t(z)) = - \int \frac{\operatorname{Im} g_t(z)}{|g_t(z) - x|^2} \mu_t(dx) < 0$

$$\Rightarrow \operatorname{Im} g_t(z) \searrow \Rightarrow T(z) = \sup \{t: \operatorname{Im} g_t > 0\}$$

Let w, v be two trajectories started from z_1 and z_2

Assume that both exist up to t

$$\partial_t(w-v) = -(w-v) \int \frac{\mu_t(dx)}{(w-x)(v-x)}$$

$$\Rightarrow w-v = (z_1 - z_2) \exp \left[- \int_0^t \int_{\mathbb{R}} \frac{\mu_s(dx)}{(w-x)(v-x)} ds \right]$$

$$w-v=0 \Leftrightarrow z_1=z_2$$

divide by $z_1 - z_2$ and pass to the limit $z_2 \rightarrow z_1$

arrive very close to z_2 and pass to the limit $z_2 \rightarrow z_1$

$$g'_t(z) = \exp\left(-\int_0^t \int_{\mathbb{R}} \frac{\mu_s(dx)}{(g_s(z)-x)^2} ds\right)$$

- $g_t(z)$ is differentiable in z
- $g'_t(z) \neq 0$

Claim: g_t is onto $\mathbb{H}$

Proof take $w \in \mathbb{H}$, $t \geq 0$

consider $\dot{h}_s(w) = - \int_{\mathbb{R}} \frac{\mu_{t-s}(dx)}{h_s(w)-x}$, $h_0(w) = w$

In $h_s(w) \nearrow \Rightarrow$ solution exists for all $s \leq t$

Take $z = h_t(w)$, then $g_t(z) = g_t(h_t(w)) = w$

Claim g_t is properly normalized

$$\begin{aligned} \dot{g}_t &= \int \frac{\mu_t(dx)}{g_t(z)-x} = \frac{\mu_t(\mathbb{R})}{g_t(z)} + o\left(\frac{1}{g_t(z)}\right) \\ &= \frac{\mu_t(\mathbb{R})}{z} + o\left(\frac{1}{z}\right) \quad \left[\text{use uniform bound on } g_t \text{ at } \infty \right] \end{aligned}$$

$$g_t(z) = z + \left(\int_0^t \mu_s(\mathbb{R}) ds\right) \frac{1}{z} + \dots$$

Radial case $\{\mu_t\}$ family of measures on $[0, 2\pi]$, $\sup_{t < T} \mu_t([0, \pi]) < \infty \quad \forall T$

$$\text{solve } \begin{cases} \dot{g}_t(z) = g_t(z) \int_0^{2\pi} \frac{e^{i\theta} + g_t(z)}{e^{i\theta} - g_t(z)} \mu_t(d\theta) \\ g_0(z) = z \end{cases}$$

$T(z)$ is time of maximal existence of g_t

($y_0(z) = z$
 $T(z)$ the time of maximal existence of g_t
 $\text{in } \mathbb{D}$

$$\Omega_t = \mathbb{D}_t = \{z \in \mathbb{D}, T(z) > t\}$$

Then $g_t: \Omega_t \rightarrow \mathbb{D}$ s.t

$$g_t(0) = 0 \quad \text{and}$$

$$g'_t(0) = \exp\left(\int_0^t \mu_s([0, 2\pi]) ds\right)$$

Standard parametrization $\mu_t([0, 2\pi]) = 1$

When K_t is a curve?

$$g_t(z) = \int \frac{\mu_t(dx)}{g_t(z) - x}$$



For K_t to be a cont curve

μ_t must be $\delta_{K_t(t)}$

Th g_t, K_t driving function of g_t is $u(t)$

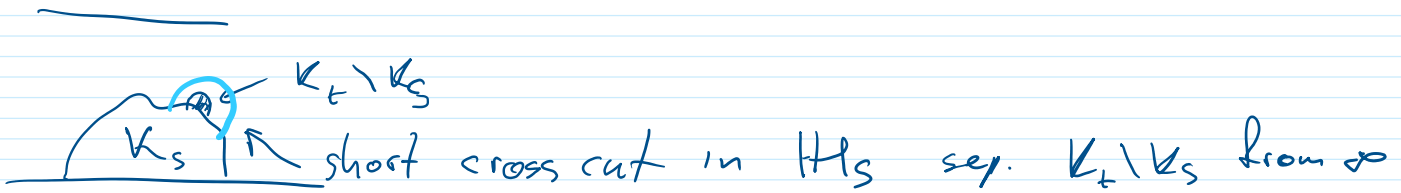
Then the following are equivalent

① $u(t)$ is cont.

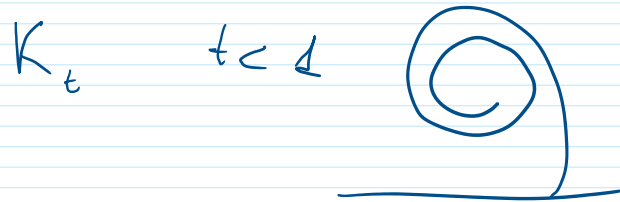
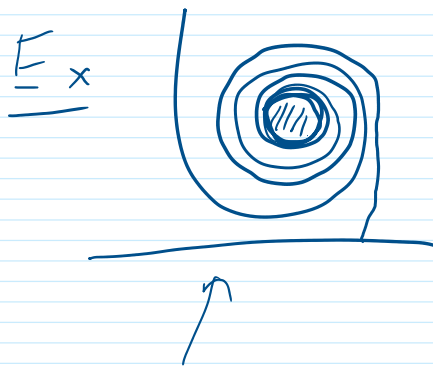
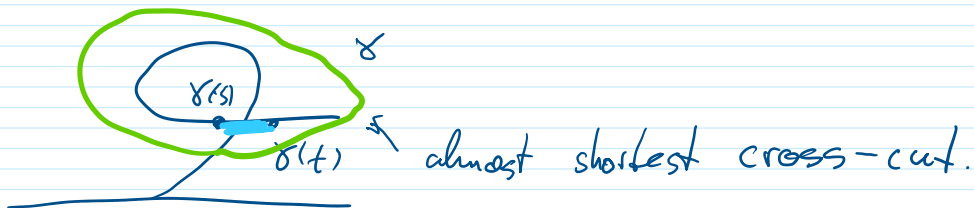
② $\forall \varepsilon > 0 \exists \delta$ s.t $|s - t| < \delta$ then

$\exists$ cross-cut in H_s of diam $\leq \varepsilon$
 which separates $K_s \setminus K_t$ from ∞

→ cross-cut in H_S at diam. ≈ 2
which separates $K_t \setminus K_S$ from ∞



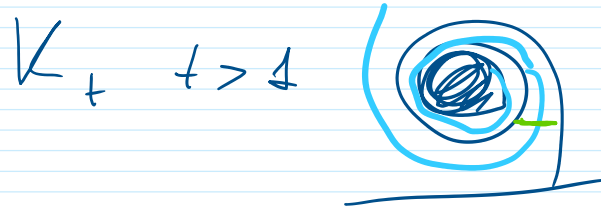
$\Rightarrow u(t)$ is cont.



$u(t)$ is cont.

but at time $t=1$

$$K_1 \setminus \bigcup_{t < 1} K_t = \text{disc}$$

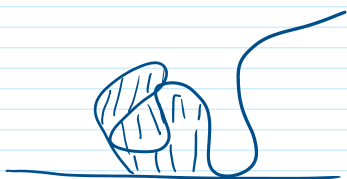


$\Rightarrow K_t$ is not generated by a curve

$(\exists \gamma \text{ s.t. } H_t = H \setminus K_t = \text{unbounded comp of } H \setminus \gamma[0, t])$

Def $\gamma(t)$ is the trace of K_t

$$K_t = \gamma[0, t] + \text{all loops}$$



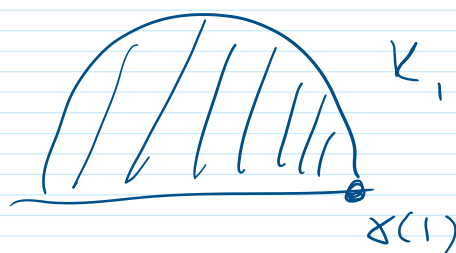
Th Let us assume that

$$\lim_{y \rightarrow 0} g_t^{-1}(u(t) + iy) \stackrel{\text{def}}{=} \gamma(t) \quad \text{exists}$$

Then γ is right cont. function and
it is the trace of the Loewner Evolution



$t < 1$



$t = 1$

γ is not left cont at $t=1$

K_t is generated by a Loewner Evolution
with cont $u(t)$

Th if $u(t)$ is Hölder- $\frac{1}{2}$ cont.
with small norm, then there is
a cont. simple trace

$$\sup_{s \neq t} \frac{|u(t) - u(s)|}{|t - s|^{\frac{1}{2}}} \stackrel{\text{def}}{=} \|u\|_{\frac{1}{2}} < \infty$$

Basic Properties of LE

Ex $u(t) = 0$

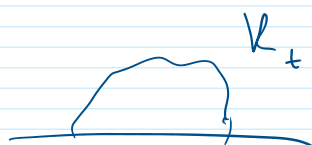
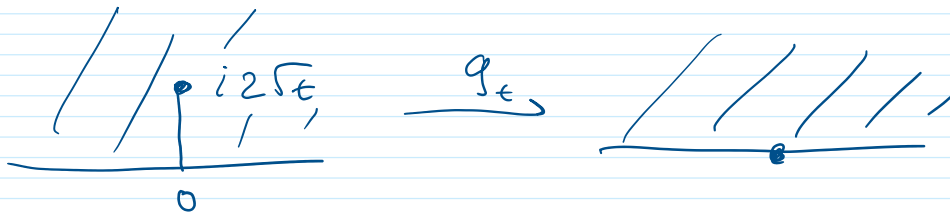
$$\dot{g}_t(z) = \frac{2}{g_t} \Rightarrow z g_t \dot{g}_t = 2 \Rightarrow$$

$$\dot{g}_t(z) = \frac{z}{g_t} \Rightarrow \underbrace{2g_t \dot{g}_t = 4} \Rightarrow$$

$$\Rightarrow \partial_t (g_t^2) = 4 = g_t^2 = 4t + \text{const}(z)$$

$$\text{At } t=0 \quad z^2 = \text{const} \Rightarrow$$

$$g_t(z) = \sqrt{z^2 + 4t}$$



normalized $\text{hcap } K_t = 2t$



$$\lambda K_t = K_s \quad \text{hcap}(\lambda K_t) = 2t \lambda^2$$

suggests time change $s = \lambda^2 t$

$$\text{hcap}(K_s) = 2s$$

$$\tilde{g}_s = \lambda g_{s/\lambda^2}(z/\lambda) \quad \text{diff. w.r.t } s$$

$$\partial_s \tilde{g}_s = \frac{1}{\lambda} \dot{g}_{s/\lambda^2}(z/\lambda) = \frac{1}{\lambda} \frac{2}{g_{s/\lambda^2}(z/\lambda) - u(s/\lambda^2)}$$

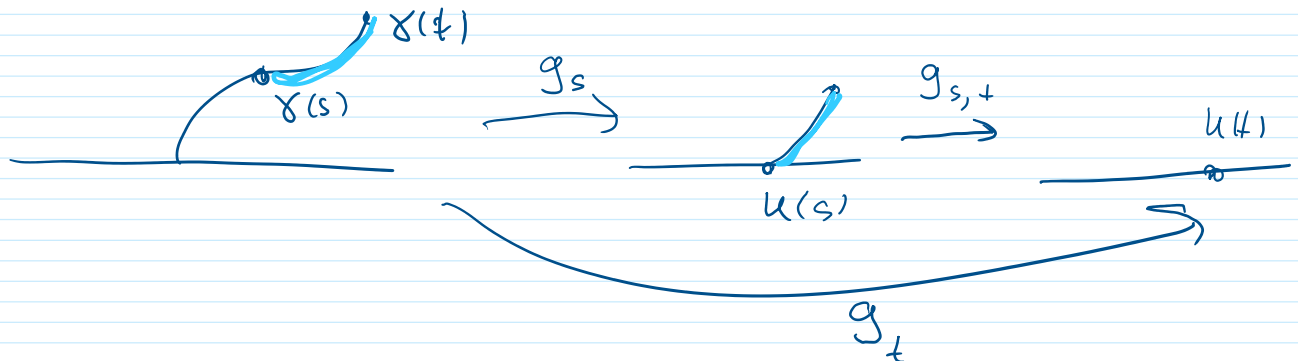
$$= \frac{2}{\underbrace{\lambda g_{s/\lambda^2}(z/\lambda)}_{\tilde{g}_s} - \underbrace{\lambda u(s/\lambda^2)}_{\text{def } u(s)}} = \frac{2}{\tilde{g}_s(z) - u(s)}$$

$$c \quad 1. \quad 1/ \quad 0 \quad 1 \quad \longrightarrow \quad s = \lambda^2 t$$

Scaling K_t by $\lambda \longleftrightarrow s = \lambda^2 t$
 $\tilde{u}(s) = \lambda u(s/\lambda^2)$

Note if $u(t)$ is BM then
 $\tilde{u}$ is also BM

Semi-group property (Markov)



$$g_t = g_{s,t} \circ g_s$$

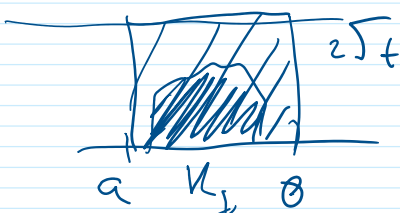
Consider $\tilde{g}_t = g_{s,s+t}$ then

$$\partial_t \tilde{g}_t = \frac{2}{\tilde{g}_t - u(s+t)} \leftarrow \text{LE with the driver}$$

$$\tilde{u}(t) = u(s+t)$$

Lemma Suppose $u(t) \in [a, b]$ for all t
then $K_t \subset [a, b] \times [0, 25t]$

E $\times$ $u(t) \equiv a$ then $K_t = \{a\} \times [0, 25t]$
 $\bullet$ $u(t) \equiv b$ $K_t = \{b\} \times [0, 25t]$



Proof Let $y_t = \operatorname{Im} z_t = \operatorname{Im} g_t(z)$

$$\dot{y}_t = - \frac{2y_t}{|g_t(z) - u(t)|^2} \geq - \frac{2}{y_t} \quad \left[\begin{array}{l} \text{Note: this is sharp} \\ \text{when } \operatorname{Re} z \equiv u(t) \end{array} \right]$$

$$y_t^2 \geq y_0^2 - 4t$$

y_t can not hit 0 before $t = \frac{y_0^2}{4}$

or if $y_t = 0 \Rightarrow 4t \geq y_0^2 \Rightarrow y_0 \leq 2\sqrt{t}$

$\Rightarrow$ if $y_0 > 2\sqrt{t}$ then $z \notin K_t$

$$(2) \quad \dot{x}_t = \frac{2(x_t - u(t))}{|g_t(z) - u(t)|^2}$$

if $x = x_0 > b$ then $\dot{x}_t > 0 \quad \forall t$

$\Rightarrow x_t > b \Rightarrow z_t$ can not hit $u(t)$

$$\dot{y}_t \geq - \frac{2y_t}{(x_0 - b)^2} \Rightarrow y_t \geq y_0 e^{-2t(x_0 - b)^2}$$

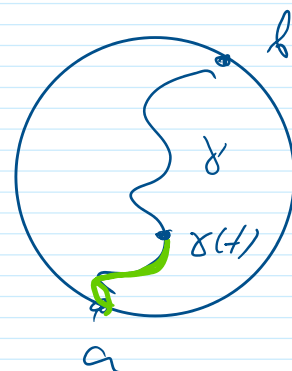
$\Rightarrow T(z) = \infty$

The same holds when $x_0 < a$



Schramm Loewner Evolution

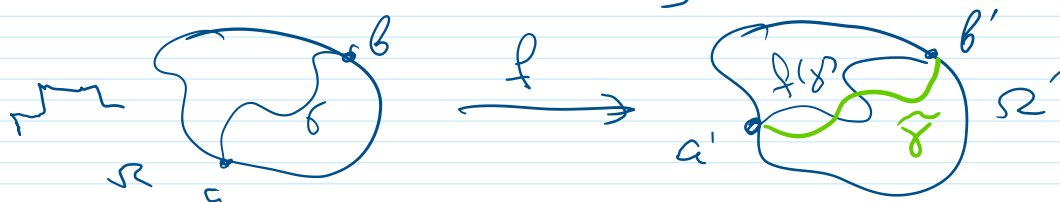
Def Let $\mu(\Omega, a, b)$ be a measure on curves/kulks from a to b inside Ω



① μ satisfies the Domain Markov property if

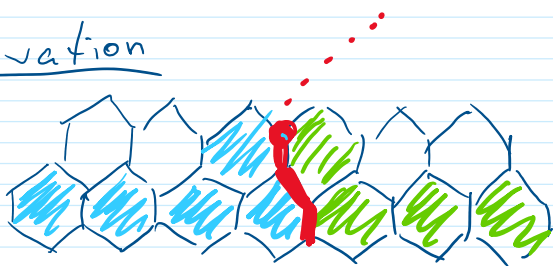
$$\mu(\Omega, a, b \mid \gamma[0, t]) = \mu(\Omega \setminus \gamma([0, t]), \gamma(t), b)$$

② μ is conformally invariant if



$$f(\mu(\Omega, a, b)) = \mu(\Omega', a', b')$$

Motivation



Condition that red curve starts like this



For percolation, we get DMP for free

Also true for Ising model

True for all models with short-range (nearest neighbours) interaction

• Conf inv inv under rotations
 inv under inversion

1 " 1 " 1 " 1 " 1 "

inv under inversion

suggests that on large scales the model is inv. under conf. transformations

Th (Schramm's Principle)

Let μ be a cont. invariant family of measures satisfying the Domain Markov property.

