## Lie Groups

Section C course Hilary 2022

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#### Example sheet 3

# Section A (introductory questions, not for marking, solutions available)

1. Let  $\mathfrak{sl}(2,\mathbb{R})$  denote the space of  $2 \times 2$  real matrices of trace zero. Show that  $\mathfrak{sl}(2,\mathbb{R})$  is a Lie algebra with basis

$$h = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad e = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad f = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

and work out the bracket relations for e, f, h.

By considering subalgebras of this Lie algebra, show that it is not isomorphic to  $\mathfrak{su}(2)$ .

**Solution** Since  $\operatorname{trace}(AB) = \operatorname{trace}(BA)$ , the trace of any commutator of square matrices is zero, so  $\mathfrak{sl}(2,\mathbb{R})$  is a Lie algebra when endowed with the matrix commutator. Any traceless  $2 \times 2$  real matrix is uniquely expressible in the form

$$A = \left(\begin{array}{cc} a & b \\ c & -a \end{array}\right)$$

for real numbers a, b and c, so  $\{h, e, f\}$  is a basis for  $\mathfrak{sl}(2, \mathbb{R})$ . By direct calculation we have

$$[h, e] = 2e,$$
  $[h, f] = -2f,$   $[e, f] = h.$ 

Recall  $\mathfrak{su}(2) \cong (\mathbb{R}^3, \times)$  where  $\times$  is the cross product. Any two linearly independent elements of  $\mathbb{R}^3$  generate  $(\mathbb{R}^3, \times)$  since  $v \times w$  is orthogonal to both v and w and is non-zero if v and w are linearly independent. Therefore  $\mathfrak{su}(2)$  has no 2-dimensional Lie subalgebras. However  $\mathbb{R}\{h, e\}$  is a 2-dimensional Lie subalgebra of  $\mathfrak{sl}(2, \mathbb{R})$ . Thus  $\mathfrak{sl}(2, \mathbb{R})$  and  $\mathfrak{su}(2)$  cannot be isomorphic.

# Section B (questions to be handed in for marking)

2. Let  $\varphi: G_1 \to G_2$  be a Lie group homomorphism. Show that

$$\ker \varphi \subseteq G_1$$

is a closed (hence embedded) Lie subgroup with Lie algebra

$$\ker(D_1\varphi)\subset\mathfrak{g}_1.$$

A vector subspace  $J \subseteq (V, [\cdot, \cdot])$  of a Lie algebra is called an **ideal** if

$$[v,j] \in J$$
 for all  $v \in V, j \in J$ .

Show that ideals are Lie subalgebras. Show that for a Lie subgroup  $H \subseteq G$ , with H, G connected,

$$H\subseteq G$$
 is a normal subgroup  $\Leftrightarrow \mathfrak{h}\subseteq \mathfrak{g}$  is an ideal

(You may find it helpful to first show the identity  $ge^Yg^{-1} = e^{\operatorname{Ad}(g).Y}$  for  $g \in G$  and  $Y \in \mathfrak{g}$ ). The **centre** of a Lie algebra  $(V, [\cdot, \cdot])$  is

$$Z(V) = \{ v \in V : [v, w] = 0 \text{ for all } w \in V \}.$$

For G connected, prove that the centre of the group G is<sup>1</sup>

$$Z(G) = \ker(\operatorname{Ad}: G \to \operatorname{Aut}(\mathfrak{g}))$$

Deduce that the centre of G is a closed (hence embedded) Lie subgroup of G which is abelian, normal and has Lie algebra

$$Lie(Z(G)) = Z(\mathfrak{g}).$$

 $<sup>^{1}\</sup>text{Recall the centre of a group is }Z(G)=\{g\in G:hg=gh\text{ for all }h\in G\}=\{g\in G:hgh^{-1}=g\text{ for all }h\in G\}.$ 

Finally deduce that, for G connected,

$$G$$
 is abelian  $\Leftrightarrow \mathfrak{g}$  is abelian.

3. Show that if X, Y belong to the Lie algebra of a Lie group G then

$$[X, Y] = 0 \Rightarrow \exp(X + Y) = \exp(X) \exp(Y).$$

Prove that if G is a connected Lie group with  $Z(G) = \{1\}$  then G can be identified with a Lie subgroup of  $GL(m, \mathbb{R})$ , for some m, so  $\mathfrak{g}$  is a Lie subalgebra of  $\mathfrak{gl}(m, \mathbb{R})$ .

If  $(V, [\cdot, \cdot])$  is a Lie algebra with  $Z(V) = \{0\}$ , show that V is the Lie algebra of some Lie group.

- 4. Find all the connected Lie subgroups of SO(3).
- 5. Show that Lebesgue measure  $\mathbf{dx}$  is the bi-invariant Haar measure on  $\mathbb{R}^n$  viewed as an additive group.

Find the bi-invariant Haar measure on  $(\mathbb{R}_{>0}, \times)$ , the multiplicative group of positive reals.

6. Give an example of an *irreducible* representation of  $S^1$  on  $\mathbb{R}^2$ . Describe what happens to this representation when we complexify it.

## Section C (optional extension questions, not to be handed in for marking)

- 7. (i) Let  $\phi: G \to \operatorname{Aut}(V)$  be a representation. If  $\alpha: G \to G$  is an automorphism show that  $\phi \circ \alpha$  is another representation on the same vector space.
- (ii) If  $\alpha(g) = hgh^{-1}$  for some  $h \in G$  show that the two representations are equivalent.
- (iii) Give an example of an automorphism where the two representations are not equivalent [ $Think: complex\ conjugation$ ].
- 8. Consider the action of SO(3) on  $\mathbb{R}^3$  and let  $f:\mathbb{R}^3\to\mathbb{R}$  be a smooth real-valued function.
- (i) For  $A \in SO(3)$  show that  $(Af)(x) = f(A^{-1}x)$  defines an action of SO(3) on the space of all smooth functions.
- (ii) If  $r^2 = x_1^2 + x_2^2 + x_3^2$  show that Af = f.
- (iii) Let  $\Delta$  denote the Laplace operator

$$\Delta f = \sum_{i=1}^{3} \frac{\partial^2 f}{\partial x_i^2}.$$

Show that  $A\Delta f = \Delta A f$ .

- (iv) Consider the vector space of functions of the form f = p where  $p(x_1, x_2, x_3)$  is a homogeneous polynomial of degree m. Show that this is a finite-dimensional representation  $V_m$  of SO(3) and calculate its dimension.
- (v) Let  $H_m \subseteq V_m$  be the subspace of solutions to  $\Delta f = 0$  for  $f \in V_m$ , the harmonic polynomials of degree m. Show that  $H_m$  is a representation space for SO(3) and that  $V_2 = H_2 \oplus r^2 H_0$  and  $V_3 = H_3 \oplus r^2 H_1$  are decompositions into inequivalent representations.
- (vi) Can you generalize this?