

Section 5b: Homoclinic Chaos

1. Bernoulli shift

Dynamical systems

1. The space on which it is defined
2. The dynamics mapping sets to sets

Ex: Bernoulli shift

1. The space of bi-infinite sequence: Σ
2. a shift mapping sequences to sequences

$$\sigma: \Sigma \rightarrow \Sigma$$

Analysis of this system reveals infinitely periodic orbits
infinitely quasi-periodic orbits, a dense orbit.

=> Sensitive dependence to i.c. and Chaos

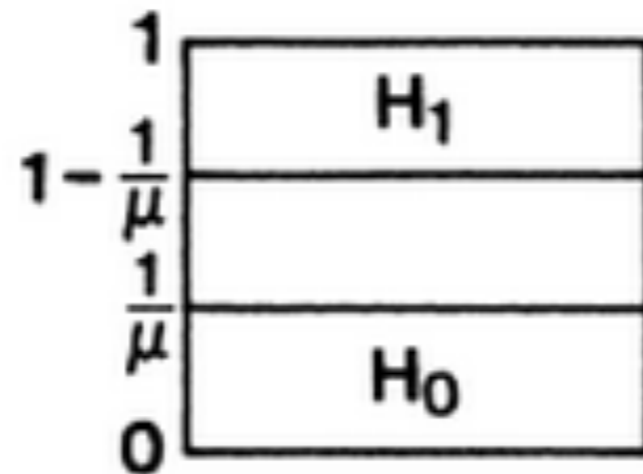
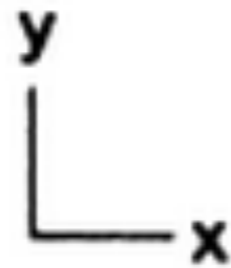
2. SMALE'S HORSESHOE

SMALE'S HORSESHOE

First, define two rectangular regions in the unit square

$$H_0 = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq 1, 0 \leq y \leq 1/\mu\}$$

$$H_1 = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq 1, 1 - 1/\mu \leq y \leq 1\}$$

