

## C3.5 Lie Groups

### Sheet 3 — MT23

Section A contains an introductory question. Section B contains material to test understanding of the course. Section C contains further questions which are optional. Only answers to Section B should be submitted for marking.

### Section A

1. Let  $\mathfrak{sl}(2, \mathbb{R}) = \{A \in M_2(\mathbb{R}) : \text{tr } A = 0\}$ .

(a) Show that  $\mathfrak{sl}(2, \mathbb{R})$  is a Lie algebra with basis

$$e = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad f = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad h = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix},$$

and work out the bracket relations for  $e, f, h$ .

(b) Show that  $\mathfrak{sl}(2, \mathbb{R})$  is not isomorphic to  $\mathfrak{su}(2)$ .

#### Solution:

(a) Since  $\text{tr}(AB) = \text{tr}(BA)$ , the trace of any commutator of square matrices is zero, so  $\mathfrak{sl}(2, \mathbb{R})$  is a Lie algebra when endowed with the matrix commutator. Any traceless  $2 \times 2$  real matrix is uniquely expressible in the form

$$A = \begin{pmatrix} a & b \\ c & -a \end{pmatrix}$$

for real numbers  $a, b$  and  $c$ , so  $\{e, f, h\}$  is a basis for  $\mathfrak{sl}(2, \mathbb{R})$ . By direct calculation we have

$$[h, e] = 2e, \quad [h, f] = -2f, \quad [e, f] = h.$$

(b) Recall  $\mathfrak{su}(2) \cong (\mathbb{R}^3, \times)$  where  $\times$  is the cross product. Any two linearly independent elements of  $\mathbb{R}^3$  generate  $(\mathbb{R}^3, \times)$  since  $v \times w$  is orthogonal to both  $v$  and  $w$  and is non-zero if  $v$  and  $w$  are linearly independent. Therefore  $\mathfrak{su}(2)$  has no 2-dimensional Lie subalgebras. However  $\mathbb{R}\{h, e\}$  is a 2-dimensional Lie subalgebra of  $\mathfrak{sl}(2, \mathbb{R})$ . Thus  $\mathfrak{sl}(2, \mathbb{R})$  and  $\mathfrak{su}(2)$  cannot be isomorphic.

## Section B

2. (a) Let  $\varphi : G_1 \rightarrow G_2$  be a Lie group homomorphism. Show that  $\ker \varphi \subseteq G_1$  is a closed (hence embedded) Lie subgroup with Lie algebra  $\ker(d\varphi_e) \subseteq \mathfrak{g}_1$ .
- (b) A vector subspace  $J \subseteq (V, [\cdot, \cdot])$  of a Lie algebra is called an *ideal* if  $[v, j] \in J$  for all  $v \in V, j \in J$ . Show that ideals are Lie subalgebras.
- (c) Let  $H$  be a Lie subgroup of  $G$ , with  $H, G$  connected. Show that  $H$  is a normal subgroup of  $G \Leftrightarrow \mathfrak{h} \subseteq \mathfrak{g}$  is an ideal.  
 [You may find it helpful to show that  $ge^Yg^{-1} = e^{\text{Ad}(g).Y}$  for  $g \in G$  and  $Y \in \mathfrak{g}$ .]
- (d) The *centre* of a Lie algebra  $(V, [\cdot, \cdot])$  is

$$Z(V) = \{v \in V : [v, w] = 0 \text{ for all } w \in V\}.$$

For  $G$  connected, prove that the centre of the group  $G$  is

$$Z(G) = \ker(\text{Ad} : G \rightarrow \text{Aut}(\mathfrak{g}))$$

- (e) Deduce that the centre of  $G$  is a closed (hence embedded) Lie subgroup of  $G$  which is abelian, normal and has Lie algebra  $\text{Lie}(Z(G)) = Z(\mathfrak{g})$ .
- (f) Finally deduce that, for  $G$  connected,  $G$  is abelian  $\Leftrightarrow \mathfrak{g}$  is abelian.
3. (a) Show that if  $X, Y$  belong to the Lie algebra of a Lie group  $G$  then
- $$[X, Y] = 0 \Rightarrow \exp(X + Y) = \exp(X)\exp(Y).$$
- (b) Prove that if  $G$  is a connected Lie group with  $Z(G) = \{e\}$  then  $G$  can be identified with a Lie subgroup of  $\text{GL}(N, \mathbb{R})$ , for some  $N$ , so  $\mathfrak{g}$  is a Lie subalgebra of  $\mathfrak{gl}(N, \mathbb{R})$ .
- (c) If  $(V, [\cdot, \cdot])$  is a Lie algebra with  $Z(V) = \{0\}$ , show that  $V$  is the Lie algebra of some Lie group.
4. Find all the connected Lie subgroups of  $\text{SO}(3)$ .
5. (a) Show that Lebesgue measure is the bi-invariant Haar measure on  $\mathbb{R}^n$  viewed as an additive group.
- (b) Find the bi-invariant Haar measure on  $(\mathbb{R}_{>0}, \times)$ , the multiplicative group of positive reals.
6. Give an example of an *irreducible* representation of  $S^1$  on  $\mathbb{R}^2$ . Describe what happens to this representation when we complexify it.

## Section C

7. (a) Let  $\phi : G \rightarrow \text{Aut}(V)$  be a representation. If  $\alpha : G \rightarrow G$  is an automorphism show that  $\phi \circ \alpha$  is another representation on the same vector space.
- (b) If  $\alpha(g) = hgh^{-1}$  for some  $h \in G$  show that the two representations are equivalent.
- (c) Give an example of an automorphism where the two representations are not equivalent.
8. Consider the action of  $\text{SO}(3)$  on  $\mathbb{R}^3$  and let  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  be a smooth real-valued function.
- (a) For  $A \in \text{SO}(3)$  show that  $(Af)(x) = f(A^{-1}x)$  defines an action of  $\text{SO}(3)$  on the space of all smooth functions.
- (b) If  $r^2 = x_1^2 + x_2^2 + x_3^2$  show that  $Af = f$ .
- (c) Let  $\Delta$  denote the Laplace operator

$$\Delta f = \sum_{i=1}^3 \frac{\partial^2 f}{\partial x_i^2}.$$

Show that  $A\Delta f = \Delta Af$ .

- (d) Consider the vector space of functions of the form  $f = p$  where  $p(x_1, x_2, x_3)$  is a homogeneous polynomial of degree  $m$ . Show that this is a finite-dimensional representation  $V_m$  of  $\text{SO}(3)$  and calculate its dimension.
- (e) Let  $H_m \subseteq V_m$  be the subspace of solutions to  $\Delta f = 0$  for  $f \in V_m$ , the harmonic polynomials of degree  $m$ . Show that  $H_m$  is a representation space for  $\text{SO}(3)$  and that  $V_2 = H_2 \oplus r^2 H_0$  and  $V_3 = H_3 \oplus r^2 H_1$  are decompositions into inequivalent representations.
- (f) Can you generalize this?