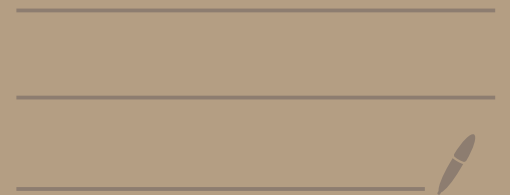


STRING THEORY I

Lecture 10



[4] Interactions

4.1 Generalities ✓

4.2 Vertex operators: introduction ✓

4.3 Vertex operators: open string ✓

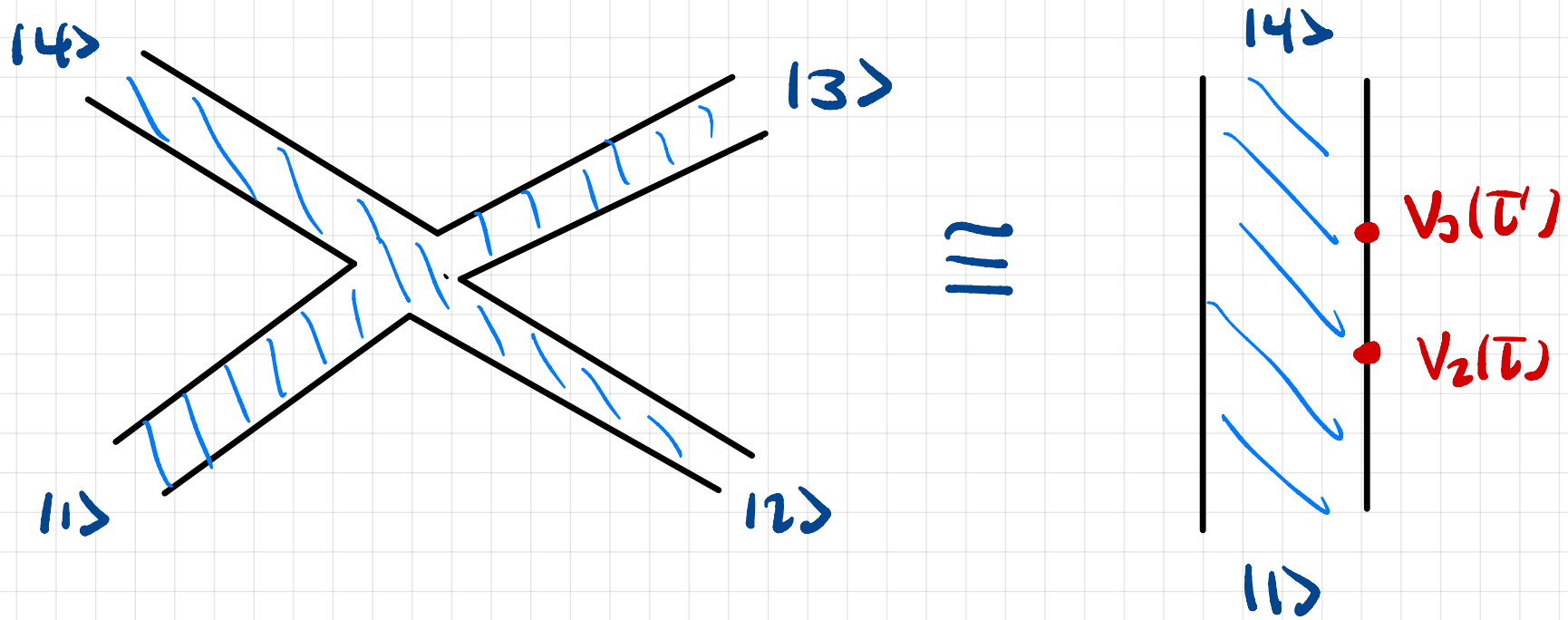
4.4 The state vertex correspondence ✓

4.5 3-point interactions ✓

4.6 4-point tachyon amplitude (open string)