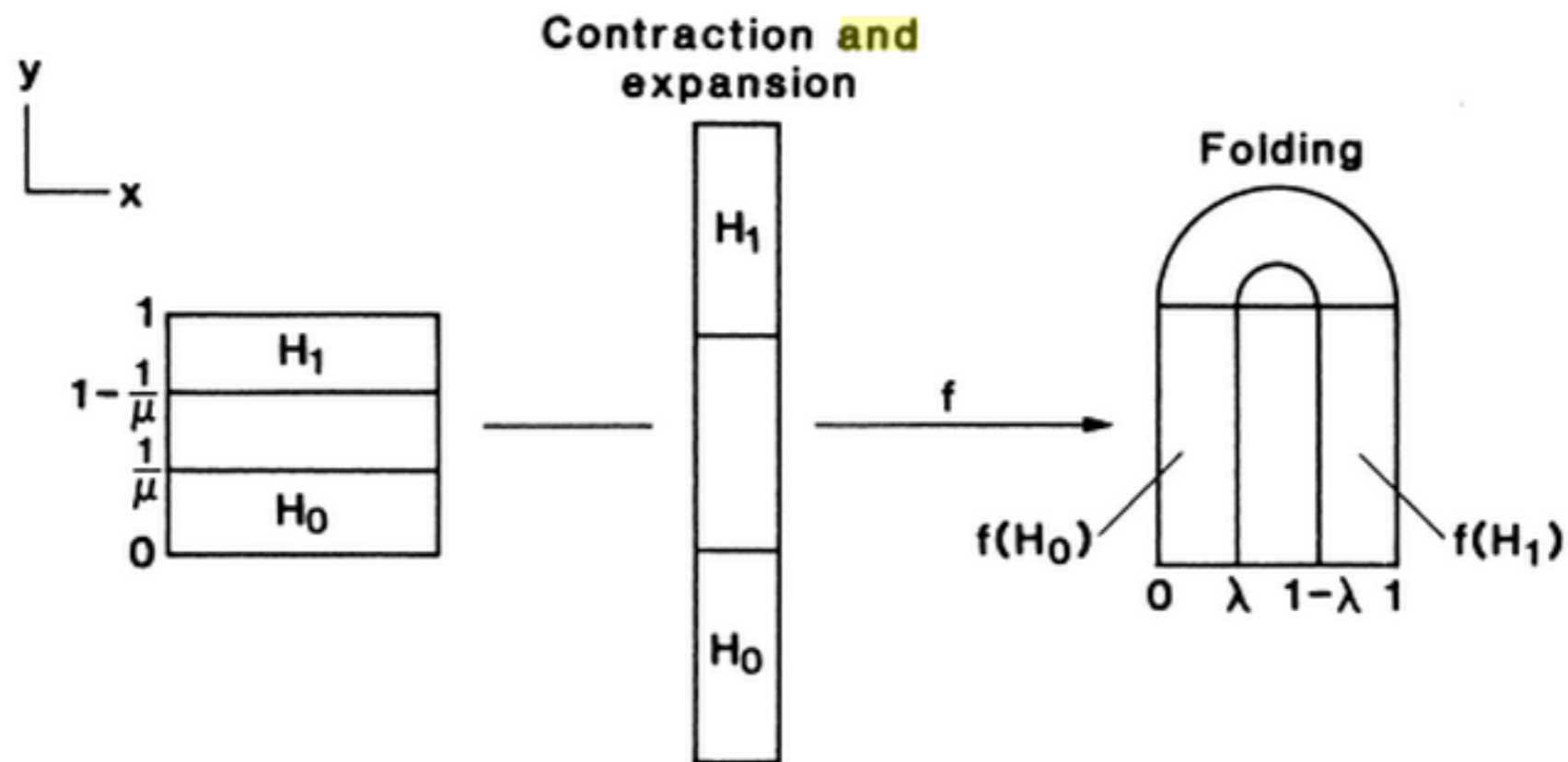


SMALE'S HORSESHOE

Second, define a map of these rectangle into themselves

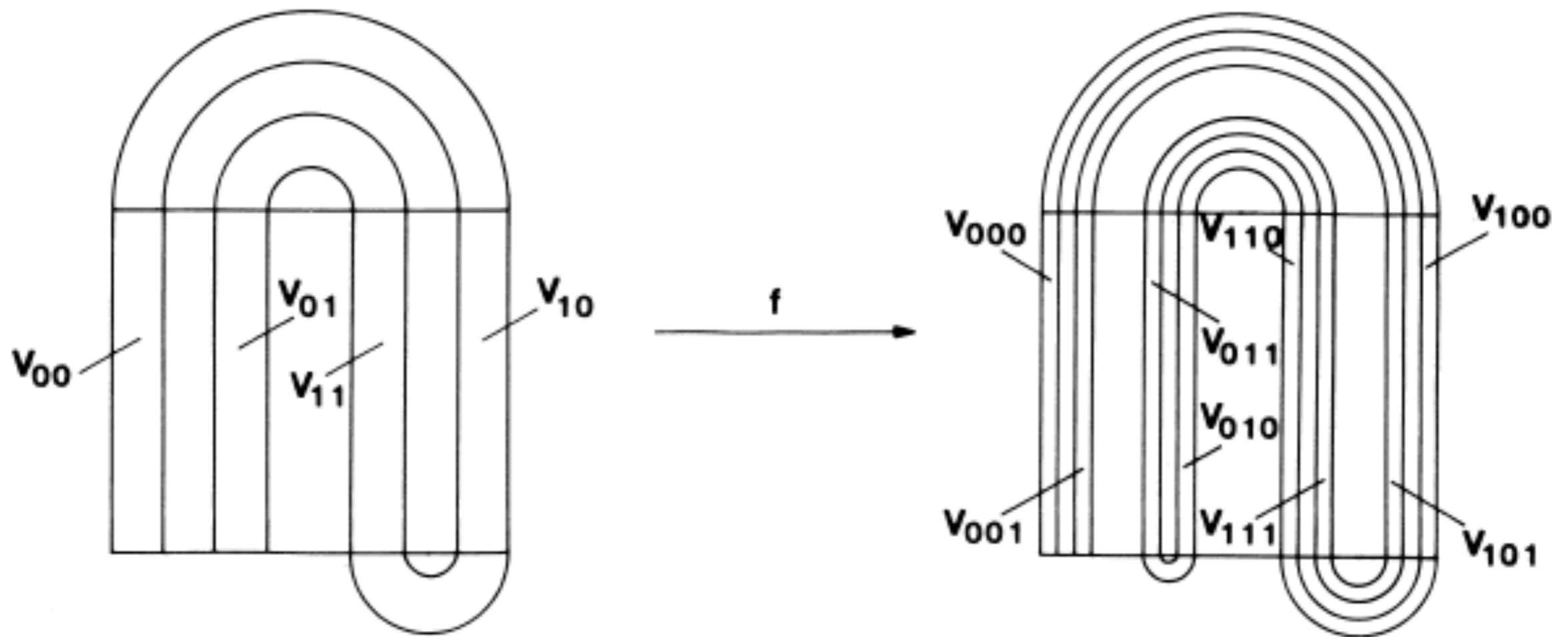
$$H_0 : \begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} \lambda & 0 \\ 0 & \mu \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$H_1 : \begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} -\lambda & 0 \\ 0 & -\mu \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} 1 \\ \mu \end{pmatrix}$$



