

C3.3 Differentiable manifolds - Class 2 / Sheet 2 13 Nov Set 3

3(a). Let $S^n = \{(x_0, \dots, x_n) \in \mathbb{R}^{n+1} : \sum_{j=0}^n |x_j|^2 = 1\}$

Explain why $T_{(x_0, \dots, x_n)} S^n \cong \{(y_0, \dots, y_n) \in \mathbb{R}^{n+1} / x_0 y_0 + \dots + x_n y_n = 0\}$

Proof. We first recall our definitions

Def. Let X be a mfd. A tangent vector at $x \in X$ is a linear map $v: C^\infty(X) \rightarrow \mathbb{R}$ satisfying $v(ab) = a(x)v(b) + b(x)v(a)$ (Leibniz rule).

Set of tangent vectors at a point $x: T_x X \cong \mathbb{R}^n, n = \dim X$

Def. Given $f: X \rightarrow Y$ smooth, define the differential

$T_x f: T_x X \rightarrow T_{f(x)} Y$ by $(T_x f)(v): a \mapsto v(a \circ f)$ for $v \in T_x X, a \in C^\infty(Y)$.

Prop. If $g: Y \rightarrow Z, T_x(g \circ f) = T_{f(x)} g \circ T_x f: T_x X \rightarrow T_z Z$.
Chain rule

Def. An immersion f satisfies $T_x f: T_x X \rightarrow T_{f(x)} Y$ is an injection $\forall x$.
submanifold

embedding if it is an immersion & $f: X \rightarrow f(X)$ is a homeomorphism.
 $f(X) \subset Y$ the subspace topology.

Recall that $S^n \hookrightarrow \mathbb{R}^{n+1}$ is an embedding, consequently an immersion. We have a map $f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ given

$$\text{by } f(x) = f((x_0, \dots, x_n)) = x_0^2 + \dots + x_n^2 - 1.$$

We would like to compute $T_x f: T_x \mathbb{R}^{n+1} \rightarrow \mathbb{R}$.

Let's do this, in full generality. This is the last time you'll see explicit charts, I promise...

Let $f: X \rightarrow Y$ be smooth, $x \in X$, $\varphi: U \rightarrow X$ a chart in a neigh. of x and $\psi: V \rightarrow Y$ a chart in a neigh. of $f(x)$.

Suppose $\varphi(\vec{u}) = x$ and $\psi(\vec{v}) = f(x)$. We know that $\{\partial_j^x, j=1, \dots, n\}$ are a basis for $T_x X$, where

$$\partial_j^x: C^\infty(X) \rightarrow \mathbb{R} \text{ is given by } \partial_j^x(b) = \frac{\partial}{\partial x_j}(b \circ \varphi) \Big|_{\vec{u}}.$$

similarly, basis $\partial_j^y(a) = \frac{\partial}{\partial y_j}(a \circ \psi) \Big|_{\vec{v}}$ for $T_{f(x)} Y$.

We also choose coordinates $y_1, \dots, y_m$ on Y ; now compute $T_x f$: by def'n $(T_x f)(v): a \mapsto v(a \circ f)$, where $a \in C^\infty(Y)$.

Take $v = \partial_j^x$; then $[(T_x f)(\partial_j^x)](a)$

$$= \partial_j^x(a \circ f) = \frac{\partial}{\partial x_j}(a \circ f \circ \varphi) \Big|_{\vec{u}} = \frac{\partial}{\partial x_j}((a \circ \psi) \circ (\psi^{-1} \circ f \circ \varphi)) \Big|_{\vec{u}}$$

Now, write f in coordinates, more explicitly $\psi^{-1} \circ f \circ \varphi: \mathbb{R}^n \rightarrow \mathbb{R}^m$ as $(\psi^{-1} \circ f \circ \varphi)(x_1, \dots, x_n) = \begin{pmatrix} f_1(x_1, \dots, x_n) \\ \vdots \\ f_m(x_1, \dots, x_n) \end{pmatrix}.$