4.7 Comments on the general picture

4.6 4-point tachyon amplitude (open string)



$$A_4(k_1, k_2, k_3, k_4) = g_0^2 \int_{\tau' > \tau} d\tau' d\tau \langle 0; -k_4 | V_3(\tau') V_2(\tau) | 0; k_1 \rangle \quad \text{Vol(conf)}$$

$$= g_0^2 \int_{\tau' > 0} d\tau' d\tau \langle 0; -k_4 | e^{i\tau' L_0} V_3(0) e^{-i\tau' L_0} V_2(\tau) | 0; k_1 \rangle \quad \text{Vol(conf)}$$

Use the residual gauge freedom to fix $\tau' = 0$

$$\Phi_4(k_1, k_2, k_3, k_4) = g_0^2 \int_{-\infty}^0 d\bar{\tau} \langle 0; -k_4 | V_3(0) V_2(\bar{\tau}) | 0; k_1 \rangle$$

$$= g_0^2 \int_{-\infty}^0 d\bar{\tau} \langle 0, -k_4 | V_3(0) e^{i\bar{\tau}L_0} V_2(0) \underbrace{e^{-i\bar{\tau}L_0} | 0; k_1 \rangle}_{e^{-i\bar{\tau}} | 0; k_1 \rangle}$$

$$= g_0^2 \int_{-\infty}^0 d\bar{\tau} \langle 0; -k_4 | V_3(0) e^{i\bar{\tau}(L_0-1)} V_2(0) | 0; k_1 \rangle$$

$$= g_0^2 \langle 0; -k_4 | V_3(0) \underbrace{\left(\int_{-\infty}^0 d\bar{\tau} e^{i\bar{\tau}(L_0-1)} \right)}_{\text{propagator}} V_2(0) | 0; k_1 \rangle$$

What do we do with $\int_{-\infty}^0 d\tau e^{i\tau(L_0-1)}$?

$$\int_{-\infty}^0 d\tau e^{i\tau(L_0-1)} \stackrel{?}{=} \frac{-i + \text{oscillatory}}{L_0-1} \quad ??$$

Analogy in QFT in Schwinger proper-time formalism:

$$\int_{-\infty}^0 d\tau e^{i\tau(p^2+m^2-i\epsilon)} = -\frac{i}{p^2+m^2-i\epsilon}$$

to avoid poles due to on shell particles

rotate the contour of integration
 $t = i\tau$

as long as $p^2+m^2 > 0$ i.e.
below threshold for production

$$\int_{-\infty}^0 dt e^{t(p^2+m^2)} = \frac{1}{p^2+m^2}$$

$$\Phi_4(k_1, k_2, k_3, k_4) = g_0^2 \langle 0; -k_4 | V_3(0) \left(\int_{-\infty}^0 d\bar{t} e^{i\bar{t}(L_0-1)} \right) V_2(0) | 0; k_1 \rangle$$

$$= g_0^2 \langle 0; -k_4 | V_3(0) \left(\int_{-\infty}^0 d\bar{t} e^{i\bar{t}(L_0-1-i\epsilon)} \right) V_2(0) | 0; k_1 \rangle$$

$\downarrow$ rotate contour $\bar{t} = -it$

$$= g_0^2 \langle 0; -k_4 | V_3(0) \left(\int_{-\infty}^0 dt e^{t(L_0-1)} \right) V_2(0) | 0; k_1 \rangle$$