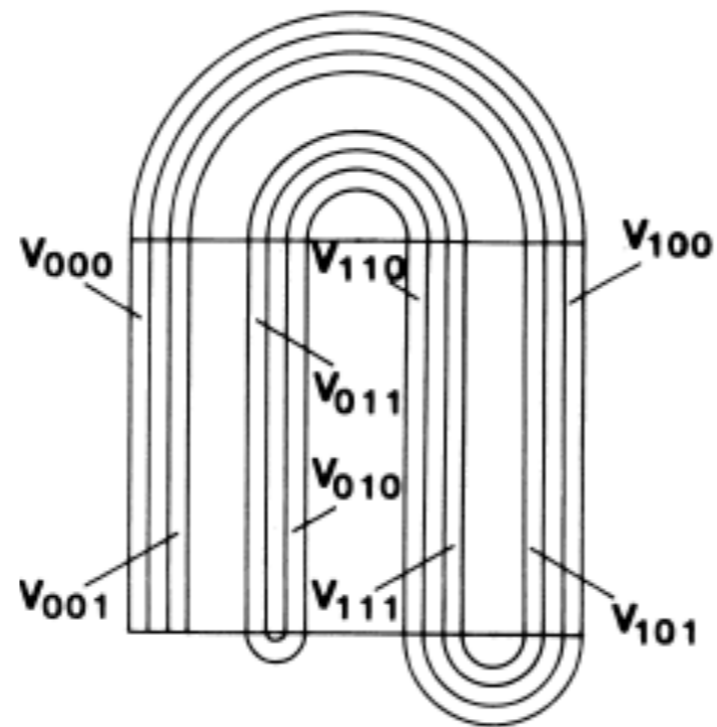
SMALE'S HORSESHOE

Third, repeat the operation



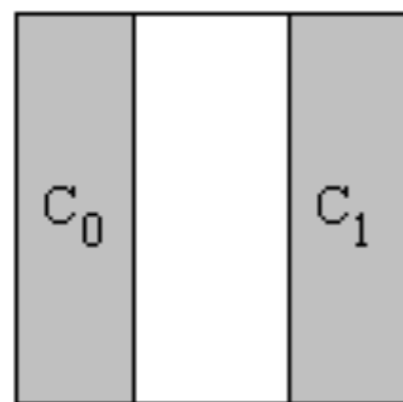
SMALE'S HORSESHOE

Fourth, introduce a coding

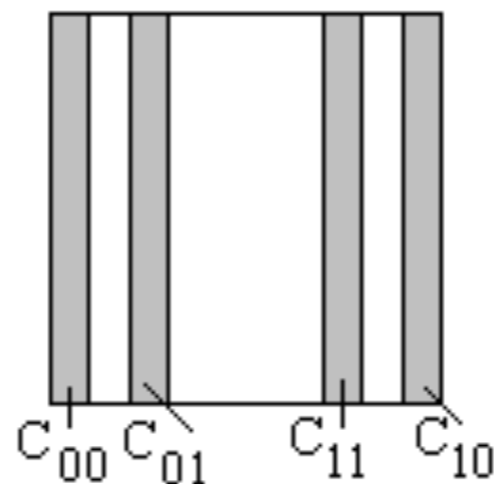


Coding: 01 means

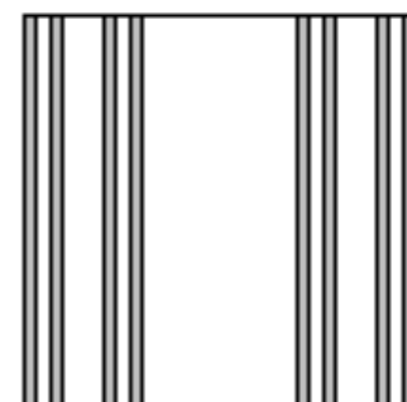
that it was right at the first iteration left at the second



(a)



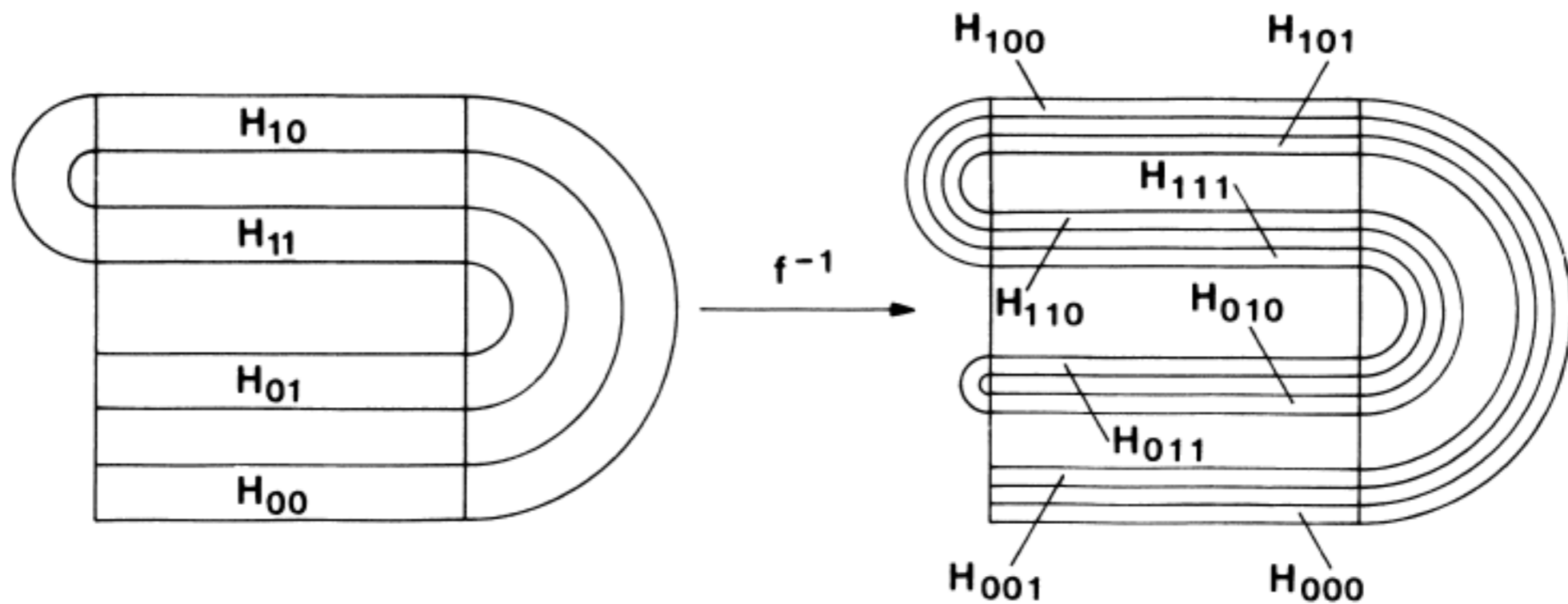
(b)



