

C3.3 Differentiable manifolds - Class 3 (27 Nov 2024)

Part B.

6. Let $\alpha \in \wedge^k V$, $\dim V = n$. Let $A_\alpha: \wedge^{n-k} V \rightarrow \wedge^n V$ be defined by $A_\alpha(\beta) = \alpha \wedge \beta$.

(i) Show that if $\alpha \neq 0$, then $A_\alpha \neq 0$.

proof. Choose a basis v_1, \dots, v_n for V and suppose w.l.o.g. that the component^c of $\alpha \neq 0$ in $v_1 \wedge \dots \wedge v_k$ is nonzero. Let

$$\beta = v_{k+1} \wedge \dots \wedge v_n; \text{ then } \alpha \wedge \beta = c v_1 \wedge \dots \wedge v_n \neq 0$$

every other term in α has one of the vectors v_{k+1}, \dots, v_n and consequently $(\alpha - c v_1 \wedge \dots \wedge v_k) \wedge \beta = 0$.

So $A_\alpha(\beta) \neq 0$, $A_\alpha \neq 0$. \square

(ii) Show that $\alpha \mapsto A_\alpha$ is an isomorphism $\wedge^k V \cong \text{Hom}(\wedge^{n-k} V, \wedge^n V)$.

proof. We know that $\dim \wedge^{n-k} V = \dim \wedge^k V = \binom{n}{k}$ and

$$\dim \wedge^n V = 1, \text{ so } \dim \text{Hom}(\wedge^{n-k} V, \wedge^n V) = \binom{n}{k}.$$

We showed in (a) that this map is injective, which is sufficient. \square

7. Is $S^2 \times \mathbb{R}P^2$ orientable? What about $\mathbb{R}P^2 \times \mathbb{R}P^2$?

Answer: no for both. For $S^2 \times \mathbb{R}P^2$, suppose it is, and pull back the volume form to $S^2 \times S^2$, and consider the antipodal map on the second factor.

For $\mathbb{R}P^2 \times \mathbb{R}P^2$, pull back the volume form to get a volume form on $S^2 \times \mathbb{R}P^2$, which is a contradiction.

These are special cases of a much more general fact:

Proposition. Let M, N be smooth manifolds. Then $M \times N$ is orientable if and only if both M and N are orientable.

proof. The "if" direction is problem 5 of part A.

For "only if", suppose that $M \times N$ is orientable. Let $U \subseteq N$ be a subset diffeomorphic to \mathbb{R}^n . Then $M \times U \subseteq M \times N$ is an open submanifold and thus is orientable.

Given any atlas $\{V_i\}$ on M , $\{N_i \times \mathbb{R}^n\}$ is an atlas on $M \times U$, with chart maps $\psi_i \times \varphi, \varphi: \mathbb{R}^n \xrightarrow{\cong} U$.

Then, given that $(\psi_i \times \varphi)^{-1} \circ (\psi_j \times \varphi)$

$$= (\psi_i^{-1} \circ \psi_j) \times \text{id}_{\mathbb{R}^n} \text{ has determinant}$$

> 0 , clearly $\psi_i^{-1} \circ \psi_j$ also has determinant > 0 and consequently M is orientable. Similarly for N . \square

(The result also follows from some properties of de Rham cohomology such as the Künneth formula.)

8. A Riemann surface is a 2-manifold with an atlas whose transition maps $\mathbb{C} \rightarrow \mathbb{C}$ are holomorphic. Show that a Riemann surface is orientable.

proof. Let ϕ_i, ϕ_j be ~~charts~~ charts, and let

$f = \phi_j^{-1} \circ \phi_i : \mathbb{C} \rightarrow \mathbb{C}$ be the transition map

$$f(x, y) = u(x, y) + i v(x, y) \quad f \text{ is holomorphic, so the}$$

$$= f(x + iy) = f(z) = \begin{pmatrix} u(x, y) \\ v(x, y) \end{pmatrix}$$

Cauchy-Riemann equations give $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}, \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$.

Then $\det \text{Jac } f = \det \begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} - \frac{\partial u}{\partial y} \frac{\partial v}{\partial x}$

$$= \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 \geq 0. \quad f \text{ is a local homeo.}$$

so in fact $\det \text{Jac } f > 0$. Thus all transition maps are orientation-preserving and consequently the manifold is orientable.

9. Using the facts that $H^0(X) = \mathbb{R}^{\# \text{ of connected components of } X}$,

$$H^0(\mathbb{R}^n) = \mathbb{R}, \quad H^k(\mathbb{R}^n) = 0 \quad \text{and} \quad H^k(X \times \mathbb{R}^n) \cong H^k(X)$$

for all $k, n \geq 0$ and X , show that $H^k(S^m) = \begin{cases} \mathbb{R} & k=0, m \\ 0 & \text{otherwise} \end{cases}$

with $H^k(S^0) = \begin{cases} \mathbb{R}^2 & k=0 \\ 0 & \text{otherwise} \end{cases}$.