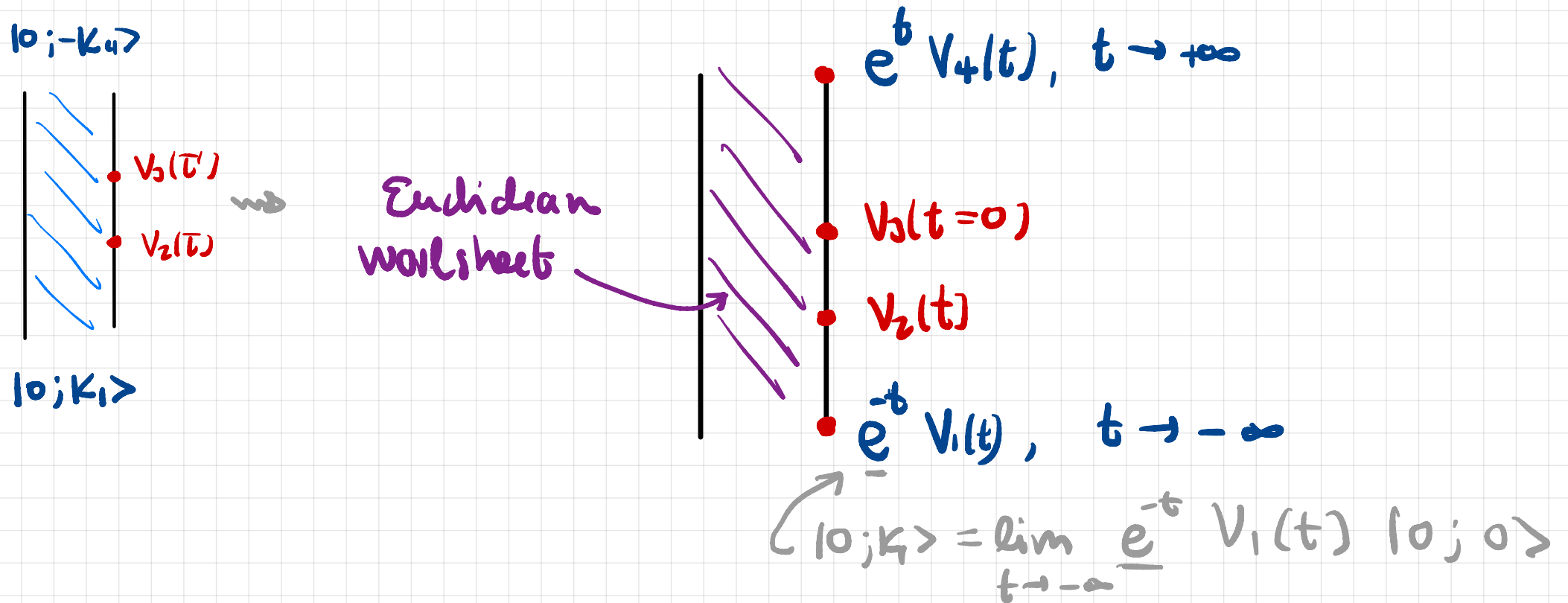
$$= g_0^2 \int_{-\infty}^0 dt \langle 0; -k_4 | V_3(0) e^{tL_0} V_2(0) e^{-tL_0} | 0; k_1 \rangle$$

$$= g_0^2 \int_{-\infty}^0 dt \langle 0; -k_4 | V_3(0) V_2(it) | 0; k_1 \rangle$$

all operators are now in Euclidean worldsheet time.

The amplitude now has an interpretation in
Euclidean worksheet.

$$\phi_4(K_1, K_2, K_3, K_4) = g^2 \int_{-\infty}^0 dt \langle 0; -K_4 | V_3(0) V_2(it) | 0; K_1 \rangle$$



Consider now a Euclidean conformal map

$$z = e^{t+i\sigma}, \quad \bar{z} = e^{t-i\sigma}$$

$$\text{so } dz d\bar{z} = e^{2t} (dt^2 + d\sigma^2) \longrightarrow dt^2 + d\sigma^2$$