(c)

SMALE'S HORSESHOE

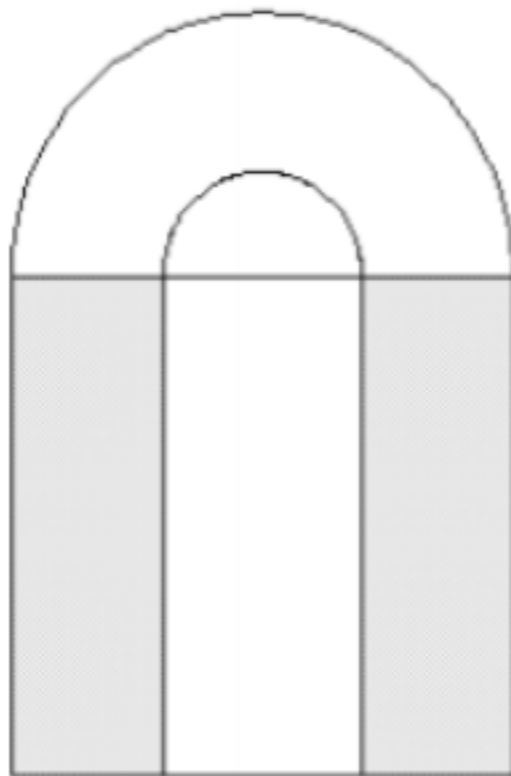
Fifth, do the same operation for the inverse map



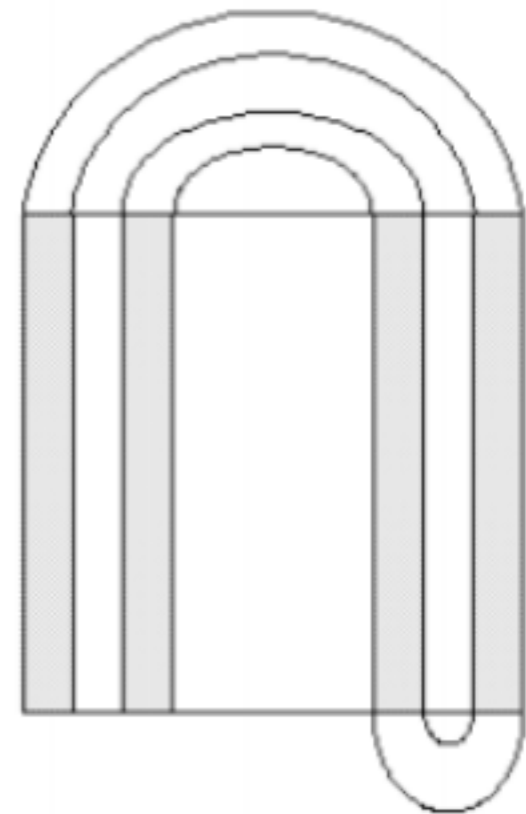
Sixth, take the intersection between the two sets