Let $U = S^m \setminus \{(1, 0, \dots, 0)\}$, $V = S^m \setminus \{(-1, 0, \dots, 0)\}$ and $W = U \cap V$. Then $U \cup V = S^m$ and there are diffeomorphisms

$$U \cong \mathbb{R}^m, \quad V \cong \mathbb{R}^m, \quad W \cong S^{m-1} \times \mathbb{R}.$$

Let $B \subseteq A \subseteq S^n$ be open, and write

$\rho_{AB}: \Omega^k(A) \rightarrow \Omega^k(B)$ for the restriction.

Then there is the exact sequence

$$0 \rightarrow \Omega^k(S^n) \xrightarrow{\rho_{S^u} \oplus \rho_{S^v}} \Omega^k(U) \oplus \Omega^k(V) \xrightarrow{\rho_{UW} \oplus \rho_{VW}} \Omega^k(W) \rightarrow 0.$$

(a) Suppose that $\alpha \in \Omega^k(S^n)$ for $k > 1$ with $d\alpha = 0$. Show that there are $\beta \in \Omega^{k-1}(U)$, $\gamma \in \Omega^{k-1}(V)$ with $\alpha|_U = d\beta$, $\alpha|_V = d\gamma$.

proof. U and V have vanishing ~~H^k~~ -th cohomology, so closed forms are exact.

Let $\delta = \beta|_W - \gamma|_W \in \Omega^{k-1}(W)$. Show that $d\delta = 0$.

proof. $d\delta = d\beta|_W - d\gamma|_W = d\alpha|_W - d\alpha|_W = 0$.

Show that $[\delta] \in H^{k-1}(W)$ depends only on $[\alpha] \in H^k(S^n)$.

proof. First, fix α and let $\beta' = \beta + d\tilde{\beta}$, $\gamma' = \gamma + d\tilde{\gamma}$ be other representatives of $[\beta]$ and $[\gamma]$ respectively. Then

$$\begin{aligned} \delta' - \delta &= \beta'|_W - \gamma'|_W - (\beta|_W - \gamma|_W) = d\tilde{\beta}|_W - d\tilde{\gamma}|_W \\ &= d((\tilde{\beta} - \tilde{\gamma})|_W) \text{ so that } [\delta'] = [\delta] \in H^{k-1}(W). \end{aligned}$$

So, for α fixed, $[\delta]$ is independent of the choices of β, γ within H^{k-1} .

Now, if we choose a different $\alpha' \in [\alpha]$, a priori the choices of $[\beta]$, $[\gamma]$ would have to be different, so we need to prove this separately. In fact, let $\alpha' = \alpha + d\tilde{\alpha}$;

we had ~~$d\beta = \alpha|_u$~~ $\alpha|_u = d\beta$ and $\alpha|_v = d\gamma$; clearly now if we choose $\beta' = \beta + \tilde{\alpha}|_u$ and $\gamma' = \gamma + \tilde{\alpha}|_v$, we'd have $d\beta' = \alpha'|_u$ and $d\gamma' = \alpha'|_v$, as required.

$$\text{Then } \delta' = \beta'|_w - \gamma'|_w = \beta|_w - \gamma|_w + \tilde{\alpha}|_w - \tilde{\alpha}|_w$$

(b) We thus have a linear map $\mathbb{I} = \mathbb{J}$ as required. $\mathbb{I} : H^k(S^n) \rightarrow H^{k-1}(W)$,

Suppose that $[\delta] = \mathbb{I}([\alpha]) = 0$. $[\alpha] \mapsto [\delta]$.
Then $\delta = d\varepsilon$ for some $\varepsilon \in \Omega^{k-2}(W)$. Show that $[\alpha] = 0$, so that

\mathbb{I} is injective.

proof. We follow the hint & let $\{\eta_u, \eta_v\}$ be a partition of unity.

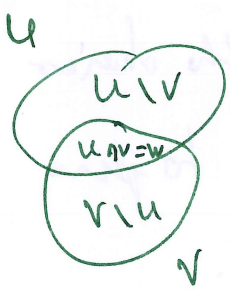
First, we compute

$$\beta|_w - d(\eta_v \varepsilon) = \beta|_v - d(1 - \eta_u) \varepsilon$$

$$= \beta|_w - d\varepsilon + d(\eta_u \varepsilon)$$

$$= \gamma|_w + d(\eta_u \varepsilon) \text{ since } \delta = d\varepsilon = \beta|_w - \gamma|_w.$$

We know that $\alpha|_u = d\beta$ and $\alpha|_v = d\gamma$. We want to construct a smooth form $\eta \in \Omega^{k-1}(S^n)$ s.t. $d\eta = \alpha$.