$$|z|^2 = e^{2t}$$

↑
Weyl transformation

$$\text{ie } \frac{dz d\bar{z}}{|z|^2} = dt^2 + d\sigma^2$$

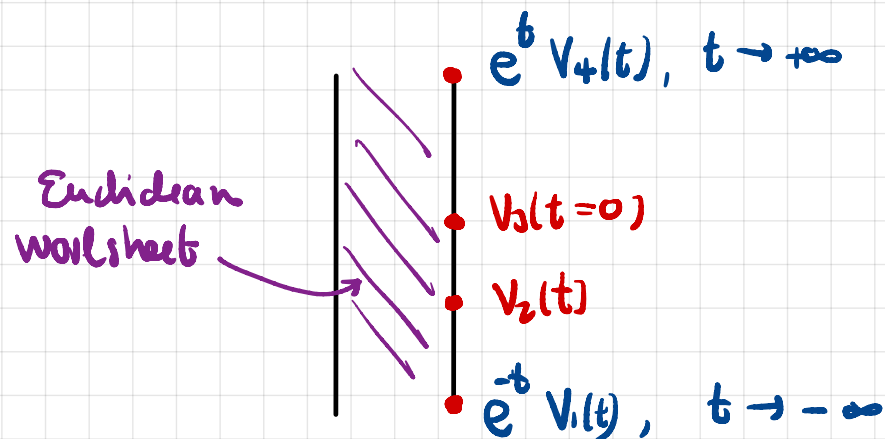
This is the metric on the upper half-plane (UHP)

$$\text{Im } z = e^t \sin \sigma$$

$$0 \leq \sigma < \pi$$

$$\text{Im } z \geq 0$$

The strip



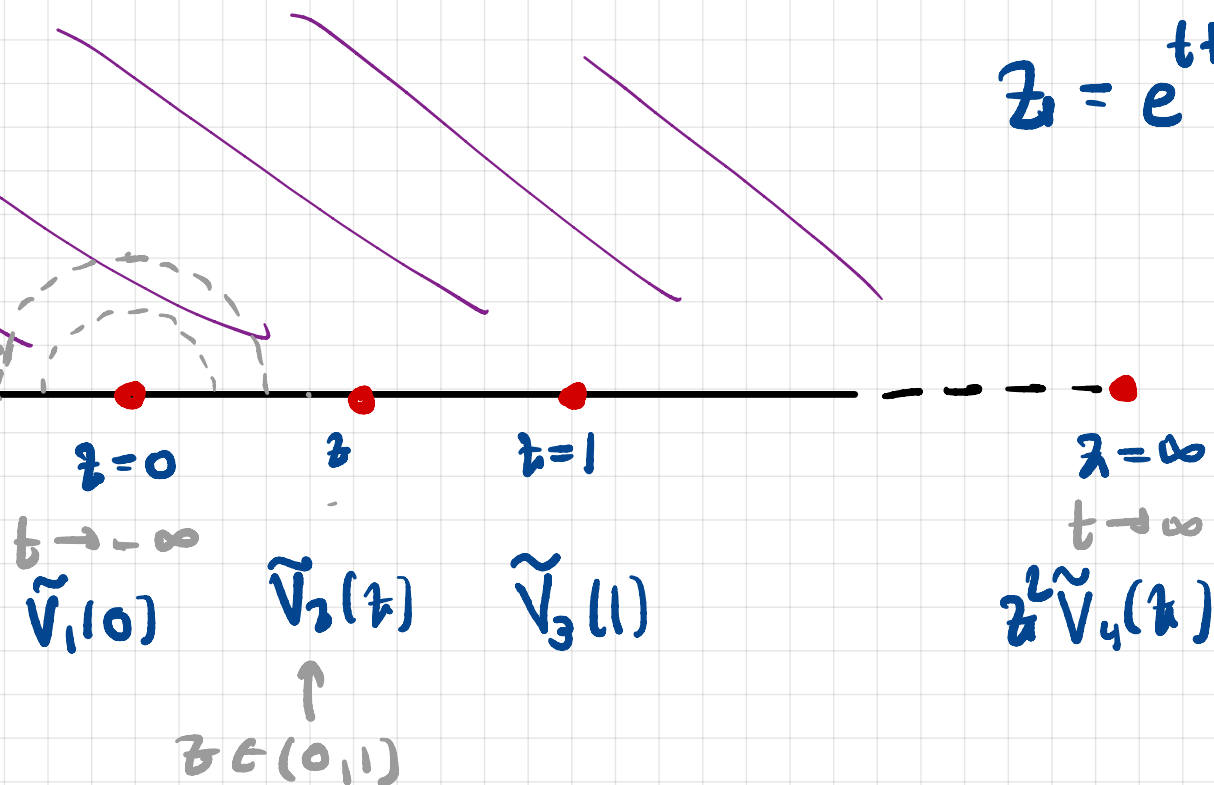
is mapped to the UHP with four marked points