We now use the chain rule $\mathbb{R}^n \xrightarrow{\psi^{-1} \circ f \circ \psi} \mathbb{R}^m \xrightarrow{a \circ f} \mathbb{R}$ to get

$$= \sum_{i=1}^m \frac{\partial}{\partial x_j} (\psi^{-1} \circ f \circ \psi)_i \Big|_{\vec{u}} \cdot \frac{\partial}{\partial y_i} (a \circ f) \Big|_{\vec{v}} (\psi^{-1} \circ f \circ \psi)(\vec{u})$$

Hence, $\psi(\vec{u}) = x$, $f(x) = \psi(\vec{v})$, so $(\psi^{-1} \circ f \circ \psi)(\vec{u}) = \vec{v}$
and this is consequently

$$= \sum_{i=1}^m \frac{\partial f_i}{\partial x_j}(\vec{u}) \frac{\partial}{\partial y_i} (a \circ f) \Big|_{\vec{v}} = \left(\sum_{i=1}^m \frac{\partial f_i}{\partial x_j}(\vec{u}) \vec{\partial}_i^Y \right) a$$

where $\{\vec{\partial}_i^Y \mid i=1, \dots, m\}$ span $T_{f(x)}Y$ via $\vec{\partial}_i^Y a = \frac{\partial}{\partial y_i} (a \circ f) \Big|_{\vec{v}}$.

Therefore the general formula is

$$T_x f \left(\sum_{j=1}^n c_j \partial_j^X \right) = \sum_{i,j=1}^{m,n} c_j \frac{\partial f_i}{\partial x_j}(\vec{u}) \partial_i^Y$$

Coming back to our problem, taking coordinate y on $\mathbb{R}$, (ident is identity)

$$\begin{aligned} (T_x f)(y_0, \dots, y_n) &= T_x f \left(\sum_{j=0}^n y_j \frac{\partial}{\partial x_j} \right) = \sum_{j=0}^n y_j \frac{\partial f}{\partial x_j} \Big|_x \frac{d}{dr} \\ &= \left(\sum_{j=0}^n 2x_j y_j \right) \frac{d}{dr} = \sum_{j=0}^n 2x_j y_j, \text{ where we identify } T_x \mathbb{R}^{n+1} \cong \mathbb{R}^{n+1} \end{aligned}$$

Since $\vec{x} \neq 0$ on S^n , $T_x f$ is surjective.

Now we make use of the functoriality of the pushforward. $T_0 \mathbb{R} \cong \mathbb{R}$.

$$\begin{array}{ccccc} S^n & \xrightarrow{i} & \mathbb{R}^{n+1} & \xrightarrow{f} & \mathbb{R} \\ (x_0, \dots, x_n) & \mapsto & (x_0, \dots, x_n) & \mapsto & x_0^2 + \dots + x_n^2 - 1 \end{array} \quad \text{satishies } f \circ i = 0.$$

Consequently there are the induced maps

$$0 \longrightarrow T_x S^n \xrightarrow{T_x i} T_x \mathbb{R}^{n+1} \xrightarrow{T_x f} T_x \mathbb{R} \longrightarrow 0$$

$$T_x f \circ T_x i = T_x(f \circ i) = T_x 0 = 0$$

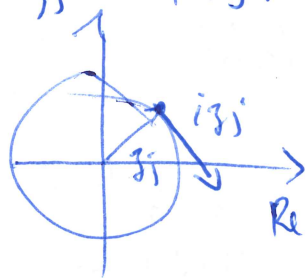
$T_x i$ is injective since i is an embedding; $T_x f$ is surjective by what we just showed. $\rightarrow \dim \ker(T_x f) = n$; since this is a chain complex with $\text{im } T_x i \subseteq \ker T_x f$ and both are of dim n , we have that it is a short exact sequence of vector spaces & it is split, so that $\exists$ canonical isomorphism

$$T_x S^n \cong \ker(T_x f) = \{(y_0, \dots, y_n) \mid \sum_{j=0}^n x_j y_j = 0\}.$$

(b) Show that each odd-dimensional sphere has a nonvanishing vector field.