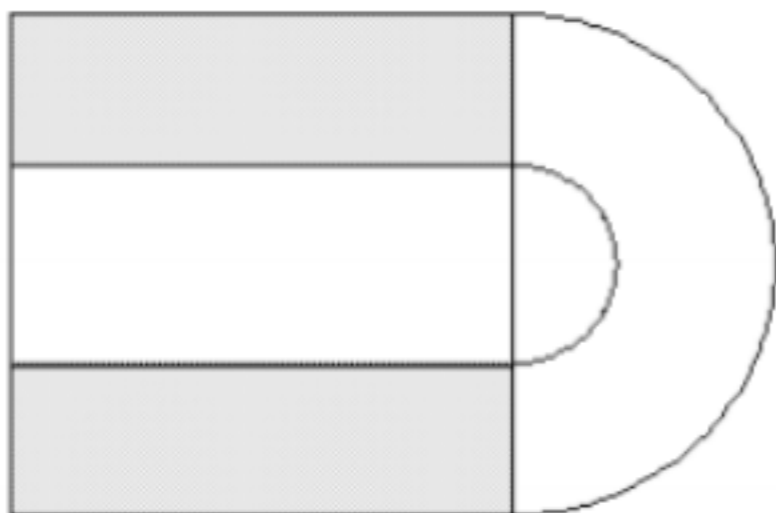
D



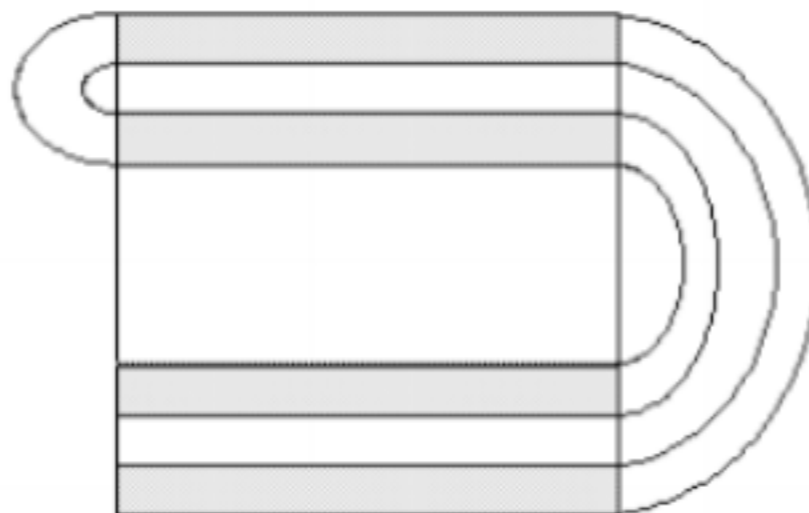
$D \cap F(D)$



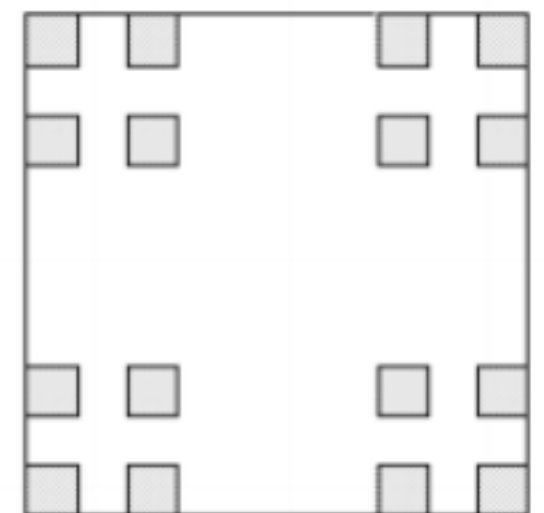
$D \cap F(D) \cap F^2(D)$



$D \cap F^{-1}(D)$

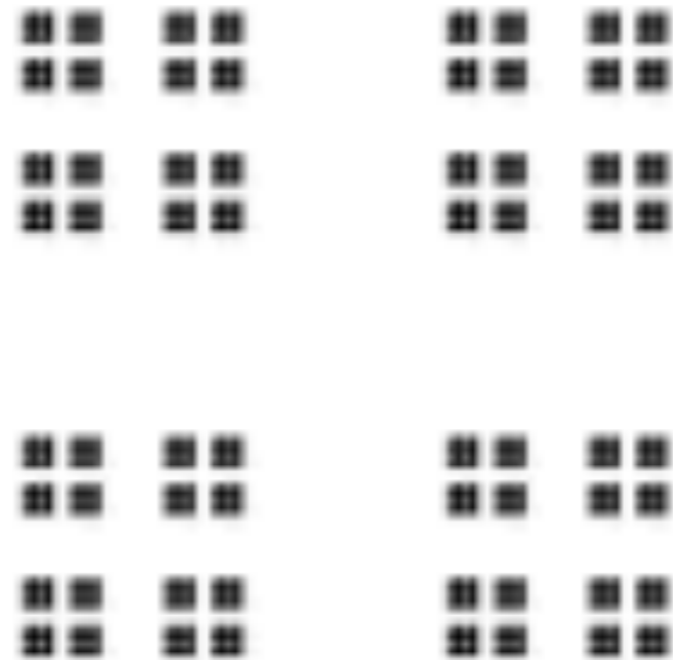


$D \cap F^{-1}(D) \cap F^2(D)$



$F^{-2}(D) \cap F^{-1}(D) \cap D \cap F(D) \cap F^2(D)$

SMALE'S HORSESHOE



$$\Lambda = \bigcap_{n \in \mathbb{Z}^+} H^n \cap \bigcap_{n \in \mathbb{Z}^+} V^n = \bigcap_{n \in \mathbb{Z}} f^n(H_0 \cup H_1).$$