UHP

equal
time
slice

$$z = e^{t+i\sigma}$$

boundary $\sigma=0$
where $\bar{z} = z$



Modification to the transformation rules of
Vertex operators:

Recall that a vertex operator $V(\tau)$ transforms as

$$V(\tau) \longrightarrow \tilde{V}(\tilde{\tau}) = \left(\frac{d\tau}{d\tilde{\tau}} \right)^1 V(\tau)$$

Then

$$z = e^{t+i\sigma}$$

$$\tilde{V}(\underbrace{z = \bar{z}}_{\sigma=0}) = \frac{dt}{dz} V(t) = z^{-1} V(t)$$

Then for the operators V_i we have:

- $V_2(t)$: $V_2(t) dt = \tilde{V}_2(z) \frac{1}{z} dz = \tilde{V}_2(z) dz$

- $V_3(t=0)$: $V_3(t=0) = \tilde{V}_3(1)$

- incoming state $|0; k_1\rangle = \lim_{t \rightarrow -\infty} e^{-t} V_1(t) |0; 0\rangle$

$$\lim_{t \rightarrow -\infty} e^{-t} V_1(t) = \lim_{z \rightarrow 0} \tilde{V}_1(z)$$

- outgoing state $\langle 0; -k_4| = \lim_{t \rightarrow \infty} e^t V_4(t)$

$$\lim_{t \rightarrow \infty} e^t V_4(t) = \lim_{z \rightarrow \infty} z^2 \tilde{V}_4(z)$$

Let's try to discuss conformal transformations and the gauge fixing procedure in more generality:

The group of conformal transformations of the upper-half plane is $PSL(2, \mathbb{R})$ <sup>L_{-1}, L_0, L_1
Möbius group</sup>

$$z \mapsto \frac{az+b}{cz+d}, \quad a, b, c, d \in \mathbb{R}, \quad \det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = 1$$

This is a three dimensional group of residual gauge symmetries.

One can find a transformation which maps any three points z_1, z_3, z_4

$$z_1 \longrightarrow 0$$

$$z_3 \longrightarrow 1$$

$$z_4 \longrightarrow \infty$$

Indeed, for any 3 points z_1, z_2, z_4

set
$$z_{ij} = z_i - z_j \quad (i \neq j)$$

Then
$$z \mapsto \frac{z_{34}}{z_{13}} \frac{z_1 - z}{z - z_4}$$

maps $z_1 \rightarrow 0$, $z_3 \rightarrow 1$ and $z_4 \rightarrow \infty$.

One can use this to gauge fix the tree point amplitude.

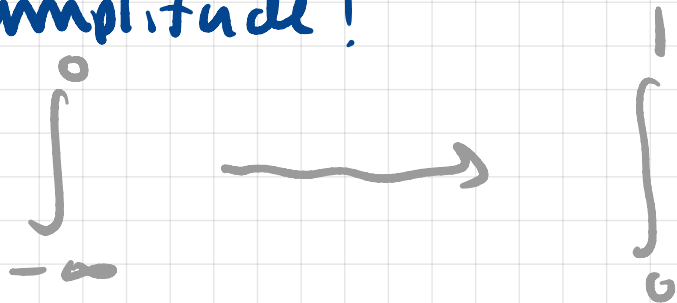
Of particular interest for us is the fact that the group of conformal transformations $PSL(2, \mathbb{R})$ of the UHP preserves the cyclic ordering of any four points on the boundary.

