

Numerical Solution of Partial Differential Equations

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Lecture 12

Finite difference approximation of hyperbolic equations

The simplest example of a second-order linear hyperbolic equation is the linear wave equation

$$\frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = f(x, t),$$

where $c > 0$ is the wave speed and f is a given source term.

When $f \equiv 0$ and the equation is considered on the whole real line, $x \in \mathbb{R}$, by supplying two initial conditions

$$\begin{aligned}u(x, 0) &= u_0(x) \quad \text{for } x \in \mathbb{R}, \\ \frac{\partial u}{\partial t}(x, 0) &= u_1(x) \quad \text{for } x \in \mathbb{R},\end{aligned}$$

where $u_0 \in C^2(\mathbb{R})$ and $u_1 \in C^1(\mathbb{R})$, the solution is given by **d'Alembert's formula**:

$$u(x, t) = \frac{1}{2} [u_0(x - ct) + u_0(x + ct)] + \frac{1}{2c} \int_{x-ct}^{x+ct} u_1(\xi) \, d\xi.$$

More generally, if $f \in C(\mathbb{R} \times [0, \infty))$, then

$$\begin{aligned} u(x, t) = & \frac{1}{2} [u_0(x - ct) + u_0(x + ct)] \\ & + \frac{1}{2c} \int_{x-ct}^{x+ct} u_1(\xi) d\xi \quad + \frac{1}{2c} \int_0^t \int_{x-c(t-\tau)}^{x+c(t-\tau)} f(s, \tau) ds d\tau. \end{aligned}$$

We shall be interested in a problem of the above form in the physically more realistic setting where $x \in [a, b]$, with $a < b$, and $t \in [0, T]$, $T > 0$.

Then, in addition to the two initial conditions above, boundary conditions need to be prescribed at $x = a$ and $x = b$, and the problem thus becomes an initial-boundary-value problem.

Finite difference approximation of hyperbolic equations

We shall be concerned with the initial-boundary-value problem

$$\begin{aligned}\frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} &= f(x, t) && \text{for } (x, t) \in (a, b) \times (0, T], \\ u(x, 0) &= u_0(x) && \text{for } x \in [a, b], \\ \frac{\partial u}{\partial t}(x, 0) &= u_1(x) && \text{for } x \in [a, b], \\ u(a, t) = 0 \quad \text{and} \quad u(b, t) &= 0 && \text{for } t \in [0, T].\end{aligned}\tag{1}$$

Here, $f \in C((a, b) \times (0, T])$, $u_0, u_1 \in C([a, b])$, and we shall assume compatibility of the initial data with the boundary conditions, in the sense that $u_0(a) = u_0(b) = 0$ and $u_1(a) = u_1(b) = 0$; $c > 0$ is the wave speed.

Energy (in)equality

The analysis of the finite difference scheme for (1) is based on a ‘discrete energy inequality’, which will imply the stability of the scheme.

We begin by describing the derivation of the ‘energy inequality’ for the solution of the initial-boundary-value problem (1).

Note:

The proof of existence of a solution to the initial-boundary-value problem (1) is beyond the scope of this course; we shall suppose here that a solution u to (1) exists and that u is sufficiently smooth, so that our calculations are meaningful.

We begin by multiplying the PDE (1)₁ by the time derivative of u , and we then integrate over the interval $[a, b]$; thus,

$$\begin{aligned} \int_a^b \frac{\partial^2 u}{\partial t^2}(x, t) \frac{\partial u}{\partial t}(x, t) dx - c^2 \int_a^b \frac{\partial^2 u}{\partial x^2}(x, t) \frac{\partial u}{\partial t}(x, t) dx \\ = \int_a^b f(x, t) \frac{\partial u}{\partial t}(x, t) dx. \end{aligned} \quad (2)$$

As $u(a, t) = 0$ and $u(b, t) = 0$ for all $t \in [0, T]$, it follows that

$$\frac{\partial u}{\partial t}(a, t) = 0 \quad \text{and} \quad \frac{\partial u}{\partial t}(b, t) = 0 \quad \text{for all } t \in [0, T].$$

By partial integration with respect to x in the second term on the left-hand side of (2):

$$\begin{aligned} \int_a^b \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial t}(x, t) \right) \frac{\partial u}{\partial t}(x, t) dx \\ + c^2 \int_a^b \frac{\partial u}{\partial x}(x, t) \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial x}(x, t) \right) dx = \int_a^b f(x, t) \frac{\partial u}{\partial t}(x, t) dx. \end{aligned} \quad (3)$$

Clearly,

$$\frac{\partial}{\partial t} \left(\frac{\partial u}{\partial t} \right) \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial t} \right)^2 \quad \text{and} \quad \frac{\partial u}{\partial x} \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial x} \right) = \frac{1}{2} \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial x} \right)^2,$$

and therefore

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int_a^b \left(\frac{\partial u}{\partial t} \right)^2 (x, t) dx + \frac{c^2}{2} \frac{d}{dt} \int_a^b \left(\frac{\partial u}{\partial x} \right)^2 (x, t) dx \\ = \int_a^b f(x, t) \frac{\partial u}{\partial t}(x, t) dx. \end{aligned} \quad (4)$$

When f is identically zero, the r.h.s. of (4) vanishes, and after integrating the expression from 0 to t , for any $t \in (0, T]$, we have

$$\begin{aligned} \frac{1}{2} \int_a^b \left(\frac{\partial u}{\partial t} \right)^2 (x, t) dx + \frac{c^2}{2} \int_a^b \left(\frac{\partial u}{\partial x} \right)^2 (x, t) dx \\ = \frac{1}{2} \int_a^b \left(\frac{\partial u}{\partial t} \right)^2 (x, 0) dx + \frac{c^2}{2} \int_a^b \left(\frac{\partial u}{\partial x} \right)^2 (x, 0) dx. \end{aligned} \tag{5}$$

The l.h.s. side of the equality (5) can be viewed as the ‘total energy’ at time t and the r.h.s. as the ‘initial total energy’. Thus, (5) expresses conservation of the total energy during the course of the evolution of the solution from time 0 to time $t \in (0, T]$, in the absence of a source term.

