

# Viscous Flow

## Sheet : $\nabla^2 \mathbf{u}$ — Michaelmas Term 2024

1. Given that in spherical polar coordinates  $x = r \sin \theta \cos \phi$ ,  $y = r \sin \theta \sin \phi$ ,  $z = r \cos \theta$ , for any differentiable scalar field  $f$  and any differentiable vector field  $\mathbf{F} = F_r \mathbf{e}_r + F_\theta \mathbf{e}_\theta + F_\phi \mathbf{e}_\phi$ ,

$$\begin{aligned}\nabla f &= \frac{\partial f}{\partial r} \mathbf{e}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \mathbf{e}_\theta + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} \mathbf{e}_\phi, \\ \nabla \cdot \mathbf{F} &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 F_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (F_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial F_\phi}{\partial \phi}, \\ \nabla \wedge \mathbf{F} &= \frac{1}{r^2 \sin \theta} \begin{vmatrix} \mathbf{e}_r & r \mathbf{e}_\theta & r \sin \theta \mathbf{e}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ F_r & r F_\theta & r \sin \theta F_\phi \end{vmatrix}\end{aligned}$$

and

$$\nabla^2 f = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2},$$

work out  $\nabla^2 \mathbf{u}$  in spherical coordinates.

### Solution:

We establish the relationship by considering each of the three components. First we calculate

$$\begin{aligned}\nabla \wedge \mathbf{u} &= \frac{1}{r^2 \sin \theta} \left[ \left( \frac{\partial}{\partial \theta} (r \sin \theta u_\phi) - \frac{\partial}{\partial \phi} (r u_\theta) \right) \mathbf{e}_r + r \left( \frac{\partial u_r}{\partial \phi} - \frac{\partial}{\partial r} (r \sin \theta u_\phi) \right) \mathbf{e}_\theta \right. \\ &\quad \left. + r \sin \theta \left( \frac{\partial}{\partial r} (r u_\theta) - \frac{\partial u_r}{\partial \theta} \right) \mathbf{e}_\phi \right] \\ &= \left( \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{\cos \theta}{r \sin \theta} u_\phi - \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} \right) \mathbf{e}_r + \left( \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{1}{r} u_\phi - \frac{\partial u_\phi}{\partial r} \right) \mathbf{e}_\theta \\ &\quad + \left( \frac{\partial u_\theta}{\partial r} + \frac{1}{r} u_\theta - \frac{1}{r} \frac{\partial u_r}{\partial \theta} \right) \mathbf{e}_\phi.\end{aligned}$$

We first consider the components in the  $\mathbf{e}_r$  direction, so

$$\begin{aligned}(\nabla \wedge \nabla \wedge \mathbf{u}) \cdot \mathbf{e}_r &= \frac{1}{r^2 \sin \theta} \left[ \frac{\partial}{\partial \theta} \left( r \sin \theta \left( \frac{\partial u_\theta}{\partial r} + \frac{1}{r} u_\theta - \frac{1}{r} \frac{\partial u_r}{\partial \theta} \right) \right) \right. \\ &\quad \left. - \frac{\partial}{\partial \phi} \left( \frac{1}{\sin \theta} \frac{\partial u_r}{\partial \phi} - u_\phi - r \frac{\partial u_\phi}{\partial r} \right) \right] \\ &= \frac{1}{r} \frac{\partial^2 u_\theta}{\partial \theta \partial r} + \frac{1}{r^2} \frac{\partial u_\theta}{\partial \theta} - \frac{1}{r^2} \frac{\partial^2 u_r}{\partial \theta^2} - \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_r}{\partial \phi^2} + \frac{1}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} \\ &\quad + \frac{1}{r \sin \theta} \frac{\partial^2 u_\phi}{\partial \phi \partial r} + \frac{\cos \theta}{r \sin \theta} \frac{\partial u_\theta}{\partial r} + \frac{\cos \theta}{r^2 \sin \theta} u_\theta - \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial u_r}{\partial \theta}.\end{aligned}$$

We also have that

$$\begin{aligned}
 (\nabla(\nabla \cdot \mathbf{u})) \cdot \mathbf{e}_r &= \frac{\partial}{\partial r} \left( \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 u_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (u_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right) \\
 &= \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial u_r}{\partial r} \right) - \frac{2}{r^2} u_r - \frac{1}{r^2} \frac{\partial u_\theta}{\partial \theta} + \frac{1}{r} \frac{\partial^2 u_\theta}{\partial r \partial \theta} - \frac{\cos \theta}{r^2 \sin \theta} u_\theta \\
 &\quad + \frac{\cos \theta}{r \sin \theta} \frac{\partial u_\theta}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial^2 u_\phi}{\partial r \partial \phi} - \frac{1}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi}.
 \end{aligned}$$