Consider a fourth point z_2 , with $z_1 < z_2 < z_3 < z_4$. Then

$$z_2 \longmapsto \frac{z_{12} z_{34}}{z_{13} z_{24}} \in (0, 1) \quad \text{conformal cross ratio}$$

Fixing three points z_1, z_3 & z_4 at $0, 1$ and ∞ , then, the fourth point $0 < z_2 < 1$

This is what we are integrating over in the four point amplitude!



We say that $(0,1)$ is the moduli space of conformal structures on the UHP with four marked points.

Faddeev-Popov gauge fixing:

We could have written the four point amplitude as

$$g_o^2 \int \underbrace{d\tau_1 d\tau_2 d\tau_3 d\tau_4}_{\text{overcounts configurations}} \langle \tilde{V}_4(\tau_4) \tilde{V}_3(\tau_3) \tilde{V}_2(\tau_2) \tilde{V}_1(\tau_1) \rangle_{\text{UHF}} / \text{Vol}(\text{SU}(2; \mathbb{R}))$$

and then use the Faddeev-Popov procedure to fix the gauge.

Imposing: $\tau_1 = \tau_1^0$ $\tau_3 = \tau_3^0$ $\tau_4 = \tau_4^0$

$$g_o^2 \int d\tau_1 d\tau_2 d\tau_3 d\tau_4 \delta(\tau_1 - \tau_1^0) \delta(\tau_3 - \tau_3^0) \delta(\tau_4 - \tau_4^0) \left| \text{Det} \frac{\partial(\tau_1, \tau_3, \tau_4)}{\partial(\lambda_1, \lambda_3, \lambda_4)} \right|$$

$$\times \langle \tilde{V}_4(\tau_4) \tilde{V}_3(\tau_3) \tilde{V}_2(\tau_2) \tilde{V}_1(\tau_1) \rangle_{\text{UHF}}$$

Faddeev-Popov determinant

$$\left| \text{Det} \frac{\partial(z_1, z_2, z_3)}{\partial(\lambda_{-1}, \lambda_0, \lambda_1)} \right| = \text{Jacobian of the transformation}$$

from z_1, z_2, z_3 to $\lambda_{-1}, \lambda_0, \lambda_1$

$$= (z_3 - z_1)(z_1 - z_2)(z_2 - z_3)$$

where $\delta z = \lambda_{-1} z + \lambda_0 z^2 + \lambda_1 z^3$

$\uparrow \quad \uparrow \quad \uparrow$
 $L_{-1} \quad L_0 \quad L_{+1}$

(Infinitesimal Möbius transformation: $\lambda_{-1} = \delta b$
 $\lambda_0 = 2\delta c$
 $\lambda_1 = -\delta c$)

Expand around $a=d=1$
 $c=b=0$

$$Jac = \begin{vmatrix} 1 & 1 & 1 \\ z_1 & z_2 & z_3 \\ z_1^2 & z_2^2 & z_3^2 \end{vmatrix}$$

$$= z_{43} z_{21} z_{41}$$

$$\partial z^i / \partial \lambda$$

$dn = \text{measure on UHP}$

$$g_0^2 \int d\tau_1 d\tau_2 d\tau_3 d\tau_4 \delta(\tau_1 - \tau_1^0) \delta(\tau_2 - \tau_2^0) \delta(\tau_4 - \tau_4^0) |(\tau_4 - \tau_3)(\tau_3 - \tau_1)(\tau_4 - \tau_1)|^{-1} \\ \times \langle \tilde{V}_4(\tau_4) \tilde{V}_3(\tau_3) \tilde{V}_2(\tau_2) \tilde{V}_1(\tau_1) \rangle_{\text{UHP}}$$

choose $\tau_1^0 = 0$, $\tau_3^0 = 1$, $\tau_4^0 = \Lambda \rightarrow \infty$

$$= \lim_{\Lambda \rightarrow \infty} g_0^2 \int d\tau_2 (\Lambda - 1) \Lambda \langle \tilde{V}_4(\Lambda) \tilde{V}_3(1) \tilde{V}_2(\tau_2) \tilde{V}_1(0) \rangle_{\text{UHP}} \\ = g_0^2 \int d\tau \langle 4 | \tilde{V}_3(1) \tilde{V}_2(\tau) | 1 \rangle$$

