# B4.1 Functional Analysis I 

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This set of lecture notes builds upon Hilary Priestley's and Melanie Rupflin's lecture notes who taught the course in previous years.

WARNING. There has been a change of syllabus between the academic years 2022/23 and 2023/24, which means that some of the material that was previously covered in B4.1 has now been moved to B4.2 (namely aspects of spectral theory), or removed (like the proof of Hahn-Banach) while some material from B4.2 has moved into B4.1 (namely basic aspects of Hilbert spaces, the Riesz-representation theorem, the projection theorem and the definition of adjoint operators). Please keep this in mind when using resources for exam preparation.

The following literature was also used (either for this set of notes, or for my predecessors'):
E. Kreyszig, Introductory Functional Analysis with Applications, Wiley, revised edition, 1989.
M. Reed and B. Simon, Methods of Modern Mathematical Physics Vol. I. Functional Analysis, Academic Press, 1980.
H. Brezis, Functional Analysis, Sobolev Spaces and Partial Differential Equations, Universitext, Springer, 2011.
P.D. Lax, Functional Analysis, Wiley, 2002.
R.L. Wheeden and A. Zygmund, Measure and Integral: An Introduction to Real Analysis, Dekker, 1977.
M. Struwe, Funktionalanalysis I und II, Lecture notes, ETH Zurich, 2013-2014.
D. Werner, Funktionalanalysis, Springer, 2011.

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## Chapter 1

## Banach spaces and Hilbert spaces

### 1.1 Normed spaces and Banach spaces

### 1.1.1 Definitions and basic properties

Definition 1.1.1. Let $X$ be a vector space (over either $\mathbb{F}=\mathbb{R}$ or $\mathbb{F}=\mathbb{C}$ ).
A norm $\|\cdot\|: X \rightarrow \mathbb{R}$ is a function so that $\forall x, y \in X, \forall \lambda \in \mathbb{F}$
(N1) $\|x\| \geq 0$ with $\|x\|=0 \Leftrightarrow x=0$
(N2) $\|\lambda x\|=|\lambda|\|x\|$
(N3) $\|x+y\| \leq\|x\|+\|y\|$ (Triangle inequality)
We call a pair $(X,\|\cdot\|)$ a normed space.
Recall that every norm $\|\cdot\|$ induces a metric

$$
d: X \times X \rightarrow \mathbb{R}
$$

via $d(x, y):=\|x-y\|$ and hence all standard notions and properties of a metric space encountered in part A are applicable:

We recall in particular:

- Definition of convergence of a sequence $\left(x_{n}\right)$ :

$$
x_{n} \underset{n \rightarrow \infty}{\longrightarrow} x \quad \Longleftrightarrow\left\|x_{n}-x\right\| \underset{n \rightarrow \infty}{\longrightarrow} 0
$$

- $\left(x_{n}\right)$ is a Cauchy-sequence if $\forall \varepsilon>0 \quad \exists N$ so that $\forall n, m \geq N$

$$
\left\|x_{n}-x_{m}\right\|<\varepsilon
$$

- A function $f:\left(X,\|\cdot\|_{X}\right) \rightarrow\left(Y,\|\cdot\|_{Y}\right)$ is continuous if and only if for every $x \in X$ and every sequence $\left(x_{n}\right)$ in $X$

$$
x_{n} \rightarrow x \Longrightarrow f\left(x_{n}\right) \rightarrow f(x),
$$

i.e.

$$
\left\|x_{n}-x\right\|_{X} \rightarrow 0 \Longrightarrow\left\|f\left(x_{n}\right)-f(x)\right\|_{Y} \rightarrow 0
$$

- A set $\Omega \subset X$ is open if for every $x_{0} \in \Omega$ there exists a $r>0$ so that

$$
B_{r}\left(x_{0}\right):=\left\{x \in X:\left\|x-x_{0}\right\|<r\right\} \subset \Omega .
$$

- By definition, a set $F \subset X$ is closed if $F^{c}$ is open and we have the following equivalent characterisations of closed sets:
- $F$ is closed if and only if $F$ contains all its limit points
- $F$ is closed if and only if for every sequence $\left(x_{n}\right)$ that consists of elements $x_{n} \in F$ and that converges $x_{n} \rightarrow x$ in $X$ we have that the limit $x$ is again an element of $F$.
- We also recall that $x \mapsto\|x\|$ is a continuous map and hence that if $x_{n} \rightarrow x$ then of course also $\left\|x_{n}\right\| \rightarrow\|x\|$.

Notation: We will use the convention that $A \subset B$ simply means that $A$ is a subset of $B$, not necessarily a proper subset, i.e. allowing for $A=B$. If our assumption is that $A$ is proper subset of $B$ then we will either explicitly say so or write $A \varsubsetneqq B$.

We also recall that two norms $\|\cdot\|$ and $\|\cdot\|^{\prime}$ are equivalent if and only if there exist a constant $C>0$ so that for all $x \in X$

$$
C^{-1}\|x\| \leq\|x\|^{\prime} \leq C\|x\|,
$$

or equivalently if there exist two constants $C_{1,2} \in \mathbb{R}$ so that for all $x \in X$

$$
\|x\| \leq C_{1}\|x\|^{\prime} \text { and }\|x\|^{\prime} \leq C_{2}\|x\|
$$

and that equivalent norms lead to equivalent definitions of convergence, Cauchy sequences, open and closed sets,....

One of the key objects we study in this course are Banach spaces and linear maps between such spaces.

Definition 1.1.2. A normed space $(X,\|\cdot\|)$ is a Banach space if it is complete, i.e. if every Cauchy sequence in $X$ converges.

We first note that for any given subspace $Y$ of a normed space $(X,\|\cdot\|)$ we obtain a norm on $Y$ simply by restricting the given norm to $Y$. For the resulting normed space $(Y,\|\cdot\|)$ we have

Proposition 1.1.3. Let $(X,\|\cdot\|)$ be a Banach space, $Y \subset X$ a subspace. Then

$$
(Y,\|\cdot\|) \text { is complete } \Leftrightarrow Y \subset X \text { is closed } .
$$

Proof.
" $\Rightarrow$ ":
Let $\left(y_{n}\right)$ be so that $y_{n} \in Y, y_{n} \rightarrow x \in X$. Then $\left(y_{n}\right)$ is a Cauchy sequence in $Y$ so converges in $(Y,\|\cdot\|)$ to some $y \in Y$. Hence $x=y \in Y$ by uniqueness of limits. Hence $Y$ is closed.
" $\Leftarrow ":$
If $\left(y_{n}\right)$ is a Cauchy sequence in $(Y,\|\cdot\|)$, it is also a Cauchy sequence in $(X,\|\cdot\|)$ and must hence converge in $X$, say $y_{n} \rightarrow x \in X$. But as $Y$ is closed we must have that $x \in Y$ and hence that $\left(y_{n}\right)$ converges in $(Y,\|\cdot\|)$. Thus $Y$ is complete.

WARNING. Many properties of finite dimensional normed spaces are NOT true for general infinite dimensional spaces, or maps between such spaces. A few examples of this are:

- Linear maps from $\mathbb{R}^{n}$ to $\mathbb{R}^{m}$ (or indeed, as we shall see later, linear maps from any finite dimensional space to any normed space $Y$ ) are always continuous, BUT
not all linear maps $L:\left(X,\|\cdot\|_{X}\right) \rightarrow\left(Y,\|\cdot\|_{Y}\right)$ from a Banach space $\left(X,\|\cdot\|_{X}\right)$ are continuous.
- Bounded, closed sets in $\mathbb{R}^{n}$ are compact (Heine-Borel-Theorem), BUT
while compact sets are always bounded and closed, the converse is WRONG for infinite dimensional spaces
- Every subspace of $\mathbb{R}^{n}$ is a closed set, BUT
not all subspaces of infinite dimensional spaces are closed.
Our intuition can further be wrong as we are used to thinking about Euclidean spaces $\mathbb{R}^{n}$ whose norm is introduced by an inner product via $\|x\|=(x, x)^{1 / 2}$.

We recall that an inner product $(\cdot, \cdot): X \times X \rightarrow \mathbb{R}$ is a map that is symmetric $(x, y)=$ $(y, x)$ if $\mathbb{F}=\mathbb{R}$, respectively hermitian $(x, y)=\overline{(y, x)}$ if $\mathbb{F}=\mathbb{C}$, that is linear in the first variable and positive definite and call a vector space $X$ together with an inner product $(\cdot, \cdot)$ an inner product space.

WARNING. There are several important properties that hold true in $\mathbb{R}^{n}$, and more generally in Hilbert spaces, but that do not hold for general Banach spaces. Examples of this include

- In $\mathbb{R}^{n}$ (and indeed any Hilbert space as we will see later on) minimal distances to closed subspaces are attained, i.e. given any closed subspace $S \subset \mathbb{R}^{n}$ and any $p \in \mathbb{R}^{n}$ there exists a unique element $s_{0} \in S$ so that

$$
\left\|p-s_{0}\right\|=\inf _{s \in S}\|p-s\| .
$$

In Banach spaces this does not hold true in general.

- If $\mathbb{R}^{n}=W \oplus V$ for two orthogonal subspaces $W$ and $V$ then the projection $P_{V}: v+w \mapsto$ $v$ is so that

$$
\left\|P_{V}(z)\right\| \leq\|z\| .
$$

This is not true for general direct sums $\mathbb{R}^{n}=W \oplus V$ of subspaces that are not orthogonal (a picture illustrates that nicely) and is in particular not true for general Banach spaces $X=W \oplus W$ where there is not even a notion of "orthogonal".

### 1.1.2 Examples

$\left(\mathbb{R}^{n},\|\cdot\|_{p}\right)$ and $\left(\mathbb{C}^{n},\|\cdot\|_{p}\right), 1 \leq p \leq \infty$
Consider $\mathbb{R}^{n}$, or $\mathbb{C}^{n}$, equipped with

$$
\|x\|_{p}:=\left(\sum_{i}\left|x_{i}\right|^{p}\right)^{1 / p} \text { for } 1 \leq p<\infty
$$

respectively

$$
\|x\|_{\infty}:=\sup _{i \in\{1, \ldots, n\}}\left|x_{i}\right|
$$

One can show that these are all norms, with the challenging bit being the proof of the $\Delta$-inequality

$$
\|x+y\|_{p}=\left(\sum_{i}\left(x_{i}+y_{i}\right)^{p}\right)^{1 / p} \leq\|x\|_{p}+\|y\|_{p}
$$

WARNING. This inequality does not hold if we were to extend the definition of $\|\cdot\|_{p}$ to $0<p<1$, and hence the above expression does not give a norm on $\mathbb{R}^{n}$ if $p<1$.

A useful property to deal with the $p$ norms $1 \leq p \leq \infty$ (and their generalisations to sequence and functions spaces) is Hölder's inequality.

Lemma 1.1.4 (Hölder's inequality in $\mathbb{R}^{n}$ ). For $1 \leq p, q \leq \infty$ with
(*) $\frac{1}{p}+\frac{1}{q}=1$
we have that for any $x, y \in \mathbb{C}^{n}$

$$
\left|\sum_{i=1}^{n} x_{i} y_{i}\right| \leq\|x\|_{p}\|y\|_{q}
$$

In $(\star)$ we use the convention that $\frac{1}{p}=0$ for $p=\infty$, and one often calls numbers $p, q \in$ $[1, \infty]$ satisfying $(\star)$ conjugate exponents.

Proof. The proof of this inequality (both for $\mathbb{C}^{n}$ as well as the analogues for the sequence and function spaces $\ell^{p}$ and $L^{p}$ ) can be found in most textbooks and is left as an exercise.

Remark 1.1.5. As you will show on Problem sheet 1, we have that for all $1 \leq p<\infty$

$$
\|x\|_{\infty} \leq\|x\|_{p} \leq n^{1 / p}\|x\|_{\infty} .
$$

Hence the $\infty$-norm is equivalent to every $p$-norm and thus, by transitivity, we have that $\|\cdot\|_{p}$ is equivalent to $\|\cdot\|_{q}$ for every $1 \leq p, q \leq \infty$.

## Sequence spaces $\left(\ell^{p},\|\cdot\|_{p}\right)$

An infinite dimensional analogue of $\left(\mathbb{R}^{n},\|\cdot\|_{p}\right)$, respectively $\left(\mathbb{C}^{n},\|\cdot\|_{p}\right)$ are the spaces of sequences $\left(\ell^{p},\|\cdot\|_{p}\right), 1 \leq p \leq \infty$, where for $1 \leq p<\infty$

$$
\ell^{p}:=\left\{\left(x_{j}\right)_{j \in \mathbb{N}}: \sum_{j=1}^{\infty}\left|x_{j}\right|^{p}<\infty\right\}
$$

while $\ell^{\infty}$ denotes the space of bounded sequences, equipped with $\|\cdot\|_{p}$ where for $1 \leq p<\infty$

$$
\|x\|_{\ell^{p}}=\left(\sum_{j=1}^{\infty}\left|x_{j}\right|^{p}\right)^{1 / p}
$$

while for $p=\infty$

$$
\left\|\left(x_{j}\right)\right\|_{\infty}:=\sup _{j}\left|x_{j}\right| .
$$

For any $1 \leq j \leq \infty$ we have that $\left(\ell^{p},\|\cdot\|_{p}\right)$ is a normed space (where we define addition and scalar-multiplication component-wise) and one can furthermore prove:

- the spaces $\left(\ell^{p},\|\cdot\|_{p}\right)$ are all complete and hence Banach spaces, we carry out the proof of this for $p=2$ in the next section.
- the Hölder inequality holds true, i.e. for every $1 \leq p, q \leq \infty$ with $\frac{1}{p}+\frac{1}{q}=1$ and any $\left(x_{j}\right) \in \ell^{p}$ and $\left(y_{j}\right) \in \ell^{q}$ we have that $\sum x_{j} y_{j}$ converges and

$$
\left|\sum_{j} x_{j} y_{j}\right| \leq\left\|\left(x_{j}\right)\right\|_{p}\left\|\left(y_{j}\right)\right\|_{q}
$$

We will sometimes also consider the subspace

$$
c_{0}:=\left\{\left(x_{n}\right) \in \ell^{\infty}: x_{n} \underset{n \rightarrow \infty}{\longrightarrow} 0\right\}
$$

of $\ell^{\infty}$, which is closed and hence, when equipped with the $\ell^{\infty}$ - norm a Banach space.

## Function spaces with supremum-norm

If we consider vector spaces of bounded functions $f: \Omega \rightarrow \mathbb{F}, \Omega$ some given subset of $\mathbb{R}$ or $\mathbb{R}^{n}$, such as

- $\mathcal{F}^{b}(\Omega):=\{f: \Omega \rightarrow \mathbb{F}$ bounded $\}$,
- $C_{b}(\Omega):=\{f: \Omega \rightarrow \mathbb{F}$ continuous and bounded $\}$,
or on compact sets simply $C(\Omega):=\{f: \Omega \rightarrow \mathbb{F}$ continuous $\}=C_{b}(\Omega)$, we can consider the supremum norm, denoted either by $\|\cdot\|_{\infty}$ or $\|\cdot\|_{\text {sup }}$ or (in case of $C_{b}$ ) often also by $\|\cdot\|_{C^{0}}$ that is simply defined by

$$
\|f\|_{\text {sup }}:=\sup \{|f(x)|: x \in \Omega\}
$$

Similarly, on spaces of differentiable functions (with bounded derivatives) such as $C^{1}([0,1])$ we will generally use norms that are built using the sup norm of both the function and its derivative such as $\|f\|_{C^{1}}:=\|f\|_{\text {sup }}+\left\|f^{\prime}\right\|_{\text {sup }}$.

It is important to note that convergence with respect to the supremum norm is the same as uniform convergence of functions, so as seen in Prelims and Part A analysis lectures, one often proves convergence of a given sequence $f_{n}$ in three steps: First we prove that the sequence converges pointwise to some function $f$ which is then the only candidate for the limit of $f_{n}$ as uniform convergence implies pointwise convergence. We then need to check that $f$ is in the corresponding space and finally to establish uniform convergence of $f_{n}$ to $f$.

Function spaces $\left(L^{p}(\Omega),\|\cdot\|_{L^{p}}\right), 1 \leq p \leq \infty$
Let $\Omega \subset \mathbb{R}$ be an interval, or more generally any measurable subset of $\mathbb{R}^{n}$. Consider for $1 \leq p<\infty$ the space of functions

$$
\mathcal{L}^{p}(\Omega):=\left\{f: \Omega \rightarrow \mathbb{R} \text { (or } \mathbb{C} \text { ) measurable so that } \int_{\Omega}|f|^{p} d x<\infty\right\}
$$

respectively

$$
\mathcal{L}^{\infty}:=\{f: \Omega \rightarrow \mathbb{R} \text { (or } \mathbb{C} \text { ) measurable so that } \exists M \text { with }|f| \leq M \text { a.e. }\} .
$$

Here and in the following all integrals are computed with respect to the Lebesgue measure and we shall only ever consider functions that are measurable so you may assume in any application that the functions you encounter are measurable without having to provide a proof for this. Conversely, we recall that not all measurable functions are integrable and that indeed for a general measurable function the integral might not even be defined, so justification is needed to consider integrals in general. However we also recall that the integral of a non-negative functions $f$ is always defined though might be infinite.

We equip these spaces with

$$
\|f\|_{L^{p}}:=\left(\int_{\Omega}|f|^{p} d x\right)^{1 / p} \text { for } 1 \leq p<\infty
$$

respectively

$$
\|f\|_{L^{\infty}}:=\operatorname{ess} \sup |f|:=\inf \{M:|f| \leq M \text { a.e. }\} .
$$

We note that $\|\cdot\|$ is only a seminorm on $\mathcal{L}^{p}$ with $\|f-g\|_{L^{p}}=0$ if and only if $f=g$ a.e. We can hence turn $\left(\mathcal{L}^{p},\|\cdot\|\right)$ into a normed space by taking the quotient with respect to the equivalence relation

$$
f \sim g \Leftrightarrow f=g \text { a.e.. }
$$

The resulting quotient space

$$
L^{p}(\Omega):=\mathcal{L}^{p} / \sim \text { equipped with }\|\cdot\|_{L^{p}}
$$

is one of the most important spaces of functions in the modern theory of PDE (as developed e.g. in the course C4.3 Functional analytic methods for PDEs) and has the following properties: For any (measurable) set $\Omega \subset \mathbb{R}^{n}$

- $L^{p}(\Omega), 1 \leq p \leq \infty$ is a Banach space (completeness of $L^{1}$ was proven in A. 4 Integration).
- The so called Minkowski-inequality (=triangle inequality for $\|\cdot\|_{L^{p}}$ ) holds true

$$
\|f+g\|_{L^{p}} \leq\|f\|_{L^{p}}+\|g\|_{L^{p}} .
$$

- Hölder's inequality holds: If $f \in L^{p}(\Omega)$ and $g \in L^{q}(\Omega)$ where $\frac{1}{p}+\frac{1}{q}=1$ then their product $f g$ is integrable with

$$
\left|\int_{\Omega} f g d x\right| \leq\|f\|_{L^{p}}\|g\|_{L^{q}} .
$$

None of the $L^{p}$ norms are equivalent, though when $\Omega$ has positive and finite measure, we can estimate the $L^{p}$ norm of functions by their $L^{q}$ norm if $p<q$ and we have

$$
\begin{equation*}
L^{\infty}(\Omega) \varsubsetneqq L^{q}(\Omega) \varsubsetneqq L^{p}(\Omega) \varsubsetneqq L^{1}(\Omega) \text { for any } 1<p<q<\infty \tag{1.1}
\end{equation*}
$$

As an example consider $\Omega=(0,2) \subset \mathbb{R}$ and $p=2, q=4$. Adding in a multiplication by the constant function $g=1$ we can estimate, using Hölder's inequality,

$$
\|f\|_{L^{2}}^{2}=\int|f|^{2} \cdot 1 d x \leq\left\||f|^{2}\right\|_{L^{2}}\|1\|_{L^{2}}=\left(\int_{0}^{2} f^{4} d x\right)^{1 / 2} \cdot\left(\int_{0}^{2} 1 d x\right)^{1 / 2}=\sqrt{2}\|f\|_{L^{4}}^{2}
$$

so we get $\|f\|_{L^{2}} \leq \sqrt{2}\|f\|_{L^{4}}$ and in particular that every $f \in L^{4}([0,2])$ is also an element of $L^{2}([0,2])$. The general case is discussed on the first problem sheet.

WARNING. The inclusion (1.1) is wrong for unbounded domains, e.g. the constant function $f=1$ is an element of $L^{\infty}(\mathbb{R})$ but isn't contained in any $L^{p}(\mathbb{R}), 1 \leq p<\infty$.

Remark 1.1.6. In practice it is can be useful to extend $\|\cdot\|_{L^{p}}$ to a function from the space of all (measurable) functions to $[0, \infty) \cup\{\infty\}$ by simply setting $\|f\|_{L^{p}}=\infty$ if $\int|f|^{p}=\infty$ (respectively for $p=\infty$ if $f \notin L^{\infty}$ ), and we note that also with this 'abuse of notation' the triangle and Hölder-inequality still hold (with the convention that $0 \cdot \infty=0$ for Hölder's inequality). Similarly we can extend $\|\cdot\|_{p}$ to a function that maps all sequences to $[0, \infty) \cup\{\infty\}$ but we stress that while this notation/convention can be useful and used in the literature, these functions into $[0, \infty) \cup\{\infty\}$ are not norms as a norm is by definition a function into $[0, \infty)$.

WARNING. Note that the inclusions of the function spaces $L^{p}(\Omega)$ for sets $\Omega$ with bounded measure are the "other way around" compared with the inclusions of the sequence spaces $\ell^{p}$.

## Product of normed spaces

Given two normed spaces $\left(X,\|\cdot\|_{X}\right)$ and $\left(Y,\|\cdot\|_{Y}\right)$ we can define a norm on $X \times Y$ e.g. by

$$
\begin{equation*}
\|(x, y)\|=\left(\|x\|^{2}+\|y\|^{2}\right)^{1 / 2} \tag{1.2}
\end{equation*}
$$

or more generally using any of the $p$-norms on $\mathbb{R}^{2}$ to define

$$
\|(x, y)\|:=\|(\|x\|,\|y\|)\|_{p}=\left(\|x\|^{p}+\|y\|^{p}\right)^{1 / p} \text { respectively }\|(x, y)\|:=\max (\|x\|,\|y\|)
$$

where here and in the following we simply write $\|\cdot\|$ instead of $\|\cdot\|_{X}$ and $\|\cdot\|_{Y}$ if it is clear from the context what norm we are using.

We note that for all of these norms on $X \times Y$ we obtain that $X \times Y$ is again a Banach space if both $X$ and $Y$ are Banach spaces. If $X$ and $Y$ are inner product spaces then one uses in general the norm (1.2) as for this choice of norm also the product $X \times Y$ will again be a inner product space with inner product $\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)=\left(x, x^{\prime}\right)_{X}+\left(y, y^{\prime}\right)_{Y}$, while none of the norms with $p \neq 2$ preserve the structure of an inner product space.

## Sums of subspaces

If $X_{1}, X_{2} \subset X$ are subspaces of a normed space $\left(X,\|\cdot\|_{X}\right)$ then also

$$
X_{1}+X_{2}:=\left\{x_{1}+x_{2}: x_{1} \in X_{1}, x_{2} \in X_{2}\right\}
$$

is again a subspace of $X$, but

## WARNING.

$$
X_{1}, X_{2} \subset X \text { closed } \nRightarrow X_{1}+X_{2} \text { closed. }
$$

## Quotient spaces

Given a vector space $X$ and a semi-norm $|\cdot|$ on $X$, i.e. a function $|\cdot|: X \rightarrow[0, \infty)$ satisfying (N2) and (N3), we can consider the quotient space $X / X_{0}$ where $X_{0}:=\{x \in X:|x|=0\}$. Then one can define a norm on $X / X_{0}$ by defining $\left\|x+X_{0}\right\|:=|x|$, see problem sheet 1 for details.

This is the process whereby $L^{p}$ spaces are obtained from the corresponding $\mathcal{L}^{p}$ spaces by identifying functions which are equal a.e.

### 1.1.3 Completeness

The spaces discussed above are all complete. The proof of completeness often follows the following rough pattern: Given a Cauchy sequence $\left(x_{n}\right)$ in a normed space $\left(X,\|\cdot\|_{X}\right)$

1. Identify a candidate $x$ for $\lim x_{n}$
2. Show that $x \in X$ and $\left\|x-x_{n}\right\|_{X} \rightarrow 0$ as $n \rightarrow \infty$.

We illustrate this by proving the completeness of some of the spaces introduced in the previous section:

## Completeness of $\left(C_{b}(\Omega, \mathbb{R}),\|\cdot\|_{s u p}\right), \quad \Omega \subset \mathbb{R}^{d}$

Given a Cauchy sequence $\left(f_{n}\right)$ in $\left(C_{b}(\Omega),\|\cdot\|_{\text {sup }}\right)$ we have that for every $x \in \Omega$

$$
\left|f_{n}(x)-f_{m}(x)\right| \rightarrow 0 \text { as } n, m \rightarrow \infty
$$

i.e. $\left(f_{n}(x)\right)$ is a Cauchy sequence in $\mathbb{R}$ so, as $\mathbb{R}$ is complete, converges to some limit. We define as candidate for the limit of the sequence of functions $f_{n}$ the function $f(x):=\lim _{n \rightarrow \infty} f_{n}(x)$ obtained by this pointwise convergence and now show that

Claim: $f \in C_{b}(\Omega)$ and $\left\|f_{n}-f\right\|_{\text {sup }} \rightarrow 0$ (i.e. $f_{n} \rightarrow f$ uniformly).

Proof. Let $\varepsilon>0$. As $\left(f_{n}\right)$ is a Cauchy sequence, there exists some $N$ so that for every $n, m \geq N$

$$
\left\|f_{n}-f_{m}\right\|_{s u p} \leq \varepsilon
$$

Thus for every $x \in \Omega, n \geq N$ we have

$$
\left|f_{n}(x)-f(x)\right|=\left|f_{n}(x)-\lim _{m \rightarrow \infty} f_{m}(x)\right| \leq \varepsilon
$$

This implies in particular that $f$ is bounded, namely that $\sup _{x \in \Omega}|f(x)| \leq\left\|f_{N}\right\|_{\text {sup }}+\varepsilon$, and that for every $n \geq N,\left\|f-f_{n}\right\|_{\text {sup }}<\varepsilon$. As $\varepsilon>0$ was arbitrary this proves that $f_{n}$ converges to $f$ with respect to the supremum norm. Finally we obtain that $f \in C_{b}(\Omega)$ as $f$ is uniform limit of a sequence of continuous functions and hence continuous (c.f. Analysis II and Part A Metric spaces, is proved using $\varepsilon / 3$ argument).

## Completeness of $\left(L^{\infty}(\Omega, \mathbb{R}),\|\cdot\|_{L^{\infty}}\right), \quad \Omega \subset \mathbb{R}^{d}$

The proof is more or less similar to the one we see above, except that we have to tend to the almost everywhere nature of things.