Clearly we can define $\eta = \beta$ on $U \setminus V$ and $\eta = \alpha$ on $V \setminus U$.
 What about on the intersection? Smoothness is the problem. We let

$$\eta = \begin{cases} \beta & \text{on } S^m \setminus V \\ \alpha & \text{on } S^m \setminus U \end{cases}$$

$$\beta|_W - d(\eta|_V) = \alpha|_W + d(\eta|_U) \text{ on } W.$$

Then $d\eta$ is just " α " but the additional terms preserve smoothness. Then $d\eta = \alpha$, so $[\alpha] = 0 \in H^k(S^n)$. \square

(c) Suppose that $\delta \in \Omega^{k-1}(W)$ with $d\delta = 0$. Show that we can choose α, β, γ s.t. $\mathcal{F}([\alpha]) = [\delta]$, so that \mathcal{F} is surjective.

proof. The issue here is that we need both that

$\beta|_W - \alpha|_W = \delta$ and that $d\beta, d\alpha$ are both nonvanishing. Treating " δ as a constant form", we see that it suffices to "split" δ via $\beta = \eta_V \delta$ and $\alpha = -\eta_U \delta$.

This way, β is defined on all of U , as it vanishes outside of V ; similarly for α . Then

$$\beta|_W - \alpha|_W = (\eta_V + \eta_U)|_W \delta = \delta \text{ as required, and}$$

$$d\beta = d\eta_V \wedge \delta = d(1 - \eta_U) \wedge \delta = -d\eta_U \wedge \delta = d\alpha \text{ on } W;$$

So just set $\alpha = d\beta$; it works since β is supported in W . \square

(d). Show that $H^k(S^n) \cong H^{k-1}(S^{n-1})$ if $k > 1$.

proof. $W \subseteq S^{n-1}$, so this is obvious. \square

(e) what goes wrong when $k=1$ & how to fix this to show that $H^1(S^1) \cong \mathbb{R}$ & $H^1(S^n) = 0$ for $n > 1$?

~~proof~~. What goes wrong here is that $H^{k-1}(\mathbb{R}^n) = H^0(\mathbb{R}^n)$

henceforth, when we showed that $\oint [dx] \neq 0$ did not depend on the choice of β, γ , now we can choose different cohomology classes.

There are other ways to fix this, but we can just compute explicitly.

First, note that $H^1(S^1) = \mathbb{R}$. To see this, let $d\theta$ be the coordinate; then if there is a function

$f: S^1 \rightarrow \mathbb{R}$ s.t. $df = d\theta$, we must have

$$\int_0^{2\pi} df = \int_0^{2\pi} d\theta = 2\pi = f(2\pi) - f(0), \text{ which is}$$

impossible as f is continuous. Consequently $[d\theta] \neq 0 \in H^1(S^1)$.

~~Consider any 1-form $h(x)dx$, the \int checks the space is 1-dimensional, which can be seen by choosing coordinates.~~

Checks, as the manifold is 1-dimensional, so is $H^1(S^1)$.

Now we compute $H^k(S^k)$ for $k > 1$.

Consider U, V as before; they are topologically \mathbb{R}^k and therefore, given a 1-form ω on S^k , $\omega|_U = df$, $\omega|_V = dg$ for some f, g functions on U, V respectively.

But on W , $d(f-g)|_W = 0 \Rightarrow f-g = \text{constant}$; so

we just define $h = \begin{cases} f & \text{on } U \\ f - C & \text{on } V \end{cases}$ and then $dh = \omega$;

so that $H^k(S^k) = 0$.

To summarise, we know that:

$$H^k(S^n) = H^{k-1}(S^{n-1}) \text{ for all } k > 1$$

$$H^1(S^1) \cong \mathbb{R}, \quad H^k(S^k) = 0 \text{ for all } k > 1.$$

From this, it follows immediately that $H^k(S^k) \cong \mathbb{R}$ for all $k > 0$ and that $H^k(S^n) = 0$ if $k \neq 0, n$.

Note that $H^k(S^n) = 0$ if $k > n$ since an n -manifold has no nontrivial higher-order forms.

Fixed solution for problem 7.

Proposition. $M \times N$ is orientable if and only if M and N are both orientable.

proof. Let ω be a volume form on $M \times N$. Let $q \in N$, let $e^1, \dots, e^n \in T_q N$. Define the form η on M by

$$\eta(X_1, \dots, X_m) = \omega(X_1, \dots, X_m, e^1, \dots, e^n).$$

Since ω is a volume form, η is nonvanishing on all of M and consequently is a volume form.

More specifically, in coordinates, if

$$\omega = f(x_1, \dots, x_m, y_1, \dots, y_n) dx_{1,1} \dots dx_{m,1} dy_{1,1} \dots dy_{n,1},$$

$$\text{then } \eta = f(x_1, \dots, x_m, q_1, \dots, q_n) dx_{1,1} \dots dx_{m,1},$$

where (q_1, \dots, q_n) are the N -coordinates of q .

Therefore M is orientable. Similarly, N is orientable.