#### Numerical Solution of Partial Differential Equations

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Lecture 11

# The discrete maximum principle

#### Theorem (Discrete maximum principle for the $\theta$ -scheme)

The  $\theta$ -scheme for the Dirichlet initial-boundary-value problem for the heat equation, with  $0 \le \theta \le 1$  and  $\mu(1-\theta) \le \frac{1}{2}$ , yields a sequence of numerical approximations  $\{U_i^m\}_{j=0,...,J;\ m=0,...,M}$  satisfying

$$U_{\min} \leq U_j^m \leq U_{\max}$$

where

$$U_{\min} = \min\left\{\min\{U_0^m\}_{m=0}^M, \min\{U_j^0\}_{j=0}^J, \min\{U_J^m\}_{m=0}^M
ight\}$$

and

$$U_{\max} = \max\left\{\max\{U_0^m\}_{m=0}^M, \, \max\{U_j^0\}_{j=0}^J, \, \max\{U_J^m\}_{m=0}^M\right\}$$

**PROOF:** We rewrite the  $\theta$ -scheme as

$$(1+2\theta\mu) U_{j}^{m+1} = \theta\mu \left( U_{j+1}^{m+1} + U_{j-1}^{m+1} \right) + (1-\theta)\mu \left( U_{j+1}^{m} + U_{j-1}^{m} \right) + [1-2(1-\theta)\mu] U_{j}^{m},$$

and recall that, by hypothesis,

$$heta \mu \geq 0 \qquad (1- heta) \mu \geq 0, \qquad 1-2(1- heta) \mu \geq 0.$$

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Suppose that U attains its maximum value  $U_j^{m+1}$  at an internal mesh point  $(x_j, t_{m+1})$  where  $j \in \{1, \ldots, J-1\}$ ,  $m \in \{0, \ldots, M-1\}$ . If this is not the case, the proof is complete.

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We define

$$U^{\star} := \max\{U_{j+1}^{m+1}, U_{j-1}^{m+1}, U_{j+1}^{m}, U_{j-1}^{m}, U_{j}^{m}\}.$$

Then,

$$egin{aligned} &(1+2 heta\mu)\,U_{j}^{m+1}\leq 2 heta\mu U^{\star}+2(1- heta)\mu U^{\star}\ &+\left[1-2(1- heta)\mu
ight]U^{\star}=(1+2 heta\mu)\,U^{\star}, \end{aligned}$$

and therefore

$$U_j^{m+1} \leq U^*.$$

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and therefore

$$U_j^{m+1} \leq U^\star.$$

However, also,

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The same argument then applies to these neighbouring points, and we can then repeat this process until the boundary at x = a or x = b or at t = 0is reached, in a finite number of steps.

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By an identical argument the minimum is attained at a boundary point.  $\diamond$ 

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This condition is clearly more demanding than the  $\ell_2$ -stability condition:

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E.g., the Crank-Nicolson scheme is unconditionally stable in the  $\ell_2$  norm, yet it only satisfies the discrete maximum principle when  $\mu := \frac{\Delta t}{(\Delta x)^2} \leq 1$ .

# Convergence of the $\theta$ -scheme in the maximum norm

We close our discussion of finite difference schemes for the heat equation in one space-dimension with the convergence analysis of the  $\theta$ -scheme for the Dirichlet initial-boundary-value problem.

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We begin by rewriting the scheme as follows:

$$(1+2\theta\mu) U_{j}^{m+1} = \theta\mu \left( U_{j+1}^{m+1} + U_{j-1}^{m+1} \right) + (1-\theta)\mu \left( U_{j+1}^{m} + U_{j-1}^{m} \right) + [1-2(1-\theta)\mu] U_{j}^{m}.$$

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The scheme is considered subject to the initial condition

$$U_j^0 = u_0(x_j), \qquad j = 0, \ldots, J,$$

and the boundary conditions

$$U_0^{m+1} = A(t_{m+1}), \ U_J^{m+1} = B(t_{m+1}), \ m = 0, \dots, M-1.$$

The **consistency error** for the  $\theta$ -scheme is defined by

$$T_j^m = \frac{u_j^{m+1} - u_j^m}{\Delta t} - (1 - \theta) \frac{u_{j+1}^m - 2u_j^m + u_{j-1}^m}{(\Delta x)^2} - \theta \frac{u_{j+1}^{m+1} - 2u_j^{m+1} + u_{j-1}^{m+1}}{(\Delta x)^2}, \quad \begin{cases} j = 1, \dots, J - 1, \\ m = 0, \dots, M - 1, \end{cases}$$

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Define the **global error**, that is the discrepancy at a mesh-point between the exact solution and its numerical approximation, by

$$e_j^m := u(x_j, t_m) - U_j^m, \quad \begin{cases} j = 0, \dots, J, \\ m = 0, \dots, M. \end{cases}$$

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It then follows that

$$e_0^{m+1} = 0, \ e_J^{m+1} = 0, \ e_j^0 = 0, \quad j = 0, \dots, J,$$

and

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We define,

$$E^m = \max_{0 \leq j \leq J} |e_j^m|$$
 and  $T^m = \max_{1 \leq j \leq J-1} |T_j^m|.$ 

$$heta \mu \geq 0, \qquad (1- heta) \mu \geq 0, \qquad 1-2(1- heta) \mu \geq 0,$$

we have that

$$(1+2\theta\mu)E^{m+1} \le 2\theta\mu E^{m+1} + E^m + \Delta tT^m.$$

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As  $E^0 = 0$ , upon summation,

$$E^{m} \leq \Delta t \sum_{n=0}^{m-1} T^{n}$$
  
$$\leq m\Delta t \max_{\substack{0 \leq n \leq m-1 \\ 0 \leq m \leq M-1}} T^{n}$$
  
$$\leq T \max_{\substack{0 \leq m \leq M-1 \\ 1 \leq j \leq J-1}} \max_{\substack{|T_{j}^{m}|, }}$$