Let γ be a random curve in H given by $\mu(H, 0, \infty)$. Let us parametrize γ by capacity, γ can be described by a Loewner Evolution with the driving function u . Then $u(t) \stackrel{d}{=} c B_t$ where B_t is a standard Brownian Motion.

Def Let $x \geq 0$ then $SLE(x)$, SLE_x is the Loewner Evolution driven by $u(t) = \sqrt{x} B_t \stackrel{d}{=} B_{xt}$

Idea of the proof

Idea of the proof

$\text{Law} \left(\begin{array}{c} \text{red curve } \gamma(t) \\ \text{starting at } 0 \end{array} \right) \stackrel{\text{Markov}}{=} \text{Law} \left(\begin{array}{c} \text{cut along } \gamma \\ \text{blue and green curves} \end{array} \right)$

// equal up to
a shift

$$\text{Law} \left(\begin{array}{c} \text{---} \\ | \\ u(t) \end{array} \right) = \text{Law} \left(\begin{array}{c} \text{---} \\ | \\ u(t) \end{array} \right)$$

Driving function for this is $u(t+s)$

$$\tilde{u}(s) = u(t+s)$$

$$\Rightarrow \text{Law}(u(t+s) - u(t)) = \text{Law}(u(s))$$

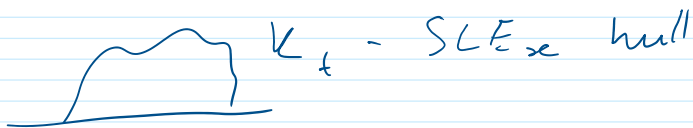
Driving function has stationary indep. increments

$\Rightarrow$ multiple of BM



Properties of SLE

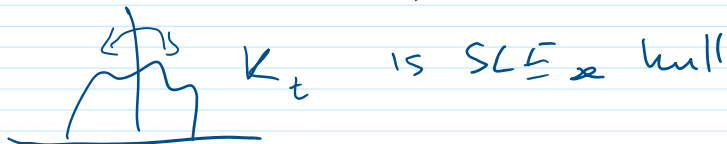
- SLE is scale invariant.



λK_t — this is given by LE driven
by $\tilde{u} = \lambda u(t/\lambda^2) = \lambda \sqrt{x} B_{t/\lambda^2} \stackrel{d}{=} \sqrt{x} B_t$

Scaled SLE_x $\stackrel{d}{=}$ time changed SLE_x

- SLE is symmetric



$$\hat{K}_t = \{x+iy \in \mathbb{H} \text{ s.t. } -x+iy \in K_t\}$$

driving function for $\hat{K}_t$ is $-u(t) =$
 $= -\sqrt{x} B_t \stackrel{d}{=} \sqrt{x} B_t$

Th (Rohde-Schramm) Let g_t be SLE maps

Then a.s. $\exists \gamma(t)$ s.t.

$$\gamma(t) = \lim_{n \rightarrow \infty} g_n^{-1}(u(t)+iy)$$

$$\gamma(t) = \lim_{y \rightarrow 0} g_t^{-1}(u(t) + iy)$$

$H_t = H \setminus K_t$ = the unbounded comp of $H \setminus \gamma[0, t]$.
In other words a.s. there is an SLE trace.

Phase Transitions

Th 4.7 Let γ be SLE_x trace then

- ① $x \in [0, 4]$ then $\gamma(t)$ is a.s. a simple curve s.t. $\gamma(t) \rightarrow \infty$ as $t \rightarrow \infty$
- ② $x \in (4, 8)$ then γ is not a simple curve, $\bigcup K_t \supset \overline{H}$ and $\text{dist}(0, H_t) \rightarrow \infty$ (and $\gamma \rightarrow \infty$)
- ③ $x \geq 8$ then γ is a space-filling curve
 $\forall z \in \overline{H} \quad \exists t \text{ s.t. } \gamma(t) = z$
 $\gamma(t) \rightarrow \infty$ as $t \rightarrow \infty$

Lemma (Boundary phase transition) [4.8 Lecture notes]

Let γ be SLE_x trace

① $x \leq 4$ then $\gamma([0, \infty)) \cap \mathbb{R} = \emptyset$

② $4 < x < 8$ then for all $x, y > 0$
 γ intersects $[x, x+y)$ a.s.

$$0 < \mathbb{P}(\gamma \text{ hits } [x, x+y)) = \mathbb{P}\left(\frac{y}{x+y}\right) < 1$$

③ $x \geq 8$ then $\mathbb{R} \subset \gamma([0, \infty))$

Lemma $X_t = g_t(x) - \sqrt{x} dB_t$

$$dX_t = \frac{2}{x} dt - \sqrt{x} dB_t, \quad X_0 = x \in \mathbb{R}$$

$$0 < r < x < y < R < \infty$$

Denote $T_x = \inf \{s : x_s = 0\}$, $\tau = \inf \{s : x_s \notin [r, R]\}$

$$T(R) = \inf \{s : x_s = R\}$$

Then

$$x \leq r \quad \text{then} \quad \mathbb{P}(T_x = \infty) = 1 \quad \checkmark$$

$$x > y \quad \text{then} \quad \mathbb{P}(T_x = \infty) = 0 \quad \checkmark$$

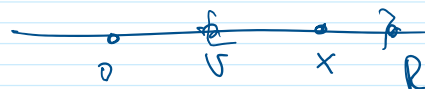
$$r < x < y$$

$$\mathbb{P}(T_x = T_y) = \frac{\int_0^{x/y} (1-s)^{8/x-2} s^{-4/x} ds}{\int_0^1 (1-s)^{8/x-2} s^{-4/x} ds}$$

$$x \geq y \quad \mathbb{P}(T_x = T_y) = 0$$

Proof

$$F(x) = \mathbb{P}^x(x_\tau = r)$$



Markov property $\Rightarrow F(X_{t \wedge \tau})$ is a martingale

$$\mathbb{P}^x(x_\tau = r | \mathcal{F}_t) = F(X_{t \wedge \tau})$$

Assume that $F \in C^2$

Ito $\Rightarrow$

$$dF(X_t) = \underbrace{\left(\frac{2}{x_t} F'(x_t) + \frac{x_t}{2} F''(x_t) \right)}_{\leftarrow \text{Martingale}} dt - \sqrt{x_t} F'(x_t) dB_t$$

$$\left(x \frac{F''(x)}{1} + \frac{2}{2} F'(x) \right) = 0$$

$$\begin{cases} \frac{x}{2} F''(x) + \frac{2}{x} F'(x) = 0 \\ F(r) = 1, F(R) = 0 \end{cases}$$

$$x \neq 4 \quad \tilde{F}(x) = \frac{R^{1-4/x} - x^{1-4/x}}{R^{1-4/x} - r^{1-4/x}}$$

$$x = 4 \quad \tilde{F}(x) = \frac{\ln R - \ln x}{\ln R - \ln r}$$

Consider $M_t = \tilde{F}(X_{t \wedge \tau})$. This is a martingale

Optional stopping theorem. $\Rightarrow M_t = F(X_t)$

$$\Rightarrow F(x) = \tilde{F}(x)$$

Case $x \leq 4$ $P(X_\tau = r) \rightarrow 0$ as $r \rightarrow 0$

$$\Rightarrow \forall R \quad P(T(R) < T_x) = 0$$

$$\Rightarrow P(T_x = \infty) = 1$$

$x = 4$ fix r , then $F(x) \rightarrow 1$ as $R \rightarrow \infty$

as X_t will visit any nbhd of 0  $R \gg 1$

Case $x > 4$ Consider the limit $r \rightarrow 0$

$$P(T(R) < T_x) = 1 - \lim_{r \rightarrow 0} F(x) = \left(\frac{x}{R}\right)^{1-4/x} \xrightarrow{R \rightarrow \infty} 0$$

$$\Rightarrow \mathbb{P}(T_x = \infty) = 0$$

$$\mathbb{P}(T_x < \infty) = 1$$

$$\varphi(x, y) = \mathbb{P}(T_x = T_y) \quad \text{a.s.}$$

By monotonicity $X_t < Y_t \Rightarrow T_x \leq T_y < \infty$

$\varphi(X_t, Y_t)$ is a martingale

$$d\varphi(X_t, Y_t) = \left(\frac{2}{x_t} dt + \sqrt{x_t} dB_t \right) \varphi_x + \left(\frac{2}{y_t} dt + \sqrt{y_t} dB_t \right) \varphi_y \right] \quad \text{requires } \varphi \in C^2$$

$$+ \frac{x}{2} (\varphi_{xx} + \varphi_{yy} + 2\varphi_{xy}) dt$$

Martingale $\Rightarrow$ drift = 0 $\Rightarrow$ PDE

$$\frac{2}{x} \varphi_x + \frac{2}{y} \varphi_y + \frac{x}{2} \varphi_{xx} + \frac{x}{2} \varphi_{yy} + 2x \varphi_{xy} = 0$$

SLE is scale invariant $\Rightarrow$

$\varphi(x, y) = h(x/y)$, change variables $t = x/y$

$$h''(t) x t(t-1) = h'(t) 2(t(x-2)-2)$$

$$(\ln h')' = \frac{2}{x} \left(-\frac{2}{t} - \frac{4-x}{1-t} \right)$$

$$h(t) = c_1 \int_0^t (1-s)^{8/x-2} s^{-4/x} ds + c_2$$

$$h(0) = 0 \Rightarrow c_2 = 0$$

$$h(1) = 1 \Rightarrow \frac{1}{c_1} = \int_0^1 (1-s)^{8/x-2} s^{-4/x} ds$$

requires $x < 8$

If $x \geq 8$ the only bounded solution

If $x \geq 8$ the only bounded solution with $h(0) = 0$ is $h(t) = 0$

$$\Rightarrow P(T_x = T_y) = 0$$



$$\int_0^1 \dots = \frac{\Gamma(\frac{8}{x}-1) \Gamma(\frac{x-4}{x})}{\Gamma(\frac{4}{x})}$$

Solution to ODE

$$c_1 \frac{x}{x-4} t^{1-\frac{4}{x}} {}_2F_1\left(2-\frac{8}{x}, \frac{x-4}{x}, 1+\frac{x-4}{x}, t\right) + c_2$$

${}_2F_1(a, b, c, z)$ Hypergeometric function ${}_2F_1$

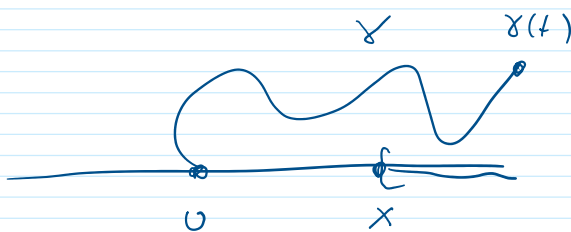
$$\sum_{n=0}^{\infty} \frac{(a)_n (b)_n}{(c)_n} z^n, \quad (a)_n = a(a+1)\dots(a+n-1)$$

$$z(1-z)f''(z) + (c - (a+b+1)z)f'(z) - abf(z) = 0$$

which is regular at $z=0$
with $f(0) = 1$

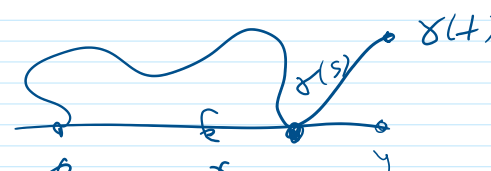


Proof of the boundary phase transition



If $\gamma([0, t]) \cap [x, \infty) = \emptyset$
then by compactness
 $[x, \infty)$ is not in a nbhd
of K_t

$$\Rightarrow x \notin K_t \Rightarrow \underline{T_x > t}$$

If  if $x(s) \in [x, \infty)$ then $T_x \leq T_{x(s)} = s \leq t$

$$\{x([0, t]) \cap [x, \infty) \neq \emptyset\} = \{T_x \leq t\}$$

$$\{x([0, t]) \cap [x, y] \neq \emptyset\} = \{T_x < T_y\}$$

$$\neg \mathbb{P} \quad x \leq y$$

$$P(x \text{ hits } \mathbb{R} \setminus \{0\}) = \lim_{n \rightarrow \infty} P(x \text{ hits } \mathbb{R} \setminus [\frac{1}{n}, \frac{1}{n}]) = 0$$

$T_x = \infty$ a.s. $\forall x$

If $x \geq 0$ i.s. $\forall x, y \in \mathbb{Q} \quad \exists t$ s.t. $x(t) \in [x, y]$
 $T_x < T_y$

Since x is continuous the same is true for all $x, y \in \mathbb{R}$

$$\Rightarrow \mathbb{R} \subset x([0, \infty))$$

If $4 < x < 8$

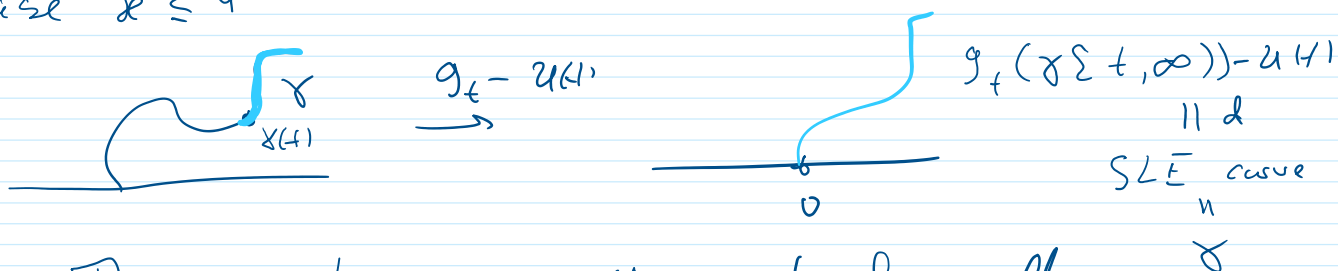
$$P(x \text{ hits } [x, x+y]) = P(T_x < T_{x+y})$$

$$= 1 - \frac{\int_0^{\frac{x}{x+y}} (1-s)^{8x-2} s^{-4/x} ds}{\int_0^1 \dots ds} = \frac{\int_{1-\frac{y}{x+y}}^1 \dots}{\int_0^1 \dots}$$

$$= \varphi\left(\frac{y}{x+y}\right)$$

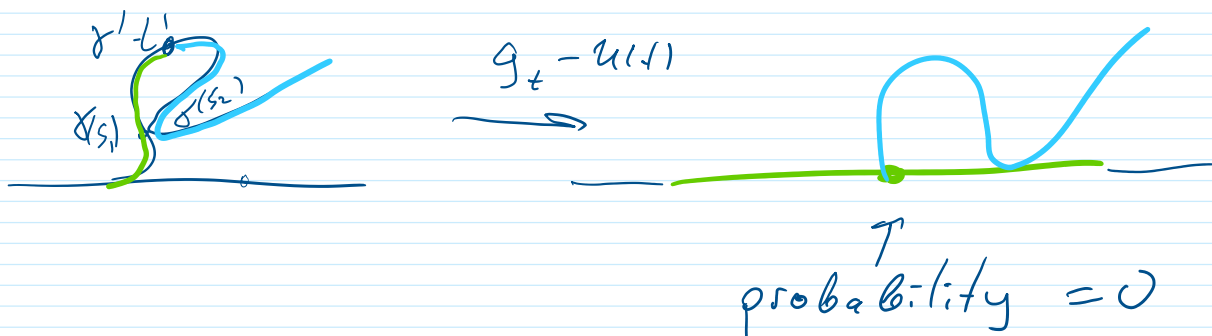
"Proof" of the phase transition.