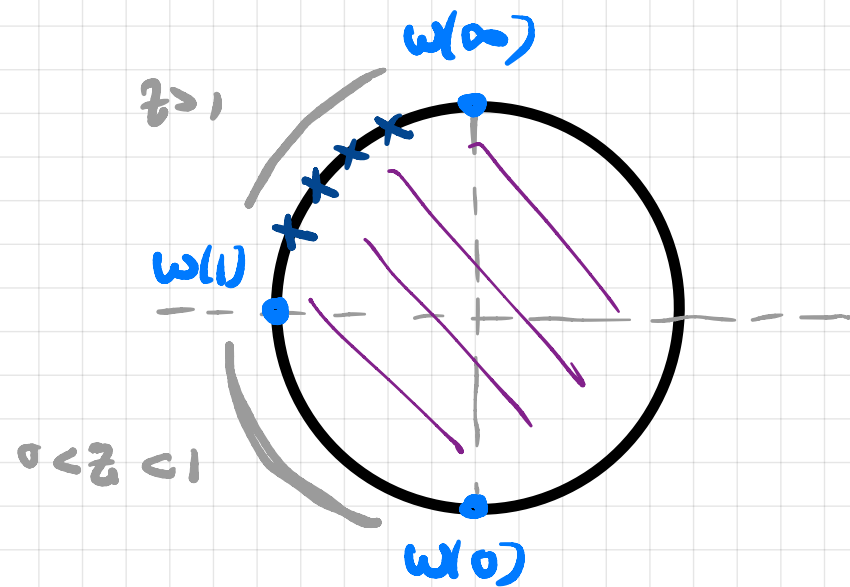
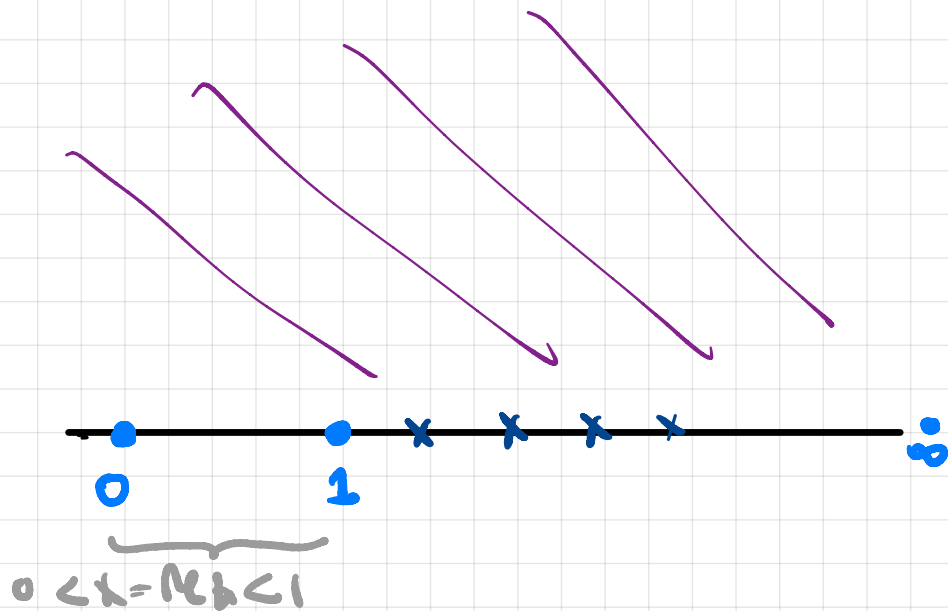
PS 3 This is the Veneziano amplitude -

cyclic symmetry: an elegant way to make the cyclic symmetry of amplitudes manifest is by introducing the map

$$z \mapsto w = \frac{iz-1}{z-i}$$

which maps

UHP $\rightarrow$ unit disk



Next 4.7

General comments on amplitudes