So

$$\begin{aligned}
 (\nabla^2 \mathbf{u}) \cdot \mathbf{e}_r &= (\nabla(\nabla \cdot \mathbf{u})) \cdot \mathbf{e}_r - (\nabla \wedge \nabla \wedge \mathbf{u}) \cdot \mathbf{e}_r \\
 &= \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial u_r}{\partial r} \right) - \frac{2}{r^2} u_r - \frac{1}{r^2} \frac{\partial u_\theta}{\partial \theta} + \frac{1}{r} \frac{\partial^2 u_\theta}{\partial r \partial \theta} - \frac{\cos \theta}{r^2 \sin \theta} u_\theta \\
 &\quad + \frac{\cos \theta}{r \sin \theta} \frac{\partial u_\theta}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial^2 u_\phi}{\partial r \partial \phi} - \frac{1}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} \\
 &\quad - \frac{1}{r} \frac{\partial^2 u_\theta}{\partial \theta \partial r} - \frac{1}{r^2} \frac{\partial u_\theta}{\partial \theta} + \frac{1}{r^2} \frac{\partial^2 u_r}{\partial \theta^2} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_r}{\partial \phi^2} - \frac{1}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} \\
 &\quad - \frac{1}{r \sin \theta} \frac{\partial^2 u_\phi}{\partial \phi \partial r} - \frac{\cos \theta}{r \sin \theta} \frac{\partial u_\theta}{\partial r} - \frac{\cos \theta}{r^2 \sin \theta} u_\theta + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial u_r}{\partial \theta} \\
 &= \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial u_r}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u_r}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial u_r}{\partial \theta} + \frac{1}{r^2 \sin \theta} \frac{\partial^2 u_r}{\partial \phi^2} \\
 &\quad - \frac{2}{r^2} u_r - \frac{2}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} - \frac{2 \cos \theta}{r^2 \sin \theta} u_\theta - \frac{2}{r^2} \frac{\partial u_\theta}{\partial \theta},
 \end{aligned}$$

$$\boxed{\therefore (\nabla^2 \mathbf{u}) \cdot \mathbf{e}_r = \nabla^2 u_r - \frac{2}{r^2} u_r - \frac{2}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (u_\theta \sin \theta) - \frac{2}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \theta}},$$

where we have used the definition of  $\nabla^2 f$  to simplify the RHS. Next we look at the  $\mathbf{e}_\theta$  components:

$$\begin{aligned}
 (\nabla \wedge \nabla \wedge \mathbf{u}) \cdot \mathbf{e}_\theta &= \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \phi} \left( \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{\cos \theta}{r \sin \theta} u_\phi - \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} \right) \right. \\
 &\quad \left. - \frac{\partial}{\partial r} \left( r \sin \theta \frac{\partial u_\theta}{\partial r} + \sin \theta u_\theta - \sin \theta \frac{\partial u_r}{\partial \theta} \right) \right] \\
 &= \frac{1}{r^2 \sin \theta} \frac{\partial^2 u_\phi}{\partial \theta \partial \phi} + \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi} - \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\theta}{\partial \phi^2} - \frac{1}{r} \frac{\partial u_\theta}{\partial r} \\
 &\quad - \frac{\partial^2 u_\theta}{\partial r^2} - \frac{1}{r} \frac{\partial u_\theta}{\partial r} + \frac{1}{r} \frac{\partial^2 u_r}{\partial r \partial \theta},
 \end{aligned}$$

while

$$\begin{aligned}
 (\nabla(\nabla \cdot \mathbf{u})) \cdot \mathbf{e}_\theta &= \frac{1}{r} \frac{\partial}{\partial \theta} \left( \frac{\partial u_r}{\partial r} + \frac{2}{r} u_r + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{\cos \theta}{r \sin \theta} u_\theta + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right) \\
 &= \frac{1}{r} \frac{\partial^2 u_r}{\partial \theta \partial r} + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} + \frac{1}{r^2} \frac{\partial^2 u_\theta}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial u_\theta}{\partial \theta} - \frac{u_\theta}{r^2 \sin^2 \theta} \\
 &\quad + \frac{1}{r^2 \sin \theta} \frac{\partial^2 u_\phi}{\partial \theta \partial \phi} - \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi}.
 \end{aligned}$$