Case $\kappa \leq 4$



This is true simultaneously for all rational t

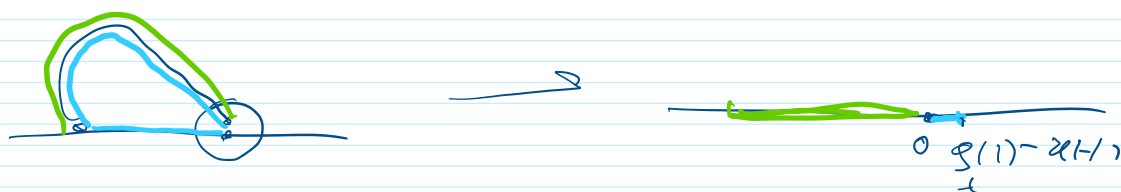
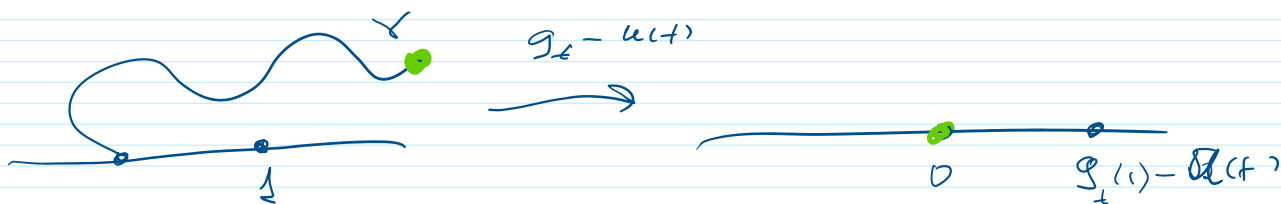
Assume that $\gamma(s_1) = \gamma(s_2)$ $s_1 < s_2$
 $\exists$ rational $t \in (s_1, s_2)$



$\Rightarrow \gamma$ is simple with $P = 1$

If $\kappa < 4$ $\inf_{t>0} g_t(1) - \sqrt{\kappa} B_t > 0$ a.s

$\Rightarrow \inf_{t>0} |\gamma(t) - 1| > 0$ a.s



γ will leave a neighborhood of the origin.

... ..

γ will leave a nbhd of the origin.
 0-1 law / scaling $\Rightarrow \gamma$ will leave any
 nbhd of 0

$$\Rightarrow \gamma \rightarrow \infty$$

If $4 < \kappa < 8$ (considers $\text{dist}(0, H_t)$)

$\gamma([0, 1]) \leftarrow$ will a.s. hit $(0, \infty)$ and $(-\infty, 0)$



$\exists$ nbhd of 0 s.t.
 this nbhd is inside K_1

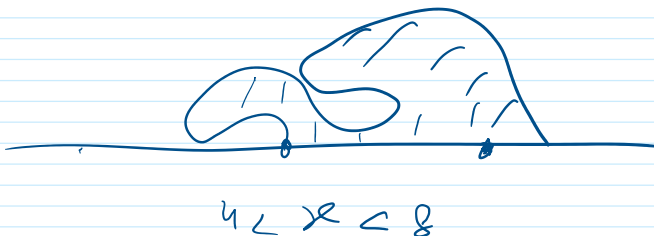
$$P(\text{dist}(0, H_t) > 0 \forall t) = 1$$

$$P(\text{dist}(0, H_t) \leq r) = P(\text{dist}(0, H_1) \leq \frac{r}{\sqrt{t}}) \xrightarrow[t \rightarrow \infty]{} 0$$

$$\Rightarrow \text{dist}(0, H_t) \rightarrow \infty \text{ as } t \rightarrow \infty \text{ a.s.}$$

$$\Rightarrow \gamma(t) \rightarrow \infty \text{ as } t \rightarrow \infty \text{ a.s.}$$

γ is space-filling



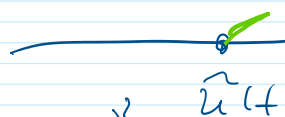
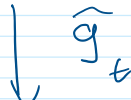
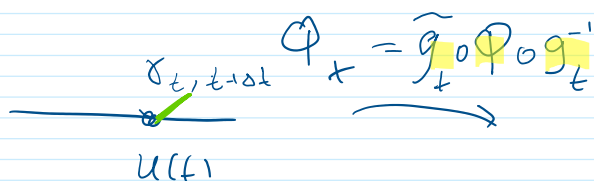
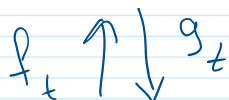
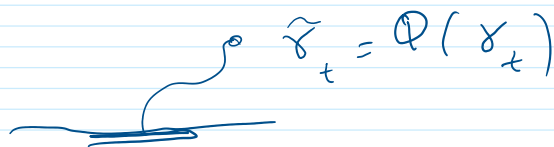
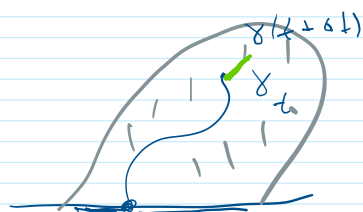
$$4 < \kappa < 8$$



$$\kappa \geq 8$$

Locality

Range of local coordinates in LE



Φ is univalent
in a neighborhood
of x
 Φ is real
on $\mathbb{R}$

$$\text{Claim } \partial_t \tilde{g}_t(z) = \frac{2(\Phi'_t(u(t)))^2}{\tilde{g}_t - \hat{u}(t)}$$

$$\Leftrightarrow \partial_t \text{hcap } \tilde{\gamma}[0, t] = 2(\Phi'_t(u(t)))^2$$

$$\text{hcap}(g_t(\gamma[t, t+\Delta t])) = 2\Delta t$$

$$\text{hcap}(\tilde{g}_t(\tilde{\gamma}[t, t+\Delta t])) = \text{hcap}(\Phi_t(\gamma_{t, t+\Delta t}))$$

$$\Phi_t \approx \Phi_t(u(t)) + \Phi'_t(u(t))(z - u(t)) + \dots$$

$$\approx (\Phi'_t(u(t)))^2 2\Delta t$$

$$\text{Claim } \dot{\Phi}_t(z) = 2 \left(\frac{(\Phi'_t(u(t)))^2}{\Phi_t(z) - \Phi_t(u(t))} - \Phi'_t(z) \frac{1}{z - u(t)} \right)$$

$$\dot{\Phi}_t(u(t)) = \lim_{z \rightarrow u(t)} \dot{\Phi}_t(z) = -3\Phi''_t(u(t))$$

Th (Locality of SLE(6))

Let γ be an SLE(κ) trace, $u(t) = \sqrt{\kappa} B_t$

Let Φ be as above



Then $\tilde{\gamma}_t$ is a time-changed SLE(κ) curve if and only if $\kappa = 6$

Proof $\tilde{\gamma}$ is given by a LE with the driver $\tilde{u}(t) = \Phi_t(u(t))$

By Ito

$$\begin{aligned} d\tilde{u}(t) &= \dot{\Phi}_t(u(t))dt + \Phi'_t \sqrt{\kappa} dB_t + \frac{1}{2} \Phi''_t \kappa dt \\ &= \left(\left(\frac{\kappa}{2} - 3 \right) \Phi'' \right) dt + \sqrt{\kappa} \underbrace{\Phi'_t dB_t}_{d\tilde{B}_s} \end{aligned}$$

$$\tilde{u} \text{ is a mart.} \Leftrightarrow \kappa = 6$$



$\tilde{u}$ is a time-changed BM

$$\delta_t \text{ map } \tilde{\gamma}[0, t] \Rightarrow 2(\Phi'_t(u_t))^2$$

new time $s(t)$ given by

$$s = \int_0^t (\Phi'_\tau(u(\tau)))^2 d\tau \quad \leftarrow \text{random change of time}$$

$$\text{If } \kappa = 6 \quad d\tilde{u}(s) = \sqrt{\kappa} d\tilde{B}_s, \quad \tilde{B}_s - \text{BM}$$

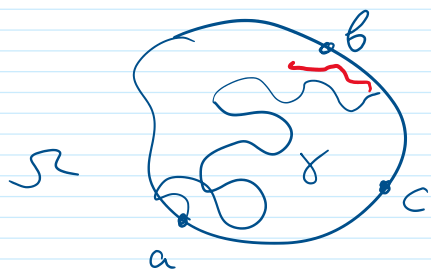
Corollary SLE(6) is target independent. ▀



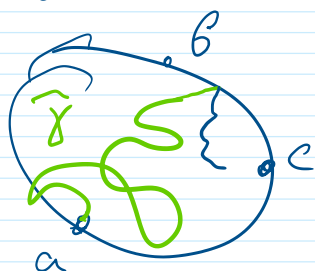
corollary



Corollary $SLE(6)$ is target independent.

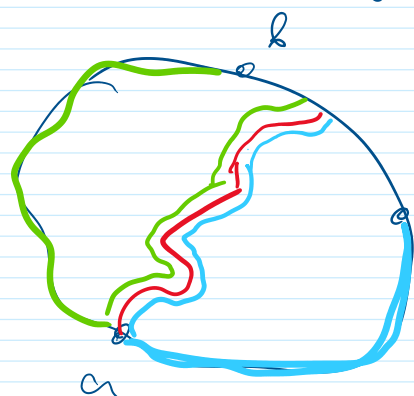


γ is $SLE(6)$ trace in Ω from a to b



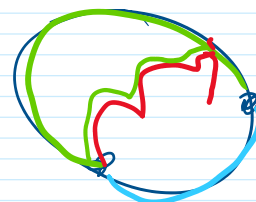
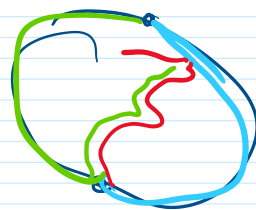
$\hat{\gamma}$ is $SLE(6)$ trace in Ω from a to c

Law of γ = Law of $\hat{\gamma}$ up to the first time they separate b and c (up to time change)



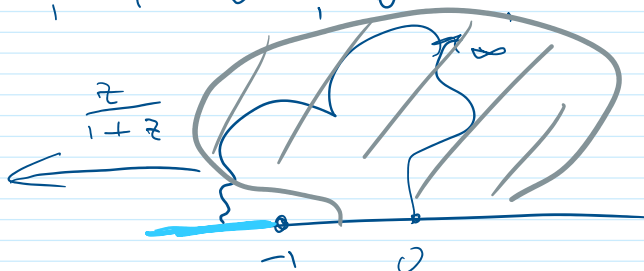
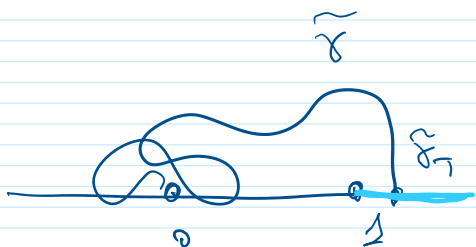
aim at b

aim at c



Proof

$\Omega = \mathbb{H}$, $a = 0$, $b = 1$, $c = \infty$



Dy
def

$\tilde{\gamma} = (\text{time changed})$ $SLE(\mathbb{H}, 0 \rightarrow 1)$

$T = \inf \{ t > 0, \tilde{\gamma}_t \in [1, \infty) \}$

$T = \inf \{ t > 0, \gamma_t \in [-\infty, 1] \}$

$$T = \inf \{ t > 0 \mid \gamma_t \in [-\infty, 1] \}$$

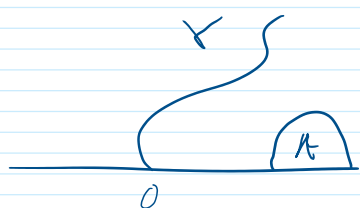
$$x = 6 > 4 \Rightarrow T < \infty \quad \text{a.s.}$$

$$x = 6 < 8 \Rightarrow \tilde{\gamma}_T > 1$$

For $t < T$ $\gamma[0, t]$ is in some s.c. nbhd of 0. By our theorem applied to $\tilde{\gamma}$ in this nbhd $\tilde{\gamma}$ is a time changed SLE(6) [in H from 0 to ∞]

Restriction

Let γ be a simple curve from 0 to ∞ in H

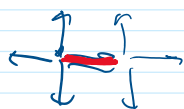


Let A be an H -hull separated from 0. V_A is the event

$$\gamma([0, \infty)) \cap A = \emptyset$$

Def We say that γ has the restriction property if the law of γ conditioned on V_A is the same as the law of γ in $H \setminus A$

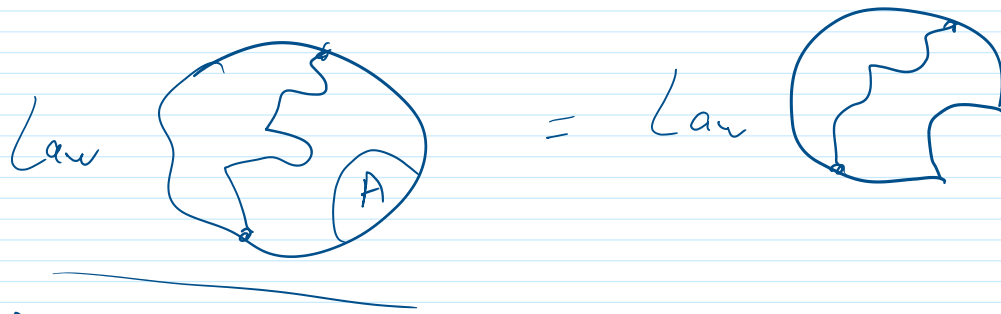
Self-avoiding random walk (SAW)