Proof. Let $\left(f_{n}\right)$ be a Cauchy sequence in $L^{\infty}(\Omega, \mathbb{R})$. Fix some $\varepsilon>0$ for the moment. Then there exists $N$ such that

$$
\left\|f_{n}-f_{m}\right\|_{L^{\infty}} \leq \varepsilon \text { for all } n, m \geq N
$$

This means that, for each $n, m \geq N$, there is a null subset $Z_{n, m}$ of $\Omega$ such that

$$
\left|f_{n}(x)-f_{m}(x)\right| \leq \varepsilon \text { for } x \in \Omega \backslash Z_{n, m}
$$

Let $Z=\cup_{n, m \geq N} Z_{n, m}$, which, as a countable union of null set, is null. Then,

$$
\begin{equation*}
\left|f_{n}(x)-f_{m}(x)\right| \leq \varepsilon \text { for all } n, m \geq N, x \in \Omega \backslash Z \tag{1.3}
\end{equation*}
$$

So for almost all $x \in \Omega,\left(f_{n}(x)\right)$ is Cauchy, and hence converges to some $f(x)$.
Being an almost everywhere limit of measurable functions, $f$ is measurable. Sending $m \rightarrow \infty$ while keeping $n$ fixed in (1.3) we get

$$
\left|f_{n}(x)-f(x)\right| \leq \varepsilon \text { for all } n \geq N, x \in \Omega \backslash Z
$$

This shows that $\left\|f_{n}-f\right\|_{L^{\infty}} \leq \varepsilon$ for all $n \geq N$. This implies on one hand that $f_{n}-f$ and hence $f$ belong to $L^{\infty}(\Omega)$ and on the other hand that $f_{n} \rightarrow f$ in $L^{\infty}(\Omega)$.

Completeness of $\left(L^{p}(\Omega, \mathbb{R}),\|\cdot\|_{L^{p}}\right), \quad 1 \leq p<\infty, \quad \Omega \subset \mathbb{R}^{d}$
This proof is slightly more involved with 2 twists: (1) the limit object arises now as a limit a long a subsequence, and (2) the norm is not preserved under taking limit.

Proof. Let $\left(f_{n}\right)$ be a Cauchy sequence in $L^{p}(\Omega, \mathbb{R})$.
Step 1: We show that $\left(f_{n}\right)$ is Cauchy in measure, i.e. for every $\delta>0$,

$$
\left|\left\{x \in \Omega:\left|f_{n}(x)-f_{m}(x)\right|>\delta\right\}\right| \rightarrow 0 \text { as } n, m \rightarrow \infty .
$$

Fix some $\varepsilon>0$ for the moment. Then there exists $N$ such that

$$
\left\|f_{n}-f_{m}\right\|_{L^{p}}^{p}=\int_{\Omega}\left|f_{n}-f_{m}\right|^{p} d x \leq \varepsilon^{p} \text { for all } n, m \geq N
$$

Shrinking the domain of integration to $\left\{x \in \Omega:\left|f_{n}(x)-f_{m}(x)\right|>\delta\right\}$, we obtain

$$
\delta^{p}\left|\left\{x \in \Omega:\left|f_{n}(x)-f_{m}(x)\right|>\delta\right\}\right| \leq \varepsilon^{p} \text { for all } n, m \geq N .
$$

Sending $\varepsilon \rightarrow 0$ (but keeping $\delta$ fixed), we obtain Step 1.
Step 2: Birth of the limit.
For this we use a general result from Integration, which asserts that every Cauchy-inmeasure sequence of measurable functions has a subsequence which converges a.e. So by Step 1, there exists a subsequence $\left(f_{n_{j}}\right)$ which converges a.e. to $f(x)$, which is measurable.

Step 3: Bounding $\left\|f_{n}-f\right\|_{L^{p}}$.
Fix $\varepsilon>0$ for the moment. We know that

$$
\left\|f_{n}-f_{n_{j}}\right\|_{L^{p}}^{p}=\int_{\Omega}\left|f_{n}-f_{n_{j}}\right|^{p} d x \leq \varepsilon^{p} \text { for all } n, n_{j} \geq N
$$

As $j \rightarrow \infty$, the a.e. limit of the integrand is $\left|f_{n}-f\right|^{p}$. Moreover, the integrand is nonnegative. By Fatou's lemma, we have

$$
\int_{\Omega}\left|f_{n}-f\right|^{p} d x \leq \liminf _{j \rightarrow \infty} \int_{\Omega}\left|f_{n}-f_{n_{j}}\right|^{p} d x \leq \varepsilon^{p} \text { for all } n \geq N
$$

In other words, $\left\|f_{n}-f\right\|_{L^{p}} \leq \varepsilon$ for all $n \geq N$. This implies on one hand that $f_{n}-f$ and hence $f$ belong to $L^{p}(\Omega)$ and on the other hand that $f_{n} \rightarrow f$ in $L^{p}(\Omega)$.

Completeness of $\left(\ell^{2}(\mathbb{R}),\|\cdot\|_{2}\right)$
Let $\left(x^{(n)}\right), x^{(n)}=\left(x_{j}^{(n)}\right)_{j \in \mathbb{N}}$, be a Cauchy-sequence in $\left(\ell^{2},\|\cdot\|_{2}\right)$. As for every $j \in \mathbb{N}$

$$
\left|x_{j}^{(n)}-x_{j}^{(m)}\right| \leq\left\|x^{(n)}-x^{(m)}\right\|_{2} \underset{n, m \rightarrow \infty}{\longrightarrow} 0
$$

the sequence $\left(x_{j}^{(n)}\right) \subset \mathbb{R}$ is Cauchy so converges, say $x_{j}^{(n)} \underset{n \rightarrow \infty}{\longrightarrow} x_{j}$.
Claim: $x=\left(x_{j}\right) \in \ell^{2}$ and $\left\|x-x^{(n)}\right\|_{2} \underset{n \rightarrow \infty}{\longrightarrow} 0$.
Proof: Let $\varepsilon>0$. Then as $\left(x^{(n)}\right)$ is Cauchy there exists $N$ so that for all $n, m \geq N$

$$
\left\|x^{(n)}-x^{(m)}\right\|_{2} \leq \varepsilon
$$

Thus for every $K \in \mathbb{N}$ and for all $n \geq N$ we have that

$$
\sum_{j=1}^{K}\left|x_{j}^{(n)}-x_{j}\right|^{2}=\lim _{m \rightarrow \infty} \sum_{j=1}^{K}\left|x_{j}^{(n)}-x_{j}^{(m)}\right|^{2} \leq \varepsilon^{2}
$$

As this holds for every $K$ we can take $K \rightarrow \infty$ to get that $\left\|x^{(n)}-x\right\|_{2}^{2} \leq \varepsilon^{2}$ for every $n \geq N$. As $\varepsilon>0$ was arbitrary, we thus obtain that $\left\|x^{(n)}-x\right\|_{2} \underset{n \rightarrow \infty}{\longrightarrow} 0$. As above we also get that $x \in \ell^{2}$ as

$$
\|x\|_{2} \stackrel{\Delta}{\leq}\left\|x^{(n)}-x\right\|_{2}+\left\|x^{(n)}\right\|_{2}<\infty .
$$

(Note that here we use the above mentioned "abuse of notation" of defining $\|\cdot\|_{2}$ for arbitrary sequence by setting $\|x\|_{2}=\infty$ if $x \notin \ell^{2}$ to be able to already talk of $\|x\|_{2}$ when we do not yet know that $x \in \ell^{2}$.)

## Useful results to prove completeness

For the proof of completeness it is often useful to note:
Lemma 1.1.7. Let $\left(x_{n}\right)$ be a Cauchy sequence in a normed space $(X,\|\cdot\|)$. Then the following are equivalent:
(i) $\left(x_{n}\right)$ converges,
(ii) $\left(x_{n}\right)$ has a convergent subsequence.

Proof. $(i) \Rightarrow(i i)$ is trivial.
(ii) $\Rightarrow(i)$

Suppose $x_{n_{k}} \rightarrow x$. Given any $\varepsilon>0$, we can choose $N$ so that for all $n, m \geq N$

$$
\left\|x_{n}-x_{m}\right\|<\varepsilon / 2
$$

and furthermore choose $K$ so that for $k \geq K$

$$
\left\|x_{n_{k}}-x\right\|<\varepsilon / 2 .
$$

Then for $n \geq N$ we have, choosing some $k \geq K$ so that $n_{k} \geq N$,

$$
\left\|x-x_{n}\right\| \stackrel{\Delta}{\leq}\left\|x-x_{n_{k}}\right\|+\left\|x_{n_{k}}-x_{n}\right\|<\varepsilon / 2+\varepsilon / 2=\varepsilon .
$$

As a consequence we obtain that a normed space is complete if and only if absolute convergence of series implies convergence of series:
Corollary 1.1.8. Let $(X,\|\cdot\|)$ be a normed space. Then the following are equivalent
(i) $(X,\|\cdot\|)$ is a Banach space,
(ii) Absolute convergence of series implies convergence, i.e. for sequences ( $x_{n}$ ) in $X$ and the corresponding partial sums $s_{n}:=\sum_{k=1}^{n} x_{k}$ we have

$$
\sum_{i=1}^{\infty}\left\|x_{n}\right\|<\infty \quad \Rightarrow \quad s_{n} \text { converges to some } s \in X
$$

Proof. (i) $\Rightarrow$ (ii)
If $\sum_{n=1}^{\infty} \overline{\left\|x_{n}\right\|<\infty}$ then $s_{n}$ is a Cauchy sequence in $(X,\|\cdot\|)$ since for $m>n \geq N$

$$
\left\|s_{n}-s_{m}\right\|=\left\|\sum_{k=n+1}^{m} x_{k}\right\| \stackrel{\Delta}{\leq} \sum_{k=n+1}^{m}\left\|x_{k}\right\| \leq \sum_{k=N+1}^{\infty}\left\|x_{k}\right\| \rightarrow 0 \text { as } N \rightarrow \infty
$$

As $(X,\|\cdot\|)$ is complete we thus obtain that $s_{n}$ converges to some element $s \in X$.
Let $\frac{(i i) \Rightarrow(i)}{\left(x_{n}\right) \text { be a Cauchy sequence. Select a subsequence } x_{n_{j}} \text { so that }}$

$$
\left\|x_{n_{j}}-x_{n_{j+1}}\right\| \leq 2^{-j}
$$

where the existence of such a subsequence is ensured by the fact that $x_{n}$ is Cauchy. Then $\sum_{j=1}^{\infty}\left\|x_{n_{j+1}}-x_{n_{j}}\right\| \leq 1<\infty$ so (ii) ensures that $\sum_{j=1}^{\infty}\left(x_{n_{j+1}}-x_{n_{j}}\right)$ converges. Hence $x_{n_{k}}=x_{n_{1}}+\sum_{j=1}^{k-1}\left(x_{n_{j+1}}-x_{n_{j}}\right)$ converges, so $\left(x_{n}\right)$ has a convergent subsequence and must thus, by Lemma 1.1.7, itself converge.

## Incomplete spaces

Example 1.1.9 (Examples of incomplete spaces). We can construct many examples of noncomplete spaces by equipping a well known space such as $C_{b}, C^{1}, \ell^{p}$, $L^{p}$ with the 'wrong' norm, or by choosing a subspace of a Banach space that is not closed. As an example we show that $C^{0}([0,1])$ equipped with $\|f\|_{L^{1}}=\int_{0}^{1}|f| d x$ is not complete.

Proof. We give two examples: one by direct argument and the other via Corollary 1.1.8.
Example 1: Let

$$
g_{n}(x)= \begin{cases}(2 x)^{n} & \text { for } x \in[0,1 / 2) \\ 1 & \text { for } x \in[1 / 2,1]\end{cases}
$$

For $n<m$, we have

$$
\left\|g_{n}-g_{m}\right\|_{L^{1}}=\int_{0}^{1 / 2}\left[(2 x)^{n}-(2 x)^{m}\right] d x=\frac{1}{2(n+1)}-\frac{1}{2(m+1)}
$$

so $\left(g_{n}\right)$ is Cauchy. On the other hand, $\left(g_{n}\right)$ is a decreasing sequence of non-negative functions which is bounded from above by 1. Its pointwise limit is the characteristic function of the interval $[1 / 2,1]$. By Lebesgue's dominated convergence theorem, $g_{n}$ converges to $\chi_{[1 / 2,1]}$ in $L^{1}$ and this limit is discontinuous, hence not in $C([0,1])$. In other words $\left(g_{n}\right)$ has no limit in $C([0,1])$.

Example 2: For

$$
f_{n}(x):= \begin{cases}1-n^{2} x & \text { for } x \in\left[0, \frac{1}{n^{2}}\right] \\ 0 & \text { else }\end{cases}
$$

we have that $\left\|f_{n}\right\|_{L^{1}}=\frac{1}{2 n^{2}}$ so $\sum\left\|f_{n}\right\|_{L^{1}}$ converges. However $\sum f_{n}$ cannot converge to an element of $C([0,1])$. Indeed suppose, seeking a contradiction, that $\sum f_{n} \rightarrow f$ converges in $L^{1}$ to a function $f \in C([0,1])$. Then, as continuous functions on compact sets are bounded, there exists some $M \in \mathbb{R}$ so that $f \leq M$ on $[0,1]$. Hence choosing $N \in \mathbb{N}$ so that $N \geq 2(M+1)$ we obtain that for any $n \geq N$ and any $x \in\left[0, \frac{1}{2 N^{2}}\right]$

$$
\sum_{j=1}^{n} f_{j}(x)-f(x) \geq \sum_{j=1}^{N} \frac{1}{2}-f(x) \geq N / 2-M \geq 1
$$

and thus in particular $\left\|\sum_{j=1}^{n} f_{j}-f\right\|_{L^{1}} \geq \frac{1}{2 N^{2}} \nrightarrow 0$.
Example 1.1.10 (Examples of incomplete spaces). The space of polynomials on $\mathbb{R}$ admits no complete norms.

This is a consequence of the Baire category theorem, which will be proved in B4.2 Functional Analysis 2: A complete metric space is never a countable union of nowhere dense
subsets. (A nowhere dense set is a set whose closure has empty interior.) Clearly the space of polynomials is a countable union of the spaces of polynomials of degree $\leq n$. It is easy to see that a proper subspace of a space is always nowhere dense. The incompleteness of the space of polynomials follows.

### 1.2 Inner product spaces and Hilbert spaces

### 1.2.1 Definitions and basic properties

An important special case of Banach spaces are spaces whose norm is induced by an inner product.

Definition 1.2.1. An inner (scalar) product in a linear vector space $X$ over $\mathbb{R}$ is a realvalued function on $X \times X$, denoted as $\langle x, y\rangle$, having the following properties:
(i) Bilinearity. For fixed $y,\langle x, y\rangle$ is a linear function of $x$, and for fixed $x,\langle x, y\rangle$ is a linear function of $y$.
(ii) Symmetry. $\langle x, y\rangle=\langle y, x\rangle$ for all $x, y \in X$.
(iii) Positivity. $\langle x, x\rangle>0$ for $x \neq 0$.

When $X$ is a vector space over $\mathbb{C},\langle x, y\rangle$ is complex-valued and properties (i) and (ii) are replaced by
( ${ }^{\prime}$ ) Sesquilinearity. For fixed $y,\langle x, y\rangle$ is a linear function of $x$, and for fixed $x,\langle x, y\rangle$ is a skewlinear function of $y$, i.e.

$$
\langle a x, y\rangle=a\langle x, y\rangle \text { and }\langle x, a y\rangle=\bar{a}\langle x, y\rangle \text { for all } a \in \mathbb{C}, x, y \in X .
$$

(ii') Skew symmetry. $\langle x, y\rangle=\overline{\langle y, x\rangle}$ for all $x, y \in X$.
WARNING. In some textbooks, the sesquilinearity property is reversed: $\langle x, y\rangle$ is required instead to be skewlinear in $x$ and linear in $y$.

The inner product $\langle\cdot, \cdot\rangle$ generates a norm, denoted by $\|\cdot\|$, as follows:

$$
\|x\|=\langle x, x\rangle^{1 / 2}
$$

It should be clear that the positivity of the norm $\|\cdot\|$ follows from the positivity property (iii), and the homogeneity of $\|\cdot\|$ follows from the bi/sequi-linearity property (i)/(i'). To prove the triangle inequality, we use:

Theorem 1.2.2 (Cauchy-Schwarz inequality). For $x, y \in X$,

$$
|\langle x, y\rangle| \leq\|x\|\|y\| .
$$

Equality holds if and only if $x$ and $y$ are linearly dependent.
Proof. If $y=0$, the conclusion is clear. Assume henceforth that $y \neq 0$. Replacing $x$ by $a x$ with $|a|=1$ so that $a\langle x, y\rangle$ is real, we may assume without loss of generality that $\langle x, y\rangle$ is real.

For $t \in \mathbb{R}$, we compute using sesquilinearity and skew symmetry:

$$
\begin{equation*}
\|x+t y\|^{2}=\langle x+t y, x+t y\rangle=\|x\|^{2}+2 t \operatorname{Re}\langle x, y\rangle+t^{2}\|y\|^{2} . \tag{1.4}
\end{equation*}
$$

By positivity, this quadratic polynomial in $t$ is non-negative for all $t$. This implies that

$$
(\operatorname{Re}\langle x, y\rangle)^{2}-\|x\|^{2}\|y\|^{2} \leq 0
$$

which gives the desired inequality. If equality holds, then there is some $t_{0}$ such that $x+t_{0} y=$ 0 . The conclusion follows.

If we set $t= \pm 1$ in (1.4) and add the resulting identities, we obtain the so-called parallelogram law:

$$
\begin{equation*}
\|x+y\|^{2}+\|x-y\|^{2}=2\|x\|^{2}+2\|y\|^{2} \text { for all } x, y \in X \tag{1.5}
\end{equation*}
$$

It is a fact that if a norm satisfies the parallelogram law (1.5), then it comes from an inner product, which can be retrieved from the norm using polarisation:

$$
\langle x, y\rangle=\frac{1}{4}\left(\|x+y\|^{2}-\|x-y\|^{2}\right)
$$

for real scalar field and

$$
\langle x, y\rangle=\frac{1}{4}\left(\|x+y\|^{2}-\|x-y\|^{2}\right)+\frac{1}{4} i\left(\|x+i y\|^{2}-\|x-i y\|^{2}\right)
$$

for complex scalar field.
Definition 1.2.3. A linear vector space with an inner product is called an inner product space. If it is complete with the induced norm, it is called a Hilbert space.

Given an inner product space, one can complete it with respect to the induced norm. Since the inner product is a continuous function on its factors, it can be extended to the completed space. The completed space is therefore a Hilbert space.

### 1.2.2 Examples

Example 1.2.4. The space $\mathbb{C}^{n}$ or $\mathbb{R}^{n}$ is a Hilbert space with the standard inner product

$$
\langle x, y\rangle=\sum_{k=1}^{n} x_{k} \bar{y}_{k} .
$$

Example 1.2.5. The space $\ell^{2}=\left\{\left(x_{1}, x_{2}, \ldots\right)=\left(x_{n}\right): \sum_{n=1}^{\infty}\left|x_{n}\right|^{2}<\infty\right\}$ is a Hilbert space with the inner product

$$
\langle x, y\rangle=\sum_{n=1}^{\infty} x_{k} \bar{y}_{k} .
$$

Example 1.2.6. The space $C[0,1]$ of continuous functions on the interval $[0,1]$ is an incomplete inner product space with the inner product

$$
\langle f, g\rangle=\int_{0}^{1} f \bar{g} d x
$$

Example 1.2.7. Let $(E, \mu)$ be a measure space, e.g. $E$ is a subset of $\mathbb{R}^{n}$ and $\mu$ is the Lebesgue measure. The space $L^{2}(E, \mu)$ of all complex-valued square integrable functions is a Hilbert space with the inner product

$$
\langle f, g\rangle=\int_{E} f \bar{g} d \mu
$$

The completeness of $L^{2}(E, \mu)$ is a special case of the Riesz-Fischer theorem on the completeness of the Lebesgues space $L^{p}(E, \mu)$.

Example 1.2.8. A closed subspace of a Hilbert space is a Hilbert space.
Example 1.2.9 (Bergman space). Let $\mathbb{D}$ be the open unit disk in $\mathbb{C}$. The space $A^{2}(\mathbb{D})$ consists of all functions which are square integrable and holomorphic in $\mathbb{D}$ is a closed subspace of $L^{2}(\mathbb{D})$ and is thus a Hilbert space.

Example 1.2.10 (Hardy space). The space $H^{2}(\mathbb{T})$ of all functions $f \in L^{2}(-\pi, \pi)$ whose Fourier series are of the form $\sum_{n \geq 0} a_{n} e^{i n x}$ is a closed subspace of $L^{2}(-\pi, \pi)$ and is thus a Hilbert space.

### 1.2.3 Orthogonality

Definition 1.2.11. Two vectors $x$ and $y$ in an inner product space $X$ are said to be orthogonal if $\langle x, y\rangle=0$.

Definition 1.2.12. Let $Y$ be a subset of an inner product space $X$. We define $Y^{\perp}$ as the space of all vectors $v \in X$ which are orthogonal to $Y$, i.e. $\langle v, y\rangle=0$ for all $y \in Y$.

When $Y$ is a subspace of $X, Y^{\perp}$ is called the orthogonal complement of $Y$ in $X$.
Proposition 1.2.13. Let $Y$ be a subset of an inner product space $X$. Then
(i) $Y^{\perp}$ is a closed subspace of $X$.
(ii) $Y \subset Y^{\perp \perp}$.
(iii) If $Y \subset Z \subset X$, then $Z^{\perp} \subset Y^{\perp}$.
(iv) $(\overline{\operatorname{span} Y})^{\perp}=Y^{\perp}$.
(v) If $Y$ and $Z$ are subspaces of $X$ such that $X=Y+Z$ and $Z \subset Y^{\perp}$, then $Y^{\perp}=Z$.

Proof. Exercise.
Theorem 1.2.14 (Closest point in a closed convex subset). Let $K$ be a non-empty closed convex subset of a Hilbert space $X$. Then, for every $x \in X$, there is a unique point $y \in K$ which is closer to $x$ than any other points of $K$.

Proof. Let

$$
d=\inf _{z \in K}\|x-z\| \geq 0
$$

and $y_{n} \in K$ be a minimizing sequence, i.e.

$$
\lim _{n \rightarrow \infty} d_{n}=d, \quad d_{n}=\left\|x-y_{n}\right\| .
$$

Applying the parallelogram law (1.5) to $\frac{1}{2}\left(x-y_{n}\right)$ and $\frac{1}{2}\left(x-y_{m}\right)$ yields

$$
\left\|x-\frac{1}{2}\left(y_{n}+y_{m}\right)\right\|^{2}+\frac{1}{4}\left\|y_{n}-y_{m}\right\|^{2}=\frac{1}{2}\left(d_{n}^{2}+d_{m}^{2}\right) .
$$

Since $K$ is convex, $\frac{1}{2}\left(y_{n}+y_{m}\right) \in K$ and so $\left\|x-\frac{1}{2}\left(y_{n}+y_{m}\right)\right\| \geq d$. This and the above implies that $\left(y_{n}\right)$ is a Cauchy sequence. Let $y$ be the limit of this sequence, which belongs to $K$ as $K$ is closed. We then have by the continuity of the norm that $\|x-y\|=\lim \left\|x-y_{n}\right\|=d$, i.e. $y$ minimizes the distance from $x$.

That $y$ is the unique minimizer follows from the same reasoning above. If $y^{\prime}$ is also a minimizer, we apply the parallelogram law to $\frac{1}{2}(x-y)$ and $\frac{1}{2}\left(x-y^{\prime}\right)$ to obtain

$$
d^{2}+\frac{1}{4}\left\|y-y^{\prime}\right\|^{2} \leq\left\|x-\frac{1}{2}\left(y+y^{\prime}\right)\right\|^{2}+\frac{1}{4}\left\|y-y^{\prime}\right\|^{2}=\frac{1}{2}\left(\|x-y\|^{2}+\left\|x-y^{\prime}\right\|^{2}\right)=d^{2} .
$$

This implies that $y=y^{\prime}$.

Theorem 1.2.15 (Projection theorem). If $Y$ is a closed subspace of a Hilbert space $X$, then $Y$ and $Y^{\perp}$ are complementary subspaces: $X=Y \oplus Y^{\perp}$, i.e. every $x \in X$ can be decomposed uniquely as a sum of a vector in $Y$ and in $Y^{\perp}$.

Proof. Certainly $Y \cap Y^{\perp}=\{0\}$. It remains to show that $X=Y+Y^{\perp}$.
Take any $x \in X$ and, since $Y$ is a non-empty closed convex subset of $X$, there is a point $y_{0} \in Y$ which is closer to $x$ than any other points of $Y$ by Theorem 1.2.14. To conclude, we show that $x-y_{0} \in Y^{\perp}$. Indeed, for all $y \in Y$ and $t \in \mathbb{R}$, we have

$$
\left\|x-y_{0}\right\|^{2} \leq\|x-\underbrace{\left(y_{0}-t y\right)}_{\in Y}\|^{2}=\left\|x-y_{0}\right\|^{2}+2 t \operatorname{Re}\left\langle x-y_{0}, y\right\rangle+t^{2}\|y\|^{2}
$$

It follows that $2 t \operatorname{Re}\left\langle x-y_{0}, y\right\rangle+t^{2}\|y\|^{2} \geq 0$ for all $t \in \mathbb{R}$. This implies $\operatorname{Re}\left\langle x-y_{0}, y\right\rangle=0$. This concludes the proof if the scalar field is real.

If the scalar field is complex, we proceed as before with $t$ replaced by it to show that $\operatorname{Im}\left\langle x-y_{0}, y\right\rangle=0$.

WARNING. It follows from Theorem 1.2.15 that every closed subspace of a Hilbert space has a closed complement. This is not true for all Banach spaces.

Corollary 1.2.16. If $Y$ is a closed subspace of a Hilbert space $X$, then $Y=Y^{\perp \perp}$.
Definition 1.2.17. The closed linear span of a set $S$ in a Hilbert space $X$ is the smallest closed linear subspace of $X$ containing $S$, i.e. the intersection of all such subspaces.

It is easy to see that the closed linear span of a set $S$ is the closure of the linear span Span $S$.

Proposition 1.2.18. Let $S$ be a set in a Hilbert space $X$. Then the closed linear span $Y$ of $S$ is $S^{\perp \perp}$.

Proof. Exercise.
Definition 1.2.19. A subset $S$ of a Hilbert space $X$ is called an orthonormal set if $\|x\|=1$ for all $x \in S$ and $\langle x, y\rangle=0$ for all $x \neq y \in S$.
$S$ is called an orthonormal basis (or a complete orthonormal set) for $X$ if $S$ is an orthonormal set and its closed linear span is $X$.

Theorem 1.2.20. Every Hilbert space contains an orthonormal basis.
Proof. We will only give a proof in the case when the Hilbert space $X$ under consideration is separable, i.e. it contains a countable dense subset $S$. The proof in the more general case draws on more sophisticated arguments such as Zorn's lemma.

Label the elements of $S$ as $y_{1}, y_{2}, \ldots$ Applying the Gram-Schmidt process ${ }^{1}$ we obtain an orthonormal set $B=\left\{x_{1}, x_{2}, \ldots\right\}$ such that, for every $n$, the span of $\left\{x_{1}, \ldots, x_{n}\right\}$ contains $y_{1}, \ldots, y_{n}$. As $\bar{S}=X$, this implies that $X=\overline{\operatorname{span} B}$, and so $X$ is the closed linear span of $B$.

