## Proof of Second Order Necessary Optimality Conditions for Constrained Problems Theorem 19

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C6.2/B2: Continuous Optimization

<u>Theorem 19</u> (Second-order necessary conditions) Let some CQ hold for (CP). Let  $x^*$  be a local minimizer of (CP), and  $(y^*, \lambda^*)$  Lagrange multipliers of the KKT conditions at  $x^*$ . Then

 $s^T \nabla^2_{xx} \mathcal{L}(x^*, y^*, \lambda^*) s \ge 0$  for all  $s \in F(\lambda^*)$ ,

where  $\mathcal{L}(x, y, \lambda) = f(x) - y^T c_E(x) - \lambda^T c_I(x)$  is the Lagrangian function.

Proof of Theorem 19 (for equality constraints only) [NON-EXAMINABLE]: Let  $I = \emptyset$  and so  $\mathcal{F}(x^*) = F(\lambda^*)$ . We have to show that

 $s^T \nabla^2_{xx} \mathcal{L}(x^*, y^*, \lambda^*) s \ge 0$  for all s such that  $J_E(x^*) s = 0$ .

As in the proof of Th16, we consider feasible perturbations/paths  $x(\alpha)$  around  $x^*$ , where  $\alpha$  (sufficiently small) scalar,  $x(\alpha) \in C^2(\mathbb{R}^n)$  and

## Second-order optimality conditions...

Proof of Theorem 19 (for equality constraints only) (continued)  $x(0) = x^*, x(\alpha) = x^* + \alpha s + \frac{1}{2}\alpha^2 p + \mathcal{O}(\alpha^3), \text{ and } c(x(\alpha)) = 0^{(\dagger)}.$ (†) requires constraint qualifications, namely, assuming the existence of  $s \neq 0, p \neq 0$  with above properties.

For any  $i \in E$ , by Taylor's theorem for  $c_i(x(\alpha))$  around  $x^*$ ,

$$\begin{array}{lll} 0 &=& c_i(x(\alpha)) = c_i(x^* + \alpha s + \frac{1}{2}\alpha^2 p + \mathcal{O}(\alpha^3)) \\ &=& c_i(x^*) + \nabla c_i(x^*)^T (\alpha s + \frac{1}{2}\alpha^2 p) + \frac{1}{2}\alpha^2 s^T \nabla^2 c_i(x^*) s + \mathcal{O}(\alpha^3) \\ &=& \alpha \nabla c_i(x^*)^T s + \frac{1}{2}\alpha^2 \left[ \nabla c_i(x^*)^T p + s^T \nabla^2 c_i(x^*) s \right] + \mathcal{O}(\alpha^3). \end{array}$$

where we used  $c_i(x^*) = 0$ . Thus for all  $i \in E$ ,

$$\begin{aligned} \nabla c_i(x^*)^T s &= 0 \text{ and } \nabla c_i(x^*)^T p + s^T \nabla^2 c_i(x^*) s = 0, \\ \text{and so } J_E(x^*)s &= 0. \text{ Now expanding } f, \text{ we deduce} \\ f(x(\alpha)) &= f(x^*) + \nabla f(x^*)^T (\alpha s + \frac{1}{2}\alpha^2 p) + \frac{1}{2}\alpha^2 s^T \nabla^2 f(x^*) s + \mathcal{O}(\alpha^3) \\ &= f(x^*) + \alpha \nabla f(x^*)^T s + \frac{1}{2}\alpha^2 \left[ \nabla f(x^*)^T p + s^T \nabla^2 f(x^*) s \right] + \mathcal{O}(\alpha^3). \end{aligned}$$

Proof of Theorem 19 (for equality constraints only):(continued) As  $x^*$  is a local minimizer, we must have that

$$abla f(x^*)^T p + s^T 
abla^2 f(x^*) s \ge 0.$$
 (\*)

From the KKT conditions,  $\nabla f(x^*) = J_E(x^*)^T y^*$  and so

$$abla f(x^*)^T p = (y^*)^T J_E(x^*) p = -\sum_{i \in E} y_i^* s^T \nabla^2 c_i(x^*) s.$$
 (\*\*)

From (\*) and (\*\*), we deduce

$$egin{array}{rcl} 0 &\leq & s^T 
abla^2 f(x^*) s - \sum_{i \in E} y_i^* s^T 
abla^2 c_i(x^*) s \ &= & s^T [
abla^2 f(x^*) - \sum_{i \in E} 
abla^2 c_i(x^*)] s \ &= & s^T 
abla^2_{xx} \mathcal{L}(x^*,y^*) s. & \Box \end{array}$$