RW of length n is the uniform measure on all lattice paths of length n

SAW of length n is the unif. measure on all simple lattice paths of length n

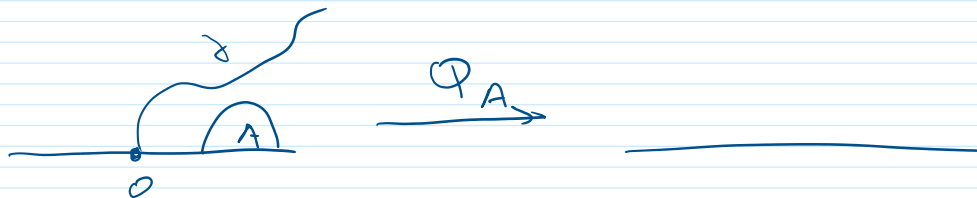
simple lattice paths of length n



If $\forall A$ we know whether $\gamma \cap A = \emptyset$ or $\neq \emptyset$
then we know γ

If γ is random then knowing $P(\gamma \cap A = \emptyset)$
for all A gives us full info. about the law of γ

Lemma Let $\kappa \leq 4$, γ is $SLE(\kappa)$ trace
Let A be a positive hull ($A \cap \mathbb{R} \subset [0, \infty)$)

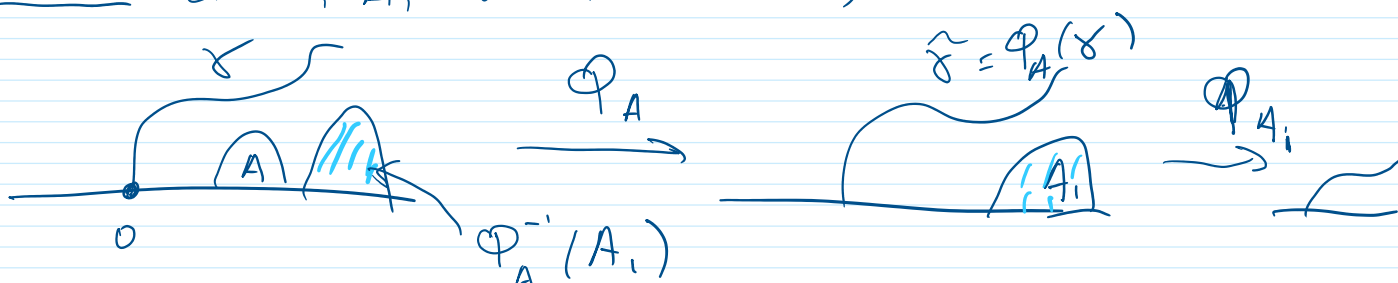


$\varphi_A: \mathbb{H} \setminus A \rightarrow \mathbb{H}$ s.t. $\varphi_A(0) = 0, \varphi_A(\infty) = \infty$

$\varphi'_A(\infty) = 1$ ($\varphi(z) = z + \dots$ at ∞)

If $\exists \alpha > 0$ s.t. $P(V_A) = \varphi'_A(0)^\alpha \quad \forall A$
then $SLE(\kappa)$ has the restriction property

Proof Let A, A_1 be two hulls



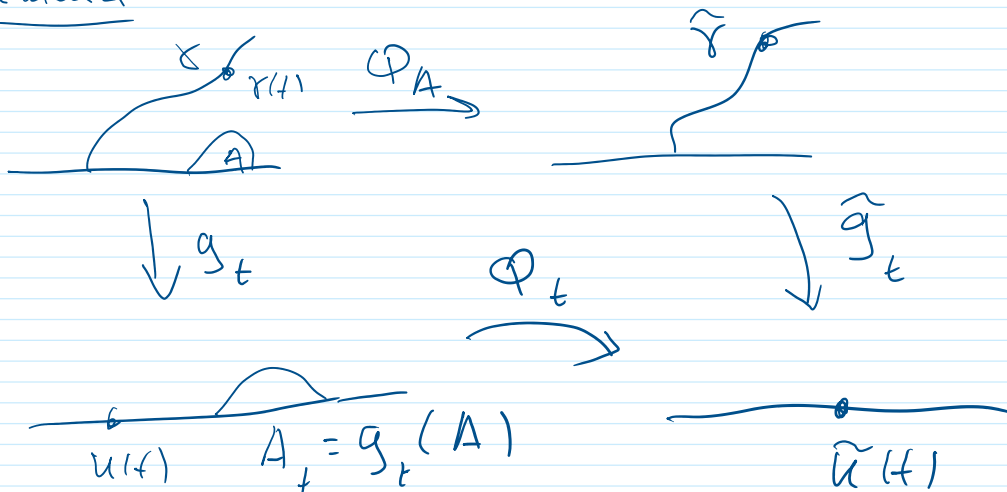
$$\begin{aligned}
 & \mathbb{P}(\Phi_A(\gamma) \cap A_1 = \emptyset, \gamma \cap A = \emptyset) = \\
 &= \mathbb{P}(\gamma \cap (A \cup \Phi_A^{-1}(A_1)) = \emptyset) = \mathbb{P}(\bigvee_{A \cup \Phi_A^{-1}(A_1)} \gamma) \\
 & \left[\begin{array}{l} \Phi_{A \cup \Phi_A^{-1}(A_1)} = \Phi_{A_1} \circ \Phi_A \quad \text{by chain rule} \\ \Phi'_{A \cup \Phi_A^{-1}(A_1)}(0) = \Phi'_{A_1}(0) \Phi'_A(0) \end{array} \right] \\
 &= \left(\Phi'_{A \cup \Phi_A^{-1}(A_1)}(0) \right)^\alpha = \left(\Phi'_{A_1}(0) \right)^\alpha \left(\Phi'_A(0) \right)^\alpha
 \end{aligned}$$

$$\begin{aligned}
 \mathbb{P}(\tilde{\gamma} \cap A_1 = \emptyset \mid \gamma \cap A = \emptyset) &= \frac{\mathbb{P}(\tilde{\gamma} \cap A_1 = \emptyset, \gamma \cap A = \emptyset)}{\mathbb{P}(\gamma \cap A = \emptyset)} \\
 &= \frac{(\Phi'_{A_1}(0))^\alpha (\Phi'_A(0))^\alpha}{(\Phi'_A(0))^\alpha} = (\Phi'_{A_1}(0))^\alpha = \mathbb{P}(\gamma \cap A_1 = \emptyset)
 \end{aligned}$$

$$\Rightarrow \text{Law } \tilde{\gamma} \mid V_A = \text{Law } \gamma = \text{SLE in } \mathbb{H}$$

$$\Rightarrow \text{Law } \gamma \mid V_A = \text{Law } \Phi_A^{-1}(\text{SLE}) = \text{Law of SLE}$$

Lemma



$$u(t) \quad A_t = g_t(A)$$

$$\tilde{u}(t)$$

Then $\dot{\Phi}'_t(u(t)) = \frac{\Phi''_t(u(t))^2}{2\Phi'_t(u(t))} - \frac{4}{3}\Phi'''_t(u(t))$

The $SLE(8/3)$ satisfy the restriction property

Proof $M_t = (\Phi'_t(u(t)))^\alpha \mathbb{1}_{t < T}$

where $T_A = \inf\{t > 0 : \gamma[0, t] \cap A \neq \emptyset\}$

$$V_A = \{T_A = \infty\}$$

Assume that $t < T$

By Ito

$$\frac{dM_t}{M_t} = \left[\frac{(\alpha-1)\alpha+1}{2} \left(\frac{\Phi''_t(u(t))}{\Phi'_t(u(t))} \right)^2 + \left(\frac{\alpha}{2} - \frac{4}{3} \right) \frac{\Phi'''_t(u(t))}{\Phi'_t(u(t))} \right] dt + \frac{\Phi''_t(u(t))}{\Phi'_t(u(t))} \sqrt{\alpha} dB_t$$

$\alpha = 5/8, \alpha = 8/3$

if $\alpha = 8/3$, $\alpha = 5/8 \rightarrow M_t$ is a ^{local} martingale

Claims • $M_t \leq 1$ ✓

• M_t is cont $M_{t \wedge T_A} \rightarrow M_\infty = \mathbb{1}_{V_A}$

$$\mathbb{E} M_{T_A} = M_0 = (\Phi'_A(0))^{5/8}$$

$$\mathbb{P}(V_A)$$

by the previous lemma

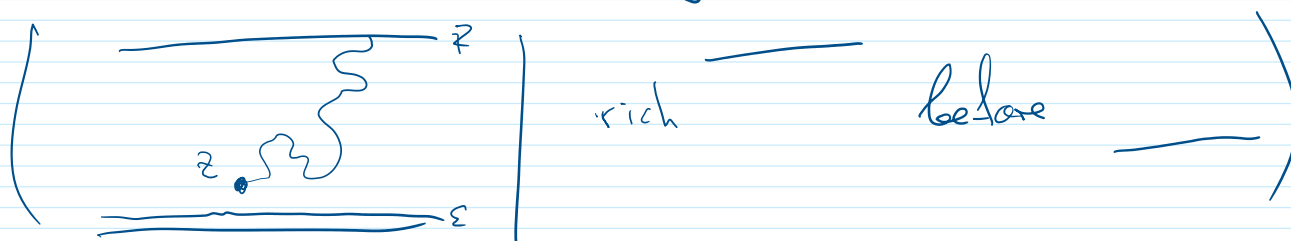
$P(V_A)$

by the previous lemma
there is the restriction property

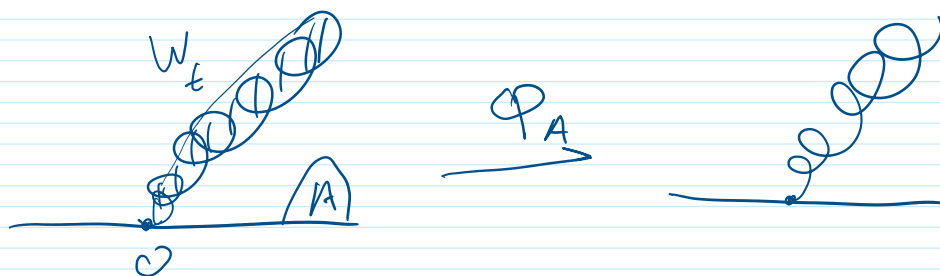


About these claims

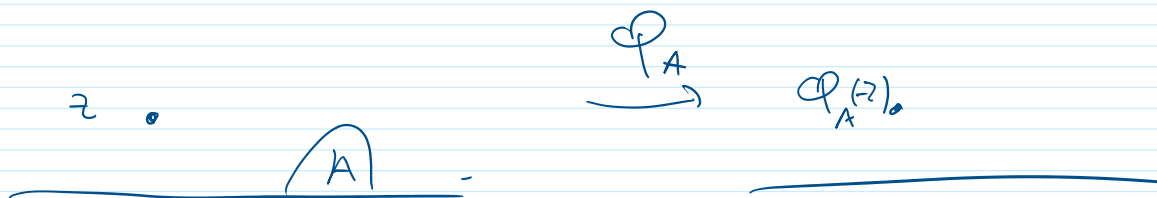
Brownian excursion in $H = \text{B.M. in } H$
conditioned to stay in H



Pass to the limit as $\epsilon \rightarrow 0$ and $R \rightarrow \infty$
With one more limit we can define
an excursion started on the boundary



$$\underbrace{P^z(W_t \text{ does not hit } A)}_R = \frac{\text{Im } \Phi_A(z)}{\text{Im } z} \Bigg] \approx \text{Im } z = R$$



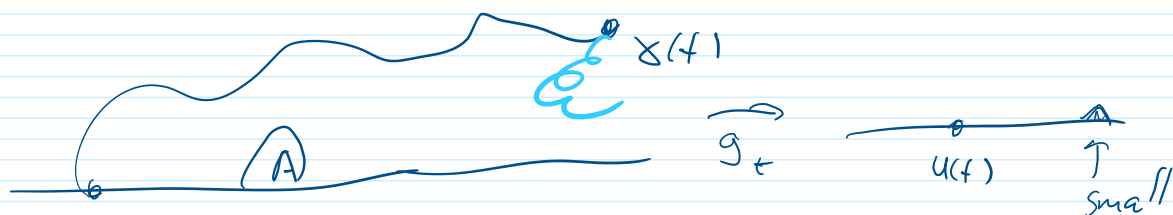
$$P^x(W_t \text{ does not hit } A) = \Phi'_A(x)$$

$$P^0(W_t \text{ does not hit } A) = \Phi'_A(0) \leq 1$$

$$M \rightarrow \mathbb{H}_{V_A}$$

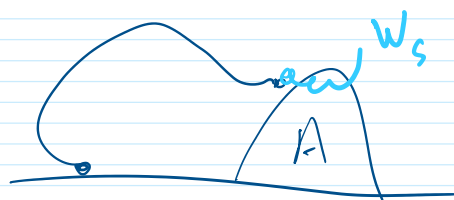
if $T_A = \infty$

$$t \gg 1$$



$$P^{x(t)}(W \cap A = \emptyset) \approx 1$$

if $T_A < \infty$, take $t = T_A - \varepsilon$

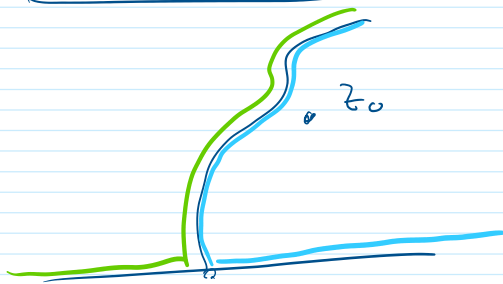


$$P^{x(t)}(W_s \cap A = \emptyset) \approx 0$$

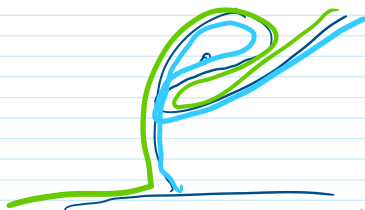
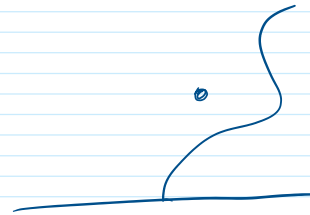
Standard SLE techniques

Schramm's formula

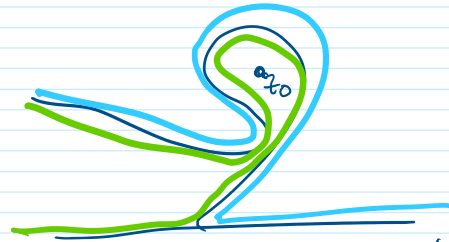
$\kappa < 8$, γ is SLE(κ) curve
 $z_0 \in \mathbb{H}$



or



clockwise $\Rightarrow$ to the left



to the right.