Theorem 1.2.21 (Pythagorean theorem). Let $X$ be a Hilbert space and $S=\left\{x_{1}, x_{2}, \ldots, x_{m}\right\}$ be a finite orthonormal set in $X$. For every $x \in X$, there holds

$$
\|x\|^{2}=\sum_{n=1}^{m}\left|\left\langle x, x_{n}\right\rangle\right|^{2}+\left\|x-\sum_{n=1}^{m}\left\langle x, x_{n}\right\rangle x_{n}\right\|^{2} .
$$

The proof of this is a direct computation and is omitted. An immediate consequence is:
Lemma 1.2.22 (Bessel's inequality). Let $X$ be a Hilbert space and $S=\left\{x_{1}, x_{2}, \ldots\right\}$ be an orthonormal sequence in $X$. Then, for every $x \in X$, there holds

$$
\sum_{n=1}^{\infty}\left|\left\langle x, x_{n}\right\rangle\right|^{2} \leq\|x\|^{2}
$$

We have the following characterisation of the closed linear span of an orthonormal sequence, whose proof will be done in B4.2 Functional Analysis II.

Theorem 1.2.23. Let $X$ be a Hilbert space and $S=\left\{x_{1}, x_{2}, \ldots\right\}$ be an orthonormal sequence in $X$. Then the closed linear span of $S$ consists of vectors of the form

$$
\begin{equation*}
x=\sum_{n=1}^{\infty} a_{n} x_{n} \tag{1.6}
\end{equation*}
$$

where the sequence of scalar $\left(a_{1}, a_{2}, \ldots\right)$ belongs to $\ell^{2}$. The sum in (1.6) converges in the sense of the Hilbert space norm. Furthermore

$$
\left.\|x\|^{2}=\sum_{n=1}^{\infty}\left|a_{n}\right|^{2} \quad \text { (Parserval's identity }\right)
$$

and

$$
a_{n}=\left\langle x, x_{n}\right\rangle .
$$

[^0]
## Chapter 2

## Bounded linear operators between normed vector spaces

The most important class of maps between normed spaces are:
Definition 2.0.1. Let $\left(X,\|\cdot\|_{X}\right)$ and $\left(Y,\|\cdot\|_{Y}\right)$ be normed spaces (aways assumed to be over the same field $\mathbb{F})$. Then we say that $T: X \rightarrow Y$ is a bounded linear operator if $T$ is linear, i.e. $T(x+\alpha \tilde{x})=T x+\alpha T \tilde{x}$ for all $x, \tilde{x} \in X$ and $\alpha \in \mathbb{F}$, and $T$ has the property that there exists some number $M \in \mathbb{R}$ so that

$$
\begin{equation*}
\|T x\|_{Y} \leq M\|x\|_{X} \text { for all } x \in X \tag{2.1}
\end{equation*}
$$

We let

$$
\mathscr{B}(X, Y):=\{T: X \rightarrow Y \text { bounded linear operator }\}
$$

which we always equip with the so called operator norm, which is defined by

$$
\|T\|_{\mathscr{B}(X, Y)}:=\inf \{M:(2.1) \text { holds true }\}, \quad T \in \mathscr{B}(X, Y) .
$$

We will often abbreviate the space $\mathscr{B}(X, X)$ of bounded linear operators from a normed space $(X,\|\cdot\|)$ to itself by $\mathscr{B}(X)$. In some texts, $\mathscr{B}(X, Y)$ is also denoted as $\mathscr{L}(X, Y)$.

We will later see that an important special case is the space of 'bounded linear functionals', i.e. bounded linear functions from a normed vector space to the corresponding field $\mathbb{F}=\mathbb{R}$ (respectively $\mathbb{F}=\mathbb{C}$ for complex vector spaces) and this so called dual space $X^{*}:=\mathscr{B}(X, \mathbb{F})$ will be discussed in far more detail in chapters 6 and 7 .

One can easily check that $\|\cdot\|_{\mathscr{B}(X, Y)}$ is a norm on $\mathscr{B}(X, Y)$ and as this is the only norm on $\mathscr{B}(X, Y)$ that we shall use, we will often write for short $\|T\|$ for the norm of an operator $T \in \mathscr{B}(X, Y)$ (provided it is clear from the context what $X$ and $Y$ are and with respect to which norms on $X$ and $Y$ the operator norm has to be computed). In applications the following equivalent expressions for the norm of an operator are often more useful than the above definition

Remark 2.0.2. (i) For $T \in \mathscr{B}(X, Y), X \neq\{0\}$, we have

$$
\|T\|_{\mathscr{B}(X, Y)}=\sup _{x \in X, x \neq 0} \frac{\|T x\|}{\|x\|}=\sup _{x \in X,\|x\|=1}\|T x\|=\sup _{x \in X,\|x\| \leq 1}\|T x\|
$$

and we have in particular that for any $x \in X$

$$
\|T x\| \leq\|T\|\|x\|
$$

i.e. the infimum in the definition of the norm of a bounded linear operator is actually a minimum. Conversely, the supremum in the above expressions for the norm of an operator is in general not achieved, and we shall see examples of this later.
(ii) Moreover, if $X$ and $Y$ are Hilbert spaces, then

$$
\|T\|_{\mathscr{B}(X, Y)}=\sup \left\{|\langle T x, y\rangle|: x \in X, y \in Y,\|x\|_{X}=\|y\|_{Y}=1\right\}
$$

This is a consequence of (i) and the fact that $\|T x\|_{Y}=\sup _{y \in Y,\|y\|_{Y}=1}|\langle T x, y\rangle|$.
WARNING. $T$ being a bounded linear operator does not mean that $T(X) \subset Y$ is bounded. Indeed, the only linear operator with a bounded image is the trivial operator that maps each $x \in X$ to $T(x)=0$.

One of the main reasons why $\mathscr{B}(X, Y)$ gives a very natural class of operators between normed spaces is that it can be equivalently characterised as the space of continuous linear maps:

Proposition 2.0.3. Let $(X,\|\cdot\|)$ and $(Y,\|\cdot\|)$ be normed spaces and let $T: X \rightarrow Y$ be linear. Then the following are equivalent:
(i) $T$ is Lipschitz continuous,
(ii) $T$ is continuous,
(iii) $T$ is continuous at $x_{0}=0$,
(iv) $T \in \mathscr{B}(X, Y)$.

Proof. $(i) \Rightarrow(i i) \Rightarrow(i i i)$ are trivial.

$$
(i i i) \Rightarrow(i v)
$$

Suppose that $T$ is continuous at $x_{0}=0$. Then there is some $\delta>0$ such that

$$
\|T x\|=\|T x-T 0\| \leq 1 \text { for }\|x\|=\delta
$$

It follows that, for any $x \neq 0$,

$$
\|T x\|=\frac{\|x\|}{\delta} T\left(\frac{\delta x}{\|x\|}\right) \leq \frac{\|x\|}{\delta}
$$

Clearly, this continues to holds for $x=0$. Hence $T$ is bounded with $\|T\| \leq \frac{1}{\delta}$.
$(i v) \Rightarrow(i)$
Let $M \in \mathbb{R}$ be so that (2.1) holds. Then as $T$ is linear we obtain that for any $x, \tilde{x} \in X$

$$
\|T x-T \tilde{x}\|=\|T(x-\tilde{x})\| \leq M\|x-\tilde{x}\|,
$$

i.e. $T$ is Lipschitz continuous.

In order to prove that a map $T:(X,\|\cdot\|) \rightarrow(Y,\|\cdot\|)$ is a bounded linear operator we need to
(1) Check that $T$ is well defined, in particular that $T x \in Y$ for all $x \in X$,
(2) Check that $T$ is linear (which is usually routine and in such situations does not need a long explanation or proof),
(3) Find some $M$ so that for all $x \in X$

$$
\|T x\|_{Y} \leq M\|x\|_{X}
$$

As (1) and (3) often require similar arguments, in particular when working with spaces like $\ell^{p}$ or $L^{p}$ where the key step is to be able to bound a sum/integral respectively to prove that it is finite, one often discusses these two steps at the same time.

We remark that to show that a linear map $T: X \rightarrow Y$ is an element of $\mathscr{B}(X, Y)$ we just require some (possibly far from optimal) number $M$ for which (3) holds and that any such $M$ will be an upper bound on the operator norm. If we need to additionally determine the norm of $T$ then we usually proceed as follows:
(i) Determine a candidate $M$ for $\|T\|$ and show that

$$
\|T x\| \leq M\|x\| \text { for every } x \in X
$$

This proves that $\|T\| \leq M$.
(ii) Prove that there exists a sequence $\left(x_{n}\right)$ in $X$ so that

$$
\frac{\left\|T x_{n}\right\|}{\left\|x_{n}\right\|} \rightarrow M
$$

This establishes that $\|T\| \geq M$.

Instead of (ii) one might be tempted to try to find some element $x \in X$ so that $\|T x\|=M\|x\|$, but

WARNING. For general bounded linear operators, one cannot expect that there exists $x \in$ $X$ so that $\|T x\|=M\|x\|$, i.e. the supremum $\sup _{x \neq 0} \frac{\|T x\|}{\|x\|}$ is in general not achieved.

We note that for any $T \in \mathscr{B}(X, Y)$ both the kernel $\operatorname{ker}(T):=\{x \in X: T(x)=0\}$ of $T$ and its image $T X=:\{T x: x \in X\}$ are subspaces (of $X$ respectively $Y$ ), but that while $\operatorname{ker}(T)$ is always closed, as it can be viewed as the preimage of the closed set $\{0\}$ under a continuous operator, the image $T X$ is in general not closed.

### 2.1 Examples

## Shift operators and projections on $\ell^{p}, 1 \leq p \leq \infty$

Define the shift operators $L, R: \ell^{p} \rightarrow \ell^{p}$ by

$$
R\left(\left(x_{1}, x_{2}, x_{3}, \ldots\right)\right):=\left(0, x_{1}, x_{2}, x_{3}, \ldots\right) \text { and } L\left(\left(x_{1}, x_{2}, x_{3}, \ldots\right)\right):=\left(x_{2}, x_{3}, x_{4}, \ldots\right)
$$

and for $k \in \mathbb{N}$ the projections $\pi_{k}: \ell^{p} \rightarrow \mathbb{F}$ by $\pi_{k}\left(\left(x_{1}, x_{2}, x_{3}, \ldots\right)\right)=x_{k}$.
Claim: $L, R \in \mathscr{B}\left(\ell^{p}\right)=\mathscr{B}\left(\ell^{p}, \ell^{p}\right)$ with $\|L\|=\|R\|=1$ while $\pi \in \mathscr{B}\left(\ell^{p}, \mathbb{F}\right)=\left(\ell^{p}\right)^{*}$ also with $\left\|\pi_{k}\right\|=1$.

Proof: Clearly all three operators are linear and well defined and for every $x \in \ell^{p}$ we have $\|R x\|_{p}=\|x\|_{p}$ and hence of course $R \in \mathscr{B}\left(\ell^{p}, \ell^{p}\right)$ with $\|R\|=1$ (indeed $R$ preserves norms, i.e. is so called isometric which is a much stronger property than merely having $\|R\|=1$ ). For $L$ and $\pi_{k}$ we immediately see from the definition of the $\ell^{p}$ norm that

$$
\|L x\|_{p} \leq\|x\|_{p} \text { as well as }\left|\pi_{k}(x)\right| \leq\|x\|_{p}
$$

so that both are bounded linear operators (namely $L \in \mathscr{B}\left(\ell^{p}, \ell^{p}\right)$ and $\left.\pi_{k} \in\left(\ell^{p}\right)^{*}\right)$ and the corresponding operator norms are bounded from above by $\|L\| \leq 1$ and $\left\|\pi_{k}\right\| \leq 1$. To see that also $\|L\| \geq 1$ we may use that $\|L(0,1,0, \ldots)\|_{p}=\|(1,0, \ldots)\|_{p}=1=\|(0,1,0, \ldots)\|_{p}$, while choosing $x=e^{(k)}$, the sequence that is defined by $e^{(k)}=\left(\delta_{k j}\right)_{j \in \mathbb{N}}$, we also get that $1=\left|\pi_{k}(x)\right|=\|x\|_{p}$ and hence that $\left\|\pi_{k}\right\| \geq 1$.
Definition 2.1.1. We call a linear function $T: X \rightarrow Y$ isometric if for every $x \in X$ we have $\|T x\|=\|x\|$.

We note that if $T \in \mathscr{B}(X, Y)$ is both isometric and bijective, then we have that also $T^{-1}$ is linear and isometric (so in particular a bounded linear operator) as for every $x \in X$

$$
\left\|T^{-1} x\right\|=\left\|T\left(T^{-1} x\right)\right\|=\|x\|
$$

Such a map is called an isometric isomorphism and the spaces $X$ and $Y$ are called isometrically isomorphic, written for short as $X \cong Y$.

## Multiplication by functions (i)

Let $X=C^{0}([0,1])$, as always equipped with the supremum norm and let $g \in C^{0}([0,1])$. Then

$$
T: X \rightarrow X \text { defined by }(T f)(x):=f(x) g(x)
$$

is linear, well defined (as the product of continuous functions is continuous) and bounded as

$$
\|T f\|_{\text {sup }} \leq\|g\|_{\text {sup }}\|f\|_{\text {sup }}
$$

In particular $\|T\| \leq\|g\|_{\text {sup }}$ and choosing $f \equiv 1$ we get $T f=g$ so as $\|f\|_{\text {sup }}=1$ also

$$
\|T\|=\sup _{h \in X,\|h\|_{\text {sup }}=1}\|T h\|_{\text {sup }} \geq\|T f\|=\|g\|_{\text {sup }}
$$

so indeed $\|T\|=\|g\|_{\text {sup }}$.

## Multiplication by functions (ii)

Consider instead $g \in L^{\infty}([0,1])$ and let $X=L^{2}([0,1])$ (equipped of course with the $L^{2}$ norm). Then the map $T: X \rightarrow X$ defined as above is well defined as

$$
\int_{0}^{1}|(T f)(t)|^{2} d t=\int_{0}^{1} f^{2}(t) g^{2}(t) d t \leq\|g\|_{L^{\infty}}^{2} \int|f(t)|^{2} d t
$$

so

$$
\|T f\|_{L^{2}} \leq\|g\|_{L^{\infty}}\|f\|_{L^{2}} \text { for all } f \in X
$$

and thus $\|T\| \leq\|g\|_{L^{\infty}}$. Indeed one can show that $\|T\|=\|g\|_{L^{\infty}}$, though to prove this for general functions requires a careful argument using some techniques from Part A integration. To illustrate some idea, we only consider as an example $g(t)=t$. Then $\|g\|_{L^{\infty}}=1$, so the above calculation implies that $\|T\| \leq 1$ while choosing $f_{n}:=\chi_{\left[1-\frac{1}{n}, 1\right]}$ gives

$$
\left\|T f_{n}\right\|_{L^{2}}^{2}=\int_{1-\frac{1}{n}}^{1} t^{2} d t \geq \frac{1}{n}\left(1-\frac{1}{n}\right)^{2}
$$

so as $\left\|f_{n}\right\|_{L^{2}}^{2}=\frac{1}{n}$ we have $\frac{\left\|T f_{n}\right\|_{L^{2}}}{\left\|f_{n}\right\|_{L^{2}}} \geq 1-\frac{1}{n} \rightarrow 1$ so also $\|T\| \geq 1$ and hence $\|T\|=1=\|g\|_{L^{\infty}}$.
At the same time one can show that for any $f \in L^{2}([0,1])$

$$
\|T f\|_{L^{2}}<\|f\|_{L^{2}}
$$

(this proof is a nice exercise related to the part A course in integration) so this gives an example of an operator for which the supremum $\sup _{f \neq 0} \frac{\|T f\|}{\|f\|}$ is not attained for any element of the Banach space $X=L^{2}([0,1])$.
(A kind of converse to the above is true: If a measurable $g$ is such that $T f=f g \in X$ for all $f \in X$, then $T \in \mathscr{B}(X)$ and $g$ is an element of $L^{\infty}([0,1])$. This is a consequence of the Closed graph theorem, which will be treated in B4.2 Functional Analysis 2.)

## Linear maps between Euclidean Spaces

We know that any linear map $T: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$ can be written as

$$
T x=A x \text { for some } A \in M_{m \times n}(\mathbb{R}) .
$$

There are several different norms on the space of matrices, including the analogues of the $p$-norms on $\mathbb{R}^{n}$. Particularly useful is the analogue of the Euclidean norm (i.e. of the case $p=2$ ) given by

$$
\|A\|:=\left(\sum_{i, j}\left|a_{i j}\right|^{2}\right)^{\frac{1}{2}}
$$

which is also called the Hilbert-Schmidt norm and is widely used in Numerical Analysis. A useful property of this norm is that it gives a simple way of obtaining an upper bound on the operator norm of the corresponding map $T: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$

Lemma 2.1.2. Let $T: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$ be defined by $T x=A x$ for some $A \in M_{m \times n}(\mathbb{R})$ where we equip $\mathbb{R}^{n}$ and $\mathbb{R}^{m}$ with the Euclidean norm. Then $T \in \mathscr{B}\left(\mathbb{R}^{n}, \mathbb{R}^{m}\right)$ and its operator norm is bounded by the Hilbert-Schmidt norm of $A$ :

$$
\|T\| \leq\|A\|
$$

Remark 2.1.3. For most matrices we have

$$
\|T\|<\|A\|
$$

and computing $\|T\|$ can be difficult. For symmetric $n \times n$ matrices however we can easily show (using material from Prelims Linear Algebra) that

$$
\|T\|=\max \left\{\left|\lambda_{1}\right|, \ldots .\left|\lambda_{n}\right|\right\}, \quad \lambda_{i} \text { the eigenvalues of } A
$$

Proof of Lemma 2.1.2.

$$
\|T x\|^{2}=\sum_{i=1}^{m}(A x)_{i}^{2}=\sum_{i=1}^{m}\left(\sum_{j=1}^{n} a_{i j} x_{j}\right)^{2} \stackrel{\text { C.S. }}{\leq} \sum_{i=1}^{m}\left(\sum_{j=1}^{n} a_{i j}^{2}\right) \cdot\left(\sum_{j=1}^{n} x_{j}^{2}\right)=\|A\|^{2}\|x\|^{2}
$$

## Integral operator on $C([0,3], \mathbb{R})$ :

Let $X=C([0,3])$ as always be equipped with the sup-norm. Given any $k \in C([0,3] \times[0,3])$ we map each $x \in X$ to the function $T x:[0,3] \rightarrow \mathbb{R}$ that is given by

$$
T x(t):=\int_{0}^{3} k(s, t) x(s) d s
$$

where the integral is well defined as the integrand is bounded,

$$
|k(s, t) x(s)| \leq\|k\|_{s u p} \cdot\|x\|_{s u p},
$$

and thus (Lebesgue) integrable over the bounded interval [0,3]. Here the supremum norms of $k$ and $x$ are computed over the corresponding domains, i.e. $[0,3] \times[0,3]$ respectively $[0,3]$.

Claim: $T \in \mathscr{B}(X)$.
Proof. $T$ is obviously linear and for any $t \in[0,3]$ we can bound

$$
|T x(t)| \leq \int_{0}^{3}|k(s, t) x(s)| d s \leq 3\|k\|_{s u p}\|x\|_{s u p}
$$

Provided we show that $T: X \rightarrow X$ is actually well defined, we will thus obtain that $T \in \mathscr{B}(X)$ with $\|T\| \leq 3\|k\|_{\text {sup }}$. To prove that $T$ is well defined we have to show that for any function $x \in C([0,3])$ also $T x$ is continuous on [0,3], i.e. that for any $t_{0} \in[0,3]$ and any sequence $t_{n} \rightarrow t_{0} T x\left(t_{n}\right) \rightarrow T x\left(t_{0}\right)$. To this end we set $f_{n}(s):=k\left(s, t_{n}\right) x(s)$ and $f(s):=k\left(s, t_{0}\right) x(s)$ and observe that

- $f_{n}(s) \rightarrow f(s)$ for every $s \in[0,3]$, so in particular $f_{n} \rightarrow f$ a.e.
- $\left|f_{n}\right| \leq g$ on $[0,3]$ for the constant function $g:=\|k\|_{\text {sup }}\|x\|_{\text {sup }}$ which is of course integrable over the interval $[0,3]$.

Hence, by the dominated convergence theorem of Lebesgue, we have that

$$
\lim _{n \rightarrow \infty}(T x)\left(t_{n}\right)=\lim _{n \rightarrow \infty} \int_{0}^{3} f_{n}(s) d s \stackrel{D C T}{=} \int_{0}^{3} \lim _{n \rightarrow \infty} f_{n} d s=\int_{0}^{3} f(s) d s=(T x)\left(t_{0}\right)
$$

as claimed.

### 2.2 Properties of (the space of) bounded linear operators

### 2.2.1 Completeness of the space of bounded linear operators

An important property of the space of bounded linear operators is that it "inherits" the completeness of the target space.

Theorem 2.2.1. Let $(X,\|\cdot\|)$ be any normed space and let $(Y,\|\cdot\|)$ be a Banach space. Then $\mathscr{B}(X, Y)$ (equipped with the operator norm) is complete and thus a Banach space.

Proof. Let $\left(T_{n}\right)$ be a Cauchy-sequence in $\mathscr{B}(X, Y)$. Then for every $x \in X$ we have that

$$
\left\|T_{n} x-T_{m} x\right\| \leq\left\|T_{n}-T_{m}\right\|\|x\| \underset{n, m \rightarrow \infty}{\longrightarrow} 0
$$

so $\left(T_{n} x\right)$ is a Cauchy sequence in $Y$ and, as $Y$ is complete, thus converges to some element in $Y$ which we call $T x$.

We now show that the resulting map $x \mapsto T x$ is an element of $\mathscr{B}(X, Y)$ and $T_{n} \rightarrow T$ in $\mathscr{B}(X, Y)$, i.e. $\left\|T-T_{n}\right\| \rightarrow 0$.

We first note that the linearity of $T_{n}$ (and (AOL)) implies that also $T$ is linear. Given any $\varepsilon>0$ we now let $N$ be so that for $m, n \geq N$ we have $\left\|T_{n}-T_{m}\right\| \leq \varepsilon$. Given any $x \in X$ we thus have

$$
\left\|T x-T_{n} x\right\|=\left\|\lim _{m \rightarrow \infty} T_{m} x-T_{n} x\right\|=\lim _{m \rightarrow \infty}\left\|T_{m} x-T_{n} x\right\| \leq \varepsilon\|x\|
$$

Hence $T$ is bounded (as $\|T x\| \leq\left(\left\|T_{n}\right\|+\varepsilon\right)\|x\|$ for all $\left.x\right)$ and so an element of $\mathscr{B}(X, Y)$ with $\left\|T-T_{n}\right\| \leq \varepsilon$ for all $n \geq N$, so as $\varepsilon>0$ was arbitrary we obtain that $T_{n} \rightarrow T$ in the sense of $\mathscr{B}(X, Y)$.

We note in particular that if $X$ is a Banach-space then the space $\mathscr{B}(X):=\mathscr{B}(X, X)$ of bounded linear operators from $X$ to itself is a Banach space and that for any normed space $(X,\|\cdot\|)$ the dual space $X^{*}=\mathscr{B}(X, \mathbb{R})$ (respectively $X^{*}=\mathscr{B}(X, \mathbb{C})$ if $X$ is a complex vector space) is complete as both $\mathbb{R}$ and $\mathbb{C}$ are complete.

### 2.2.2 Composition and invertibility of bounded linear operators

Given any normed spaces $\left(X,\|\cdot\|_{X}\right),\left(Y,\|\cdot\|_{Y}\right)$ and $\left(Z,\|\cdot\|_{Z}\right)$ and any linear operators $T \in \mathscr{B}(X, Y)$ and $S \in \mathscr{B}(Y, Z)$ we can consider the composition $S T=S \circ T: X \rightarrow Z$ and observe that

Proposition 2.2.2. The composition $S T$ of two bounded linear operators $S \in \mathscr{B}(Y, Z)$ and $T \in \mathscr{B}(X, Y)$ between normed spaces $X, Y, Z$ is again a bounded linear operator and we have

$$
\|S T\|_{\mathscr{B}(X, Z)} \leq\|S\|_{\mathscr{B}(Y, Z)}\|T\|_{\mathscr{B}(X, Y)}
$$

Proof. Clearly $S T$ is linear. Given any $x \in X$ we can furthermore bound

$$
\|S T x\|=\|S(T x)\| \leq\|S\|\|T x\| \leq\|S\|\|T\|\|x\|
$$

which implies the claim.

Remark 2.2.3. The proposition implies in particular that for sequences $T_{n} \rightarrow T$ in $\mathscr{B}(X, Y)$ and $S_{n} \rightarrow S$ in $\mathscr{B}(Y, Z)$ also

$$
S_{n} T_{n} \rightarrow S T \text { in } \mathscr{B}(X, Z)
$$

since

$$
\left\|S_{n} T_{n}-S T\right\| \stackrel{\Delta}{\leq}\left\|\left(S_{n}-S\right) T_{n}\right\|+\left\|S\left(T_{n}-T\right)\right\| \leq\left\|S_{n}-S\right\|\left\|T_{n}\right\|+\|S\|\left\|T_{n}-T\right\| \rightarrow 0
$$

where we use in the last step that $\left\|T_{n}\right\|$ is bounded since $T_{n}$ converges.
We also note that for operators $T \in \mathscr{B}(X)$ from a normed space $(X,\|\cdot\|)$ to itself we can consider the composition of $T$ with itself, and more generally powers $T^{n}=T \circ T \circ \ldots \circ T \in$ $\mathscr{B}(X)$ which, by the above proposition have norm

$$
\left\|T^{n}\right\| \leq\|T\|^{n}
$$

We conclude in particular
Remark 2.2.4. Let $X$ be a Banach space and let $A \in \mathscr{B}(X)$. Then

$$
\exp (A):=\sum_{k=0}^{\infty} \frac{1}{k!} A^{k}
$$

converges in $\mathscr{B}(X)$ and hence $\exp (A)$ is a well defined element of $\mathscr{B}(X)$.
Proof. We know that

$$
\sum_{k=0}^{\infty}\left\|\frac{1}{k!} A^{k}\right\| \leq \sum_{k=0}^{\infty} \frac{\|A\|^{k}}{k!}=\exp (\|A\|)<\infty
$$

i.e. that the series converges absolutely. As $X$ is complete and thus, by Theorem 2.2.1, also $\mathscr{B}(X)$ is complete we hence obtain from Corollary 1.1 .8 that the series converges.

In many applications, including spectral theory which will be discussed in B4.2 Functional Analysis II, the following lemma turns out to be useful to prove that an operator is invertible:

Lemma 2.2.5 (Convergence of Neumann-series). Let $X$ be a Banach space and let $T \in$ $\mathscr{B}(X)$ be so that $\|T\|<1$. Then the operator $I d-T$ is invertible with

$$
(I d-T)^{-1}=\sum_{j=0}^{\infty} T^{j} \in \mathscr{B}(X) .
$$

Here and in the following we use the following definition.

Definition 2.2.6. An element $T \in \mathscr{B}(X)$ is called invertible (short for invertible in $\mathscr{B}(X)$ ) if there exists $S \in \mathscr{B}(X)$ so that $S T=T S=I d$.