proof. The hint said $\mathbb{R}^{2k+2} \cong \mathbb{C}^{k+1}$; more specifically we can say $S^{2k+1} = \{(z_0, \dots, z_k) \in \mathbb{C}^{k+1} \mid |z_0|^2 + \dots + |z_k|^2 = 1\}$; projecting onto the j -th factor gives

$$\text{Im } z_j: |z_j|^2 = 1 - |z_0|^2 - \dots - |z_{j-1}|^2 - |z_{j+1}|^2 - \dots - |z_k|^2, \text{ this is a circle.}$$



You can pick a nonvanishing v.f. using the identification of (1) by $(-x_{2j+1}, x_{2j})$

$$\text{i.e. } z_j = x_{2j} + i x_{2j+1} \mapsto i z_j = -x_{2j+1} + i x_{2j}$$

One can now postulate of those found; each is nonvanishing when $\beta_i \neq 0$ and they are "orthogonal"; we get a vector field N given at $x = x_0, \dots, x_{2k+1}$ by

$$(-x_1, x_0, -x_3, x_2, \dots, -x_{2k+1}, x_{2k})$$

Claim. There are no nonvanishing vector fields on S^{2n} , $n > 0$.

proof. The Poincaré-Hopf theorem says that for a v.f. v ,

$$\sum_{\text{zeros of } v} \text{index}_i(v) = \chi(M). \quad \text{The Euler characteristic}$$

$$\text{is defined as } \chi(M) = \sum \dim H_i(M, \mathbb{R}) (-1)^i$$

$$\text{we have } H_i(S^k) = \begin{cases} \mathbb{Z} & \text{if } i=0, k \\ 0 & \text{otherwise} \end{cases}, \text{ so}$$

$$\chi(S^{2n}) = 2, \quad \chi(S^{2n+1}) = 0.$$

So, if v is nonvanishing everywhere, we get $0 = 2$, contradiction. □

alternatively,

- rescale v to unit length

- then it via the exponential map to length π

↳ we get an antipodal map homotopic to id.

but antipodal map has degree $(-1)^{n+1}$, since it is the composition of the $(n+1)$ plane reflections.

4. v, w vector fields on X^n .

$$[v, w] = \sum_{i,j=1}^n \left(v_i \frac{\partial w_j}{\partial x_i} \frac{\partial}{\partial x_j} - w_j \frac{\partial v_i}{\partial x_j} \frac{\partial}{\partial x_i} \right)$$

show that this is indep. of coordinates.

proof. First note that

$$v = \sum_j v_j \frac{\partial}{\partial x_j} = \sum_{a,i} v_j \frac{\partial y_a}{\partial x_j} \frac{\partial}{\partial y_a}$$

$$w_b' = \sum_j w_j \frac{\partial y_b}{\partial x_j}$$

$$v_a' = \sum_j v_j \frac{\partial y_a}{\partial x_j}$$

$$= \sum_a v_a' \frac{\partial}{\partial y_a} \text{ with}$$

Consequently

$$[v, w]' = \sum_{a,b} \left(v_a' \frac{\partial w_b'}{\partial y_a} \frac{\partial}{\partial y_b} - w_b' \frac{\partial v_a'}{\partial y_b} \frac{\partial}{\partial y_a} \right)$$

~~$$= \sum_{a,b,i,j} \left(v_j \frac{\partial y_a}{\partial x_j} \right) \left(\frac{\partial w_j}{\partial y_a} \frac{\partial y_b}{\partial x_j} \right) \frac{\partial}{\partial x_j} - w_j \frac{\partial y_b}{\partial x_j} \frac{\partial}{\partial x_j} \left(v_i \frac{\partial y_a}{\partial x_i} \right) \frac{\partial}{\partial y_a}$$~~

$$= \sum_{a,b,i,j} v_i \frac{\partial y_a}{\partial x_i} \frac{\partial}{\partial y_a} \left(w_j \frac{\partial y_b}{\partial x_j} \right) \frac{\partial}{\partial y_b} - w_j \frac{\partial y_b}{\partial x_j} \frac{\partial}{\partial y_b} \left(v_i \frac{\partial y_a}{\partial x_i} \right) \frac{\partial}{\partial y_a}$$