Th

$$\begin{aligned} \mathbb{P}[\gamma \text{ passes to the left of } z_0] &= \\ &= \frac{1}{2} + \frac{\Gamma(\frac{\kappa}{2})}{\sqrt{\pi} \Gamma(\frac{8-\kappa}{2\kappa})} \frac{x_0}{y_0} {}_2F_1\left(\frac{1}{2}, \frac{\kappa}{2}, \frac{3}{2}, -\frac{x_0^2}{y_0^2}\right) \end{aligned}$$

when $\kappa = 2$
$$P = 1 + \frac{x_0 y_0}{\pi |z_0|^2} - \frac{\arg z_0}{\pi}$$

$\kappa = 8/3$
$$P = \frac{1}{2} + \frac{x_0}{2|z_0|}$$

$\kappa = 4$
$$P = 1 - \frac{\arg z_0}{\pi}$$

$\kappa = 8 \quad \text{r.h.s} = \frac{1}{2}$

Lemma a.s γ passes to the left of z_0

Lemma a.s γ passes to the left of z_0
if and only if $\lim_{t \rightarrow T(z_0)} \frac{x_t}{y_t} = \infty$

where $x_t + iy_t = z_t = g_t(z) - \sqrt{t} B_t$

γ passes to the right $\Leftrightarrow \lim_{t \rightarrow T(z_0)} \frac{x_t}{y_t} = -\infty$

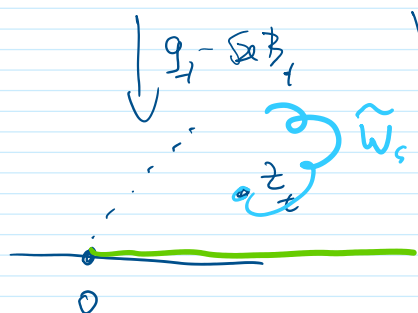
Proof Case $x \leq y$

In this case $T(z_0) = \infty$ a.s



W_s - BM started from z_0
stopped when it hits γ or $\mathbb{R}$

γ is to the left if and only if
 W_s a.s hits the right side of γ or $[0, \infty)$



$\tilde{W}_s \perp = P(\tilde{W}_s \text{ hits the right side of } \gamma \text{ or } [0, \infty))$
 $\approx P(\tilde{W} \text{ hits } [0, \infty))$

$$= \frac{1}{\pi} \int_0^\infty \frac{y_t}{y_t^2 + (x_t - s)^2} ds = \frac{1}{\pi} \left(\frac{\pi}{2} - \arctan \left(-\frac{x_t}{y_t} \right) \right)$$

$\downarrow \Leftrightarrow \frac{x_t}{y_t} \rightarrow \infty$
 $\perp$

Case $y < x < 8$

$T(z_0) < \infty$ a.s.

z_0 is in unbounded comp. of $\mathbb{H} \setminus \gamma[0, t]$ $\forall t < T(z_0)$



z_0 is in a bdd comp
of $\mathbb{H} \setminus \gamma([0, T(z_0)])$

W_s stopped when it hits
 $\gamma[0, t]$ or $\mathbb{R}$

γ is to the left
 $\Leftrightarrow$ clockwise loop

$\Rightarrow P(W_s \text{ hits right side of } \gamma[0, t] \cup [R_+])$

$\Leftrightarrow$ clockwise loop

$P[W_s \text{ hits the right side of } \gamma[0, t] \cup \mathbb{R}_+]$
 $\rightarrow P[W_s \text{ hits the right side of } \gamma[0, \infty]] = 1$

$g_t = \sqrt{x_t^2 + y_t^2}$

$P(\text{diagram}) \rightarrow 1 \Leftrightarrow \frac{x_t}{y_t} \rightarrow \infty$

$P(\text{diagram}) \rightarrow 1$

$\Leftrightarrow \frac{x_t}{y_t} \rightarrow -\infty$

||

$P(\text{diagram})$

Proof [Schramm's formula]

$$dx_t = \frac{2x_t}{x_t^2 + y_t^2} dt - \sqrt{x} dB_t, \quad dy_t = -\frac{2y_t}{x_t^2 + y_t^2} dt$$

$$w_t = \frac{x_t}{y_t}, \quad \text{Ito} \quad dw_t = -\frac{\sqrt{x} dB_t}{y_t} + \frac{4w_t dt}{x_t^2 + y_t^2}$$

Time change $ds(t) = \frac{dt}{y_t^2}$ $s(t) = \int_0^t \frac{dt}{y_t^2}$

$$\tilde{B}_s = \int_0^t \frac{dB_t}{y_t} \leftarrow \text{this is a BM}$$

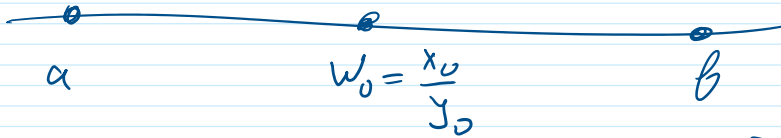
$$dw_s = -\sqrt{x} d\tilde{B}_s + \frac{4w_t}{1+w_t^2} ds$$

Note • $y_t \searrow, y_+ > 0 \Rightarrow s(t) < \infty$ if $t < T(z_0)$

Note • $y_t \downarrow$, $y_t > 0 \Rightarrow s(t) < \infty$ if $t < 1/(z_0)$

• a.s. $w \rightarrow +\infty$ as $t \rightarrow T(z_0)$
 $\Rightarrow s(t) \rightarrow \infty$ as $t \nearrow T(z_0)$

Take $a < w_0 < b$.



Define $h(w_0) = h_{a,b}(w_0) = \mathbb{P}[w_t \text{ hits } b \text{ before } a]$

$h(w_s)$ is a martingale.

assume that $h \in C^2$

$$\begin{cases} \frac{x}{2} h''(w) + \frac{4w}{w^2+1} h'(w) = 0 \\ h(a) = 0, \quad h(b) = 1 \end{cases}$$

The unique solution $\tilde{h}(w) = \frac{f(w) - f(a)}{f(b) - f(a)}$ where

$$f(w) = {}_2F_1\left(\frac{1}{2}, \frac{4}{x}, \frac{3}{2}, -w^2\right) w$$

$\tilde{h}(w_s)$ is a loc. mart + bounded $\Rightarrow$ martingale.

Optional stopping $\Rightarrow \tilde{h}(w_s) = h(w_s)$

$$\text{When } x < 8 \text{ then } \lim_{w \rightarrow +\infty} f(w) = \frac{\sqrt{\pi} \Gamma(\frac{8-x}{2x})}{2 \Gamma(\frac{4}{x})}$$

$$\Rightarrow \lim_{b \rightarrow \infty} h_{a,b}(w) > 0 \quad \forall w > 0$$

$\Rightarrow w_s$ is transient

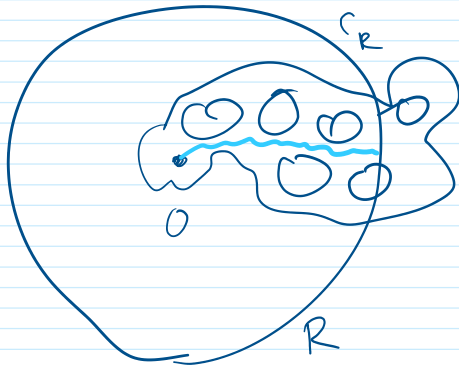
$$\mathbb{P}[\lim w_s = +\infty] = \frac{f(w_0) - f(-\infty)}{f(\infty) - f(-\infty)}$$

$$\mathbb{P} \left[\lim_{S \rightarrow \infty} W_S = +\infty \right] = \frac{f(w_0) - f(-\infty)}{f(\infty) - f(-\infty)}$$

□

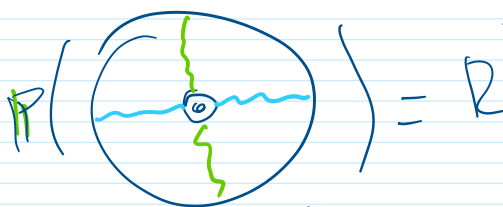
One-arm exponent

Considers percolation cluster containing the origin

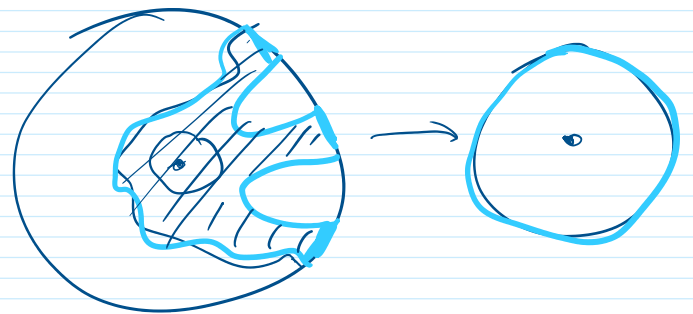
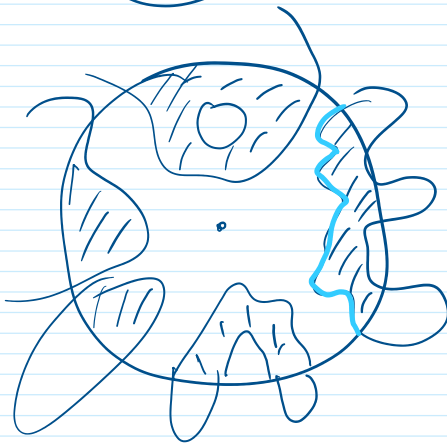


$$\mathbb{P}(0 \leftrightarrow C_R) = R^{-5/48 + o(1)}$$

one-arm exponent



$$= R^{-(4\text{-arm exponent}) + o(1)}$$



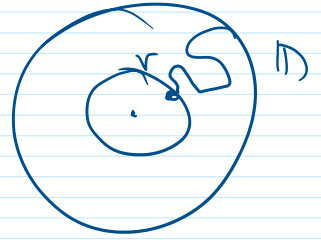
Th For every $x > 4$ there is $c > 0$ s.t.
the radial SL_{∞} path γ for $\forall r \in (0, 1)$
satisfies

$$c^{-1} r^x \leq \mathbb{P}[\gamma[0, Tr] \text{ contains no counter-clockwise } n\text{-arm around } 0] \leq c r^x$$

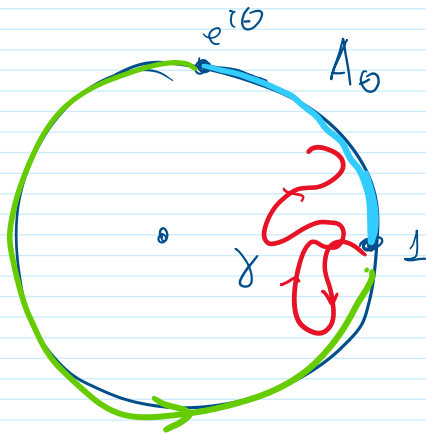
$c r \leq \mathbb{P}[\gamma[0, t] \text{ contains no counter-clockwise loop around } 0] \leq c r^{-1}$

$$T_r = \inf\{t : |\gamma(t)| = r\}$$

$$\lambda = \frac{x^2 - 16}{32x}$$



Proof

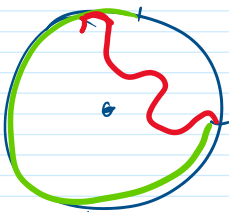


at time t dist $0 \rightarrow k_t$
is $\asymp e^{-t}$ ($g'(0) = e^t$)
(Koebe $\frac{1}{4}$ theorem)

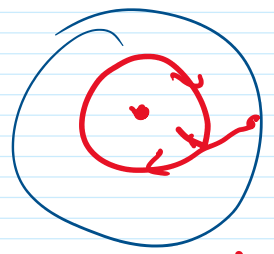
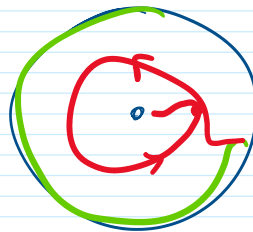
$$\mathbb{P}(\gamma[0, t] \text{ has no ccw loops}) \asymp e^{-\lambda t}$$

$$\gamma_\theta^+ = (\mathbb{T} \setminus A_\theta) \cup \gamma[0, t]$$

$E(\theta, t)$ = event that γ_θ^+ contains no counter-clockwise loop around θ



counter clockwise loop



$E E(\theta, t)$

Define $h(\theta, t) = \mathbb{P}[E(\theta, t)]$

Claim • $h \in C^2$

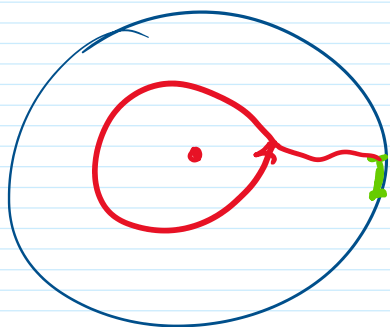
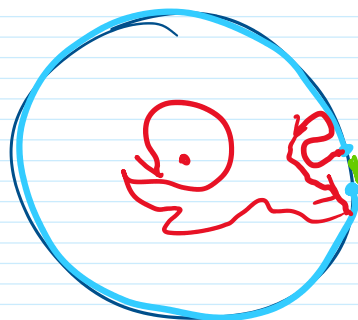
• $h(\theta, t) \rightarrow 0$ as $\theta \rightarrow 0$ $\forall t > 0$

• $\partial_\theta h(\pi, t) = 0$ $\forall t$

~~or~~

$$\mathbb{P} \left(\left(\text{circle with green boundary and red path} \right) \right) \approx 1 \Rightarrow \exists \text{ counter-clockwise loop with } \mathbb{P} \approx 1$$

$$\lim_{\theta \rightarrow 0} \frac{h(2\pi, t) - h(\theta, t)}{2\pi - \theta}$$



← counts in both $E(2\pi, t)$ and $E(\theta, t)$

$$\mathbb{P} \left(\left(\text{circle with blue boundary and red path} \right) \right) \approx (2\pi - \theta)$$

$$\mathbb{P} \left(\left(\text{circle with blue boundary and red path} \right) \right) \approx (2\pi - \theta) \cdot \mathbb{P} \left(\left(\text{circle with blue boundary and red path} \right) \right) \approx O(1)$$

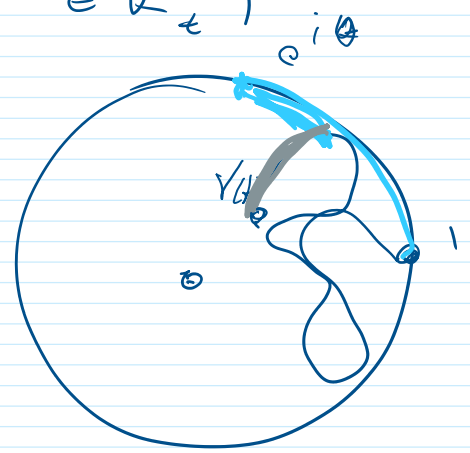
$T(\theta)$ the first time $e^{i\theta}$ is separated from 0 (time when $e^{i\theta} \in K_t$)

from 0 (time when $e^{i\theta} \in K_t$)

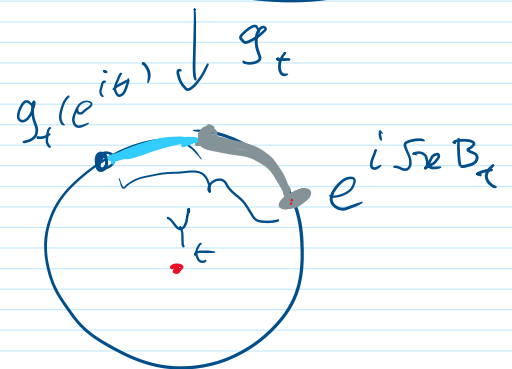
$t < T(\theta)$

$$Y_t^\theta = \frac{-i \log g_t(e^{i\theta}) - \sqrt{x} B_t}{2\pi}$$

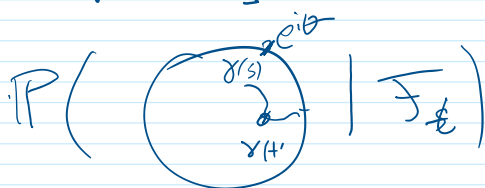
= harmonic measure of



= arclength of the image under g_t of A_θ and the right side of $\gamma[0, t]$

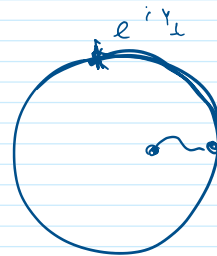


Fix s assume that $t < T \wedge s$



$E(\theta, s)$

$g_t e^{-i\sqrt{x} B_t}$



$h(Y_t^\theta, s-t)$ this is a martingale on $t < T \wedge s$

Radial SLE

$$\partial_t g_t(z) = -g_t(z) \frac{g_t(z) + e^{i\sqrt{x} B_t}}{g_t(z) - e^{i\sqrt{x} B_t}}$$