Thus,

$$\begin{aligned}
 (\nabla^2 \mathbf{u}) \cdot \mathbf{e}_\theta &= \frac{1}{r} \frac{\partial^2 u_r}{\partial \theta \partial r} + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} + \frac{1}{r^2} \frac{\partial^2 u_\theta}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial u_\theta}{\partial \theta} - \frac{u_\theta}{r^2 \sin^2 \theta} \\
 &\quad + \frac{1}{r^2 \sin \theta} \frac{\partial^2 u_\phi}{\partial \theta \partial \phi} - \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi} - \frac{1}{r^2 \sin \theta} \frac{\partial^2 u_\phi}{\partial \theta \partial \phi} - \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi} \\
 &\quad + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\theta}{\partial \phi^2} + \frac{1}{r} \frac{\partial u_\theta}{\partial r} + \frac{\partial^2 u_\theta}{\partial r^2} + \frac{1}{r} \frac{\partial u_\theta}{\partial r} - \frac{1}{r} \frac{\partial^2 u_r}{\partial r \partial \theta}
 \end{aligned}$$

$$\boxed{\therefore (\nabla^2 \mathbf{u}) \cdot \mathbf{e}_\theta = \nabla^2 u_\theta + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi}.}$$

Finally, we consider the  $\mathbf{e}_\phi$  components:

$$\begin{aligned}
 (\nabla \wedge \nabla \wedge \mathbf{u}) \cdot \mathbf{e}_\phi &= \frac{1}{r} \left[ \frac{\partial}{\partial r} \left( \frac{1}{\sin \theta} \frac{\partial u_r}{\partial \phi} - u_\phi - r \frac{\partial u_\phi}{\partial r} \right) \right. \\
 &\quad \left. - \frac{\partial}{\partial \theta} \left( \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{\cos \theta}{r \sin \theta} u_\phi - \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} \right) \right] \\
 &= \frac{1}{r \sin \theta} \frac{\partial^2 u_r}{\partial r \partial \phi} - \frac{2}{r} \frac{\partial u_\phi}{\partial r} - \frac{\partial^2 u_\phi}{\partial r^2} - \frac{1}{r^2} \frac{\partial^2 u_\phi}{\partial \theta^2} - \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \theta} \\
 &\quad + \frac{u_\phi}{r^2 \sin^2 \theta} + \frac{1}{r^2 \sin \theta} \frac{\partial^2 u_\theta}{\partial \theta \partial \phi} - \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \phi}
 \end{aligned}$$

and

$$\begin{aligned}
 (\nabla (\nabla \cdot \mathbf{u})) \cdot \mathbf{e}_\phi &= \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \left( \frac{\partial u_r}{\partial r} + \frac{2}{r} u_r + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{\cos \theta}{r \sin \theta} u_\theta + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right) \\
 &= \frac{1}{r \sin \theta} \frac{\partial^2 u_r}{\partial \phi \partial r} + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{1}{r^2 \sin \theta} \frac{\partial^2 u_\theta}{\partial \phi \partial \theta} \\
 &\quad + \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \phi} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\phi}{\partial \phi^2}
 \end{aligned}$$

Thus,

$$\begin{aligned}
 (\nabla^2 \mathbf{u}) \cdot \mathbf{e}_\phi &= \frac{1}{r \sin \theta} \frac{\partial^2 u_r}{\partial \phi \partial r} + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{1}{r^2 \sin \theta} \frac{\partial^2 u_\theta}{\partial \phi \partial \theta} + \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \phi} \\
 &\quad + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\phi}{\partial \phi^2} - \frac{1}{r \sin \theta} \frac{\partial^2 u_r}{\partial r \partial \phi} + \frac{2}{r} \frac{\partial u_\phi}{\partial r} + \frac{\partial^2 u_\phi}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 u_\phi}{\partial \theta^2} \\
 &\quad + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \theta} - \frac{u_\phi}{r^2 \sin^2 \theta} - \frac{1}{r^2 \sin \theta} \frac{\partial^2 u_\theta}{\partial \theta \partial \phi} + \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \phi}
 \end{aligned}$$

$$\boxed{\therefore (\nabla^2 \mathbf{u}) \cdot \mathbf{e}_\phi = \nabla^2 u_\phi + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r^2 \sin^2 \theta} + \frac{2 \cos \theta}{r^2 \sin \theta} \frac{\partial u_\theta}{\partial \phi}.}$$