If we only talk about $T: X \rightarrow X$ being 'invertible as a function between sets', we sometimes say that $T$ is algebraically invertible and that a function $S: X \rightarrow X$ is an algebraic inverse of $T$ if $S T=T S=$ Id (but not necessarily $S \in \mathscr{B}(X)$ ).
Corollary 2.2.7. Let $T \in \mathscr{B}(X)$ be invertible. Then for any $S \in \mathscr{B}(X)$ with $\|S\|<\left\|T^{-1}\right\|^{-1}$ we have that $T-S$ is invertible.
Proof of Lemma 2.2.5. As $\|T\|<1$ we know that $\sum\left\|A^{k}\right\| \leq \sum\|A\|^{k}<\infty$ so, by Corollary 1.1.8, the series converges

$$
S_{n}:=\sum_{k=0}^{n} T^{k} \underset{n \rightarrow \infty}{\longrightarrow} S=\sum_{k=0}^{\infty} T^{k} \text { in } \mathscr{B}(X) .
$$

As

$$
(\operatorname{Id}-T) S_{n}=\operatorname{Id}-A+A-A^{2}+A^{2}-\ldots-A^{n}+A^{n}-A^{n+1}=\operatorname{Id}-A^{n+1}
$$

and $\left\|A^{n+1}\right\| \leq\|A\|^{n+1} \rightarrow 0$ we can pass to the limit $n \rightarrow \infty$ in the above expression to obtain that $(\operatorname{Id}-T) S=\mathrm{Id}$ and similarly $S(\operatorname{Id}-T)=\operatorname{Id}$ so $S=(\operatorname{Id}-T)^{-1}$.

Proof of Corollary 2.2.7. As $T$ is invertible (which by definition means that also $T^{-1} \in$ $\mathscr{B}(X))$ we obtain can write $T-S=T\left(\operatorname{Id}-T^{-1} S\right)$ and note that $T^{-1} S \in \mathscr{B}(X)$ with $\left\|T^{-1} S\right\|_{\mathscr{B}(X)} \leq\left\|T^{-1}\right\|\|S\|<1$. By Lemma 2.2 .5 we thus find that $\left(\operatorname{Id}-T^{-1} S\right)$ is invertible with $\left(\operatorname{Id}-T^{-1} S\right)^{-1}=\sum_{j=0}^{\infty}\left(T^{-1} S\right)^{j} \in \mathscr{B}(X)$ and hence $T-S$ is the composition of two invertible operators and thus invertible, compare also Q. 1 on Problem Sheet 2.

Remark 2.2.8. We obtain in particular that if $T \in \mathscr{B}(X)$ is so that $\|I d-T\|<1$ then $T$ is invertible. Denoting by

$$
G \mathscr{B}(X):=\{T \in \mathscr{B}(X): T \text { is invertible }\}
$$

we thus know that the open unit ball $B_{1}(I d):=\{T \in \mathscr{B}(X):\|T-I d\|<1\}$ around the identity is fully contained in $G \mathscr{B}(X)$, and more generally that for any $T \in G \mathscr{B}(X)$ the ball $B_{\delta}(T)$ with $\delta=\frac{1}{\left\|T^{-1}\right\|}>0$ is contained in $G \mathscr{B}(X)$. It follows that $G \mathscr{B}(X)$ is an open subset of $\mathscr{B}(X)$.

Remark 2.2.9. As you will show on Problem sheet 2, for $S \in \mathscr{B}(X)$ algebraically invertible we have that $S^{-1} \in \mathscr{B}(X)$ if and only if
(*) $\quad \exists \delta>0$ so that $\forall x \in X$ we have $\|S(x)\| \geq \delta\|x\|$.
We will furthermore see that for any $S \in \mathscr{B}(X, Y)$ satisfying ( $\star$ ) we have that the image $S X$ is closed.

## Chapter 3

## Finite dimensional normed spaces

In this chapter we will explain why for finite dimensional spaces most of the questions raised in the previous chapters do not arise, and hence why you never had to discuss issues of continuity, completeness,... in your prelims/part A courses on Linear Algebra. We shall see in particular that

- all norms on a finite dimensional space are equivalent,
- all linear maps defined on a finite dimensional space are bounded,
- all finite dimensional spaces are complete.

We shall furthermore see that the Theorem of Heine-Borel seen in part A and Prelims for $\mathbb{R}$ and $\mathbb{R}^{n}$, that assures that bounded and closed sets in $\mathbb{R}^{n}$ are compact, remains valid in general finite dimensional normed spaces and that indeed a normed space is finite dimensional if and only if the assertion of this theorem holds.

To begin with, we prove the following important special case of the equivalence of norms, upon which we shall later base the proof of this result for general finite dimensional spaces:
Proposition 3.0.1. Any norm $\|\cdot\|$ on $\mathbb{R}^{m}, m \in \mathbb{N}$, is equivalent to the Euclidean norm $\|x\|_{2}:=\left(\sum_{i=1}^{m} x_{i}^{2}\right)^{1 / 2}$ and hence all norms on $\mathbb{R}^{m}$ are equivalent.
Proof. We first remark that the last part of the proposition simply follows from the transitivity of the relation of norms being equivalent, so it remains to show that for any norm $\|\cdot\|$ there exist constants $C_{1,2} \in \mathbb{R}$ so that for every $x \in \mathbb{R}^{m}$

$$
\|x\| \leq C_{1}\|x\|_{2} \text { and }\|x\|_{2} \leq C_{2}\|x\|
$$

To get the first inequality we note that for any $x=\left(x_{1}, \ldots, x_{m}\right)=\sum_{i=1}^{m} x_{i} e_{i} \in \mathbb{R}^{m}$

$$
\begin{equation*}
\|x\| \stackrel{\Delta}{\leq} \sum_{i=1}^{m}\left|x_{i}\right|\left\|e_{i}\right\| \stackrel{\text { C.S. }}{\leq}\left(\sum_{i=1}^{m}\left|x_{i}\right|^{2}\right)^{1 / 2}\left(\sum_{i=1}^{m}\left\|e_{i}\right\|^{2}\right)^{1 / 2}=C_{1}\|x\|_{2} \tag{3.1}
\end{equation*}
$$

where we set $C_{1}:=\left(\sum_{i=1}^{m}\left\|e_{i}\right\|^{2}\right)^{1 / 2}$.
For the proof of the reverse inequality we give two slightly different variants, which are however based on the same core idea and use in particular the Theorem of Heine-Borel in Euclidean space ( $\mathbb{R}^{m},\|\cdot\|_{2}$ ).

Variant 1 (Using that continuous functions on compact sets achieve their minimum:) We note that the function $f(x):=\|x\|$ is a Lipschitz-continuous function from ( $\mathbb{R}^{m},\|\cdot\|_{2}$ ) to $\mathbb{R}$ (though of course not an element of $\mathscr{B}\left(\mathbb{R}^{n}, \mathbb{R}\right)$ as not linear) as the reverse triangle inequality combined with (3.1) allows us to bound

$$
|f(x)-f(y)|=|\|x\|-\|y\|| \leq\|x-y\| \leq C_{1}\|x-y\|_{2} .
$$

As the (Euclidean) unit sphere $S=\left\{x \in \mathbb{R}^{n}:\|x\|_{2}=1\right\}$ is a closed and bounded subset of $\left(\mathbb{R}^{n},\|\cdot\|_{2}\right)$ and hence by Heine-Borel compact, we know that $\left.f\right|_{S}$ achieves its minimum in some point $x^{*} \in S$. As $\|\cdot\|$ is a norm, we know that $f\left(x^{*}\right)>0$ and set $C_{2}:=\frac{1}{f\left(x^{*}\right)}$. With this choice of $C_{2}$ we then get that for every $x \in X$

$$
C_{2}\|x\|=C_{2}\| \| x\left\|_{2} \cdot \frac{x}{\|x\|_{2}}\right\|=C_{2}\|x\|_{2} f(\underbrace{\frac{x}{\|x\|_{2}}}_{\in S}) \geq C_{2}\|x\|_{2} f\left(x^{*}\right)=\|x\|_{2}
$$

which gives the reverse inequality claimed above.
Variant 2 (Proof by contradiction) Suppose that there exists no constant $C_{2}$ so that the inequality $\|x\|_{2} \leq C_{2}\|x\|$ holds true for every $x \in X$. Then we can choose a sequence of elements $x^{(n)} \in \mathbb{R}^{m} \backslash\{0\}$ so that $\left\|x^{(n)}\right\|_{2} \geq n\left\|x^{(n)}\right\|$. The renormalised sequence $\tilde{x}^{(n)}=\frac{x^{(n)}}{\left\|x^{(n)}\right\|_{2}}$ then consists of elements of the Euclidean unit sphere $S$ which as observed above is compact and thus has a subsequence that converges $\tilde{x}^{\left(n_{j}\right)} \rightarrow x \in S$ with respect to the Euclidean norm $\|\cdot\|_{2}$. As $x \in S$, we know that $x \neq 0$ and thus $\|x\| \neq 0$ which contradicts the fact that

$$
\|x\| \leq\left\|x-\tilde{x}^{\left(n_{j}\right)}\right\|+\left\|\tilde{x}^{\left(n_{j}\right)}\right\| \leq C_{1}\left\|x-\tilde{x}^{\left(n_{j}\right)}\right\|_{2}+\frac{1}{n_{j}} \rightarrow 0 .
$$

We note that the exact same proof (replacing all $\mathbb{R}$ with $\mathbb{C}$ ) applies also if the field is $\mathbb{F}=\mathbb{C}$ and hence yields that all norms on $\mathbb{C}^{m}$ are equivalent. More generally we obtain

Theorem 3.0.2. Let $X$ be any finite dimensional space. Then any two norm $\|\cdot\|$ and $\|\cdot\|^{\prime}$ on $X$ are equivalent.

To simplify the notation we again carry out the proof just for real vector spaces and note that the exact same proof (with all $\mathbb{R}$ replaced by $\mathbb{C}$ ) applies for complex vector spaces.

Proof. Let $m=\operatorname{dim}(X)$. Choosing a basis $f_{1}, \ldots, f_{m}$ of $X$ we know from Prelims Linear Algebra that the map

$$
Q: \mathbb{R}^{m} \ni\left(\mu_{1}, \ldots, \mu_{m}\right) \mapsto \sum_{i=1}^{m} \mu_{i} f_{i} \in X
$$

is a linear bijection. Given any two norms $\|\cdot\|_{X}$ and $\|\cdot\|_{X}^{\prime}$ on $X$ we obtain two norms $\|\cdot\|_{\mathbb{R}^{m}}$ and $\|\cdot\|_{\mathbb{R}^{m}}^{\prime}$ on $\mathbb{R}^{m}$ by defining for every $x \in \mathbb{R}^{n}$

$$
\|x\|_{\mathbb{R}^{m}}:=\|Q(x)\|_{X} \text { respectively }\|x\|_{\mathbb{R}^{m}}^{\prime}:=\|Q(x)\|_{X}^{\prime}
$$

We note that these norms are chosen so that the maps $Q:\left(\mathbb{R}^{m},\|\cdot\|_{\mathbb{R}^{m}}\right) \rightarrow\left(X,\|\cdot\|_{X}\right)$ and $Q:\left(\mathbb{R}^{m},\|\cdot\|_{\mathbb{R}^{m}}^{\prime}\right) \rightarrow\left(X,\|\cdot\|_{X}^{\prime}\right)$ are isometric and hence, as they are bijections, so are their inverses (i.e. $Q$ and $Q^{\prime}$ are isometric isomorphisms). Using that, by Proposition 3.0.1, all norms on $\mathbb{R}^{m}$ are equivalent and hence that there exist constants $C_{1,2}$ so that

$$
\|x\|_{\mathbb{R}^{m}} \leq C_{1}\|x\|_{\mathbb{R}^{m}}^{\prime} \text { and }\|x\|_{\mathbb{R}^{m}}^{\prime} \leq C_{2}\|x\|_{\mathbb{R}^{m}}
$$

we now conclude that for any $y \in X$

$$
\|y\|_{X}=\left\|Q^{-1}(y)\right\|_{\mathbb{R}^{m}} \leq C_{1}\left\|Q^{-1}(y)\right\|_{\mathbb{R}^{m}}^{\prime}=C_{1}\|y\|_{X}^{\prime}
$$

and similarly $\|y\|_{X}^{\prime} \leq C_{2}\|y\|_{X}$, establishing the equivalence of norms.
Based on this result it is now easy to prove
Theorem 3.0.3. Let $\left(X,\|\cdot\|_{X}\right)$ be a finite dimensional normed space and let $\left(Y,\|\cdot\|_{Y}\right)$ be any normed space (not necessarily finite dimensional). Then any linear map $T: X \rightarrow Y$ is an element of $\mathscr{B}(X, Y)$, i.e. a bounded linear operator.

Proof. Given any such $T$ we set for every $x \in X$

$$
\|x\|_{T}:=\|x\|_{X}+\|T x\|_{Y} .
$$

We can easily check that this defines a norm on the finite dimensional space $X$ which, by the previous theorem, must hence be equivalent to $\|\cdot\|_{X}$. In particular, there exists a constant $C \in \mathbb{R}$ so that

$$
\|T x\|_{Y} \leq\|x\|_{T} \leq C\|x\|_{X}
$$

which ensures that $T$ is bounded and hence an element of $\mathscr{B}(X, Y)$.
An important conclusion of this result is

Corollary 3.0.4. Let $(X,\|\cdot\|)$ be a finite dimensional normed space. Then $(X,\|\cdot\|)$ is homeomorphic to $\mathbb{F}^{m}, m=\operatorname{dim}(X)$ and $\mathbb{F}=\mathbb{R}$ respectively $\mathbb{F}=\mathbb{C}$, and a linear homeomorphism from $\mathbb{F}^{m}$ to $(X,\|\cdot\|)$ can be obtained by choosing any basis $f_{1}, \ldots, f_{m}$ of $X$ and defining

$$
\begin{equation*}
Q: \mathbb{F}^{m} \ni\left(\mu_{1}, \ldots, \mu_{m}\right) \rightarrow \sum_{i=1}^{m} \mu_{i} f_{i} \in X \tag{3.2}
\end{equation*}
$$

We recall that a map $f: M \rightarrow \tilde{M}$ between two metric spaces is called a homeomorphism if $f$ is invertible and both $f$ and $f^{-1}$ are continuous. We also recall that the image $f(C)$ of a closed set $C$ under a homeomorphism $f$ is again closed as it can be viewed as the preimage of $C$ under the continuous function $f^{-1}$.

As we already know from Linear Algebra that $Q$ is a bijection, this corollary immediately follows from Theorem 3.0 .3 which implies that the linear maps $Q, Q^{-1}$ are continuous.

Combing the equivalence of norms with the completeness of $\mathbb{R}$ and $\mathbb{C}$ furthermore allows us to prove

Theorem 3.0.5. Every finite dimensional normed space $(X,\|\cdot\|)$ is complete, i.e. a Banach space.

Proof. We first recall from Prelims Analysis and Part A metric space that $\mathbb{F}^{n}, \mathbb{F}=\mathbb{R}$ or $\mathbb{F}=\mathbb{C}$ equipped with the Euclidean norm $\|\cdot\|_{2}$ is complete and remark that this can be easily proved by showing that a sequence in $\mathbb{R}^{n}$ converges/is a Cauchy-sequence if and only if all of its components converge/are Cauchy-sequences in $\mathbb{R}$. (We stress that this statement is wrong in infinite dimensional spaces such as the sequence spaces $\ell^{p}$ ).

Let now $Q$ be as in (3.2). Given a Cauchy-sequence $\left(x_{n}\right)$ in $X$ we conclude that since $Q^{-1}$ is a bounded linear operator from $\left(X,\|\cdot\|_{X}\right)$ to $\left(\mathbb{F}^{n},\|\cdot\|_{2}\right)$ we have

$$
\left\|Q^{-1}\left(x_{n}\right)-Q^{-1}\left(x_{m}\right)\right\|_{2}=\left\|Q^{-1}\left(x_{n}-x_{m}\right)\right\|_{2} \leq\left\|Q^{-1}\right\|\left\|x_{n}-x_{m}\right\|_{X} \underset{n, m \rightarrow \infty}{\longrightarrow} 0
$$

i.e. that $Q^{-1}\left(x_{n}\right)$ is a Cauchy sequence in $\left(\mathbb{R}^{n},\|\cdot\|_{2}\right)$ and therefore converges to some $y$. Setting $x=Q(y)$ we hence obtain that

$$
\left\|x_{n}-x\right\|_{X}=\left\|Q\left(Q^{-1}\left(x_{n}\right)-y\right)\right\|_{X} \leq\|Q\|\left\|Q^{-1}\left(x_{n}\right)-y\right\|_{2} \rightarrow 0
$$

i.e. that the original Cauchy sequence $\left(x_{n}\right)$ in $X$ converges.

As an immediate conclusion of the above result we obtain
Corollary 3.0.6. Every finite dimensional subspace of a normed vector space $(X,\|\cdot\|)$ is complete and hence closed.

WARNING. Not every subspace of a normed vector space $(X,\|\cdot\|)$ is closed.

Example 3.0.7. Consider $C([0,2])$ as a subspace of $\left(L^{1}([0,2]),\|\cdot\|_{L^{1}}\right)$. Then the sequence $\left(f_{n}\right)_{n \in \mathbb{N}} \subset C([0,2])$ defined by

$$
f_{n}(t)= \begin{cases}t^{n}, & 0 \leq t \leq 1 \\ 1, & t>1\end{cases}
$$

is a Cauchy sequence in $L^{1}([0,2])$ with limit $f(t)=\left\{\begin{array}{ll}0 & 0 \leq t \leq 1 \\ 1 & t>1\end{array}\right.$ however $f \notin C([0,2])$.
At a more abstract level we could also argue as follows: $C([0,2])$ is a proper subspace of $L^{1}([0,1])$ however, as we shall see later, $C([0,2])$ is dense in $L^{1}([0,1])$, so the closure of $C([0,2])$ in $L^{1}([0,1])$ is $\overline{C([0,2])}{ }^{L^{1}}=L^{1}([0,1]) \neq C([0,2])$.

We recall that the Theorem of Heine Borel ensures that every subset of $\mathbb{R}^{n}$ respectively of $\mathbb{C}^{n}$ that is bounded and closed is automatically compact. While the reverse implication, i.e. that a compact set is always bounded and closed, is valid in every normed space (and indeed more generally in every metric space), for general normed spaces closedness and boundedness does not imply compactness. Indeed, the analogue of the Heine-Borel Theorem holds true in a normed space if and only if the space has finite dimension:

Theorem 3.0.8. Let $(X,\|\cdot\|)$ a normed space. Then the following are equivalent
(1) $\operatorname{dim}(X)<\infty$.
(2) Every subset $Y \subset X$ that is bounded and closed is compact.
(3) The unit sphere $S:=\{x \in X:\|x\|=1\}$ is compact.

Remark 3.0.9. We recall that by definition a set $K$ is compact if every open cover of $K$ has a finite subcover. We also recall that for metric spaces (and hence in particular for normed space) compactness is equivalent to sequential compactness, i.e. to the property that every sequence in $K$ has a subsequence which converges in $K$. A further useful equivalent characterisation of compactness in metric spaces is that $K$ is compact if and only $K$ is complete and totally bounded (which means that for every $\varepsilon>0$ there exists a finite $\varepsilon$-net, i.e. a finite set of points $x_{1}, \ldots, x_{m} \in K$ so that $\left.K \subset \bigcup_{i=1}^{m} B_{\varepsilon}\left(x_{i}\right)\right)$.

For the difficult implication in the proof of 3.0 .8 , i.e. $(3) \Rightarrow(1)$ we shall use the following useful property of closed subspaces of normed vector spaces.

Proposition 3.0.10 (Riesz-Lemma). Let $(X,\|\cdot\|)$ be a normed vector space and $Y \varsubsetneqq X a$ closed subspace. Then to any $\varepsilon>0$ there exists an element $x \in S \subset X$ in the unit sphere so that

$$
\operatorname{dist}(x, Y):=\inf \{\|x-y\|: y \in Y\} \geq 1-\varepsilon
$$

Proof of Proposition 3.0.10. We can assume without loss of generality that $\varepsilon \in(0,1)$.
As $Y \neq X$ is closed we know that the set $X \backslash Y$ is open and non-empty, so we can choose some $x^{*} \in X \backslash Y$ and use that $d:=\operatorname{dist}\left(x^{*}, Y\right)>0$, as $X \backslash Y$ must contain some ball $B_{\delta}(x)$ which ensures that $d \geq \delta>0$.

By the definition of the infimum, we can now select $y^{*} \in Y$ so that $d \leq\left\|x^{*}-y^{*}\right\|<\frac{d}{1-\varepsilon}$ and claim that $x:=\frac{x^{*}-y^{*}}{\left\|x^{*}-y^{*}\right\|}$ has the desired properties. Clearly $\|x\|=1$, i.e. $x \in S$ as desired, and we furthermore have that

$$
\begin{align*}
\operatorname{dist}(x, Y) & =\inf _{y \in Y}\|x-y\|=\inf _{y \in Y}\left\|\frac{x^{*}}{\left\|x^{*}-y^{*}\right\|}-\frac{y^{*}}{\left\|x^{*}-y^{*}\right\|}-y\right\|=\inf _{\tilde{y} \in Y}\left\|\frac{x^{*}}{\left\|x^{*}-y^{*}\right\|}-\tilde{y}\right\|  \tag{3.3}\\
& =\inf _{\hat{y} \in Y}\left\|\frac{x^{*}-\hat{y}}{\left\|x^{*}-y^{*}\right\|}\right\|=\frac{\operatorname{dist}\left(x^{*}, Y\right)}{\left\|x^{*}-y^{*}\right\|} \geq 1-\varepsilon
\end{align*}
$$

where we used twice that $Y$ is a subspace, to replace the infimum over $y \in Y$ first by an infimum over $\tilde{y}=\frac{y^{*}}{\left\|x^{*}-y^{*}\right\|}+y$ and then an infimum over $\hat{y}$ which is related to $\tilde{y}$ by $\tilde{y}=\frac{\hat{y}}{\left\|x^{*}-y^{*}\right\|}$.
Proof of Theorem 3.0.8.
$(1) \Rightarrow(2)$
Let $Y$ be a closed and bounded set. Then the image of $Y$ under the homeomorphism $Q^{-1}: X \rightarrow \mathbb{F}^{m}$ obtained in Corollary 3.0 .4 is also closed and, as $Q^{-1}$ is a bounded linear operator, also bounded and hence by the Theorem of Heine-Borel a compact subset of $\mathbb{R}^{m}$. Hence $Y=Q\left(Q^{-1}(Y)\right)$ is the image of a compact set under the continuous function $Q$ and hence itself compact.

$$
(2) \Rightarrow(3):
$$

Is trivial as $S$ is clearly closed and bounded.

$$
(3) \Rightarrow(1):
$$

We argue by contradiction and assume that $S$ is compact but $\operatorname{dim}(X)=\infty$. We may thus choose a sequence of linearly independent elements $y_{k} \in X, k \in \mathbb{N}$. Then the subspace $Y_{k}:=\operatorname{span}\left\{y_{1}, \ldots, y_{k}\right\} \varsubsetneqq Y_{k+1}$ is finite dimensional, so by Corollary 3.0.6, a closed proper subspace of $Y_{k+1}$. Applying Proposition 3.0.10 with $\varepsilon=\frac{1}{2}$ (viewing $Y_{k}$ as a subspace of $Y_{k+1}$ instead of $X$ ) thus gives us a sequence of elements $y_{k} \in Y_{k+1} \cap S$ with $\operatorname{dist}\left(y_{k}, Y_{k}\right) \geq \frac{1}{2}$. In particular for every $k>l$ we have $\left\|y_{k}-y_{l}\right\| \geq \operatorname{dist}\left(y_{k}, Y_{l+1}\right) \geq \operatorname{dist}\left(y_{k}, Y_{k}\right) \geq \frac{1}{2}$ so no subsequence of $\left(y_{k}\right)$ can be a Cauchy-sequence. Having thus constructed a sequence $\left(y_{k}\right)$ in $S \subset X$ that does not contain a convergent subsequence we conclude that $S$ is not sequentially compact and hence not compact leading to a contradiction.

Remark 3.0.11. In the special case that $X$ is an inner product space, rather than a general normed space, then the proof that $(3) \Rightarrow(1)$ can be simplified significantly and does not require the use of Proposition 3.0.10: Given any sequence $y_{k}$ of linearly independent elements
of $X$, we can apply the Gram-Schmidt method from Prelims Linear Algebra to obtain a sequence $x_{k}$ of orthonormal elements of $X$ which hence have the property that $\left\|x_{k}-x_{l}\right\|^{2}=$ $\left\|x_{k}\right\|^{2}-2\left(x_{k}, x_{l}\right)+\left\|x_{l}\right\|^{2}=2$ which ensures that no subsequence of $\left(s_{n}\right)$ can be Cauchy and hence that $S$ is not sequentially compact.

## Chapter 4

## Density of subspaces and the Theorem of Stone-Weierstrass

### 4.1 Density of subspaces and extensions of bounded linear operators by density

Definition 4.1.1. Let $(X,\|\cdot\|)$ be a normed space. Then a subset $D \subset X$ is dense if its closure $\bar{D}$ is given by the whole space $X$, i.e. $\bar{D}=X$.

Remark 4.1.2. A useful equivalent characterisation is that a subset $D \subset X$ is dense in $X$ if and only if for every $x \in X$ there exists a sequence of elements $y_{n} \in D$ so that $y_{n} \underset{n \rightarrow \infty}{\longrightarrow} x$, i.e. $\left\|x-y_{n}\right\| \underset{n \rightarrow \infty}{\longrightarrow} 0$ or equivalently if and only if for every $x \in X$ and every $\varepsilon>0$ there exists $y \in D$ so that $\|x-y\|<\varepsilon$.

An important feature of dense subsets $D$ of normed spaces is that a bounded linear operator on $X$ is fully determined by its values on $D$. This is particularly useful if we are working on a space that contains a subspace of "well-understood" objects, e.g. the space of polynomials in the space of real valued continuous functions or the space of real valued smooth functions on $[0,1]$ in $\left(L^{2}([0,1]),\|\cdot\|_{L^{2}}\right)$.

Theorem 4.1.3. Let $\left(X,\|\cdot\|_{X}\right)$ be a normed space, let $Y$ be a dense subspace of $X$ (which we equip with the norm of $X)$ and let $\left(Z,\|\cdot\|_{Z}\right)$ be a Banach space. Then any $T \in \mathscr{B}(Y, Z)$ has a unique extension $\tilde{T} \in \mathscr{B}(X, Z)$, i.e. there exists a unique bounded linear operator $\tilde{T}: X \rightarrow Z$ so that $\tilde{T} y=T y$ for every $y \in Y$ and we furthermore have that

$$
\|\tilde{T}\|_{\mathscr{B}(X, Z)}=\|T\|_{\mathscr{B}(Y, Z)} .
$$

We first prove the following simpler result which can be useful in applications.