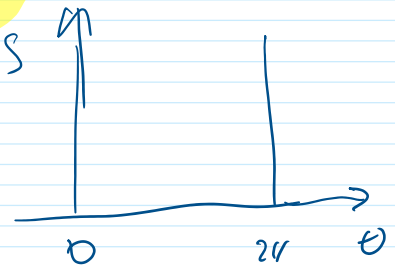
$$T/5 \Rightarrow dY_t^\theta = \cot\left(\frac{Y_t^\theta}{2}\right) dt - \sqrt{x} dB_t$$

$$T/6 \Rightarrow dh(Y_t^\theta, s-t) = \left[\frac{x}{2} \partial_{tt}^2 h + \cot\left(\frac{Y_t^\theta}{2}\right) \partial_{tt} h - \partial_{ss} h \right] dt$$

$$I_{t=0} \Rightarrow dh(Y_t^\theta, s-t) = \left[\frac{x}{2} \partial_\theta^2 h + \cot\left(\frac{\theta}{2}\right) \partial_\theta h - \partial_s h \right] dt - \sqrt{x} \partial_\theta h d\mathcal{B}_t$$

Martingale $\Rightarrow$ drift is 0 $\forall t$, use $t=0 \left[Y_t^\theta \Big|_{t=0} = \theta \right]$

$$(\star) \quad \begin{cases} \frac{x}{2} h_{\theta\theta}(\theta, s) + \cot\left(\frac{\theta}{2}\right) h_\theta(\theta, s) - h_s(\theta, s) = 0 \\ h(0, s) = 0 \quad \forall s \\ h(\pi, s) = 0 \quad \forall s \end{cases}$$



We want to understand how solutions of $(\star)$ behave as $s \rightarrow \infty$

Two approaches

① PDE. Consider $H(\theta, t) = \left(\sin \frac{\theta}{4}\right)^q e^{-\lambda t}$

$$\lambda = \frac{x^2 - 16}{32x} \quad q = \frac{x-4}{x}$$

H is a positive solution of $\Delta H = 0$ + boundary cond

$$\Delta = \underbrace{\frac{x}{2} \partial_\theta^2 + \cot \frac{\theta}{2} \partial_\theta}_{\hat{\Delta}} - \partial_t$$

$\left(\sin \frac{\theta}{4}\right)^q$ is a positive e.f. of $\hat{\Delta}$ with e.v. λ [the main e.f.]

$$\left(\sum a_i \varphi_i(\theta) e^{-\lambda_i t} \right) \sim a_1 \varphi_1(\theta) e^{-\lambda_1 t}$$

Maximum Principle for parabolic PDE

$\Rightarrow h(\theta, t) \asymp H(\theta, t)$ } There are some complications.
Coefficients have sing.

$\Rightarrow h(\theta, t) \asymp H(\theta, t)$ { There are some complications.
Coefficients have sing.

② Optional stopping

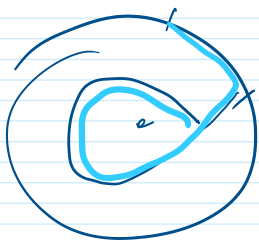
Consider $Z_t = \left(\sin \frac{Y_t}{4} \right)^q e^{\lambda t}$

Explicit computation $\Rightarrow Z_t$ is a local mart.

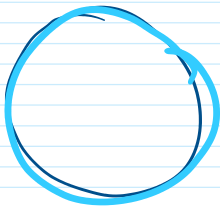
Z_t is unit bounded on every $[0, t_0]$

$\Rightarrow Z_t$ is a martingale

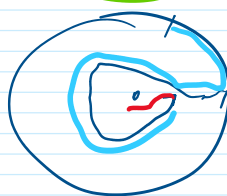
$$\left(\sin \frac{\theta}{4} \right)^q = Z_0 = \mathbb{E} Z_t = e^{\lambda t} \mathbb{E} \left[\left(\sin \frac{Y_t}{4} \right)^q \mid \inf_{s \leq t} Y_s > 0 \right] \times \mathbb{P}[\inf Y_s > 0]$$



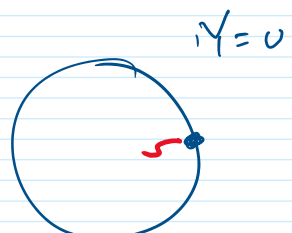
$\downarrow g_1$



$Y = 2\pi$



$\xrightarrow{g_+ e^{-\lambda B_+}}$



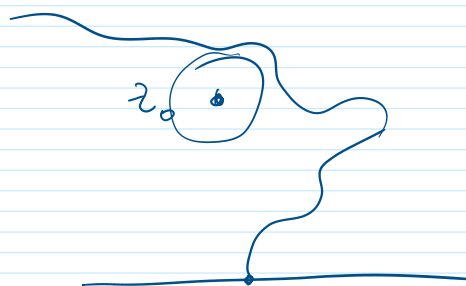
Claim $\mathbb{P}[Y \in [\frac{\pi}{2}, \pi] \mid \inf Y > 0] > 0$

$$\Rightarrow \mathbb{E} \left[\left(\sin \frac{Y_t}{4} \right)^q \mid \inf Y > 0 \right] \asymp 1$$

$$\Rightarrow \mathbb{P}[\inf Y > 0] \asymp \left(\sin \frac{\theta}{4} \right)^q e^{-\lambda t}$$

" $h(\theta, t)$

"
 $h(\theta, t)$



$\kappa < 8$

$$\begin{aligned} P(B(z_0, \varepsilon) \cap \gamma \neq \emptyset) &\asymp \\ &\asymp \left(\frac{\varepsilon}{\operatorname{Im} z_0} \right)^{1 - \frac{\kappa}{8}} \left(\sin(\arg z_0) \right)^{\frac{8}{\kappa} - 1} \end{aligned}$$

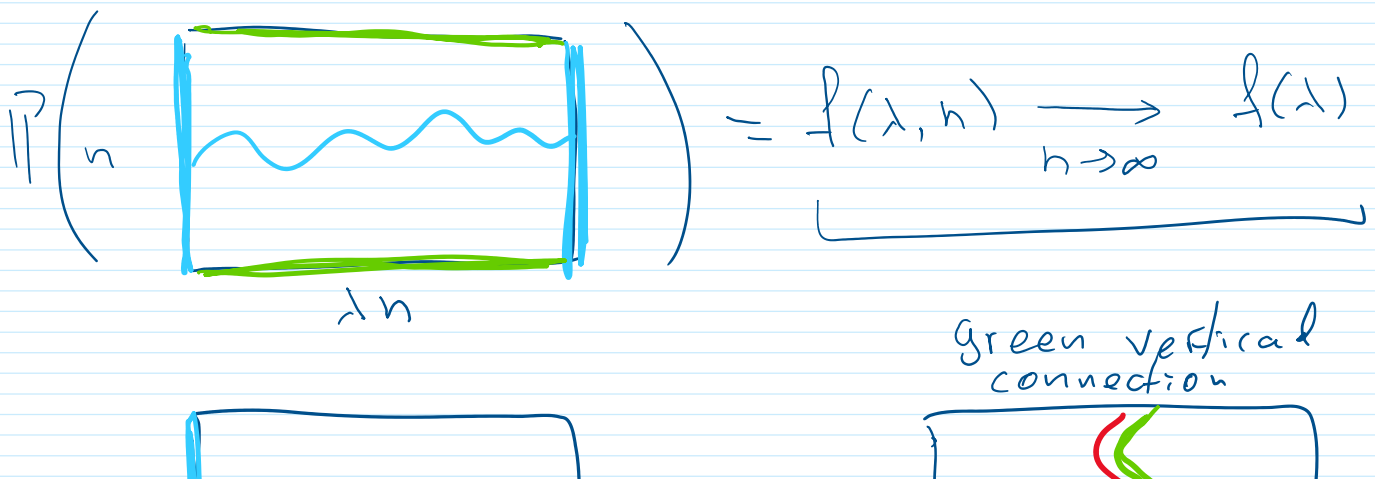
Corollary $\dim_{\mathcal{H}} \gamma \leq 2 - \left(1 - \frac{\kappa}{8}\right) = \frac{\kappa}{8} + 1$ a.s

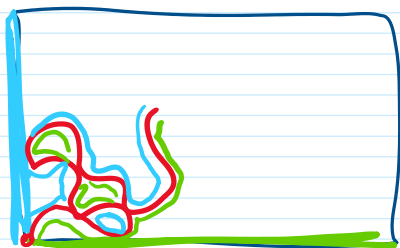
Th $\dim_{\mathcal{H}} \gamma = \frac{\kappa}{8} + 1$ a.s

Towards conformal invariance

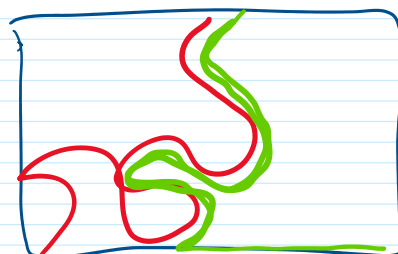
- Prove some weak estimates that imply that interfaces are not too wild.
 Perc: certain observables are Hölder functions.
 $\Rightarrow$ interfaces have subsequential scaling limits
- [Show that one observable has a conf. inv. scaling limit] There are subseq. limits. Identify this limit $\Rightarrow \exists$ limit and we know it
 This limit is a solution of some equation
 $\Rightarrow$ it is conf. invariant
- χ_s describe χ_s in terms of LE
 $\chi_s \rightsquigarrow u_s$
 using an observable $\Rightarrow \lim u_{s_n} = BM$
 $\Rightarrow \chi_s \rightarrow \chi = SLE$

Crossing probability





Or



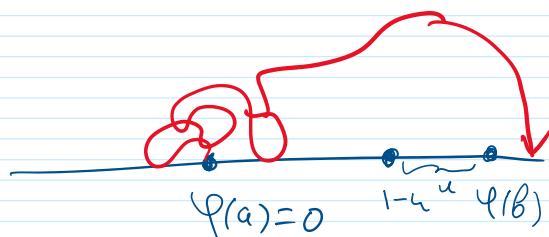
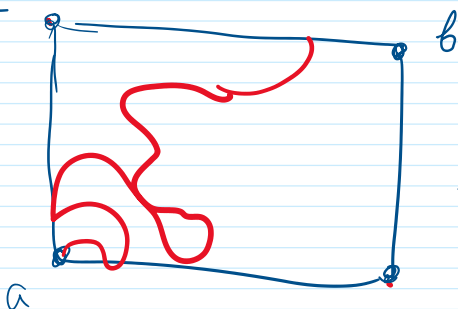
no horizontal blue connection



There is horizontal blue connection

No vertical green

Σ

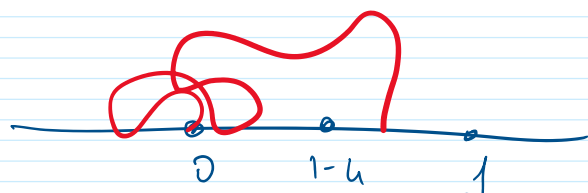


Ver. l. crossing

$$\varphi(a)=0 \quad 1-u \quad \varphi(b)=1$$



{ Vertical green crossing }



$$= \left\{ \begin{array}{l} \text{SLE}(6) \text{ in } \mathbb{H} \\ \text{hits } [1, \infty) \text{ before } [1-u, 1] \end{array} \right\}$$

$$= \{ T(1-u) = T_1 \}$$

$$\{ \text{Horizontal blue crossing} \} = \{ \text{SLE}(6) \text{ hits } [1-u, 1] \}$$

$$= \{ T(1-u) < T(1) \}$$

$$4 < \kappa = 6 < 8$$

IP

=

$$1 - \frac{\Gamma(\frac{\kappa}{2}-1) \Gamma(\frac{\kappa-4}{2})}{\Gamma(\frac{\kappa}{2})} \int_{1-u}^1 (1-x)^{\frac{\kappa}{2}-2} x^{-\frac{4}{\kappa}} dx$$

$$IP = \left[1 - \frac{\Gamma(\frac{k}{2}-1) \Gamma(\frac{x-y}{2})}{\Gamma(\frac{k}{4})} \int_0^1 (1-x)^{2k} x^y dx \right]$$

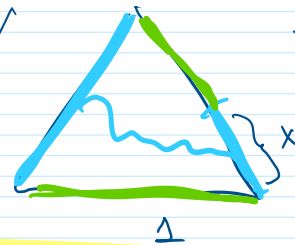
in terms of u , but u is a function of λ

Cardy's formula Using Conformal Field Theory

Carleson: This expression $\frac{\Gamma(1/3)}{\Gamma(1/3)\Gamma(1/3)} u^{1/3} {}_2F_1\left(\frac{1}{3}, \frac{1}{3}, \frac{4}{3}, u\right)$ is a conformal map

$/// \rightarrow \triangle$

Carleson - Cardy formula

$$P\left(\triangle \text{ with boundary } \gamma \right) = x$$


Russo - Seymour - Welsh estimate

$$RSW \quad 0 < c < P\left(n \left[\begin{array}{|c|} \hline \text{wavy line} \\ \hline \end{array} \right] \right) < 1 - c < 1$$

$\exists c = c(\lambda) > 0$

λn

Crossing events are positively correlated

$$P\left(\left[\begin{array}{|c|} \hline \text{wavy line} \\ \hline \end{array} \right] \cap \left[\begin{array}{|c|} \hline \text{zigzag line} \\ \hline \end{array} \right] \right) \geq P\left(\left[\begin{array}{|c|} \hline \text{wavy line} \\ \hline \end{array} \right] \right) P\left(\left[\begin{array}{|c|} \hline \text{zigzag line} \\ \hline \end{array} \right] \right)$$

$$P\left(\begin{array}{|c|c|c|} \hline \text{---} & \text{---} & \text{---} \\ \hline \end{array}\right) \geq P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right) P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right)$$

RSW for some $\lambda \neq 1$ then we have
 $\hookrightarrow$ SW for all λ

$$1 = P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right) + P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right) = \frac{1}{2}$$

$$P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right) + P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right) = 2P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right)$$

$$\Rightarrow P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right) = \frac{1}{2}$$

$$\text{If } P\left(\begin{array}{|c|c|} \hline \text{---} & \text{---} \\ \hline \end{array}\right) > c$$

$$P\left(\begin{array}{|c|c|c|} \hline \text{---} & \text{---} & \text{---} \\ \hline \end{array}\right) \geq \left(P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right)\right)^2 \cdot \frac{1}{2}$$

$$P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right)$$

$$P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right) \geq P\left(\begin{array}{|c|} \hline \text{---} \\ \hline \end{array}\right) \cdot \left(\frac{1}{2}\right)^{k-1} > c > 0$$

$$P \left(\begin{array}{|c|} \hline \text{wavy line} \\ \hline \end{array} \right)_{\lambda + (\lambda-1)}$$