This set is a the intersection of a Cantor set of vertical lines and a cantor sets of horizontal lines

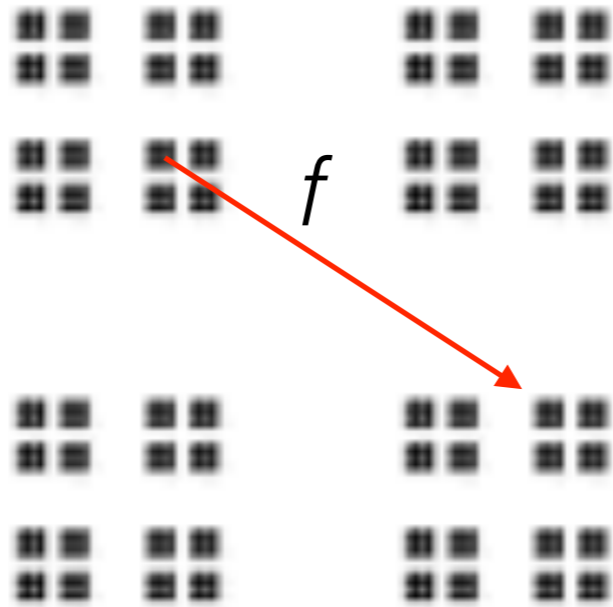
$$\Lambda = \bigcap_{n \in \mathbb{Z}^+} H^n \cap \bigcap_{n \in \mathbb{Z}^+} V^n = \bigcap_{n \in \mathbb{Z}} f^n(H_0 \cup H_1).$$

Each point in Λ can be coded by two binary sequences. The first sequence codes its vertical position, the second sequence codes its horizontal position

Therefore to each point p in Λ we can associate a bi-infinite sequence σ in Σ . Let

$$h: \Lambda \rightarrow \Sigma$$

This map h is a homeomorphism (1:1, onto, continuous with continuous inverse).