$$= \sum_{b,i,j} v_i \frac{\partial}{\partial x_i} \left(w_j \frac{\partial y_b}{\partial x_j} \right) \frac{\partial}{\partial y_b} - \sum_{a,i,j} w_j \frac{\partial}{\partial x_j} \left(v_i \frac{\partial y_a}{\partial x_i} \right) \frac{\partial}{\partial y_a}$$

$$= \sum_{b,i,j} v_i \left(\frac{\partial w_j}{\partial x_i} \frac{\partial y_b}{\partial x_j} + w_j \frac{\partial^2 y_b}{\partial x_j \partial x_i} \right) \frac{\partial}{\partial y_b} - \sum_{a,i,j} w_j \left(\frac{\partial v_i}{\partial x_j} \frac{\partial y_a}{\partial x_i} + v_i \frac{\partial^2 y_a}{\partial x_i \partial x_j} \right) \frac{\partial}{\partial y_a}$$

$$b \mapsto a = \sum_{i,j} v_i \frac{\partial w_j}{\partial x_i} \frac{\partial y_a}{\partial x_j} \frac{\partial}{\partial y_a} - w_j \frac{\partial v_i}{\partial x_j} \frac{\partial y_a}{\partial x_i} \frac{\partial}{\partial y_a}$$

$$= \sum_{i,j} v_i \frac{\partial w_j}{\partial x_i} \frac{\partial}{\partial x_j} - w_j \frac{\partial v_i}{\partial x_j} \frac{\partial}{\partial x_i} = [v, w] \text{ as required.}$$

$$J. \quad \psi_t^u(x_1, x_2) = (x_1 + t, x_2), \quad \psi_t^v(x_1, x_2) = (x_1, x_2 + t)$$

$$\psi_t^w(x_1, x_2) = (\cos t x_1 + \sin t x_2, -\sin t x_1 + \cos t x_2)$$

Recall

$$v_x = \left. \frac{d}{dt} \psi_t(x) \right|_{t=0} \quad \text{so}$$

$$u = \left. \frac{d}{dt} \psi_t^u \right|_0 = (1, 0); \quad u = \frac{\partial}{\partial x_1}$$

similarly $w = \frac{\partial}{\partial x_2}$. For w , if $\begin{pmatrix} -\sin t x_1 + \cos t x_2 \\ -\cos t x_1 - \sin t x_2 \end{pmatrix}$

$$= \begin{pmatrix} x_2 \\ -x_1 \end{pmatrix}, \quad \text{so } w = x_2 \frac{\partial}{\partial x_1} - x_1 \frac{\partial}{\partial x_2}$$

just compute the Lie brackets. intrinsic def'n

$$[X, Y]f = X(Y(f)) - Y(X(f)).$$

$$\text{check } [u, v] = 0$$

$$\begin{aligned} [u, w] &= \frac{\partial}{\partial x_1} \left(x_2 \frac{\partial}{\partial x_1} - x_1 \frac{\partial}{\partial x_2} \right) - x_2 \frac{\partial^2}{\partial x_1^2} + x_1 \frac{\partial^2}{\partial x_2 \partial x_1} \\ &= -x_1 \frac{\partial^2}{\partial x_1 \partial x_2} - \frac{\partial}{\partial x_2} + x_1 \frac{\partial^2}{\partial x_1 \partial x_2} = -\frac{\partial}{\partial x_2} = -v. \end{aligned}$$

similarly for the other one. $[v, w]$.

6. A square matrix of size n ,
$$V = \sum_{i,j} A_{ij} x_j \frac{\partial}{\partial x_i}$$

integrate this into a 1-param. group of diffeomorphisms.

proof. Recall again $V_x = \left. \frac{d}{dt} \psi_t(x) \right|_{t=0}$, write the
diffeo. $\psi_t(x)$ as $(x_1(t), \dots, x_n(t)) = \psi_t(x)$.

consequently, componentwise,

solution
$$\sum_j A_{ij} x_j = \dot{x}_i(t); \text{ this is well known to have general}$$
$$x_i(t) = \sum_j \exp(At)_{ij} c_j; \text{ this has}$$
$$x_i(0) = \text{id}_{ij} c_j = c_i$$

$$\Rightarrow \psi_t(x) = \exp(At) x.$$