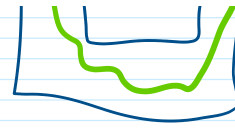
$$P \left(\begin{array}{|c|} \hline \text{wavy line} \\ \hline \end{array} \right)_{1 + (\lambda-1)k} \geq P \left(\begin{array}{|c|} \hline \text{wavy line} \\ \hline \end{array} \right)_{\lambda}^k \cdot \left(\frac{1}{2} \right)^{k-1} > c > 0$$

$$P \left(\begin{array}{|c|} \hline \text{3x3 grid of squares with wavy lines} \\ \hline \end{array} \right)_{3n} \geq \left(P \left(\begin{array}{|c|} \hline \text{wavy line} \\ \hline \end{array} \right)_{3n} \right)^4 > c$$

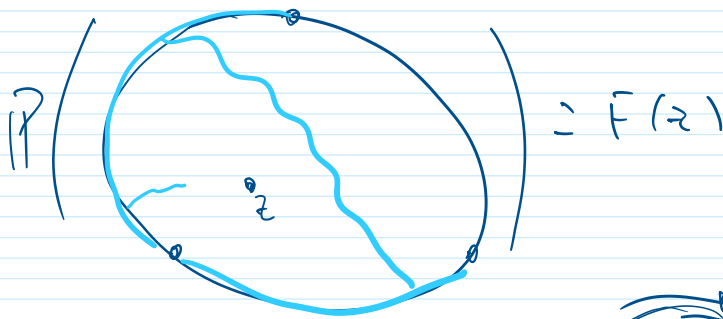
$$P \left(\begin{array}{|c|} \hline \text{square with a smaller square inside} \\ \hline \end{array} \right)$$

$$P \left(\begin{array}{|c|} \hline \text{square with a smaller square inside and a wavy line} \\ \hline \end{array} \right)_{R_n} = 1 - P \left(\begin{array}{|c|} \hline \text{square with a smaller square inside and a green boundary} \\ \hline \end{array} \right)$$

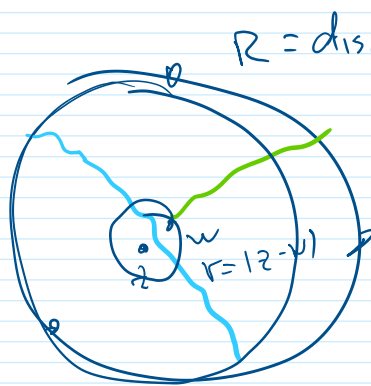
$$P \left(\begin{array}{|c|} \hline \text{square with a smaller square inside and a green boundary} \\ \hline \end{array} \right)_{3rn} \geq P \left(\begin{array}{|c|} \hline \text{square with a smaller square inside and a green boundary} \\ \hline \end{array} \right) \geq 1 - e^{-c \cdot \# \text{ layers}}$$



$$\left| \begin{array}{l} 3^N \approx \frac{R}{r} \Rightarrow N \approx \ln \frac{R}{r} \\ \mathbb{P}(\text{square}) \leq \left(\frac{R}{r}\right)^{-\alpha} \end{array} \right| \begin{array}{l} \approx 1 - C \ln \frac{R}{r} + \dots \\ \approx 1 - \left(\frac{R}{r}\right)^{-\alpha} \end{array}$$



$$F(z) - F(w) =$$

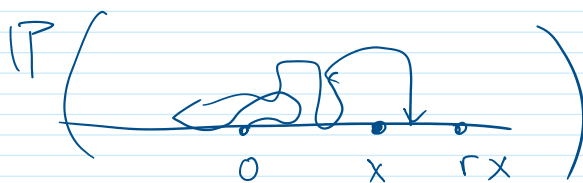


$$R = \text{dis}(z, \partial \Omega)$$

$$\leq \left(\frac{R}{r}\right)^{-\alpha}$$

$\Rightarrow F$ is Hölder with exp. α

Convergence of one observable $\Rightarrow$
conv. to SLE



$$= F(r) \leftarrow \text{explicit function (in terms of } F_1)$$

describe it in terms of LE



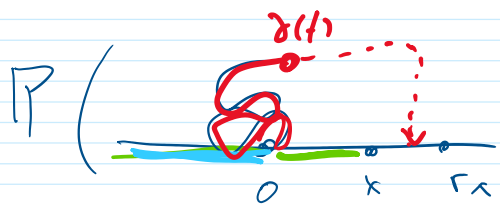


mesh = δ

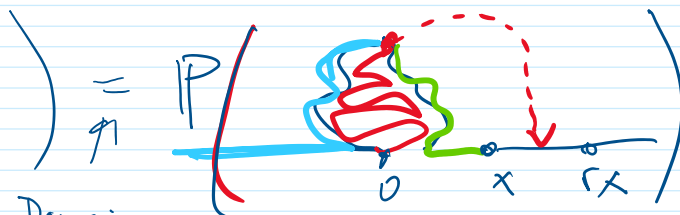
describe it in terms of LE

$g_{t,\delta}$

$u_\delta(t) \leftarrow \text{driver}$



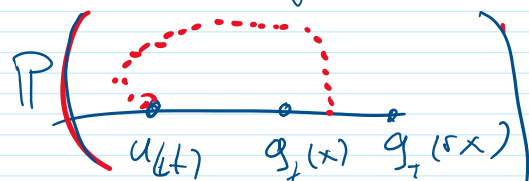
$g_{t,\delta}$



Domain Markov

$\delta \rightarrow 0$

$$F\left(\frac{g_t(rx) - u(t)}{g_t(x) - u(t)}\right) =$$



Take $\mathbb{E}$ w.r.t law of g_t

$$F(r) = \mathbb{E} F\left(\frac{g_t(rx) - u(t)}{g_t(x) - u(t)}\right)$$

expand g_t at ∞ $g_t(x) = x + \frac{2t}{x} + \dots$
 F at r

$$F\left(\frac{g_t(rx) - u(t)}{g_t(x) - u(t)}\right) = F(r) + c_1 \left(\frac{r-1}{r^2}\right)^{1/3} \frac{u(t)}{x} + c_2 \frac{(r+1)(r-1)^{1/3}}{r^{5/3}} (u(t)^2 - 6t) \frac{1}{x^2} + \dots$$

Take $\mathbb{E}$

$$\mathbb{E} u(t) = 0, \quad \mathbb{E} (u(t)^2 - 6t) = 0$$

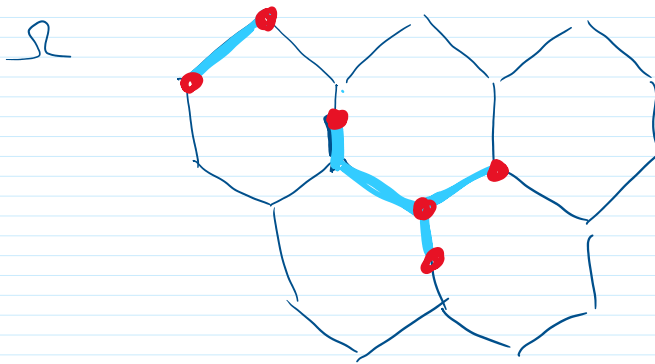
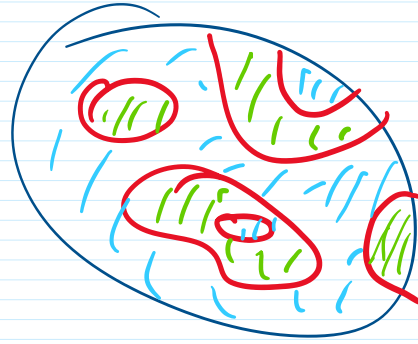
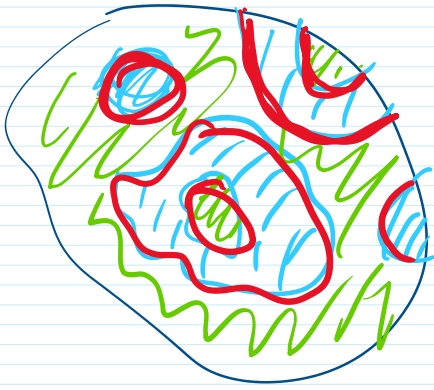
D. Markov property the same is true for

$$\mathbb{E} (u(t) - u(s)) = 0 \quad \mathbb{E} [(u(t) - u(s))^2 - 6(t-s)] = 0$$

$$\Rightarrow u(t) = \sqrt{6} B_t$$

$\Rightarrow$

$$u(t) = \sqrt{6} B_t$$



let E be a collection
of half-edges

Then ∂E is the set of all vertices and mid-edges st they touch odd number of half-edges from E

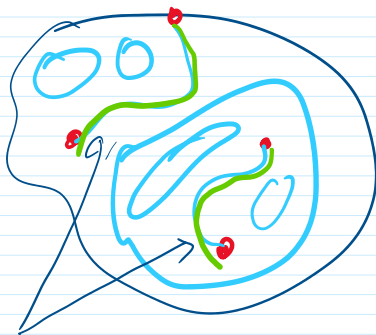
Let $U = \{u_1, \dots, u_k\}$ of marked mid-edges

$$W_{\Sigma}(u_1, \dots, u_k) = W_{\Sigma}(u) = W(u)$$

= collection of all E s.t. $\partial E = U$

configuration with disorders
at u_i

$W = \emptyset$ if k is odd

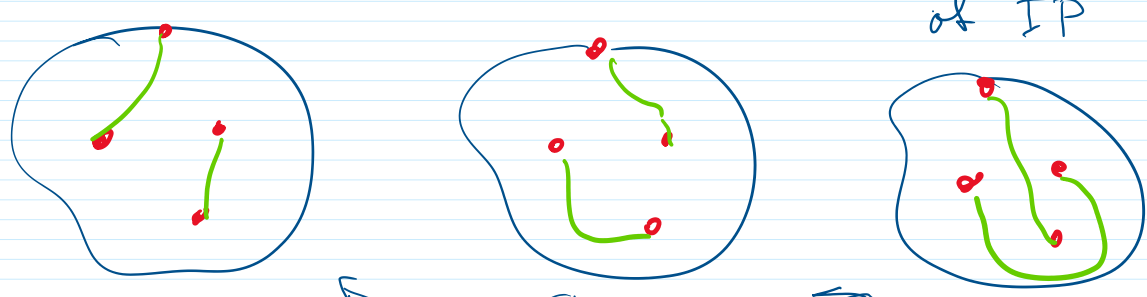

$$\neg P(E)$$

$IP(E) = \text{Important part of } E$
 $= \text{union of all connected components of } E \text{ containing at least one } u_i$

$\mathbb{IP}(E)$

at least one u_i

Connectivity pattern = homotopy class of IP



all possible connectivity patterns.

$\mathbb{P}^{\text{loop}}$ = uniform measure on $\mathcal{W}_\Omega(u_1, \dots, u_k)$

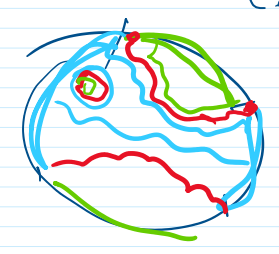
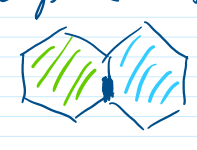
Lemma

$$\mathbb{P}^{\text{perc}} \left(\text{Diagram 1} \right) = \mathbb{P}^{\text{loop}} \left(\text{Diagram 2} \right)$$

$u_1, \dots, u_n \in \partial\Omega$

Proof Given a percolation config $\exists$ natural map to loop config.

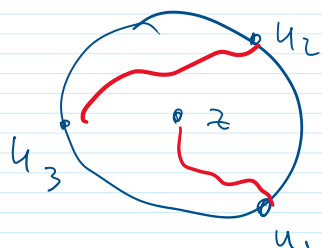
half-edge $e \in E$ if $e \not\subset \partial\Omega$



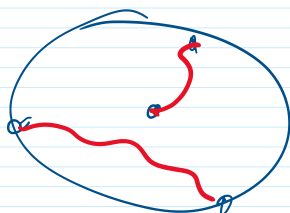
Claim This is a measure preserving config.

Proof this is a bijection $\square$

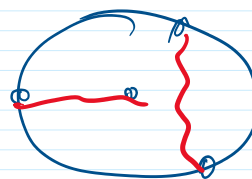
Discrete Holomorphicity



$[z \leftrightarrow u_1]$



$[z \leftrightarrow u_2]$



$[z \leftrightarrow u_3]$

Define $\tau = e^{2\pi i/3}$

Fix u_1, u_2, u_3 , think that z is a variable

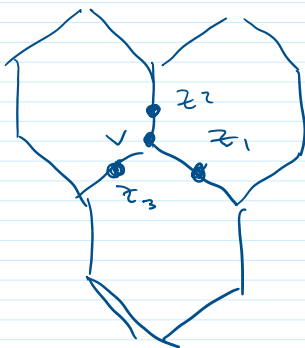
$F = F_{u_1, u_2, u_3}(z)$ function on mid-edges

$$F(z) = \mathbb{E}^{\text{loop}} H(E) = \sum_{k=1}^3 \tau^k H_k(z)$$

$$H(E) = \sum \tau^k \mathbb{1}_{[z \leftrightarrow u_k]}$$

$$H_k(z) = \mathbb{P}^{\text{loop}} [z \leftrightarrow u_k]$$

Lemma



$$\text{Then } \sum_{k=1}^3 \tau^k F(z_k) = 0$$

This is a discrete version of Cauchy-Riemann equations

Proof $\sum \tau^k F(z_k) = \sum \tau^k \sum \tau^j H_j(z_k)$

$$= \sum_{k,j} \tau^{k+j} \mathbb{P}[z_k \leftrightarrow u_j] =$$

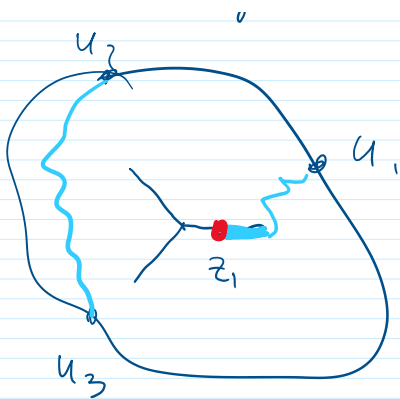
$$= c \sum \tau^{k+j} \# \text{ config s.t. } z_k \leftrightarrow u_j$$