Lemma 4.1.4. Let $\left(X,\|\cdot\|_{X}\right)$ be a normed space, $D \subset X$ a dense subset and let $\left(Z,\|\cdot\|_{Z}\right)$ be a normed space. Then for operators $T, S \in \mathscr{B}(X, Z)$ we have

$$
\left.T\right|_{D}=\left.S\right|_{D} \Longleftrightarrow T=S
$$

In particular, the only element $T \in \mathscr{B}(X, Z)$ with $\left.T\right|_{D}=0$ is $T=0$.
Proof of Lemma 4.1.4. We can prove the non-trivial direction " $\Rightarrow$ " as follows: For any $x \in X$ we can choose a sequence $d_{n} \rightarrow x$ with $d_{n} \in D$ to conclude that since both $T$ and $S$ are continuous

$$
T x=\lim _{n \rightarrow \infty} T d_{n}=\lim _{n \rightarrow \infty} S d_{n}=S x .
$$

Proof of Theorem 4.1.3. Let $x \in X$ be any element. Then as $Y$ is dense there exists a sequence $y_{n}$ of elements of $Y$ so that $y_{n} \rightarrow x$.

Claim: $T y_{n}$ converges and the limit $z=\lim _{n \rightarrow \infty} T y_{n}$ depends only on $x$ and not on the chosen sequence $y_{n}$.

Once proven, this claim allows us define $\tilde{T} x:=\lim _{n \rightarrow \infty} T y_{n}$ to obtain a well defined map $\tilde{T}: X \rightarrow Z$. This map will be linear as $T$ is linear, as we can interchange limits and addition/scalar multiplication and know that the obtained limit is independent of the chosen approximating sequence. Furthermore

$$
\|\tilde{T} x\|_{Z}=\lim _{n \rightarrow \infty}\left\|T y_{n}\right\|_{Z} \leq\|T\| \lim _{n \rightarrow \infty}\left\|y_{n}\right\|_{X}=\|T\|\|x\|_{X}
$$

so that $\tilde{T} \in \mathscr{B}(X, Z)$ with $\|T\| \geq\|\tilde{T}\|$. The reverse inequality follows from the definition of the operator norm, as

$$
\|\tilde{T}\|_{\mathscr{B}(X, Z)}=\sup _{x \in X,\|x\|_{X}=1}\|\tilde{T} x\|_{Z} \geq \sup _{y \in Y,\|y\|_{X}=1}\|\tilde{T} y\|_{Z}=\|T\|_{\mathscr{B}(Y, Z)}
$$

Hence, once the claim is proven, we obtain the desired extension which, by Lemma 4.1.4, is furthermore unique.

It thus remains to prove the claim. To this end we remark that if $y_{n} \rightarrow x$ then $\left(y_{n}\right)$ is a Cauchy sequence and hence also

$$
\left\|T y_{n}-T y_{m}\right\|_{z} \leq\|T\|\left\|y_{n}-y_{m}\right\| \underset{n, m \rightarrow \infty}{\longrightarrow} 0
$$

So $\left(T y_{n}\right)$ is a Cauchy sequence in the Banach space $Z$ and must thus converge to some limit $z$. To prove that the limit does not depend on the choice of the sequence of elements of $Y$ that approximate $x$, let $\tilde{y}_{n}$ be any alternative sequence in $Y$ that converges to $x$. Then the
argument above implies that $T \tilde{y}_{n}$ converges to some limit $\tilde{z}$ and one way to see that $z=\tilde{z}$ is to consider a third sequence $\hat{y}_{n} \rightarrow x$ chosen as $\hat{y}_{n}=y_{n}$ for $n$ odd and $\hat{y}_{n}=\tilde{y}_{n}$ for $n$ even. Then also $T \hat{y}_{n}$ must converge to a limit $\hat{z}$ which must agree with the limit of both of the subsequences $T \hat{y}_{2 n}$ and $T \hat{y}_{2 n+1}$, i.e. we must have that $z=\hat{z}=\tilde{z}$ which establishes the claim and thus completes the proof of the theorem.

### 4.2 The Theorem of Stone-Weierstrass and Density of Polynomials in the space of continuous functions

The goal of this section is to identify suitable dense subspaces of the space $C(K)=C(K, \mathbb{R})$ of real-valued continuous functions on a compact subset $K \subset \mathbb{R}^{n}$. As always we equip $C(K)$ with the sup-norm and recall that since continuous functions on compact sets are bounded this is well defined.

We begin by exploring what properties are necessary for a subspace $L \subset C(K)$ to be dense. To this end we first note that given any two points $p, q \in K$ with $p \neq q$ we can choose a continuous function $g \in C(K)$ so that $g(p) \neq g(q)$, e.g. by letting $g(x)=1-\frac{\|x-p\|}{\delta}$ in $B_{\delta}(p) \cap K$ and $g \equiv 0$ outside of this ball for some number $0<\delta<\|p-q\|$. As an aside we note that with a bit more care we could also construct such a function $g$ which is smooth, compare also section 4.3.

We now observe that since $C(K)$ contains a function $g$ with $g(p) \neq g(q), p \neq q$ any given points, also $L$ must have this property: Indeed, if $L \subset C(K)$ is dense, then there must be a sequence $f_{n} \in L$ so that $\left\|f_{n}-g\right\|_{\text {sup }} \rightarrow 0$ and hence in particular

$$
\begin{align*}
\left|f_{n}(p)-f_{n}(q)\right| & \geq|g(p)-g(q)|-\left|f_{n}(p)-g(p)\right|-\left|f_{n}(q)-g(q)\right| \\
& \geq|g(p)-g(q)|-2\left\|f_{n}-g\right\|_{\text {sup }} \rightarrow|g(p)-g(q)|>0 . \tag{4.1}
\end{align*}
$$

A necessary condition for a subspace $L \subset C(K)$ to be dense is hence that it separates points

Definition 4.2.1. We say that a subset $D \subset C(K)$ separates points if for all $p, q \in K$ with $p \neq q$ there exists a function $g \in D$ so that $g(p) \neq g(q)$.

Remark 4.2.2. It can be useful to note that for a subspace $L \subset C(K)$ that contains the constant functions, then the following are equivalent:

- L separates points,
- for any $p \neq q \in K, \exists g \in L$ with $g(p)=0$ and $g(q)=1$,
- for any $p \neq q \in K, a, b \in \mathbb{R}, \exists g \in L$ with $g(p)=a$ and $g(q)=b$.

Proof. Exercise.
For our first density result for $C(K)$ we furthermore want our subspace to be closed under the operation of taking the (pointwise) maximum or minimum of two elements of $L$, i.e. to be a so called linear sublattice:

Definition 4.2.3. A subspace $L \subset C(K)$ is called a linear sublattice if

$$
f, g \in L \Rightarrow \max (f, g) \in L \text { and } \min (f, g) \in L
$$

We note that if $L$ is a linear sublattice then also the minimum and maximum of any finite number of elements $f_{1}, \ldots, f_{m}$ is contained in $L$ since we can iteratively write $\max \left(f_{1}, \ldots, f_{m}\right)=$ $\max \left(f_{1}, \max \left(f_{2}, \ldots, f_{m}\right)\right)=\ldots$ and furthermore remark that $L$ is a sublattice if and only if

$$
f \in L \Rightarrow|f| \in L
$$

as one can easily check using e.g. that $|f|=\max (f,-f)$ and $\max (f, g)=\frac{1}{2}(f+g)+\frac{1}{2}|f-g|$.
We stress again that here we consider real valued functions $f$ (and note that this definition would make no sense for complex valued functions $f$ ).

We now prove our first main result of this section, which gives a density result for general sublattices:

Theorem 4.2.4 (Stone-Weierstrass-Theorem, lattice form). Let $K \subset \mathbb{R}^{n}$ be a compact set and let $C(K)$ be the space of continuous real-valued functions on $K$ which is equipped with the sup-norm. Let $L$ be a subspace of $C(K)$ which is such that
(i) $L$ is a linear sublattice,
(ii) $L$ contains the constant functions, and
(iii) $L$ separates points in $K$.

Then $L$ is dense in $C(K)$.
Remark 4.2.5. To see that just (i) and (iii) are not sufficient we can e.g. consider $\{f \in$ $C([0,1]): f(1)=0\}$ which is a linear sublattice that separates points but is of course not dense in $C([0,1])$ as we cannot approximate any function $f \in C([0,1])$ with $f(1) \neq 0$ by elements of this space.

Proof. Fix $f \in C(K)$ and $\varepsilon>0$. We would like to construct $g \in L$ such that $\|f-g\|_{\text {sup }} \leq \varepsilon$.
Fix some point $p$ for the moment. By Remark 4.2 .2 , for any $q \in K$, there exists $f_{p, q} \in L$ such that $f_{p, q}(p)=f(p)$ and $f_{p, q}(q)=f(q)$. Let $U_{p, q}^{\varepsilon}=\left(f-f_{p, q}\right)^{-1}((-\varepsilon, \varepsilon)) \subset K$ so that

$$
\left|f-f_{p, q}\right|<\varepsilon \text { on } U_{p, q}^{\varepsilon} .
$$

Observe that $\left\{U_{p, q}^{\varepsilon}\right\}_{q \in K}$ is an open cover of $K$ so we can find finitely many points $q_{1}, \ldots, q_{m}$ (allowed to depend on the fixed point $p \in K$ ) so that $K=\bigcup_{i=1}^{m} U_{p, q_{i}}^{\varepsilon}$.

We recall that on the sets $U_{p, q_{i}}^{\varepsilon}$ we have $\left|f-f_{p, q_{i}}\right|<\varepsilon$ and hence in particular $f_{p, q_{i}}<f+\varepsilon$. Defining $g_{p}:=\min \left(f_{p, q_{1}}, \ldots f_{p, q_{m}}\right)$ we hence obtain a function $g_{p} \in L$ which satisfies $g_{p}<f+\varepsilon$ on all of $K$ and is furthermore so that $g_{p}(p)=f(p)$ as all functions $f_{p, q}$ have the property that $f_{p, q}(p)=f(p)$.

Our construction above gives a good upper bound for $g_{p}-f$, but no lower bound. To obtain both a good upper bound and a good lower bound, we apply more or less the same procedure to $g_{p}$, but now letting $p$ vary. Let $V_{p}^{\varepsilon}=\left(f-g_{p}\right)^{-1}((-\varepsilon, \varepsilon))$ so that

$$
\left|g_{p}-f\right|<\varepsilon \text { on } V_{p}^{\varepsilon}
$$

Again $\left\{V_{p}^{\varepsilon}\right\}_{p \in K}$ is an open cover of $K$, and so has a finite subcover $K=\bigcup_{i=1}^{k} V_{p_{i}}$. Set

$$
g:=\max \left\{g_{p_{1}}, \ldots, g_{p_{k}}\right\}
$$

which is in $L$ as $L$ is a sublattice. As $g$ is the maximum of functions that satisfy $g_{p_{i}}<f+\varepsilon$ on all of $K$ we have of course still $g<f+\varepsilon$ on $K$, but now know additionally that for every $x \in K$ there is some $i$ so that $x \in V_{p_{i}}$ and hence $g(x) \geq g_{p_{i}}(x)>f(x)-\varepsilon$. Combined we thus obtain that the element $g \in L$ that we constructed satisfies $\|f-g\|_{\text {sup }}<\varepsilon$. As $\varepsilon>0$ and $f \in C(K)$ were arbitrary this completes the proof that $L$ is dense in $C(K)$.

As a major application of this result we now prove:
Theorem 4.2.6 (Theorem of Weierstrass (respectively Stone-Weierstrass) on approximation of continuous functions by polynomials). Let $K \subset \mathbb{R}^{n}$ be compact. Then the space of polynomials is dense in $C(K)$, i.e. for every $f \in C(K)$ there exists a sequence of polynomials $p_{n}$ on $K$ so that $p_{n} \rightarrow f$ in the sense of $\left(C(K),\|\cdot\|_{\text {sup }}\right)$, i.e. uniformly.

This theorem was first proven by Weierstrass in the case of $K$ a compact interval, while the proof of the more general form of the theorem given above is due to Stone. Hence one generally talks of the Theorem of Weierstrass if $K$ is a compact interval and of the Theorem of Stone-Weierstrass otherwise.

We note that the space of polynomials trivially contains the constant functions and also separates points (for this already the linear functions would be sufficient). It has furthermore the extra structure of being a subalgebra of the algebra of continuous functions

Definition 4.2.7. $A$ subspace $A \subset C(K)$ is a subalgebra if $A$ contains the constant functions and

$$
f, g \in A \Rightarrow f g \in A
$$

where $(f g)(x)=f(x) g(x)$ is obtained by pointwise multiplication.

The Theorem of Weierstrass on the density of polynomials in $C(K)$ is hence a special case of the following more general result:

Theorem 4.2.8 (Stone-Weierstrass Theorem, subalgebra form). Let $A \subset C(K)$ be a subalgebra of $C(K)$ which separates points. Then $A$ is dense in $C(K)$.

We derive this theorem from the lattice form of the Stone-Weierstrass theorem by using
Proposition 4.2.9. If $A \subset C(K)$ is a subalgebra of $C(K)$ that is closed then $A$ is a linear sublattice.

Based on this proposition which is proven below and the lattice form of the StoneWeierstrass theorem we can now immediately prove the subalgebra form of the theorem:

Proof of Theorem 4.2.8. Given a subalgebra $A$ as in the theorem we can easily check that $\bar{A}$ is also a subalgebra and hence, by Proposition 4.2.9, $\bar{A}$ is a linear sublattice. As $A$ contains the constant functions and separates points the same holds true also for $\bar{A}$ so we may apply the sublattice version of the Theorem of Stone Weierstrass to conclude that $\bar{A}$ is dense in $C(K)$, so $\bar{A}=C(K)$. Hence that $A$ is dense in $C(K)$.

Proof of Proposition 4.2.9. We only need to prove that if $f \in A$ then also $|f| \in A$. As $A$ is an algebra and $|f|=\sqrt{f^{2}}$, we only need to prove that if $g \in A$ and $g \geq 0$, then $\sqrt{g} \in A$.

Let us suppose in the first instant that $g>\delta>0$ for some small $\delta \in(0,1)$. By scaling, we may also suppose that $g<2-\delta$. Then the function $h=1-g$ satisfies $|h| \leq 1-\delta$. Note that $x:=1-\sqrt{g}$ satisfies

$$
(1-x)^{2}=g=1-h \Longleftrightarrow x=\frac{1}{2}\left(h+x^{2}\right) .
$$

Thus, we only need to show that this fixed point equation is solvable for $x \in A$.
Indeed, let $T(a)=\frac{1}{2}\left(h+a^{2}\right.$ ) and $B=\{a \in A:|a| \leq 1-\delta\}$ (which is a complete metric space). By triangle inequality, $T$ maps $B$ into itself. Moreover, it is also a contraction:

$$
|T(a)-T(b)|=\frac{1}{2}|a+b||a-b| \leq(1-\delta)|a-b| \Longrightarrow\|T(a)-T(b)\| \leq(1-\delta)\|a-b\| .
$$

By the contraction mapping theorem, $T$ has a fixed point in $B$, which is our desired $x \in$ $B \subset A$.

In the general case when we only know that $g \geq 0$, the above shows that $(g+1 / k)^{1 / 2} \in A$ for all $k>0$. Therefore, $\sqrt{g}$, being the uniform limit of $\left((g+1 / k)^{1 / 2}\right)$ (justify this!), also belongs to $A$ (as $A$ is closed).

Remark 4.2.10 (Non-examinable). There are various direct ways of proving Weierstrass's theorem on the density of polynomials e.g. in $C([0,1])$. One can prove e.g. that given any $f \in C([0,1])$ the so called Bernstein polynomials

$$
p_{n}(t):=\sum_{k=0}^{n}\binom{n}{k} t^{k}(1-t)^{k} f\left(\frac{k}{n}\right)
$$

converge to $f$ uniformly, or follow the original proof of Weierstrass using the Weierstrass transform.

Example 4.2.11 (An application of Weierstrass's theorem). We claim that the only continuous real valued function $f \in C[0,1]$ for which

$$
\int_{0}^{1} f(t) t^{n} d t=0 \text { for every } n \in \mathbb{N}
$$

is the zero function. To see this, we let $X=C[0,1]$ (as always equipped with the sup norm) and we note that any function $f \in C[0,1]$ induces a bounded linear functional $F \in$ $X^{*}=\mathscr{B}(X, \mathbb{R})$ defined by $F(x)=\int_{0}^{1} f(t) x(t) d t$, where we note that $F$ is bounded since $|F x| \leq\|f\|_{\text {sup }}\|x\|_{\text {sup }}$, so $\|F\|_{X^{*}} \leq\|f\|_{\text {sup }}$. If $f$ satisfies $(\star)$ then, by linearity, $F(p)=0$ for every polynomial. Since the polynomials are dense in $X$ we can thus apply Theorem 4.1.3 to obtain that $F=0$, in particular $F(f)=\int f^{2}(t) d t=0$. But as $f^{2} \geq 0$ this implies that $f^{2}=0$ a.e. and so as $f$ is continuous indeed $f=0$.

### 4.3 Approximation of functions in $L^{p}$

In many applications where one works with $L^{p}$ spaces, the following result is very useful
Theorem 4.3.1. For any $1 \leq p<\infty$ and any compact set $K \subset \mathbb{R}^{n}$ the space $C^{\infty}(K)$ of smooth functions is dense in $L^{p}(K)$.

WARNING. This result is wrong for $p=\infty$ as you can easily see when trying to approximate step functions by continuous functions.

The proof of this result is non-examinable (though the result and its applications are examinable), and we only sketch the proof to introduce the important concept of mollifying an integrable function to obtain a smooth function which is a good approximation to the given (in general not even continuous) function. This concept is widely used in theory of and applications to PDEs and more on this topic can be found in particular in the courses B4.3 Distribution Theory and C4.1 Functional analytic methods for PDEs.

Sketch of proof of Theorem 4.3.1 (non-examinable).
We let $\phi: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be defined by

$$
\phi(x):=c \begin{cases}\exp \left(-\frac{1}{1-|x|^{2}}\right), & \quad|x|<1 \\ 0 & \text { else }\end{cases}
$$

where $c>0$ is chosen so that $\int_{\mathbb{R}^{n}} \phi(x) d x=1$ and set $\phi_{\varepsilon}(x):=\frac{1}{\varepsilon^{n}} \phi\left(\frac{x}{\varepsilon}\right)$. These smooth functions $\phi_{\varepsilon}$ (which are often called 'mollification kernels' or a family of 'standard mollifiers') have $\int_{\mathbb{R}^{n}} \phi_{\varepsilon}=1$ and are zero outside of $B_{\varepsilon}(0)$. One can get a sequence $f_{\varepsilon}$ of smooth functions that approximates a given $f \in L^{p}(K)$ as follows: We extend $f$ by zero outside of $K$ to get a function that is defined on all of $\mathbb{R}^{n}$ and then set

$$
f_{\varepsilon}:=\phi_{\varepsilon} * f, \text { i.e. define } f_{\varepsilon}(x):=\int_{\mathbb{R}} \phi(x-y) f(y) d y
$$

Then one can easily check that $f_{\varepsilon} \in C^{\infty}\left(\mathbb{R}^{n}\right)$ with derivatives $D^{\alpha} f_{\varepsilon}=\left(D^{\alpha} \phi_{\varepsilon}\right) * f$ (follows from the differentiation theorem from Part A Integration) and one can indeed prove that $f_{\varepsilon} \rightarrow f$ in $L^{p}$ (though this proof requires more care and uses properties of $L^{p}$ functions that we do not require elsewhere in the course).

## Chapter 5

## Separability

Many but not all spaces we have encountered so far have the following useful property
Definition 5.0.1. A normed space $(X,\|\cdot\|)$ is called separable if there exists a countable set $D \subset X$ which is dense. A space which is not separable is called inseparable.

To prove that a space is separable/inseparable it can be useful to note
Lemma 5.0.2. (i) Let $X$ be a vector space and let $\|\cdot\|$ and $\|\cdot\|^{\prime}$ be two norms on $X$ that are equivalent. Then $(X,\|\cdot\|)$ and $\left(X,\|\cdot\|^{\prime}\right)$ are either both separable or both inseparable.
(ii) Let $\left(X,\|\cdot\|_{X}\right)$ and $\left(Y,\|\cdot\|_{Y}\right)$ be two normed spaces which are isometrically isomorphic, i.e. so that there exists a linear bijection $i: X \rightarrow Y$ so that $\|i(x)\|_{Y}=\|x\|_{X}$ for all $x \in X$. Then $\left(X,\|\cdot\|_{X}\right)$ and $\left(Y,\|\cdot\|_{Y}\right)$ are either both separable or both inseparable.

Proof. As equivalent norms lead to the same notion of convergent sequences we obtain that a set $D \subset X$ is dense in $(X,\|\cdot\|)$ if and only if it is dense in $\left(X,\|\cdot\|^{\prime}\right)$. Hence (i) follows. Similarly, to obtain (ii) we note that if $D \subset X$ is dense and if $i: X \rightarrow Y$ is an isometric isomorphism then $\tilde{D}:=i(D) \subset Y$ is dense as for any $y \in Y$ we can choose $d_{n} \in D$ so that $d_{n} \rightarrow x:=i^{-1}(y)$ and thus get a sequence $\tilde{d}_{n}=i\left(d_{n}\right) \in \tilde{D}$ that converges to $y$ since

$$
\left\|y-\tilde{d}_{n}\right\|_{Y}=\left\|i(x)-i\left(d_{n}\right)\right\|_{Y}=\left\|i\left(x-d_{n}\right)\right\|_{Y}=\left\|x-d_{n}\right\|_{X} \underset{n \rightarrow \infty}{\longrightarrow} 0
$$

We also recall from prelims that

- $\mathbb{Q} \subset \mathbb{R}$ and $\mathbb{Q}+\mathrm{i} \mathbb{Q} \subset \mathbb{C}$ are dense, so both $\mathbb{F}=\mathbb{R}$ and $\mathbb{F}=\mathbb{C}$ are separable
- Finite products $A_{1} \times \ldots \times A_{n}$ and countable unions $\bigcup_{j \in \mathbb{N}} A_{j}$ of countable sets are countable.

This allows us to show in particular
Proposition 5.0.3. Every finite dimensional normed space $\left(X,\|\cdot\|_{X}\right)$ is separable.
For simplicity of notation we will carry out this proof just for real normed spaces and remark that the exact same proof, with $\mathbb{R}$ replaced by $\mathbb{C}$ and $\mathbb{Q}$ replaced by $\mathbb{Q}+i \mathbb{Q}$ applies in the complex case.

Proof. We first show that $\mathbb{R}^{n}$ equipped with the 1 norm is separable. Indeed, given any $x=\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{R}^{n}$ and any $\varepsilon>0$ we can use that $\mathbb{Q}$ is dense in $\mathbb{R}$ to choose $q_{i} \in Q$ so that $\left|x_{i}-q_{i}\right|<\frac{\varepsilon}{n}$ and hence $\left\|x-\left(q_{1}, \ldots, q_{n}\right)\right\|<\varepsilon$. As $\mathbb{Q}^{n}$ is countable we thus get that $\left(\mathbb{R}^{n},\|\cdot\|_{1}\right)$ is separable. As every other norm $\|\cdot\|$ on $\mathbb{R}^{n}$ is equivalent to $\|\cdot\|_{1}$ we thus get that also $\left(\mathbb{R}^{n},\|\cdot\|\right)$ is separable thanks to Lemma 5.0.2.

Given any other real finite dimensional vector space $\left(X,\|\cdot\|_{X}\right)$ we let $Q: \mathbb{R}^{n} \rightarrow X$ be the isomorphims introduced in (3.2) and note that $Q$ is an isometric isomorphism if we equip $\mathbb{R}^{n}$ with the norm $\|x\|:=\|Q x\|_{X}$. The separability of $(X,\|\cdot\|)$ thus follows from the separability of $\left(\mathbb{R}^{n},\|\cdot\|\right)$ and Lemma 5.0.2.

While many of the spaces we have seen so far are separable, not all of them are and the most prominent examples of non-separable spaces are

Proposition 5.0.4 ( $\ell^{\infty}$ and $L^{\infty}$ are inseparable). The sequence space ( $\ell^{\infty}(\mathbb{F}),\|\cdot\|_{\infty}$ ) and the function spaces $L^{\infty}(\Omega), \Omega \subset \mathbb{R}^{n}$ any non-empty open set, are inseparable.

We provide the proof of this result for the sequence space $\ell^{\infty}$ and note that a very similar proof, using characteristic functions of sets, shows that also $L^{\infty}$ is inseparable.

Proof. We recall that the set $A:=\left\{a=\left(a_{1}, a_{2}, \ldots\right): a_{i} \in\{0,1\}\right\}$ is uncountable and note that for this subset of $\ell^{\infty}$ the distance of any two elements $a \neq \tilde{a}$ is $\|a-\tilde{a}\|_{\infty}=1$.

Let now $D$ be any dense subset of $\ell^{\infty}$. Then given any $a \in A$ there must be an element $d_{a} \in D$ so that $\left\|d_{a}-a\right\|<\frac{1}{2}$ and we define a function $f: A \rightarrow D$ by assigning to each $a$ such an element $d_{a}$. We note that $d_{a}=d_{\tilde{a}}$ implies that $\|a-\tilde{a}\|=\left\|a-d_{a}+d_{\tilde{a}}-\tilde{a}\right\| \stackrel{\Delta}{\leq}$ $\left\|a-d_{a}\right\|+\left\|\tilde{a}-d_{\tilde{a}}\right\|<1$ and hence that $a=\tilde{a}$ so this map is injective. Since $A$ is uncountable, we thus obtain that any dense subset of $\ell^{\infty}$ is uncountable. Hence $\ell^{\infty}$ is inseparable.

To prove separability of spaces we can use the following two results
Lemma 5.0.5. Let $\left(X,\|\cdot\|_{X}\right)$ be a normed space, $Y \subset X$ a subspace (which we equip as always with the same norm $\left.\|\cdot\|_{X}\right)$. Suppose that $D \subset\left(Y,\|\cdot\|_{X}\right)$ is dense and that $Y \subset\left(X,\|\cdot\|_{X}\right)$ is dense. Then also $D \subset X$ is dense.

WARNING. Here we crucially use that the sets $D \subset Y$ and $Y \subset X$ are dense with respect to the same norm.

This lemma follows from a simple $\varepsilon / 2$ argument: Given $x \in X$ and $\varepsilon>0$ we use that $Y$ is dense in $X$ to choose $y \in Y$ so that $\|x-y\|_{X}<\frac{\varepsilon}{2}$ and then use that $D \subset Y$ is dense to choose $d \in D$ with $\|d-y\|_{X}<\frac{\varepsilon}{2}$.

Proposition 5.0.6. Let $(X,\|\cdot\|)$ be a normed space and suppose that there exists a countable set $S$ so that $\operatorname{span}(\bar{S})$ is dense in $X$. Then $X$ is separable.

Here we recall that the span of a subset $A \subset X$ is the set of all finite linear combinations, i.e.

$$
\operatorname{span}(S):=\left\{\sum_{j=1}^{N} \lambda_{j} s_{j}: \lambda_{j} \in \mathbb{F}, s_{j} \in S, N \in \mathbb{N}\right\}
$$

and note that since $\operatorname{span}(S) \subset \operatorname{span}(\bar{S})$ the above proposition implies in particular that if there is a countable set $S$ whose span is dense in $X$ then $X$ is separable

As before, we carry out the proof for real normed spaces and remark that the exact same proof, with $\mathbb{R}$ and $\mathbb{Q}$ replaced by $\mathbb{C}$ and $\mathbb{Q}+i \mathbb{Q}$, apply in the complex case.