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$$\leq T \max_{0 \leq m \leq M-1} \max_{1 \leq j \leq J-1} |T_{j}^{m}|,$$

which then implies that

$$\max_{0\leq j\leq J} \max_{0\leq m\leq M} |u(x_j,t_m)-U_j^m|\leq T \max_{1\leq j\leq J-1} \max_{0\leq m\leq M-1} |T_j^m|.$$

Recall that the consistency error of the  $\theta$ -scheme is

$$T_j^m = \begin{cases} \mathcal{O}\left((\Delta x)^2 + (\Delta t)^2\right) & \text{for } \theta = 1/2, \\ \mathcal{O}\left((\Delta x)^2 + \Delta t\right) & \text{for } \theta \neq 1/2. \end{cases}$$

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For the explicit/implicit Euler schemes, for which

$$T_j^m = \mathcal{O}\left((\Delta x)^2 + \Delta t\right),$$

one has the following bound on the global error:

$$\max_{0 \leq j \leq J} \max_{0 \leq m \leq M} |u(x_j, t_m) - U_j^m| \leq \text{Const.} \left( (\Delta x)^2 + \Delta t \right),$$

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while for the Crank-Nicolson scheme, which has consistency error

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one has

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# Finite difference approximation in two space-dimensions

Consider the heat equation

$$rac{\partial u}{\partial t} = rac{\partial^2 u}{\partial x^2} + rac{\partial^2 u}{\partial y^2}, \qquad (x,y) \in \Omega := (a,b) imes (c,d), \ t \in (0,T],$$

subject to the initial condition

$$u(x, y, 0) = u_0(x, y),$$
  $(x, y) \in [a, b] \times [c, d],$ 

and the Dirichlet boundary condition

$$|u|_{\partial\Omega} = B(x, y, t), \qquad (x, y) \in \partial\Omega, \ t \in (0, T],$$

where  $\partial \Omega$  is the boundary of  $\Omega$ .

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where  $\partial \Omega$  is the boundary of  $\Omega$ .

We begin by considering the explicit Euler finite difference scheme for this problem.

# The explicit Euler scheme

Let

$$\delta_x^2 U_{ij} := U_{i+1,j} - 2U_{ij} + U_{i-1,j},$$

and

$$\delta_{y}^{2}U_{ij} := U_{i,j+1} - 2U_{ij} + U_{i,j-1}.$$

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Let, further,  $\Delta x := (b-a)/J_x$ ,  $\Delta y := (d-c)/J_y$ ,  $\Delta t := T/M$ , and define

$$\begin{aligned} x_i &= a + i\Delta x, & i = 0, \dots, J_x, \\ y_j &= c + j\Delta y, & j = 0, \dots, J_y, \\ t_m &= m\Delta t, & m = 0, \dots, M. \end{aligned}$$

The explicit Euler finite difference scheme for the unsteady heat equation on the space-time domain  $\overline{\Omega} \times [0, T]$  is then:

$$\frac{U_{ij}^{m+1}-U_{ij}^m}{\Delta t}=\frac{\delta_x^2 U_{ij}^m}{(\Delta x)^2}+\frac{\delta_y^2 U_{ij}^m}{(\Delta y)^2},$$

for  $i = 1, \dots, J_x - 1$ ,  $j = 1, \dots, J_y - 1$ ,  $m = 0, 1, \dots, M - 1$ ,

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and the boundary condition

 $U_{ij}^m = B(x_i, y_j, t_m)$ , at the boundary mesh points, for  $m = 1, \dots, M$ .

# The implicit Euler scheme

Let 
$$\Delta x := (b-a)/J_x$$
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The implicit Euler finite difference scheme for the problem is then

$$\frac{U_{ij}^{m+1} - U_{ij}^{m}}{\Delta t} = \frac{\delta_x^2 U_{ij}^{m+1}}{(\Delta x)^2} + \frac{\delta_y^2 U_{ij}^{m+1}}{(\Delta y)^2},$$
for  $i = 1, \dots, J_x - 1, j = 1, \dots, J_y - 1, m = 0, 1, \dots, M - 1,$ 

subject to the initial condition

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# The $\theta$ -scheme

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$$\frac{U_{ij}^{m+1} - U_{ij}^m}{\Delta t} = (1 - \theta) \left( \frac{\delta_x^2 U_{ij}^m}{(\Delta x)^2} + \frac{\delta_y^2 U_{ij}^m}{(\Delta y)^2} \right) + \theta \left( \frac{\delta_x^2 U_{ij}^{m+1}}{(\Delta x)^2} + \frac{\delta_y^2 U_{ij}^{m+1}}{(\Delta y)^2} \right)$$

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for  $i = 1, ..., J_x - 1$ ,  $j = 1, ..., J_y - 1$ , m = 0, 1, ..., M - 1, subject to the initial condition

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and the boundary condition

 $U_{ij}^{m+1} = B(x_i, y_j, t_{m+1}),$  at the boundary mesh points, for  $m = 0, \dots, M-1.$