Group all configurations

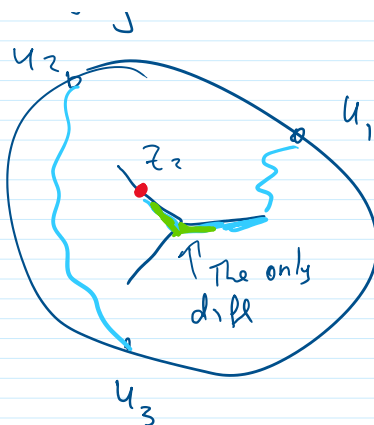


,

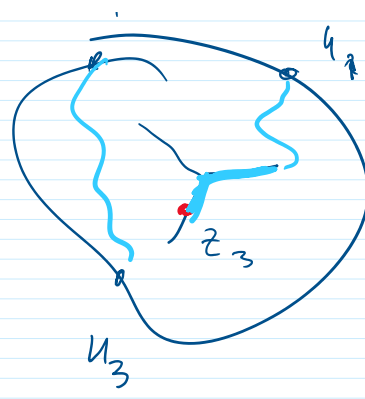




$$\tau^{1+1} = \tau^2$$

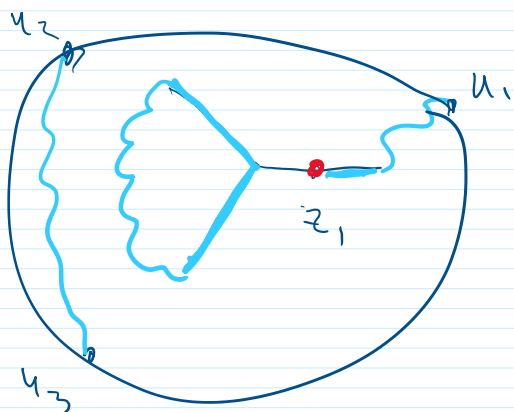


$$\tau^{2+1} = 1$$

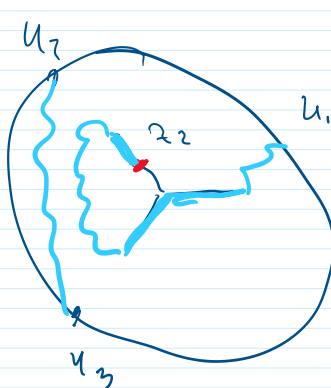


$$\tau^{3+1} = \tau$$

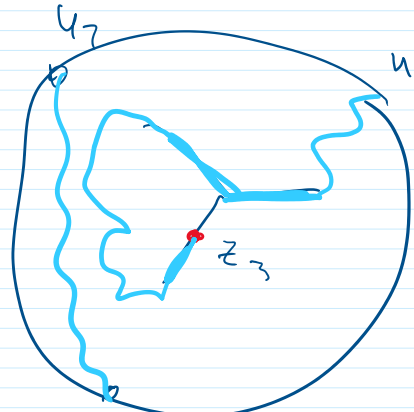
Numbers of these config are the same



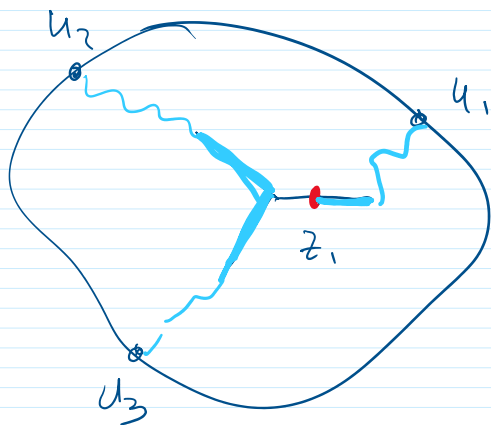
$$\tau^{1+1} = \tau^2$$



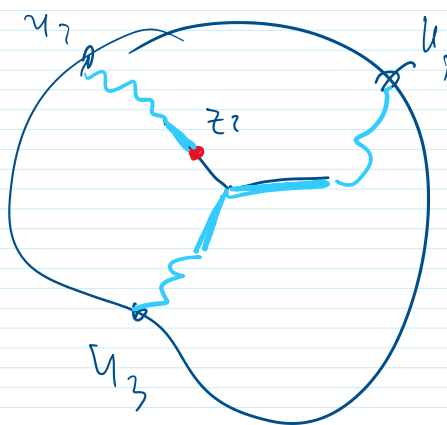
$$\tau^{2+1} = 1$$



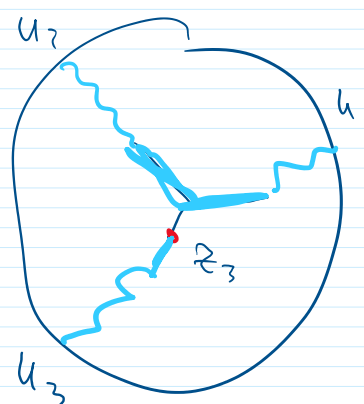
$$\tau^{3+1} = \tau$$



$$\tau^{1+1} = \tau^2$$



$$\tau^{2+2} = \tau$$



$$\tau^{3+3} = 1$$

All config can be grouped into triplets
and the weighted sum in each triplet = 0

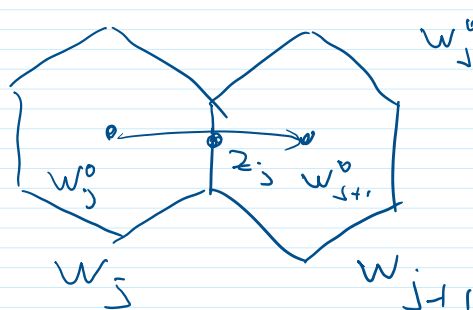


Discrete integration

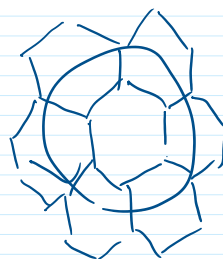
γ is a contour made of hexagons w_j

$$w_0 = w_n \quad (w_{k+n} = w_k)$$

w_j and w_{j+1} share an edge



$$w_{j+1}^0 - w_j^0$$



Let F be a function defined on mid edges

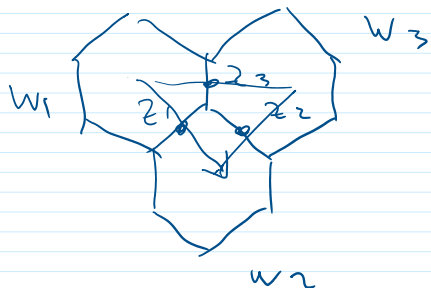
$$\int_{\gamma}^{\#} F(z) d^{\#}z = \sum_j F(z_j) (w_{j+1}^0 - w_j^0)$$

Th Let F be a function s.t $\forall$ vertex v
if z_1, z_2, z_3 are 3 mid-edges around v

$$\sum \tau^k F(z_k) = 0$$

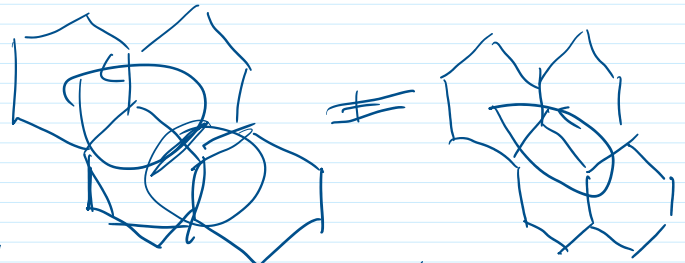
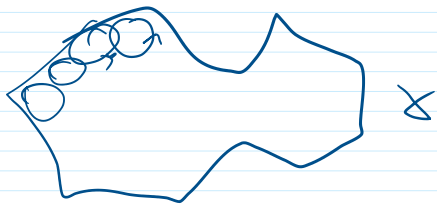
Then $\forall$ contour γ $\int_{\gamma}^{\#} F(z) d^{\#}z = 0$

Proof Consider an elementary γ



$$\begin{aligned} \int_{\gamma}^{\#} F d^{\#}z &= F(z_1)(-\tau) + \\ &\quad + F(z_2)(-\tau^2) \\ &\quad + F(z_3)(-1) \\ &= -(\tau F(z_1) + \tau^2 F(z_2) + \tau^3 F(z_3)) \end{aligned}$$

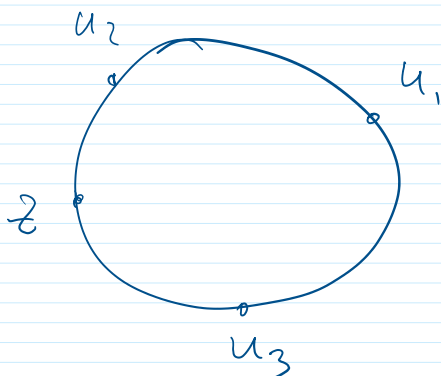
$\overset{=0}{\curvearrowright}$
C-R equation



any $\gamma = \Sigma$ of elementary contours

$$\Rightarrow \int_{\gamma}^{\#} F d^{\#} z = 0 \quad \forall \gamma \quad \square$$

$$\bar{F}(z) = \sum z^k P[z \leftrightarrow u_k]$$



if $z \in (u_2, u_3)$ then

$$H_1 = 0$$



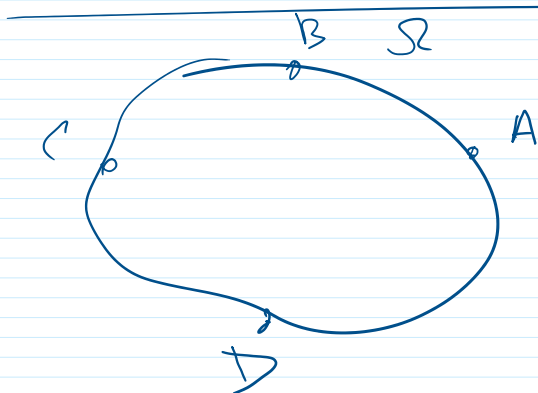
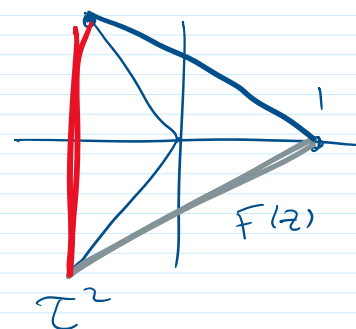
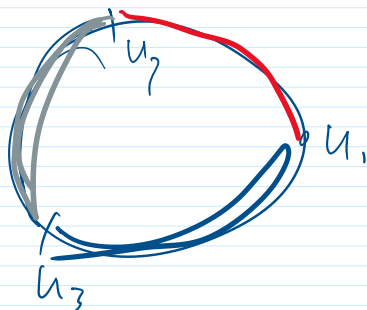
$$P[z \leftrightarrow u_3] = P\left(\begin{array}{c} u_2 \\ z \\ u_1 \\ u_3 \end{array}\right)$$

$$= P^{\text{perc}}\left(\begin{array}{c} u_2 \\ z \\ u_1 \\ u_3 \end{array}\right)$$

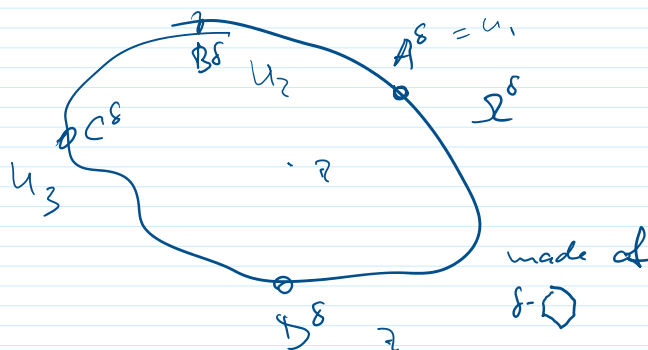
$$\begin{aligned} P[z \leftrightarrow u_2] &= P^{\text{loop}}\left(\begin{array}{c} u_1 \\ z \\ u_3 \end{array}\right) = P^{\text{perc}}\left(\begin{array}{c} u_1 \\ z \\ u_3 \end{array}\right) = \\ &= P\left(\begin{array}{c} u_1 \\ z \\ u_3 \end{array}\right) = 1 - P\left(\begin{array}{c} u_1 \\ z \\ u_3 \end{array}\right) \end{aligned}$$

$$z \in (u_2, u_3) \text{ then } \bar{F}(z) = \lambda \tau^2 + (1-\lambda) \tau^3 \quad \square$$

$z \in (u_2, u_3)$ then $f(z) = \lambda C + (1-\lambda) C$
 $z \in (u_3, u_1)$
 $z \in (u_1, u_2)$



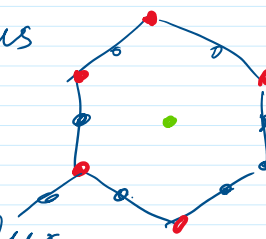
Take small S , approximate by domain with mesh S



Define $F_{\Omega^delta, A^delta, B^delta, C^delta, D^delta}^delta(z)$

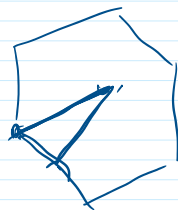
Extend to Ω^delta as a domain in $\mathbb{C}$

$f_{\delta}(\text{vertex}) = \text{average of values at neighbouring mid-edges}$



$f_{\delta}(\text{center of a hex}) = \text{average of values of mid-edges}$

inside

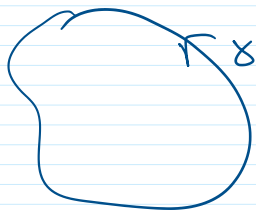


It is an affine function

ZSW $\Rightarrow \{f_{\delta}\}_{\delta}$ is Hölder bounded.

KS $\Rightarrow \{f_\delta\}_\delta$ is Morera sequence

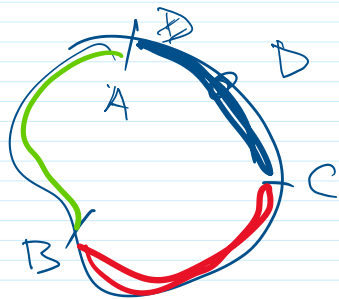
Arzela-Ascoli theorem $\Rightarrow$ if $\delta_n \rightarrow 0$ then
 $\exists \delta_{n_k} \rightarrow 0$ s.t. $f_{\delta_{n_k}} \rightarrow f$ unif on compacts



$$\begin{aligned} \int_{\gamma} f(z) dz &= \int_{\gamma_\delta} f(z) dz + o(1) = \\ &= \int_{\gamma_\delta}^{\#} F_\delta(z) dz^{\#} + o(1) \quad \text{take } \lim \delta_{n_k} \rightarrow 0 \\ &\quad \text{"0"} \end{aligned}$$

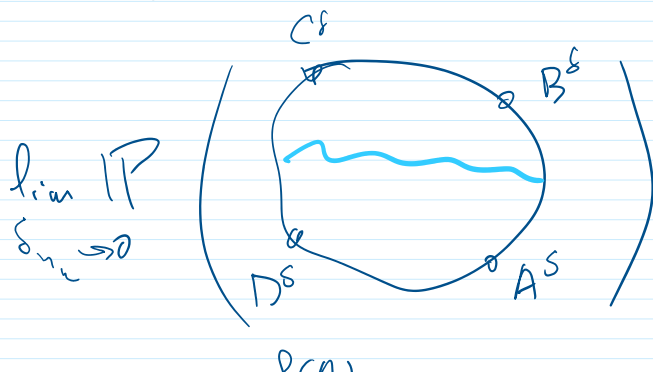
$\int_{\gamma} f(z) dz = 0 \quad \forall \gamma$. By Morera's theorem

$\Rightarrow f$ is holomorphic



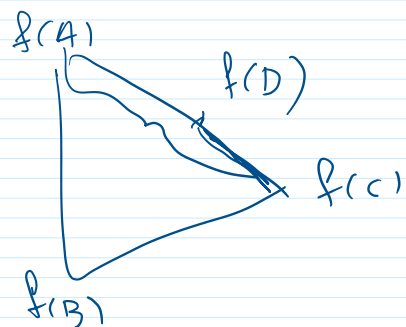
f is hol., $\partial\Omega \rightarrow \partial\Delta$

Argument principle implies that f is
 the cont map from (Ω, A, B, C) onto
 Δ with marked vertices



$$\begin{aligned} \lim_{\delta_{n_k} \rightarrow 0} \text{IP} &= \lim \frac{\tau^3 - F_\delta(D^\delta)}{\tau^3 - \tau^1} \\ &= \frac{f(C) - f(D)}{0 - 0} \end{aligned}$$

$\mathbb{D}^+ \sim H^- /$



$$= \frac{f(C) - f(D)}{f(C) - f(A)}$$

= Carleson - Carthy formula

All conv. subseq conv to the same limit.

$$\Rightarrow f_\delta \rightarrow f \quad \text{as } \delta \rightarrow 0$$