Proof. We prove that if $\operatorname{span}(\bar{S})$ is dense, then also the set

$$
Y:=\left\{\sum_{i=1}^{N} a_{i} s_{i}: a_{i} \in \mathbb{Q}, s_{i} \in S, N \in \mathbb{N}\right\}
$$

of rational linear combinations of elements of the set $S$ is dense in $X$.
Indeed given any $x \in X$ and any $\varepsilon>0$ we can first use that $\operatorname{span}(\bar{S})$ is dense in $X$ to determine $\bar{s}_{j} \in \bar{S}$ and $a_{j} \in \mathbb{R}, j=1, \ldots, N$, so that $\left\|x-\sum_{j=1}^{N} a_{j} \bar{s}_{j}\right\|<\varepsilon / 3$. In a second step we can now use that every element in the closure $\bar{S}$ of a set can be approximated by elements of the set $S$ to determine $s_{j} \in S$ so that for every $j$ we have $\left|a_{j}\right|\left\|s_{j}-\bar{s}_{j}\right\|<\frac{\varepsilon}{3 N}$. Finally, we use that $\mathbb{Q}$ is dense in $\mathbb{R}$ to determine rational numbers $b_{i}$ so that for every $j$ also $\left|a_{j}-b_{j}\right| \cdot\left\|s_{j}\right\|<\frac{\varepsilon}{3 N}$. All in all we hence obtain an element $y=\sum_{j=1}^{N} b_{j} s_{j}$ of $Y$ for which

$$
\begin{align*}
\|x-y\| & \stackrel{\Delta}{\leq}\left\|x-\sum_{j=1}^{N} a_{j} \bar{s}_{j}\right\|+\left\|\sum_{j=1}^{N}\left(a_{j} \bar{s}_{j}-b_{j} s_{j}\right)\right\|<\varepsilon / 3+\sum_{j=1}^{N}\left\|a_{j} \bar{s}_{j}-a_{j} s_{j}+a_{j} s_{j}-b_{j} s_{j}\right\| \\
& \stackrel{\Delta}{\leq} \varepsilon / 3+\sum_{j=1}^{N}\left|a_{j}\right|\left\|s_{j}-\bar{s}_{j}\right\|+\sum_{j=1}^{N}\left|a_{j}-b_{j}\right|\left\|s_{j}\right\|<\varepsilon \tag{5.1}
\end{align*}
$$

To conclude the proof of the proposition it is thus enough to show that $Y$ is countable. Writing $S=\left\{s_{1}, s_{2}, \ldots\right\}$ we obtain a surjective map $f: A \rightarrow S$ from the set

$$
A:=\bigcup_{N \in \mathbb{N}}\left\{\left(a_{1}, \ldots\right): a_{k} \in \mathbb{Q} \text { and } a_{k}=0 \text { for every } k \geq N+1\right\}
$$

of finite rational sequences to $Y$ by defining $s(a):=\sum_{j} a_{j} s_{j}$ for $a \in A$ (we note that this sum is well defined as only finitely many terms are non-zero). As $A$ is the countable union of sets that are bijective to $\mathbb{Q}^{N}$, we know that $A$ is countable and hence that also $Y$ is countable.

We are now in the position to prove that the following important Banach spaces are separable.

Proposition 5.0.7 (Separablility of $\ell^{p}$ and $L^{p}$ for $1 \leq p<\infty$ and of $C(K)$ ).

- $C(K)$ is separable for any compact set $K \subset \mathbb{R}^{n}$.
- The sequence space $\ell^{p}(\mathbb{F}), F=\mathbb{R}$ or $\mathbb{F}=\mathbb{C}$, is separable for $1 \leq p<\infty$.
- The function spaces $L^{p}(K)$ is separable for any compact subset $K \subset \mathbb{R}^{n}$ and any $1 \leq p<\infty$.

We remark that more generally $L^{p}(\Omega)$ is separable for arbitrary (measurable) domains $\Omega \subset \mathbb{R}^{n}$ and $1 \leq p<\infty$.

Proof of Proposition 5.0.7.
Proof of (i):
The set of monomials $\left\{x^{\alpha}=x_{1}^{\alpha_{1}} \ldots x_{n}^{\alpha_{n}}, \alpha \in \mathbb{N}_{0}^{n}\right\}$ is countable and by Weierstrass's Theorem we know that its span, i.e. the space of polynomials, is dense in $C(K)$. By Proposition 5.0.6 we thus get that $C(K)$ is separable.

Proof of (ii): We let $Y:=\operatorname{span}(S)$ where the countable set $S=\left\{e^{(k)}, k \in \mathbb{N}\right\}$ consists of all sequences $e^{(k)}$ for which the $e_{j}^{(k)}=\delta_{j}^{k}$.

Given any element $x=\left(x_{1}, \ldots\right) \in \ell^{p}$ we can now use that since $\sum_{j=1}^{\infty}\left|x_{j}\right|^{p}$ converges, we obtain that the cut-off sequences $x^{(k)}:=\left(x_{1}, \ldots, x_{k}, 0,0, \ldots\right)$ approximate $x$ in the sense of $\ell^{p}$, namely $\left\|x-x^{(k)}\right\|_{\ell^{p}}=\left(\sum_{j \geq k+1}\left|x_{j}\right|^{p}\right)^{1 / p} \rightarrow 0$ as $k \rightarrow \infty$. We thus conclude that $Y$ is dense in $\ell^{p}$ and thus obtain from Proposition 5.0.6 that $\ell^{p}$ is separable.

Proof of (iii), Variant 1 (using Theorem 4.3.1):
From Theorem 4.3.1 we know that $C^{\infty}(K)$ is dense in $L^{p}(K)$ and hence in particular that $C(K)$ is dense in $L^{p}(K)$. We now claim that $C(K)$ is separable also when equipped with the $L^{p}$ norm instead of the usual sup-norm. Indeed as $\|f\|_{L^{p}} \leq\left(\int_{K}\|f\|_{\text {sup }}^{p}\right)^{1 / p} \leq \mathcal{L}^{n}(K)^{1 / p}\|f\|_{\text {sup }}$ we know that if a sequence $f_{n}$ converges to some element $f \in C(K)$ in the usual sense of the sup-norm, then also

$$
\left\|f_{n}-f\right\|_{L^{p}} \leq \mathcal{L}^{n}(K)^{1 / p}\left\|f_{n}-f\right\|_{s u p} \rightarrow 0
$$

Hence any set $D \subset C(K)$ that is dense with respect to the sup-norm, will also be dense with respect to the $L^{p}$ norm. In particular the set of polynomials is dense also in $\left(C(K),\|\cdot\|_{L^{p}}\right)$. Combined with the density of $C(K) \subset L^{p}(K)$ and Lemma 5.0.5 we thus conclude that the
space of polynomials is dense in $L^{p}(K)$. The claim that $L^{p}$ is separable hence again follows from Proposition 5.0.6 and the fact that the space of polynomials is spanned by the countable set $\left\{x^{\alpha}, \alpha \in \mathbb{N}_{0}^{n}\right\}$ of monomials.

Proof of (iii), Variant 2 (using density of step functions) for $K=[a, b]$ :
We use without proof the fact that the space of step functions, that is finite linear combinations of characteristic functions of intervals, is dense in $L^{p}$. We then note that given any interval $[c, d] \subset[a, b]$ with real endpoints, we can choose $c_{n}, d_{n} \in \mathbb{Q}$ so that $c_{n} \rightarrow c$ and $d_{n} \rightarrow d$ and that this guarantees that $\chi_{\left[c_{i}, d_{i}\right]} \rightarrow \chi_{[c, d]}$ in $L^{p}$ as $\left\|\chi_{[c, d]}-\chi_{\left[c_{i}, d_{i}\right]}\right\| \leq\left(\left|c-c_{i}\right|+\left|d-d_{i}\right|\right)^{1 / p} \rightarrow 0$. Hence also the span of all characteristic functions $\chi_{[c, d]}$ of intervals with rational endpoints is dense in $L^{p}$ and as the set of such functions $\left\{\chi_{[c, d]}, c<d, c, d \in \mathbb{Q}\right\}$ is countable we obtain from Proposition 5.0.6 that $L^{p}([a, b])$ is separable.

Once we have established that a space e.g. $C(K)$ is separable, we get for free that also any subspace (equipped with the same norm) is separable:

Proposition 5.0.8. Let $\left(X,\|\cdot\|_{X}\right)$ be a separable normed space and let $Y$ be a subspace of $X$. Then also $\left(Y,\|\cdot\|_{X}\right)$ is separable.

Here it is very important that the subspace is equipped with the norm of $X$, not any other norm. E.g. we can see $L^{\infty}([0,1])$ as a subspace of $L^{1}([0,1])$ and the above proposition implies that if we were to equip $L^{\infty}([0,1])$ with the $L^{1}$ norm (which is not often done in practice as we would end up with a space that is not complete) then this would give us a separable normed space, while $L^{\infty}([0,1])$ equipped with the 'correct norm', i.e. the $L^{\infty}$ norm, is not separable (however it is complete which in practice is more important).

Proof of Proposition 5.0.8. As $X$ is separable there exists a countable dense subset $D_{X}:=$ $\left\{x_{k}, k \in \mathbb{N}\right\} \subset X$. To prove that $Y$ is separable, we now need to determine a subset of $Y$ that is dense in $Y$. To this end, we use that (by the definition of the infimum) we can choose for any $k, n \in \mathbb{N}$ an element $y_{k, n} \in Y$ so that

$$
\left\|x_{k}-y_{k, n}\right\| \leq \operatorname{dist}\left(x_{k}, Y\right)+\frac{1}{n}=\inf _{y \in Y}\left\|x_{k}-y\right\|+\frac{1}{n}
$$

note that $D:=\left\{y_{k, n}, k, n \in \mathbb{N}\right\}$ is countable. We claim that $D \subset Y$ is dense. Indeed, given any $y \in Y$ and any $\varepsilon>0$ we can first use that $D_{X}$ is dense in $X$ to find some $x_{k}$ with $\left\|y-x_{k}\right\|<\frac{\varepsilon}{3}$, which we note implies in particular that $\operatorname{dist}\left(x_{k}, Y\right)<\frac{\varepsilon}{3}$. Choosing $n$ large enough so that $\frac{1}{n}<\frac{\varepsilon}{3}$ we hence know that $\left\|x_{k}-y_{k, n}\right\|<\operatorname{dist}\left(x_{k}, Y\right)+\frac{\varepsilon}{3}<\frac{2 \varepsilon}{3}$ and hence get that

$$
\left\|y-y_{k, n}\right\| \leq\left\|y-x_{k}\right\|+\left\|x_{k}-y_{k, n}\right\|<\frac{\varepsilon}{3}+\frac{2 \varepsilon}{3}=\varepsilon .
$$

Finally we want to give a brief outlook on the use of separability and density of subspaces:

- Existence of a basis? One might ask whether for separable space $(X,\|\cdot\|)$ there is a 'useful notion' of basis of a space, and whether in a separable space one can expect such a basis to have good properties (e.g. be countable). There are several notions of basis for normed spaces that will be discussed in part C Functional Analysis, and while every space admits a so called Hamel basis $S$ (a set $S$ so that every element of $X$ can be written as finite linear combination of elements in $S$ and that is so that that every finite subset of $S$ is linearly independent), such Hamel bases are not much use in practice as one can show that a Hamel basis of a Banach space is either finite (if $X$ is finite dimensional) or else uncountable (c.f. Part C Functional Analysis ). A more useful notion of basis is that of a Schauder basis (a set $\left\{s_{1}, s_{2}, \ldots\right\}$ so that every $x \in X$ has a unique norm-convergent representation $x=\sum_{j=1}^{\infty} \lambda_{j} s_{j}$ ) and such a Schauder basis exists only for separable spaces (though as you will see in Part C Functional Analysis not for every separable space).

In the special case of Hilbert-spaces one can show the following stronger and very useful result which you will prove in B4.3 Functional Analysis 2: Every separable Hilbert space has a countable orthonormal basis $\left\{e_{n}\right\}$, where a set $S$ is called an orthogonal basis of a Hilbert space $X$ if its elements are orthogonal, have $\|s\|=1$ and $\operatorname{span}(S)$ is dense in $X$.

- Simplifications of proofs: The main application of separability in the present course will be that it will allow us to give a proof of some of our main results in case of separable spaces, most notably the Theorem of Hahn-Banach that we discuss in the next section, that avoid the use of Zorn's lemma.
- In applications, it is often possible to reduce the proof of a property or inequality to first proving the claim for a dense subset of "nice" elements of the space, such as smooth functions in case of $L^{p}$ and then a second step that uses the density of such functions to prove that this property extends to the whole space. Similarly, as a bounded linear operator $T \in \mathscr{B}(Y, Z), Z$ a Banach space, that is defined on a dense subspace $Y \subset X$ has a unique extension to an element $T \in \mathscr{B}(X, Z)$, in many instances one defines operators first on a dense subset of "nice" elements (e.g. continuous functions) and then extends this operator to the whole space.

Many instances of such arguments can be seen in the Part C course on Functional analytic methods for PDEs.

- Approximating problems on infinite dimensional spaces by finite dimensional problems:

For separable spaces there exists a sequence of finite dimensional subspaces $Y_{1} \subset Y_{2} \subset$ $\ldots$ of $X$ so that $\bigcup Y_{i}$ is dense in $X$. This property is used in many instances (be it to try to prove the existence of a solution of a problem, like a PDE, or more practically in numerics to obtain an approximate solution) when considering problems on separable

Banach spaces (e.g. subspace of $L^{p}, 1 \leq p<\infty$ ). The idea of this method (also called Galerkin's method) is to first determine solutions $x_{n} \in Y_{n}$ of approximate problems defined on the finite dimensional spaces $Y_{n}$, where results from Linear Algebra such as the rank-nullity theorem apply (and e.g. ensure that an operator $T: Y_{j} \rightarrow Y_{j}$ is invertible if and only if it is injective) and then hope to obtain that $x_{n}$ converges to a solution $x$ of the original problem (in some sense, usually one only obtains so called "weak convergence", see Part C courses on Functional Analysis and Fixed Point Methods for Nonlinear PDEs), respectively in applications in numerical analysis that $x_{n}$ provides a good approximation of the solution.

## Chapter 6

## The Theorem of Hahn-Banach and applications

The most important special case of linear operators between Banach spaces is the space of bounded linear functionals, i.e. bounded linear maps into $\mathbb{R}$ (respectively $\mathbb{C}$ ).

Definition 6.0.1. Let $(X,\|\cdot\|)$ be a normed space. Then the dual space of $X$ is defined as
$X^{*}:=\mathscr{B}(X, \mathbb{F})$ equipped with the operator norm

$$
\|f\|_{X^{*}}:=\inf \{M:|f(x)| \leq M\|x\| \text { for every } x \in X\}
$$

where as always $\mathbb{F}=\mathbb{R}$ if $(X,\|\cdot\|)$ is a real normed space, respectively $\mathbb{F}=\mathbb{C}$ for complex spaces.

We remark that since $\mathbb{R}$ (and $\mathbb{C}$ ) are complete we know from Theorem 2.2.1 that the dual space of any normed space is complete.

We also recall that for any $f \in X^{*}$

$$
|f(x)| \leq\|f\|\|x\| \text { for all } x \in X
$$

We note that if $f \in X^{*}$ and $Y$ is a subspace of $X$ (as always equiped with the same norm to turn it into a normed space), then we can restrict any $f \in X^{*}$ to obtain an element $\left.f\right|_{Y}$ of $Y^{*}$, where we of course set $\left.f\right|_{Y}(y):=f(y)$. We note that the definition of the operator norm immediately implies that $\left\|\left.f\right|_{Y}\right\|_{Y^{*}} \leq\|f\|_{X^{*}}$.

Conversely we may ask whether we can extend a functional $g \in Y^{*}$ to a bounded linear operator $G \in X^{*}$, where we call such a $G$ an extension of $g$ provided $\left.G\right|_{Y}=g$.

We have already seen that if $Y$ is dense in $X$ such an extension not only exists, but is furthermore unique and indeed the extension operator $E: Y^{*} \rightarrow X^{*}$ is an isometric isomorphims=, compare Theorem 4.1.3. While this result holds true for linear operators
into a general Banach space, the results that we will prove in this chapter are valid only for elements of the dual space, i.e. functions that map into the corresponding field $\mathbb{F}=\mathbb{R}$ respectively $\mathbb{F}=\mathbb{C}$.

The main result in this chapter is the Theorem of Hahn-Banach, that assures in particular that we can indeed extend any element $f \in Y^{*}, Y$ an arbitrary subspace of $X$, to an operator $F \in X^{*}$ without increasing its operator norm, compare Theorem 6.1.1 below.

### 6.1 Statement of the Theorem of Hahn-Banach

The first version of the Theorem of Hahn-Banach shows that we can not only extend bounded linear functionals from a subspace to the whole space, but we can do this in a way that does not increase their operator norm, namely

Theorem 6.1.1 (Theorem of Hahn-Banach on the existence of a bounded extension). Let $X$ be a (real or complex) normed space, $Y \subset X$ a subspace and let $f \in Y^{*}$ be any given element of the dual space of $Y$. Then there exists an extension $F \in X^{*}$ of $f$, i.e. an element $F$ of $X^{*}$ so that $\left.F\right|_{Y}=f$, so that

$$
\|F\|_{X^{*}}=\|f\|_{Y^{*}}
$$

To keep things simple, in the rest of this section, we only discuss the case when $X$ is real. We note that for any extension $F \in X^{*}$ we trivially have the inequality

$$
\|F\|_{X^{*}}=\sup _{x \in X,\|x\|=1}|F(x)| \geq \sup _{y \in Y,\|y\|=1}|F(y)|=\sup _{y \in Y,\|y\|=1}|f(y)|=\|f\|_{Y^{*}}
$$

so to prove the above result it is enough to prove that there exists a linear extension of $f$ so that $|F(x)| \leq p(x)$ for all $x \in X$ where we set $p(x):=\|f\|\|x\|$. We note that as $F$ is linear, this condition is equivalent to having

$$
F(x) \leq p(x)=\|f\|\|x\| \text { for all } x \in X
$$

as this then also implies that $-F(x)=F(-x) \leq\|f\|\|x\|$. We also recall that we are dealing with real vector spaces, and hence functionals with values in $\mathbb{R}$, so the above inequality is well defined.

Indeed the general version of the Hahn-Banach Theorem assures that such an extension exists for a much larger class of functions $p$ than just the $p(x)=\|f\|\|x\|$ that we obtain in the context of Theorem 6.1.1, namely for all $p: X \rightarrow \mathbb{R}$ that are so called sublinear:

Definition 6.1.2. Let $X$ be a real vector space. Then $p: X \rightarrow \mathbb{R}$ is called sublinear if for every $x, y \in X$ and every $\lambda \geq 0$ we have that

$$
p(x+y) \leq p(x)+p(y) \text { and } p(\lambda x)=\lambda p(x)
$$

We note that we do not require that $p$ is non-negative. We also note that every norm, and indeed every seminorm, on $X$ is a sublinear functional. There are also many other constructions that yield sublinear functions that are important in applications (as discussed e.g. in Part C Further Functional Analysis), such as the so called Minkowski functional associated to each convex set $C$ that contains the origin, compare section 6.4.

To get a simple example of a sublinear functional that is not induced by a semi-norm, we can consider any linear function $p: X \rightarrow \mathbb{R}$, or to a get a more geometric example consider $p: \mathbb{R}^{n} \rightarrow \mathbb{R}$ that is defined by $p(x)=\max \left(x_{n}, 0\right)$, i.e. that is given by the distance of a point $x$ to the halfspace $\left\{x: x_{n} \leq 0\right\}$.

The general version of the Theorem of Hahn-Banach (for real vector spaces) is
Theorem 6.1.3 (Theorem of Hahn-Banach (general sublinear version)). Let $X$ be a real vector space, $Y \subset X$ a subspace and $p: X \rightarrow \mathbb{R}$ sublinear. Suppose that $f: Y \rightarrow \mathbb{R}$ is a linear functional with the property that

$$
f(y) \leq p(y) \text { for all } y \in Y
$$

Then there exists a linear extension $F: X \rightarrow \mathbb{R}$ so that

$$
F(x) \leq p(x) \text { for all } x \in X
$$

WARNING. The Theorem of Hahn-Banach is specific to functionals, that is maps from a vector space to the corresponding field $\mathbb{F}$, and does not hold true for linear operators between two normed spaces.

One can e.g. show that there is no continuous linear extension of the identity map Id $: c_{0} \rightarrow c_{0}$ to a map $f: \ell^{\infty} \rightarrow c_{0}$ where $c_{0} \subset \ell^{\infty}$ denotes the closed subspace of all sequences that tend to zero.

### 6.2 A very special case of the Theorem of Hahn-Banach

In this course we shall only give the proof of a very special case of the Theorem of HahnBanach.

Lemma 6.2.1 (1-step extension lemma). Let $X$ be a real vector space, $p: X \rightarrow \mathbb{R}$ sublinear and let $Y, \tilde{Y}$ be subspaces of $X$ which are so that there exists some $x_{0} \in X$ so that

$$
\tilde{Y}=\operatorname{span}\left(Y \cup\left\{x_{0}\right\}\right)
$$

Then for any linear $f: Y \rightarrow \mathbb{R}$ for which $f(y) \leq p(y)$ for all $y \in Y$ there exists a linear extension $\tilde{f}: \tilde{Y} \rightarrow \mathbb{R}$ so that

$$
\tilde{f}(\tilde{y}) \leq p(\tilde{y}) \text { for all } \tilde{y} \in \tilde{Y} .
$$

Proof of Lemma 6.2.1. If $x_{0} \in Y$ then the claim is trivial as $\tilde{Y}=Y$. So suppose instead that $x_{0} \notin Y$. Then we can write every $\tilde{y} \in \tilde{Y}$ uniquely as

$$
\tilde{y}=y+\lambda x_{0} \text { for some } \lambda \in \mathbb{R}
$$

so given any number $r \in \mathbb{R}$ we obtain a well defined linear map $\tilde{f}_{r}: \tilde{Y} \rightarrow \mathbb{R}$ if we set

$$
\tilde{f}_{r}\left(y+\lambda x_{0}\right):=f(y)+\lambda r \text { for every } y \in Y \text { and } \lambda \in \mathbb{R}
$$

and note that $\left.\tilde{f}_{r}\right|_{Y}=f$ no matter how $r$ is chosen. We now need to show that we can choose $r$ so that this function $\tilde{f}$ has the required property that $\tilde{f}_{r}(\tilde{y}) \leq p(\tilde{y})$ for all $\tilde{y} \in \tilde{Y}$, which is equivalent to

$$
\begin{equation*}
\lambda r \leq p\left(y+\lambda x_{0}\right)-f(y) \text { for all } y \in Y, \lambda \in \mathbb{R} \tag{6.1}
\end{equation*}
$$

We first note that for $\lambda=0$ this is trivially true no matter how $r$ is chosen as by assumption $f \leq p$ on $Y$.

For $\lambda>0$ the above inequality (6.1) holds true if and only if

$$
r \leq \frac{1}{\lambda}\left[p\left(y+\lambda x_{0}\right)-f(y)\right]=p\left(\frac{1}{\lambda} y+x_{0}\right)-f\left(\frac{1}{\lambda} y\right)
$$

for all $y \in Y$ or equivalently, setting $v=\frac{1}{\lambda} y$ and using that $Y$ is a vector space, if and only if

$$
\begin{equation*}
r \leq \inf _{v \in Y}\left(p\left(v+x_{0}\right)-f(v)\right) \tag{6.2}
\end{equation*}
$$

For $\lambda<0$ we write $\lambda=-|\lambda|$ to rewrite (6.1) as $-|\lambda| r \leq p\left(y-|\lambda| x_{0}\right)-f(y)$. We hence obtain that (6.1) is satisfied for all $\lambda<0$ and $y \in Y$ if and only if

$$
r \geq-|\lambda|^{-1}\left(p\left(y-|\lambda| x_{0}\right)-f(y)\right)=f\left(|\lambda|^{-1} y\right)-p\left(|\lambda|^{-1} y-x_{0}\right)
$$

i.e. if and only if $r$ is chosen so that

$$
\begin{equation*}
r \geq \sup _{w \in Y}\left(f(w)-p\left(w-x_{0}\right)\right) \tag{6.3}
\end{equation*}
$$

For $\tilde{f}_{r}$ to be the required extension we thus need to choose $r$ so that both (6.2) and (6.3) hold, which is possible provided

$$
\inf _{v \in Y}\left(p\left(v+x_{0}\right)-f(v)\right) \geq \sup _{w \in Y}\left(f(w)-p\left(w-x_{0}\right)\right)
$$

However this easily follows since for any $v, w \in Y$ we have that

$$
\begin{aligned}
\left(p\left(v+x_{0}\right)-f(v)\right)-\left(f(w)-p\left(w-x_{0}\right)\right) & =p\left(v+x_{0}\right)+p\left(w-x_{0}\right)-f(v+w) \\
& \geq p(v+w)-f(v+w) \geq 0
\end{aligned}
$$

where we use the sublinearity of $p$ in the second and the assumption that $f \leq p$ on $Y$ in the last step.

The proof of the general version of Hahn-Banach uses this lemma together with an argument based on Zorn's lemma to obtain the desired extension as a maximal element of a partially ordered set of pairs $(\tilde{Y}, \tilde{f})$ of subspaces $\tilde{Y}$ of $X$ that contain $Y$ and extensions $\tilde{f}$ of $f$ with $\tilde{f} \leq p$. This will be carried out in detail in C4.1 Further Functional Analysis.

### 6.3 Some applications of the Theorem of Hahn-Banach

As a first application of the Theorem of Hahn-Banach we obtain the following useful result
Proposition 6.3.1. Let $(X,\|\cdot\|)$ be a normed space. Then for any $x \in X \backslash\{0\}$ there exists an element $f \in X^{*}$ with $\|f\|=1$ so that $f(x)=\|x\|$.

Proof. Let $Y=\operatorname{span}(x)$ and define $g(\lambda x)=\lambda\|x\|$ for $\lambda \in \mathbb{F}$. Then $g \in Y^{*}$ with $\|g\|=1$ and hence $g$ has an extension $f \in X^{*}$ with $\|f\|=1$ and $f(x)=g(x)=\|x\|$.

This result has several useful consequences, including the following 'dual characterisations' of the norms on $X$ and its dual space $X^{*}$

Corollary 6.3.2. Let $(X,\|\cdot\|), X \neq\{0\}$, be a normed space. Then
(i) For every $x \in X$ we have $\|x\|_{X}=\sup _{f \in X^{*},\|f\|_{X^{*}=1}}|f(x)|$.
(ii) For every $f \in X^{*}$ we have $\|f\|_{X^{*}}=\sup _{x \in X,\|x\|_{X}=1}|f(x)|$.

Proof. We already observed that the second statement is an easy consequence of the definition of the operator norm on $X$. For the proof of (i) we observe that Proposition 6.3.1 implies that $\|x\|_{X} \leq \sup _{f \in X^{*},\|f\|_{X^{*}}=1}|f(x)|$ while the reverse inequality is trivially true since $|f(x)| \leq\|f\|\|x\|=\|x\|$ for every $f \in X^{*}$ with $\|f\|=1$.