After multiplying (5) by 2 and defining

$$\mathcal{L}^2(u(\cdot, t)) := \int_a^b \left(\frac{\partial u}{\partial t} \right)^2 (x, t) dx + c^2 \int_a^b \left(\frac{\partial u}{\partial x} \right)^2 (x, t) dx$$

for $t \in [0, T]$, the equality (5) can be rewritten as

$$\mathcal{L}^2(u(\cdot, t)) = \mathcal{L}^2(u(\cdot, 0)) \quad \text{for all } t \in [0, T].$$

It is this argument that we shall try to mimic in our stability analysis of the finite difference approximation of the problem when $f \equiv 0$.

Note: The mapping

$$u \mapsto \max_{t \in [0, T]} [\mathcal{L}^2(u(\cdot, t))]^{1/2}$$

is a norm on the linear space of all functions $u \in C^1([a, b] \times [0, T])$ such that $u(a, t) = u(b, t) = 0$ for all $t \in [0, T]$, called the **energy norm**.

More generally, if f is not identically zero, then (4) implies that

$$\mathcal{L}^2(u(\cdot, t)) = \mathcal{L}^2(u(\cdot, 0)) + 2 \int_0^t \int_a^b f(x, \tau) \frac{\partial u}{\partial \tau}(x, \tau) dx d\tau.$$

As

$$2\alpha\beta \leq \alpha^2 + \beta^2, \quad \text{for all } \alpha, \beta \in \mathbb{R},$$

it follows that

$$\begin{aligned} \mathcal{L}^2(u(\cdot, t)) &\leq \mathcal{L}^2(u(\cdot, 0)) + \int_0^t \int_a^b f^2(x, \tau) dx d\tau + \int_0^t \int_a^b \left(\frac{\partial u}{\partial \tau} \right)^2(x, \tau) dx d\tau \\ &\leq \mathcal{L}^2(u(\cdot, 0)) + \int_0^t \int_a^b f^2(x, \tau) dx d\tau + \int_0^t \mathcal{L}^2(u(\cdot, \tau)) d\tau. \end{aligned} \tag{6}$$

To proceed, we need the following result.

Lemma (Gronwall's Lemma)

Suppose that A and B are continuous real-valued nonnegative functions defined on $[0, T]$, and B is a nondecreasing function of its argument. Let

$$A(t) \leq B(t) + \int_0^t A(s) \, ds$$

for all $t \in [0, T]$; then,

$$A(t) \leq e^t B(t)$$

for all $t \in [0, T]$.

PROOF: Clearly,

$$e^{-t} A(t) - e^{-t} \int_0^t A(s) \, ds \leq e^{-t} B(t),$$

and thus, equivalently,

$$\frac{d}{dt} \left[e^{-t} \int_0^t A(s) \, ds \right] \leq e^{-t} B(t).$$

By integrating this and noting that the expression in the square brackets vanishes at $t = 0$,

$$e^{-t} \int_0^t A(s) \, ds \leq \int_0^t e^{-s} B(s) \, ds.$$

Multiplying by e^t , and since B is a nondecreasing nonnegative function, whereby $B(s) \leq B(t)$ for all $s \in [0, t]$, we have that

$$\int_0^t A(s) \, ds \leq e^t B(t) \int_0^t e^{-s} \, ds = e^t B(t) (1 - e^{-t}) = e^t B(t) - B(t).$$

Substituting this into the r.h.s. of the inequality in the statement of the lemma gives: $A(t) \leq B(t) + e^t B(t) - B(t) = e^t B(t)$. \square

We now return to (6) and set

$$A(t) := \mathcal{L}^2(u(\cdot, t)) \quad \text{and} \quad B(t) := \mathcal{L}^2(u(\cdot, 0)) + \int_0^t \int_a^b f^2(x, \tau) \, dx \, d\tau.$$

It then follows from Gronwall's lemma that $A(t) \leq e^t B(t)$, that is

$$\mathcal{L}^2(u(\cdot, t)) \leq e^t \left(\mathcal{L}^2(u(\cdot, 0)) + \int_0^t \int_a^b f^2(x, \tau) \, dx \, d\tau \right),$$

with

$$\mathcal{L}^2(u(\cdot, t)) := \int_a^b \left(\frac{\partial u}{\partial t} \right)^2 (x, t) \, dx + c^2 \int_a^b \left(\frac{\partial u}{\partial x} \right)^2 (x, t) \, dx$$

and

$$\begin{aligned} \mathcal{L}^2(u(\cdot, 0)) &:= \int_a^b \left(\frac{\partial u}{\partial t} \right)^2 (x, 0) \, dx + c^2 \int_a^b \left(\frac{\partial u}{\partial x} \right)^2 (x, 0) \, dx \\ &= \|u_1\|_{L_2((a,b))}^2 + c^2 \|u_0\|_{H^1((a,b))}^2 \end{aligned}$$

This is the desired energy inequality satisfied by the solution.

It provides a bound on the (square of the) energy-norm of the solution in terms of the (square of the) norm of the initial data and the (square of the) L_2 norm of the source term f .

We shall mimic the derivation of this energy inequality in the stability analysis of the implicit and explicit finite difference schemes for the initial-boundary-value problem (1).