We note that while the supremum in (ii) is in general not achieved, Proposition 6.3.1 implies that the supremum in $(i)$ is always achieved.

A further important consequence of Proposition 6.3.1 is that it allows us to separate points

Corollary 6.3.3. Let $(X,\|\cdot\|)$ be a normed space. Then for any two elements $x \neq y$ of $X$ there exists an element $f \in X^{*}$ so that

$$
f(x) \neq f(y)
$$

This corollary follows as Proposition 6.3.1 allows us to choose $f \in X^{*}$ so that $f(x-y)=$ $\|x-y\| \neq 0$.

### 6.4 Geometric interpretation and further applications

We first note that the kernel of an element $f \in X^{*} \backslash\{0\}$ has codimension 1 , namely
Lemma 6.4.1. Let $X$ be a normed space and let $f: X \rightarrow \mathbb{F}, \mathbb{F}=\mathbb{R}$ respectively $\mathbb{F}=\mathbb{C}$ be linear so that $f \neq 0$. Then for any $x_{0} \in X$ for which $f\left(x_{0}\right) \neq 0$ we have that

$$
\operatorname{span}\left(\operatorname{ker}(f)+\left\{x_{0}\right\}\right)=X
$$

Proof. Let $x_{0} \in X$ be so that $f\left(x_{0}\right) \neq 0$. Given any $x \in X$ we set $\lambda:=\frac{f(x)}{f\left(x_{0}\right)}$ and note that $f\left(x-\lambda x_{0}\right)=0$. Hence $x-\lambda x_{0} \in \operatorname{ker}(f)$ and thus $x \in \operatorname{span}\left(\operatorname{ker}(f)+\left\{x_{0}\right\}\right)$. As $x \in X$ was arbitrary, this establishes the claim.

Geometrically we can think of Corollary 6.3.3 as follows: As Lemma 6.4.1 implies that the kernel of $f$ has codimension 1 we can think of the sets $\{x: f(x)=\lambda\}$ as hyperplanes in $X$ (that is shifts of a subspace with codimension 1) that divides our space $X$ into two parts, namely $\{x: f(x)<\lambda\}$ and $\{x: f(x)>\lambda\}$. The above corollary hence ensures that we can separate any two points by a hyperplane, with $x$ and $y$ on either side of it.

A slightly more general form of this result that we can prove is that we can separate points from closed subspaces.

Proposition 6.4.2. Let $(X,\|\cdot\|)$ be a normed space, $Y$ a proper closed subspace of $X$. Then for any $x_{0} \in X \backslash Y$ there exists an element $f \in X^{*}$ with $\|f\|=1$ so that

$$
\left.f\right|_{Y}=0 \text { while } f\left(x_{0}\right)=\operatorname{dist}\left(x_{0}, Y\right)
$$

We note that since $Y$ is closed we necessarily have $\operatorname{dist}\left(x_{0}, Y\right)>0$.
Proof of Proposition 6.4.2. We define a suitable linear map $g$ on the subspace $U=\operatorname{span}(Y \cup$ $\left.\left\{x_{0}\right\}\right)$ and then use Hahn-Banach to extend $g$ to $f$.

To this end we note that every $u \in U$ can be written uniquely as $u=y+\lambda x_{0}$ for some $\lambda \in \mathbb{R}$ and $y \in Y$ so that defining

$$
g\left(y+\lambda x_{0}\right):=\lambda d, \text { where } d:=\operatorname{dist}\left(x_{0}, Y\right)>0
$$

gives a well defined linear map on $Y$ which has the property that $g\left(x_{0}\right)=d$ and $\left.g\right|_{Y}=0$.
To see that $\|g\|_{U^{*}} \leq 1$ we note that for any $u=y+\lambda x_{0} \in U$

$$
\left\|y+\lambda x_{0}\right\|=|\lambda|\left\|x_{0}-\left(-\lambda^{-1} y\right)\right\| \geq|\lambda| \inf _{\tilde{y} \in Y}\left\|x_{0}-\tilde{y}\right\|=|\lambda| d=\left|g\left(y+\lambda x_{0}\right)\right|
$$

To prove that $\|g\|=1$ it hence remains to prove that $\|g\| \geq 1$, or equivalently that for any $\varepsilon>0$ there exists $x \in X \backslash\{0\}$ so that $\frac{|g(x)|}{\|x\|} \geq 1-\varepsilon$, where it is of course enough to consider $\varepsilon \in(0,1)$. To obtain such an $x$ we note that by the definition of $d=\operatorname{dist}\left(x_{0}, Y\right)$,
we can find for any $c>d$, an element $y \in Y$ so that $\left\|x_{0}-y\right\|<c$. We chose $c=\frac{1}{1-\varepsilon} d$, which is strictly larger than $d$ since $d>0$, and hence obtain an element $x_{0}-y \in X$ for which $\frac{\left|g\left(x_{0}-y\right)\right|}{\left\|x_{0}-y\right\|}=\frac{d}{\left\|x_{0}-y\right\|} \geq \frac{d}{c}=1-\varepsilon$ as required. Having thus shown that $\|g\|=1$ we now obtain the required $f \in X^{*}$ with $\left.f\right|_{Y}=0, f\left(x_{0}\right)=d$ and $\|f\|=\|g\|=1$ by applying the Theorem of Hahn-Banach.

There are far stronger versions of such 'geometric forms of Hahn-Banach' which will be discussed in the part C course on Functional Analysis. As already simple examples in $\mathbb{R}^{2}$ show, we cannot expect to separate sets by straight lines without imposing some constraints on their geometry. Unsurprisingly, a key role is played by the convexity of sets and one of the results of Part C Functional Analysis will be to prove that if $A$ is closed and $B$ is compact and if both sets are convex, then these sets can be strictly separated by a hyperplane in the sense that there exists an element $f \in X^{*}$ and a number $\lambda \in \mathbb{R}$ so that

$$
\sup _{a \in A} f(a)<\lambda<\inf _{b \in B} f(b) .
$$

The proof of this result uses the sublinear version of the Theorem of Hahn-Banach and the fact that for an open convex set $C$ containing the origin, one can define a sublinear function by $p(x):=\inf \{\lambda>0: x \in \lambda C\}$ (called the Minkowski functional).

Such general results play an important role also in applications to PDEs and in other advanced topics in functional analysis but go beyond the remit of this course.

To formulate another useful consequence of Proposition 6.4.2 we introduce the following notation

Definition 6.4.3. Given any subset $A \subset X$, we define the annihilator of $A$ to be

$$
A^{\circ}:=\left\{f \in X^{*}:\left.f\right|_{A}=0\right\}
$$

Furthermore, for subsets $T \subset X^{*}$ we define

$$
T_{\circ}:=\{x \in X: f(x)=0 \text { for all } f \in T\}=\bigcap_{f \in T} \operatorname{ker}(T) .
$$

We may now prove
Proposition 6.4.4. Let $(X,\|\cdot\|)$ be a normed space. Then the following hold true:
(i) Let $S \subset X$. Then $\operatorname{span}(S)$ is dense if and only if the annihilator of $S$ is trivial, i.e. $S^{\circ}=\{0\} \subset X^{*}$
(ii) If $T \subset X^{*}$ is so that $\operatorname{span}(T)$ is dense in $X^{*}$ then $T_{\circ}=\{0\} \subset X$.

Proof．（i）Suppose first that $\operatorname{span}(S)$ is dense．Then for any $f \in S^{\circ}$ ，we have by linearity that also $\left.f\right|_{Y}=0$ where we set $Y=\operatorname{span}(S)$ ．As $Y$ is dense in $X$ we thus get that $f=0$ by Lemma 4．1．4．
Conversely，suppose that $\operatorname{span}(S)$ is not dense．Then $Y=\overline{\operatorname{span}(S)}$ is a closed proper subspace of $X$ so we can choose $x_{0} \in X \backslash Y$ and apply Proposition 6．4．2 to obtain an $f \in X^{*}$ with $\left.f\right|_{Y}=0$ and $f\left(x_{0}\right)=\left\|x_{0}\right\| \neq 0$ so have found an element $f \neq 0$ of $S^{\circ}$.
（ii）Suppose that there exists $x \in T_{\circ}$ with $x \neq 0$ ．Then by Corollary 6．3．3 there exists $f \in X^{*}$ so that $f(x) \neq f(0)=0$ ．If $\operatorname{span}(T)$ is dense in $X^{*}$ we can however find a sequence $\left(f_{n}\right)$ of elements of $\operatorname{span}(T)$ that converges $f_{n} \rightarrow f$ in the sense of $X^{*}$ ． Note that since $x \in T_{\circ}$ we have that $f_{n}(x)=0$ which leads to a contradiction as $0 \neq f(x)=\lim _{n \rightarrow \infty} f_{n}(x)$ ．

We note that as the kernel of any element $f \in X^{*}$ is closed，we know that $T_{\circ}$ is an intersection of closed subspaces and hence itself a closed subspace of $X$ ．Also one can easily check from the definition that the annihilator of any set $A \subset X$ is closed subspace of $X^{*}$ ． Furthermore we have

Lemma 6．4．5．Let $A$ be any subspace of a normed space $X$ ．Then

$$
\bar{A}=\left(A^{\circ}\right)_{\circ}
$$

Proof．＂$\subset$＂As $\left(A^{\circ}\right)_{\text {o }}$ is closed，it suffices to prove that $A \subset\left(A^{\circ}\right)_{\circ}$ ．Let $a \in A$ ．Then by defi－ nition of the annihilator of $A$ we know that $f(a)=0$ for any $f \in A^{\circ}$ and hence that $a \in\left(A^{\circ}\right)$ 。．
＂$\supset$＂Suppose that there exists an element $x \in\left(A^{\circ}\right)$ 。 so that $x \notin \bar{A}$ ．As $\bar{A}$ is a closed subspace of $X$ we know from Proposition 6.4 .2 that there exists some $f \in X^{*}$ so that $f(x) \neq 0$ but with $\left.f\right|_{\bar{A}}=0$ ，i．e．with $f \in(\bar{A})^{\circ}$ and hence $f \in A^{\circ}$ ．But this contradicts the assumption that $x \in\left(A^{\circ}\right)_{\text {。 }}$ ．

## Chapter 7

## Dual spaces, second dual spaces and completion

In this chapter we further discuss the special properties of functionals, describe the dual spaces of some important spaces encountered earlier, take a first look at the second dual $X^{* *}$ of a normed space, that is the dual space of the dual space $X^{*}$ of X and explain how a space always embedds into its second dual and how this can be used to view a non-complete normed space as a subspace of a complete space.

### 7.1 A basic property of linear functionals

To begin with, we note that for linear functionals, we have the following characterisation of continuity

Lemma 7.1.1. Let $X$ be a normed space and let $f: X \rightarrow \mathbb{F}, \mathbb{F}=\mathbb{R}$ respectively $\mathbb{F}=\mathbb{C}$ be linear. Then the following are equivalent

$$
\operatorname{ker}(f) \text { is closed } \Longleftrightarrow f \in X^{*} .
$$

Proof. " $\Leftarrow$ " As $f$ is continuous and $\{0\}$ is closed we get that the preimage $\operatorname{ker}(f)=f^{-1}(\{0\})$ is also closed.
" $\Rightarrow$ " The claim is trivial if $f=0$ so suppose that $f \neq 0$ and let $x_{0}$ be so that $f\left(x_{0}\right) \neq 0$, where (after replacing $x_{0}$ by a multiple of $x_{0}$ ) we can assume without loss of generality that $f\left(x_{0}\right)=1$.

We first note that since $\operatorname{ker}(f)$ is closed, we know that $\operatorname{dist}\left(x_{0}, \operatorname{ker}(f)\right)>0$, compare problem sheet 0 . We now claim that for every $x \in X$

$$
|f(x)| \leq \delta^{-1}\|x\| \text { where } \delta:=\operatorname{dist}\left(x_{0}, \operatorname{ker}(f)\right)>0
$$

which will of course imply that $f \in X^{*}$.
This claim is trivial for $x \in \operatorname{ker}(f)$ so suppose instead that $f(x) \neq 0$. We note that since $f\left(x_{0}\right)=1$ and since $f$ is linear we have that $x-f(x) x_{0} \in \operatorname{ker}(f)$. Hence also $-\frac{1}{f(x)}(x-$ $\left.f(x) x_{0}\right) \in \operatorname{ker}(f)$ and must thus have distance of at least $\delta$ from $x_{0}$ which implies that

$$
\delta \leq\left\|x_{0}+\frac{1}{f(x)}\left(x-f(x) x_{0}\right)\right\|=\frac{\|x\|}{|f(x)|}
$$

and thus that indeed $|f(x)| \leq \delta^{-1}\|x\|$.

### 7.2 Riesz representation theorem and dual spaces of Hilbert spaces

If $X$ is a Hilbert space, and $x \in X$ is fixed, then $\langle y, x\rangle=\ell(y)$ is a linear functional of $y$, i.e. $\ell$ maps $X$ linearly into $\mathbb{R}$ or $\mathbb{C}$. Furthermore, $\ell$ is bounded, thanks to the Cauchy-Schwarz inequality, and so $\ell \in X^{*}$. It turns out that all bounded linear functionals on a Hilbert space arise this way:

Theorem 7.2.1 (Riesz representation theorem). Let $X$ be a real (or complex) Hilbert space and $\ell: X \rightarrow \mathbb{R}$ (or $\mathbb{C}$ ) be a bounded linear functional. Then $\ell$ is of the form

$$
\ell(y)=\langle y, x\rangle \text { for all } y \in X
$$

for some $x \in X$. Furthermore, the point $x$ is uniquely determined and $\|x\|=\|\ell\|_{*}$.
Remark 7.2.2. When $X$ is real, the above statement means that there exists an isometric isomorphism $\pi: X \rightarrow X^{*}$ such that $(\pi x)(y)=\langle y, x\rangle$ for all $x, y \in X$ and $\|\pi x\|_{*}=\|x\|$. So the spaces $X$ and $X^{*}$ are topologically equivalent, i.e. they are the same up to isometric isomorphism. It is notated as $X^{*} \cong X$ or even just $X^{*}=X$.

When $X$ is complex, the map $\pi$ defined above remains a surjective isometry, but it is skewlinear instead of linear: $\pi(\lambda x)=\bar{\lambda} \pi x$ for $\lambda \in \mathbb{C}, x \in X$.
Proof. If $\ell=0$, then $x=0$. Assume henceforth that $\ell \not \equiv 0$. Let $Y$ be the kernel of $\ell$. Then $Y$ is a closed subspace of $X$. By Theorem 1.2.15, $X=Y \oplus Y^{\perp}$.

Since $Y^{\perp \perp}=Y$ is a strict subspace of $X($ as $\ell \not \equiv 0), Y^{\perp}$ contains a non-zero element, say $y^{\perp}$. Note that $\ell\left(y^{\perp}\right) \neq 0$. Then for any $z \in X$, we have

$$
z-\frac{\ell(z)}{\ell\left(y^{\perp}\right)} y^{\perp} \in Y=\operatorname{Ker} \ell
$$

Taking inner product with $y^{\perp}$ yields

$$
\left\langle z, y^{\perp}\right\rangle-\frac{\ell(z)}{\ell\left(y^{\perp}\right)}\left\|y^{\perp}\right\|^{2}=0 \text { for all } z \in X .
$$

In other words, $x$ can be chosen as

$$
x=\frac{\overline{\ell\left(y^{\perp}\right)}}{\left\|y^{\perp}\right\|^{2}} y^{\perp}
$$

The uniqueness is obvious.
For the last assertion, we note by the Cauchy-Schwarz inequality that $\ell(y)=\langle y, x\rangle \leq$ $\|y\|\|x\|$ and so $\|\ell\|_{*} \leq\|x\|$. On the other hand, we have $\|x\|^{2}=\langle x, x\rangle=\ell(x) \leq\|\ell\|_{*}\|x\|$ and so $\|x\| \leq\|\ell\|_{*}$. This completes the proof.

By inspecting the proof, we obtain the following result which is true for more general vector spaces.

Lemma 7.2.3. (i) The kernel of a non-trivial linear functional on a Banach space is a closed linear subspace of codimension one.
(ii) If two linear functionals on a vector space have the same kernel space, then they are multiples of each other.

Proof. Exercise.

### 7.3 Dual spaces of particular spaces

We recall from Linear Algebra that if $X$ is a finite dimensional space then we can associate to each basis $e_{1}, \ldots, e_{n}$ of $X$ a dual basis $f_{1}, \ldots, f_{n}$ of $X^{*}$ by defining $f_{i}\left(e_{j}\right)=\delta_{i j}$. In particular $X$ and its dual $X^{*}$ are isomorphic.

WARNING. As so often in this course, the finite dimensional case leads to the wrong intuition for general normed spaces. In general, the dual space can have very different properties than a space itself, e.g. we can have that $X$ is separable while $X^{*}$ is inseparable, we will have that the dual space of any normed space is complete, even if the space $X$ itself is not complete....

To describe the dual space of a given space $X$, we would like to find another normed space which is isometrically isomorphic to $X$, written for short as $X \cong Y$, i.e. for which there exists a bijective linear map $L: Y \rightarrow X$ so that

$$
\|L y\|_{X}=\|y\|_{Y} \text { for all } y
$$

Often it is not too difficult to find a space $Y$ and a map $L$ so that $L: Y \rightarrow X^{*}$ is isometric, i.e. so that $\|L y\|_{X}=\|y\|_{Y}$ for all $y$, and hence also injective, but it can be difficult to find a space $Y$ that is large enough so that it represents all elements of $X^{*}$, i.e. so that the map $L$ is surjective, respectively to prove that a candidate $Y$ for the dual space has this property.

In general, determining the dual space of a given normed space $(X,\|\cdot\|)$ can be difficult and already the dual spaces of some very familiar spaces such as $C([a, b])$ or $L^{\infty}([a, b])$ can be complicated and their description is beyond the scope of this course, though we remark that in both cases the dual spaces can be identified with a suitable space of (signed) measures. Examples of elements of $(C[0,1])^{*}$ are e.g. the map $T: f \mapsto \int_{[0,1]} f g d x$ for any $g \in L^{1}([0,1])$ but also maps like $T: f \mapsto f\left(\frac{1}{2}\right)$ which one can interpret as the integral of $f$ with respect to a $\delta$-measure that is concentrated at $x=\frac{1}{2}$.

On the other hand, for the sequence spaces $\ell^{p}$ and the function spaces $L^{p}$ we have the following characterisations if $1 \leq p<\infty$, which we stress do not apply if $p=\infty$. For simplicity we consider real valued functions, though the results and their proofs also apply in the complex case (with some extra complex conjugates).

## Dual space of $L^{p}$

In the following discussion, the relevant Lebesgue spaces are real. The complex case can be obtained with some simple adjustment and is left as an exercise.

Theorem 7.3.1 (Dual space of $L^{p}$ ). Let $\Omega \subset \mathbb{R}^{n}$ be measurable, $1 \leq p<\infty$ and $1<q \leq \infty$ be so that $\frac{1}{p}+\frac{1}{q}=1$. Then $\left(L^{p}(\Omega)\right)^{*} \cong L^{q}(\Omega)$ where the associated isometric isomorphism $L: L^{q}(\Omega) \rightarrow\left(L^{p}(\Omega)\right)^{*}$ assigns to each $f \in L^{q}(\Omega)$ the linear map $L(f) \in\left(L^{p}(\Omega)\right)^{*}$ defined by

$$
(L(f))(g)=\int_{\Omega} f g d x \in \mathbb{R} \quad \text { for } g \in L^{p}(\Omega)
$$

In other words, the statement $\left(L^{p}(\Omega)\right)^{*} \cong L^{q}(\Omega)$ is a short-hand for the statement that the map $L$ above is a well-defined isometric isomorphism from $L^{q}(\Omega)$ into $\left(L^{p}(\Omega)\right)^{*}$.

When $p=q=2$, the theorem is a consequence of the Riesz representation theorem. The proof will be split into two parts. In Part 1, we show that $L$ is well-defined and isometric. The argument though technical is fairly elementary in nature. In Part 2, we prove that $L$ is surjective. This part is substantially more involved and needs some preparation.

Part 1 of the proof of Theorem 7.3.1. We show that $L$ is well-defined and isometric.
We note that since $p, q$ are so that $\frac{1}{p}+\frac{1}{q}=1$ we know from Hölder's inequality that the product $f g$ of two functions $f \in L^{q}(\Omega)$ and $g \in L^{p}(\Omega)$ is integrable and

$$
\begin{equation*}
\left|\int_{\Omega} f g d x\right| \leq\|f\|_{L^{q}}\|g\|_{L^{q}} \tag{7.1}
\end{equation*}
$$

We now remark that since the integral is linear, we have that for all $f, \tilde{f} \in L^{q}(\Omega), \lambda \in \mathbb{R}$ and any $g \in L^{q}(\Omega)$ that $L(f+\lambda \tilde{f})(g)=L f(g)+\lambda L \tilde{f}(g)$, i.e. that the map $L: f \rightarrow L f$ is linear. Similarly, given any $f \in L^{q}(\Omega)$ we have that for any $g, \tilde{g} \in L^{p}(\Omega)$ and any $\lambda \in \mathbb{R}$ that
$L f(g+\lambda \tilde{g})=L f(g)+\lambda L f(\tilde{g})$ so $L f$ is a linear map from $L^{p}$ to $\mathbb{R}$ and indeed an element of $\left(L^{p}(\Omega)\right)^{*}$ as it is bounded with

$$
\|L f\|_{\left(L^{p}(\Omega)\right)^{*}}=\sup _{g \in L^{q}, g \neq 0} \frac{|L f(g)|}{\|g\|_{L^{p}}}=\sup _{g \in L^{q}, g \neq 0} \frac{\left|\int f g\right|}{\|g\|_{L^{p}}} \leq \sup _{g \in L^{q}, g \neq 0} \frac{\|f\|_{L^{q}}\|g\|_{L^{p}}}{\|g\|_{L^{p}}}=\|f\|_{L^{q}}
$$

where we used (7.1) in the penultimate step.
We finally show that also

$$
\begin{equation*}
\|L f\|_{L^{p}(\Omega)^{*}} \geq\|f\|_{L^{q}} \tag{7.2}
\end{equation*}
$$

for every $f \in L^{q}$ and thus that $L$ is indeed isometric.
This proof is a bit technical as we need to be careful with the exponents, so it can be useful to first consider special cases such as $p=q=2$ or $p=1, q=\infty$, where the exponents are much nicer to see the structure of the argument, before digesting the general case. We first treat the case that $p>1$ and hence $q<\infty$.

The estimate (7.2) is trivial if $f=0$ so suppose that $f \neq 0$. We choose $g:=|f|^{q-2} f$ so that $f g=|f|^{q}$ and hence $L(f)(g)=\int_{\Omega}|f|^{q} d x=\|f\|_{L^{q}}^{q}$. We now note that since $\frac{1}{p}+\frac{1}{q}=1$ we have $(q-1) p=q$ and so

$$
\|g\|_{L^{p}}=\left(\int|g|^{p} d x\right)^{1 / p}=\left(\int\left(|f|^{(q-1)}\right)^{p} d x\right)^{1-\frac{1}{q}}=\left(\int|f|^{q} d x\right)^{\frac{1}{q}(q-1)}=\|f\|_{L^{q}}^{q-1}
$$

which means that

$$
\frac{L f(g)}{\|g\|_{L^{p}}}=\frac{\|f\|_{L^{q}}^{q}}{\|f\|_{L^{q}}^{q-1}}=\|f\|_{L^{q}}
$$

and hence that $\|L f\|_{\left(L^{p}\right)^{*}} \geq\|f\|_{L^{q}}$ as claimed in (7.2).
If $p=1$ and hence $q=\infty$ then we prove that for any $\varepsilon>0$ there exists a function $g_{\varepsilon} \in L^{1}$ so that $\frac{L f(g)}{\|g\|_{L^{1}}} \geq\|f\|_{L^{\infty}}-\varepsilon$. To this end we consider the set $A_{\varepsilon}:=\left\{x:|f(x)| \geq\|f\|_{L^{\infty}}-\varepsilon\right\}$, which is measurable (and well defined upto a null set). If this set has finite measure then we define $g_{\varepsilon}(x):=\operatorname{sign}(f(x)) \cdot \chi_{A_{\varepsilon}}$ which is in $L^{1}(\Omega)$ with $L^{1}$-norm equal to the measure of $A_{\varepsilon}$, which by the definition of the $L^{\infty}$ norm is positive. As $f g \geq\left(\|f\|_{L^{\infty}}-\varepsilon\right) \chi_{A_{\varepsilon}}$ we can thus immediately check that $L f(g) \geq\left(\|f\|_{L^{\infty}}-\varepsilon\right)\left\|g_{\varepsilon}\right\|_{L^{1}}$ which gives the claimed bound. Finally, if $A_{\varepsilon}$ has infinite measure, then we can replace $A_{\varepsilon}$ by any subset $\tilde{A}_{\varepsilon} \subset A_{\varepsilon}$ whose measure is finite and positive and apply the above argument for the corresponding function $g_{\varepsilon} \in L^{1}$.

Remark 7.3.2. By inspection, we see that the proof above can be slightly refined to show a little bit more: It shows that if $f$ is measurable, then

$$
\|f\|_{L^{q}}=\sup \left\{\left|\int_{\Omega} f g d x\right|: g \in L^{p}(\Omega),\|g\|_{L^{p}}=1 \text { and } f g \in L^{1}(\Omega)\right\}
$$

without presuming that $f \in L^{q}(\Omega)$ ! This is known as the converse of Hölder's inequality.

We turn to the surjectivity of $L$. To avoid technicality, but still keeping the main point intact, we assume for simplicity that $\Omega$ is bounded. The general case is dealt with by approximating $\Omega$ by bounded measurable sets and is left as an exercise. We start with the Radon-Nikodym theorem.

Theorem 7.3.3 (Radon-Nikodym). Let $\Omega \subset \mathbb{R}^{n}$ be a bounded (Lebesgue) measurable set and let $\mu$ be a finite signed measur defined on the $\sigma$-algebra consisting of measurable subsets of $\Omega$. Suppose that $\mu$ is absolutely continuous with respect to the Lebesgue measure, that is, every set that has zero Lebesgue measure has zero $\mu$-measure. Then $d \mu=g d x$ where $g$ is some integrable function with respect to the Lebesgue measure:

$$
\mu(E)=\int_{E} f d x \text { for every measurable } E \subset \Omega .
$$

Moreover, if $\mu$ is non-negative, so is $g$.
Proof. We follow the proof of von Neumann. We will only consider the case $\mu$ is nonnegative. ${ }^{2}$

Let $X$ be the real Hilbert space $L^{2}(\Omega, \mu+d x)$ with the norm $\|g\|^{2}=\int_{\Omega}|g|^{2} d \mu+\int_{\Omega}|g|^{2} d x$. Define

$$
\ell(g)=\int_{\Omega} g d x \text { for } f \in X
$$

By the Cauchy-Schwarz inequality, $\ell \in X^{*}$. Thus, by the Riesz representation theorem, we can find some $h \in X$ such that

$$
\ell(g)=\int_{\Omega} g h d \mu+\int_{\Omega} g h d x \text { for all } f \in X .
$$

This can be rewritten as

$$
\begin{equation*}
\int_{\Omega} g(1-h) d x=\int_{\Omega} g h d \mu \text { for all } g \in X \tag{7.3}
\end{equation*}
$$

We are now tempted to define $f=\frac{1-h}{h}$ and try $g=\frac{1}{h} \chi_{E}$ in (7.3) to conclude. Each of those has complication and we will treat them in order.

[^1](a) Proof of non-negativity and almost everywhere finiteness of $f:=\frac{1-h}{h}$. To this end, we need to show that
$$
0<h \leq 1 \text { except on a set of measure zero. }
$$

Let $F=\{h \leq 0\}$. Choosing $g=\chi_{F}$ in (7.3), we get

$$
0 \leq|F| \leq \int_{F}(1-h) d x=\int_{F} h d \mu \leq 0
$$

This implies $|F|=0$.
Let $G=\{h>1\}$. We choose $g=\chi_{G}$ in (7.3) and get

$$
0 \geq \int_{G}(1-h) d x=\int_{G} h d \mu \geq \mu(G) \geq 0
$$

where the first inequality is strict if $|G|>0$. This implies that $|G|=0$. We have thus proved that $0<h \leq 1$ except on a set of zero Lebesgue measure. Consequently, $f=\frac{1-h}{h}$ is non-negative and almost everywhere finite.
(b) Proof of integrability of $f$ and the identity $\mu(E)=\int_{E} f d x$. For $N>0$, choosing $g=\min \left\{\frac{1}{h}, N\right\} \chi_{E}$ in (7.3) gives

$$
\int_{E} \min \{f, N(1-h)\} d x=\int_{E} \min \{1, N h\} d \mu
$$

As $N \rightarrow \infty$, the integrands on the left and the right hand sides increase a.e. in $E$ to $f$ and 1 respectively. By Lebesgue's monotone convergence theorem, we have

$$
\int_{E} f d x=\int_{E} 1 d \mu=\mu(E) .
$$

Note that in the case $E=\Omega$, this gives that $\int_{\Omega} f d x=\mu(\Omega)<\infty$ which implies that $f$ is integrable (since $f \geq 0$ ). The proof is complete.
Part 2 of the proof of Theorem 7.3.1 when $\Omega$ is bounded. We show that $L$ is surjective when $\Omega$ is bounded.

Let $\ell \in\left(L^{p}(\Omega)\right)^{*}$ and we would like to find $f \in L^{q}(\Omega)$ such that $\ell(f)=\int_{\Omega} f g d x$ for all $g \in L^{p}(\Omega)$.

Observe that the set function $\psi(E)=\ell\left(\chi_{E}\right)$ is $\sigma$-additive (that is, a signed measure) and absolutely continuous with respect to the Lebesgue measure. (Note that $\psi$ is well-defined as $\chi_{E} \in L^{p}(\Omega)$, thanks to the boundedness of $\Omega$.) By the Radon-Nikodym theorem, there exists a function $f \in L^{1}(\Omega)$ such that

$$
\psi(E)=\int_{E} f d x \text { for all measurable } E \subset \Omega
$$

This implies that

$$
\ell\left(\chi_{E}\right)=\int_{E} f d x \text { for all measurable } E \subset \Omega
$$

and so by linearlity

$$
\ell(s)=\int_{\Omega} f s d x \text { for all simple functions } s
$$

Consider $h \in L^{p}(\Omega) \cap L^{\infty}(\Omega)$. Recall from Part A integration that there exists a sequence $\left(h_{j}\right)$ of simple functions such that $\left|h_{j}\right| \leq|h|$ and $h_{j} \rightarrow h$ a.e. It then follows by Lebesgue's dominated convergence theorem that

$$
\ell(h)=\lim _{j \rightarrow \infty} \ell\left(h_{j}\right)=\lim _{j \rightarrow \infty} \int_{\Omega} f h_{j} d x \stackrel{D C T}{=} \int_{\Omega} \lim _{j \rightarrow \infty} f h_{j} d x=\int_{\Omega} f h d x
$$

(Note that we do not need the (essential) boundedness of $h$ for the existence of the approximating sequence $\left(h_{j}\right)$ but we need it in the application of the dominated convergence theorem.)

Consider next $g \in L^{p}(\Omega)$. We approximate $g$ by truncation:

$$
g_{k}(x)= \begin{cases}g(x) & \text { if }|g(x)| \leq k \\ 0 & \text { otherwise }\end{cases}
$$

so that $g_{k} \rightarrow g$ in $L^{p}(\Omega)$, in view of Lebesgue's dominated convergence theorem. Then

$$
\ell(g)=\lim _{k \rightarrow \infty} \ell\left(g_{k}\right)=\lim _{k \rightarrow \infty} \int_{\Omega} f g_{k} d x
$$

but at this point we have difficulty to interchange the limit and the integration. We circumvent the issue as follows: Consider the function $\tilde{g}_{k}=\left|g_{k}\right| \operatorname{sign}(f)$. We have

$$
\|\ell\|_{\left(L^{p}\right)^{*}}\|g\|_{L^{p}} \geq\|\ell\|_{\left(L^{p}\right)^{*}}\left\|\tilde{g}_{k}\right\|_{L^{p}} \geq\left|\ell\left(\tilde{g}_{k}\right)\right|=\left|\int_{\Omega} f \tilde{g}_{k} d x\right|=\int_{\Omega}|f|\left|g_{k}\right| d x .
$$

Sending $k \rightarrow \infty$ and using Lebesgue's monotone convergence theorem, we have $\|\ell\|_{\left(L^{p}\right) *}\|g\|_{L^{p}} \geq$ $\int_{\Omega}|f||g| d x$, that is $f g$ is integrable. We can now continue the previous chain of identity with Lebesgue's dominated convergence theorem to obtain

$$
\ell(g)=\lim _{k \rightarrow \infty} \int_{\Omega} f g_{k} d x \stackrel{D C T}{=} \int_{\Omega} \lim _{k \rightarrow \infty} f g_{k} d x=\int_{\Omega} f g d x
$$

By the converse of Hölder's inequality, this also implies that $f \in L^{q}(\Omega)$ :

$$
\|f\|_{L^{q}}=\sup _{g \in L^{p}(\Omega),\|g\|_{L^{p}=1}}\left|\int_{\Omega} f g d x\right|=\sup _{g \in L^{p}(\Omega),\|g\|_{L^{p}=1}}|\ell(g)|=\|\ell\|_{\left(L^{p}\right)^{*}}
$$

This concludes the proof.

## Dual space of $\ell^{p}$

The analogue result for the sequence spaces is
Theorem 7.3.4 (Dual space of $\ell^{p}(\mathbb{R})$ ). Let $1 \leq p<\infty$ and $1<q \leq \infty$ be so that $\frac{1}{p}+\frac{1}{q}=1$. Then $\left(\ell^{p}\right)^{*} \cong \ell^{q}$ where the associated isometric isomorphism $L: \ell^{q}(\mathbb{R}) \rightarrow\left(\ell^{p}(\mathbb{R})\right)^{*}$ assigns to each $x \in \ell^{q}$ the linear map $L(x) \in\left(\ell^{p}\right)^{*}$ given by

$$
(L(x))(y)=\sum_{j=1}^{\infty} x_{j} y_{j} \in \mathbb{R} \quad \text { for } y \in \ell^{p}(\mathbb{R})
$$

Similar to the case of Lebesgue space, the statement $\left(\ell^{p}\right)^{*} \cong \ell^{q}$ is a short-hand for the statement that the map $L$ above is a well-defined isometric isomorphism from $\ell^{q}$ into $\left(\ell^{p}\right)^{*}$.

The proof that $L$ is a well defined isometric linear map from $\ell^{q}$ to $\left(\ell^{p}\right)^{*}$ is exactly the same as for the function spaces $L^{p}$ (replacing functions by sequences and integral by sums), so we do not repeat it.

Instead we explain how one can prove surjectivity of the map $L$ in case of $p=1$ to show that indeed $\left(\ell^{1}\right)^{*}=\ell^{\infty}$ :

Proof of surjectivity of $L: \ell^{\infty} \rightarrow\left(\ell^{1}\right)^{*}$. Given $f \in\left(\ell^{1}\right)^{*}$ we define a sequence $x=\left(x_{j}\right)_{j \in \mathbb{N}}$ by setting $x_{j}=f\left(e^{(j)}\right)$ where as usual $e^{(j)}$ is the sequence with $e_{k}^{(j)}=\delta_{j k}$. Then

$$
\left|x_{j}\right| \leq\|f\|_{\left(\ell^{1}\right)^{*}}\left\|e^{(j)}\right\|_{1}=\|f\|_{\left(\ell^{1}\right)^{*}}
$$

so $x \in \ell^{\infty}$. We now claim that $L x=f$. To see this we note that since both $L x$ and $f$ are linear and as by construction $(L x)\left(e^{(j)}\right)=x_{j}=f\left(e^{(j)}\right)$, we know that $\left.f\right|_{Y}=\left.L x\right|_{Y}$ for $Y:=\operatorname{span}\left(\left\{e^{(j)}, j \in \mathbb{N}\right\}\right)$. As $Y \subset \ell^{1}$ is dense, compare with the proof of Proposition 5.0.7, we thus obtain from Corollary 4.1.4 that indeed $f=L x$.

The proof of surjectivity of $L$ for general sequence spaces $\ell^{p}, 1 \leq p<\infty$ is very similar (though one needs to be more careful with the exponents).

WARNING.

$$
\left(\ell^{\infty}\right)^{*} \not \equiv \ell^{1} \text { and }\left(L^{\infty}(\Omega)\right)^{*} \not \equiv L^{1}(\Omega)
$$

While the analogue of the maps $L$ defined in Theorems 7.3 .1 and 7.3 .4 also give isometric linear maps from $L^{1}$ to $\left(L^{\infty}\right)^{*}$ (respectively $\ell^{1}$ to $\left.\left(\ell^{\infty}\right)^{*}\right)$ these maps are not surjective. For the sequence spaces one can show that $\ell^{1}$ is isomorphic to the dual of a subspace of $\ell^{\infty}$, namely $\left(c_{0}\right)^{*} \cong \ell^{1}$, where $c_{0}$ denotes the subspace of all sequences that converge to zero, compare problem sheet 4.

To see that $L: \ell^{1} \rightarrow\left(\ell^{\infty}\right)^{*}$ cannot be surjective, we consider the subspace $c \subset \ell^{\infty}$ of all sequences that converge and let $f: c \rightarrow \mathbb{R}$ be the map that assigns to each $x \in c$ its limit $f(x)=\lim _{n \rightarrow \infty} x_{n}$. Then $f$ is clearly linear and bounded on $\left(c,\|\cdot\|_{\infty}\right)$, so by Hahn-Banach,
has an extension $\tilde{f} \in\left(\ell^{\infty}\right)^{*}$ (Note that this is an instance where we apply Hahn-Banach to an inseparable space). But we cannot write $\tilde{f}$ in the form $\tilde{f}(x)=\sum_{j=1}^{\infty} x_{j} y_{j}$ for some $y \in \ell^{1}$ so $\mathscr{B}\left(\ell^{1}\right)$ is a proper subspace of $\left(\ell^{\infty}\right)^{*}$.

### 7.4 Dual operators

We recall the following construction from Part A Linear Algebra:
Let $X$ and $Y$ be any vector spaces over the same field $\mathbb{F}$ and let $X^{\prime}:=\{L: X \rightarrow \mathbb{F}$ linear $\}$ and $Y^{\prime}:=\{L: Y \rightarrow \mathbb{F}$ linear $\}$ be the corresponding sets of linear functionals (so far we do not introduce any norm on $X$ and $Y$, so it would also make no sense to talk about continuity).

Then we can associate to any linear map

$$
T: X \rightarrow Y
$$

the map

$$
T^{\prime}: Y^{\prime} \rightarrow X^{\prime}
$$

where for any $f \in Y^{\prime}$ we define $T^{\prime}(f) \in X^{\prime}$ by

$$
\left(T^{\prime}(f)\right)(x)=f(T(x)),
$$

and one easily checks that $T(f)$ is indeed linear, and thus an element of $X^{\prime}$, and that the map $f \mapsto T(f)$ is also linear. In the context of matrices, $T^{\prime}$ is simply the transpose of $T$.

We may now ask whether this construction works also in the setting of Functional Analysis, where we work with normed spaces instead of just vector spaces and bounded linear operators instead of just linear operators. The following proposition answers this question positively:

Proposition 7.4.1 (dual operator). Let $\left(X,\|\cdot\|_{X}\right)$ and $\left(Y,\|\cdot\|_{Y}\right)$ be normed spaces over the same field $\mathbb{F}=\mathbb{R}$ or $\mathbb{F}=\mathbb{C}$ and let $T \in \mathscr{B}(X, Y)$. Then the dual operator

$$
\begin{align*}
T^{\prime}: Y^{*} & \rightarrow X^{*} \\
f & \mapsto T^{\prime}(f): x \mapsto T^{\prime}(f)(x):=f(T x) \tag{7.4}
\end{align*}
$$

is well defined and a bounded linear operator $T^{\prime} \in \mathscr{B}\left(Y^{*}, X^{*}\right)$ with

$$
\left\|T^{\prime}\right\|_{\mathscr{B}\left(Y^{*}, X^{*}\right)}=\|T\|_{\mathscr{B}(X, Y)}
$$

Proof. As already mentioned, the fact that for each $f \in X^{*}$ the map $T^{\prime}(f)$ is linear and that $T$ itself is a linear operator is easily checked (and the proof is exactly the same as in the finite dimensional case that was covered in part A Linear Algebra). We first show that $T^{\prime}(f) \in X^{*}$ with

$$
\begin{equation*}
\left\|T^{\prime}(f)\right\|_{X^{*}} \leq\|T\|_{\mathscr{B}(X, Y)}\|f\|_{Y^{*}} \text { for every } f \in Y^{*} \tag{7.5}
\end{equation*}
$$

which ensures that $T^{\prime}$ is a well defined operator in $\mathscr{B}\left(Y^{*}, X^{*}\right)$ with $\left\|T^{\prime}\right\|_{\mathscr{B}\left(Y^{*}, X^{*}\right)} \leq\|T\|_{\mathscr{B}(X, Y)}$. To see this we note that for every $x \in X$ with $\|x\|_{X}=1$

$$
\left|T^{\prime}(f)(x)\right|=|f(T(x))| \leq\|f\|_{Y^{*}}\|T x\|_{Y} \leq\|f\|_{Y^{*}}\|T\|_{\mathscr{B}(X, Y)}\|x\|_{X}=\|f\|_{Y^{*}}\|T\|_{\mathscr{B}(X, Y)}
$$

so that (7.5) follows from the definition of the operator norm. To see that also $\left\|T^{\prime}\right\| \geq\|T\|$ we will prove that

$$
\begin{equation*}
\|T x\|_{Y} \leq\left\|T^{\prime}\right\|_{\mathscr{B}\left(Y^{*}, X^{*}\right)}\|x\|_{X} \text { for all } x \in X \tag{7.6}
\end{equation*}
$$

which implies that $\|T\|=\inf \{M:\|T x\| \leq M\|x\|\} \leq\left\|T^{\prime}\right\|$.
This estimate (7.6) trivially holds true for all $x \in \operatorname{ker}(T)$, so suppose that $T x \neq 0$. Then Proposition 6.3.1 (which was a consequence of the Theorem of Hahn-Banach) gives us an element $f \in Y^{*}$ with $\|f\|_{Y^{*}}=1$ so that

$$
f(T x)=\|T x\| .
$$

Hence

$$
\|T x\|=f(T x)=\left(T^{\prime}(f)\right)(x) \leq\left\|T^{\prime}(f)\right\|\|f\| \leq\left\|T^{\prime}\right\|\|f\|\|x\|=\left\|T^{\prime}\right\|\|x\|
$$

as claimed.

You have seen in Part A Linear Algebra that for finite dimensional spaces there are several relations involving kernels of maps/dual maps and annihilators of the images of dual maps/maps. Many of these relations have an analogue for general normed spaces, but one needs to be careful in particular with statements that involve spaces, such as the images $T X$ or $T^{\prime} Y^{*}$, that are in general not closed, and such statements often require us to take the closure of the corresponding sets. Some of these relations will be proven on problem sheet 4 .

### 7.5 Adjoint operators

Let $X$ and $Y$ be Hilbert spaces and consider $A \in \mathscr{B}(X, Y)$. Then for fixed $y \in Y,\langle A x, y\rangle_{Y}$ defines a bounded linear functional on $X$. Thus, by the Riesz representation theorem, there is some $A^{*} y \in X$ such that $\langle A x, y\rangle_{Y}=\left\langle x, A^{*} y\right\rangle_{X}$. The map $y \mapsto A^{*} y$ from $Y$ to $X$ is called the adjoint operator of $A$. This extends the notion of conjugate transposed matrices.

Proposition 7.5.1. The adjoint operator satisfies the following properties.
(i) $\langle A x, y\rangle_{Y}=\left\langle x, A^{*} y\right\rangle_{X}$.
(ii) There is a unique operator $A^{*}$ satisfying (i).
(iii) $A^{*} \in \mathscr{B}(Y, X)$.
(iv) If we identify $X$ with $X^{*}$ and $Y$ with $Y^{*}$ via the surjective isometric (skew)linear maps $\pi_{X}$ and $Y$ as in Remark 7.2.2, then $A^{*}=\pi_{X}^{-1} A^{\prime} \pi_{Y}$.
(v) $\|A\|_{\mathscr{B}(X, Y)}=\left\|A^{*}\right\|_{\mathscr{B}(Y, X)}$.
(vi) $A^{* *}=A$.
(vii) If $A, B \in \mathscr{B}(X, Y)$ and $a, b \in \mathbb{C}$, then $(a A+b B)^{*}=\bar{a} A^{*}+\bar{b} B^{*}$.
(viii) If $T \in \mathscr{B}(X, Y)$ and $S \in \mathscr{B}(Y, Z)$, then $(S T)^{*}=T^{*} S^{*}$.

If $X=Y$, we also have that
(viii) $I_{X}^{*}=I_{X}$.
(ix) $A \in \mathscr{B}(X)$ is invertible if and only if $A^{*}$ is invertible.

Proof. Exercise.
Example 7.5.2. Let $X=\mathbb{R}^{n}, Y=\mathbb{R}^{m}$ and $A x=M x$ where $M$ is some $m \times n$ matrix. Then $A^{*}$ is given by $A^{*} y=M^{*} y$ where $M^{*}$ is the conjugate transpose of $M$.

Example 7.5.3. Let $X=Y=L^{2}(0,1)$ and $A$ be the integral operator

$$
(A f)(x)=\int_{0}^{1} k(x, y) f(y) d y
$$

where $k:(0,1)^{2} \rightarrow \mathbb{R}$ is a given bounded measurable function. Then $A$ is a linear operator of $L^{2}(0,1)$ into itself. The adjoint operator $A^{*}$, which is also a linear operator of $L^{2}(0,1)$ into itself, is given by

$$
\left(A^{*} g\right)(x)=\int_{0}^{1} \overline{k(y, x)} g(y) d y
$$

This is because, by Fubini's theorem,

$$
\begin{aligned}
&\langle A f, g\rangle=\int_{0}^{1} \int_{0}^{1} k(x, y) f(y) d y \bar{g}(x) d x \\
&=\int_{0}^{1} f(y) \overline{\int_{0}^{1} \overline{k(x, y)} g(x) d x} d y=\left\langle f, A^{*} g\right\rangle
\end{aligned}
$$

Example 7.5.4. Let $X=Y=\ell^{2}$ and $R$ be the right-shift $R\left(\left(x_{1}, x_{2}, \ldots\right)\right)=\left(0, x_{1}, x_{2}, \ldots\right)$.
Then $R^{*}$ is the left-shift $L\left(\left(x_{1}, x_{2}, \ldots\right)\right)=\left(x_{2}, x_{3}, \ldots\right)$.
Example 7.5.5. Let $X=Y=L^{2}(\mathbb{R})$ and $h: \mathbb{R} \rightarrow \mathbb{C}$ be a bounded measurable function. Define the multiplication operator $M_{h}$ by $M_{h} f(x)=h(x) f(x)$. Then $M_{h} \in \mathscr{B}(X)$ and $M_{h}^{*}=M_{\bar{h}}$.

We have the following result on the kernel and image of adjoint operators.
Proposition 7.5.6. Let $X$ and $Y$ be Hilbert spaces and $A \in \mathscr{B}(X, Y)$. Then
(i) $\operatorname{Ker} A=\left(\operatorname{Im} A^{*}\right)^{\perp}$.
(ii) $(\operatorname{Ker} A)^{\perp}=\overline{\operatorname{Im} A^{*}}$.

Proof. Exercise.

### 7.6 Second dual spaces and completion

As the dual space $\left(X^{*},\|\cdot\|_{X^{*}}\right)$ of a normed space $(X,\|\cdot\|)$ is again a normed space, we can consider its dual space $X^{* *}$ which is called the second dual space or bidual space of $X$. The most important property of this space is that it will always contain an isometric image of the space $X$ itself, obtained via the canonical map

$$
\begin{equation*}
i: X \rightarrow X^{* *}, \quad i(x)(f):=f(x) \tag{7.7}
\end{equation*}
$$

that maps each element $x$ to the functional $i(x): X^{*} \rightarrow \mathbb{R}$ that evaluates elements $f \in X^{*}$ at the point $x$.

Proposition 7.6.1. Let $(X,\|\cdot\|)$ be a normed space and let $i: X \rightarrow X^{* *}$ be the canonical map defined by (7.7). Then $i$ is linear and isometric, i.e.

$$
\|i(x)\|_{X^{* *}}=\|x\|_{X}
$$

WARNING. We remark that $i$ is in general NOT surjective, e.g.

$$
\left(L^{1}\right)^{* *} \cong\left(L^{\infty}\right)^{*} \nsubseteq L^{1}
$$

However, it turns out that for many important spaces the space $X$ is isometrically isomorphic to its bidual $X^{* *}$. Spaces for which $i(X)=X^{* *}$ are called reflexive, and their properties will be further analysed in part C Functional analysis. Reflexivity (and also separability) is in particular relevant in applications, as it allows one to extract a subsequence of any given bounded sequence that 'converges in the weak sense' to some limit, a property that is hugely relevant as one often tries to prove the existence of a solution of a problem (be it an abstract equation on some Banach space, the existence of a minimiser in calculus of variations or a solution of a PDE) by considering a sequence of approximate solutions (or solutions of approximations of the problem) and hoping to find a subsequence of these approximate solutions that converges in some sense to a solution of the original problem.

From the characterisation of the dual spaces of $\ell^{p}$ and $L^{p}$ obtained above we know in particular

- $\ell^{p}$ is reflexive for $1<p<\infty$ as for $q \in(1, \infty)$ with $\frac{1}{p}+\frac{1}{q}=1$ we have $\left(\ell^{p}\right)^{* *} \cong\left(\ell^{q}\right)^{*} \cong \ell^{p}$
- $L^{p}$ is reflexive for $1<p<\infty$ as for $q \in(1, \infty)$ with $\frac{1}{p}+\frac{1}{q}=1$ we have $\left(L^{p}\right)^{* *} \cong\left(L^{q}\right)^{*} \cong$ $L^{p}$
- $L^{1}, L^{\infty}, \ell^{1}$ and $\ell^{\infty}$ are not reflexive.

By the Riesz representation theorem, we also know that Hilbert spaces are reflexive.
Proof of Proposition 7.6.1. $i$ is clearly a linear map from $X^{*} \rightarrow \mathbb{R}$ and as for any $f \in X^{*}$ with $\|f\|_{X^{*}}=1$

$$
|i(x)(f)|=|f(x)| \leq\|f\|\|x\|=\|x\|
$$

we have that

$$
\|i(x)\|_{X^{* *}}=\sup _{f \in X^{*},\|f\|_{X^{*}}=1}|f(x)| \leq\|x\| .
$$

To see that also $\|i(x)\| \geq\|x\|$ we now choose $f \in X^{*}$ with $\|f\|_{X^{*}}=1$ as in Proposition 6.3.1 so that $f(x)=\|x\|$.

We note that this argument is essentially just a repetition of the proof of Corollary 6.3.2 (i) which directly gives that $\|i(x)\|=\|x\|$.

As the dual space of any normed space is complete, we know in particular that $X^{* *}$ is complete and hence that every closed subspace of $X^{* *}$ is itself a Banach space. This allows us to view any non-complete normed space as a dense subspace of a Banach space.

Corollary 7.6.2. Let $(X,\|\cdot\|)$ be any normed space. Then $(X,\|\cdot\|)$ is isometrically isomorphic to $i(X)$ which can be seen as dense subspace of the Banach space $\left(Y,\|\cdot\|_{X^{* *}}\right)$ where $Y=\overline{i(X)} \subset X^{* *}$.

A Banach space $\left(Y,\|\cdot\|_{Y}\right)$ into which $X$ embeds isometrically as a dense subset is called completion of $X$. Such a completion is determined up to isometric isomorphisms, i.e. given any two spaces $Y, \tilde{Y}$ so that there exist isometric maps $J: X \rightarrow \tilde{\tilde{J}}$ respectively $\tilde{J}: X \rightarrow \tilde{Y}$ for which $J(X)$ (respectively $\tilde{J}(X)$ ) is dense in $Y$ (respectively $\tilde{Y}$ ), we have that there is a (unique) isometric isomorphism $I: Y \rightarrow \tilde{Y}$ so that

$$
\tilde{J}=I \circ J .
$$

Indeed, this map $I$ is determined as the unique extension of $\tilde{J} \circ H, H: J(X) \rightarrow X$ the inverse of the bijective map $J: X \rightarrow J(X)$, from the dense subspace $J(X) \subset Y$ to the whole space $Y$, compare Theorem 4.1.3.


[^0]:    ${ }^{1}$ The Gram-Schmidt process is usually applied to a set of finitely many linearly independent vectors yielding an orthogonal basis of the same cardinality. In our setting, we will lose the latter property as the vectors $y_{i}$ 's are not necessarily linearly independent.

[^1]:    ${ }^{1}$ This means that $\mu$ is a function from the $\sigma$-algebra consisting of measurable subsets of $\Omega$ into $\mathbb{R}$ which is $\sigma$-additive: $\mu\left(\cup_{j=1}^{\infty} E_{j}\right)=\sum_{j=1}^{\infty} \mu\left(E_{j}\right)$ for measurable and mutually disjoint $E_{j}$ 's.
    ${ }^{2}$ The general case of a general finite signed measure is treated using the Hahn-Jordan decomposition theorem, which we do not require for this course. For those who are interested, this theorem asserts that there exists a partition of $\Omega=\Omega^{+} \cup \Omega^{-}$with $\Omega^{ \pm}$measurable such that $\mu(E) \geq 0$ for $E \subset \Omega^{+}$and $\mu(E) \leq 0$ for $E \subset \Omega^{-}$, and consequently $\mu$ can be written as the difference of two non-negative measures $\mu=\mu^{+}-\mu^{-}$ with $\mu^{ \pm}(E)=\left|\mu\left(E \cap \Omega^{ \pm}\right)\right|$. Note that if $|E|=0$, then $\left|E \cap \Omega^{ \pm}\right|=0$, hence $\mu^{ \pm}(E)=0$, that is $\mu^{ \pm}$are absolutely continuous with respect to the Lebesgue measure. Therefore, it suffices to consider the case of non-negative measures.