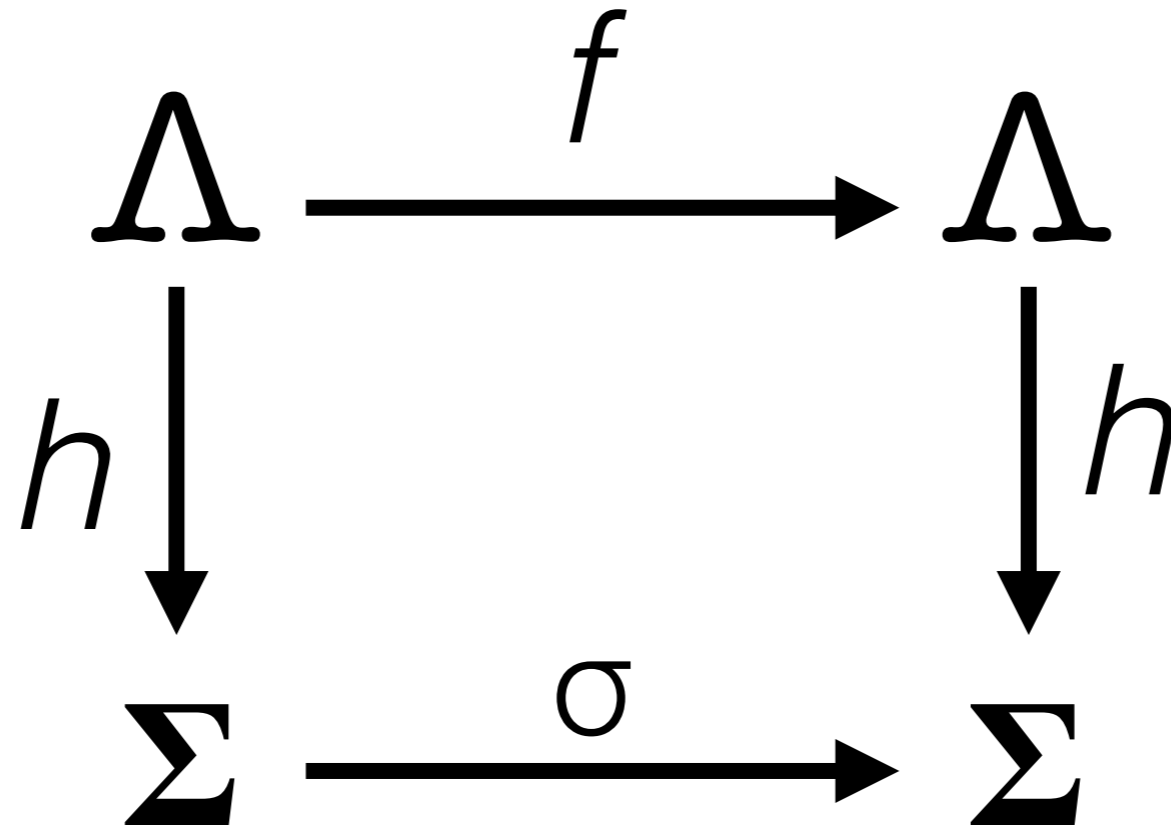
The dynamics on Λ is given by $f: \Lambda \rightarrow \Lambda$.

It maps points to points.

By construction, Λ is an invariant set

Since there exists a homeomorphism h , it implies that the dynamics of f on Λ is *topologically conjugate* to the dynamics of σ on Σ .

Topological equivalence



To each orbit in Σ there is a corresponding orbit on Δ

Therefore, the system has, a countable infinity of periodic orbits, an uncountable infinity of non-periodic orbit, a dense orbit, sensitivity dependence to initial conditions.

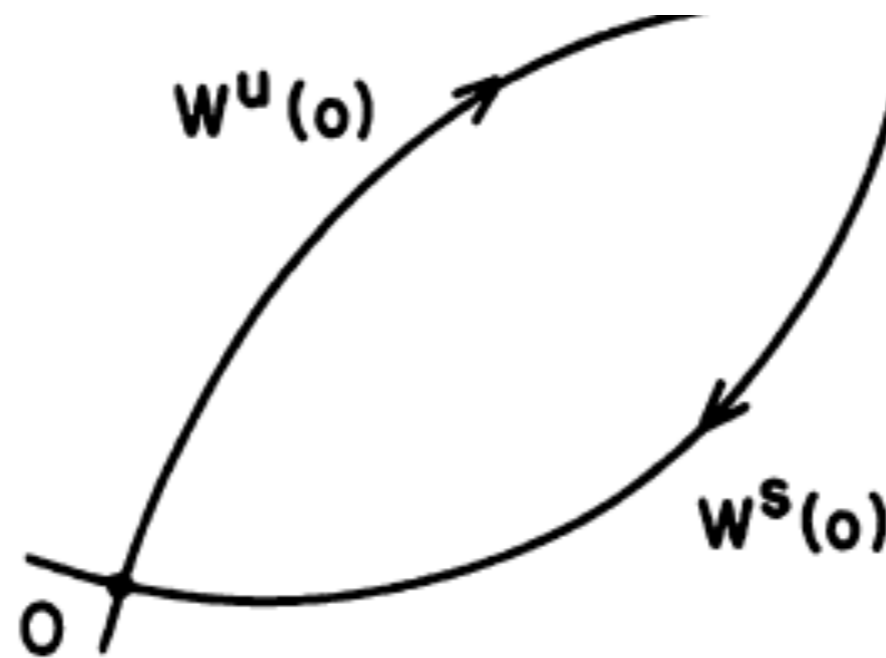
We conclude that f on Δ is chaotic.

3. TRANSVERSE HOMOCLINIC POINTS

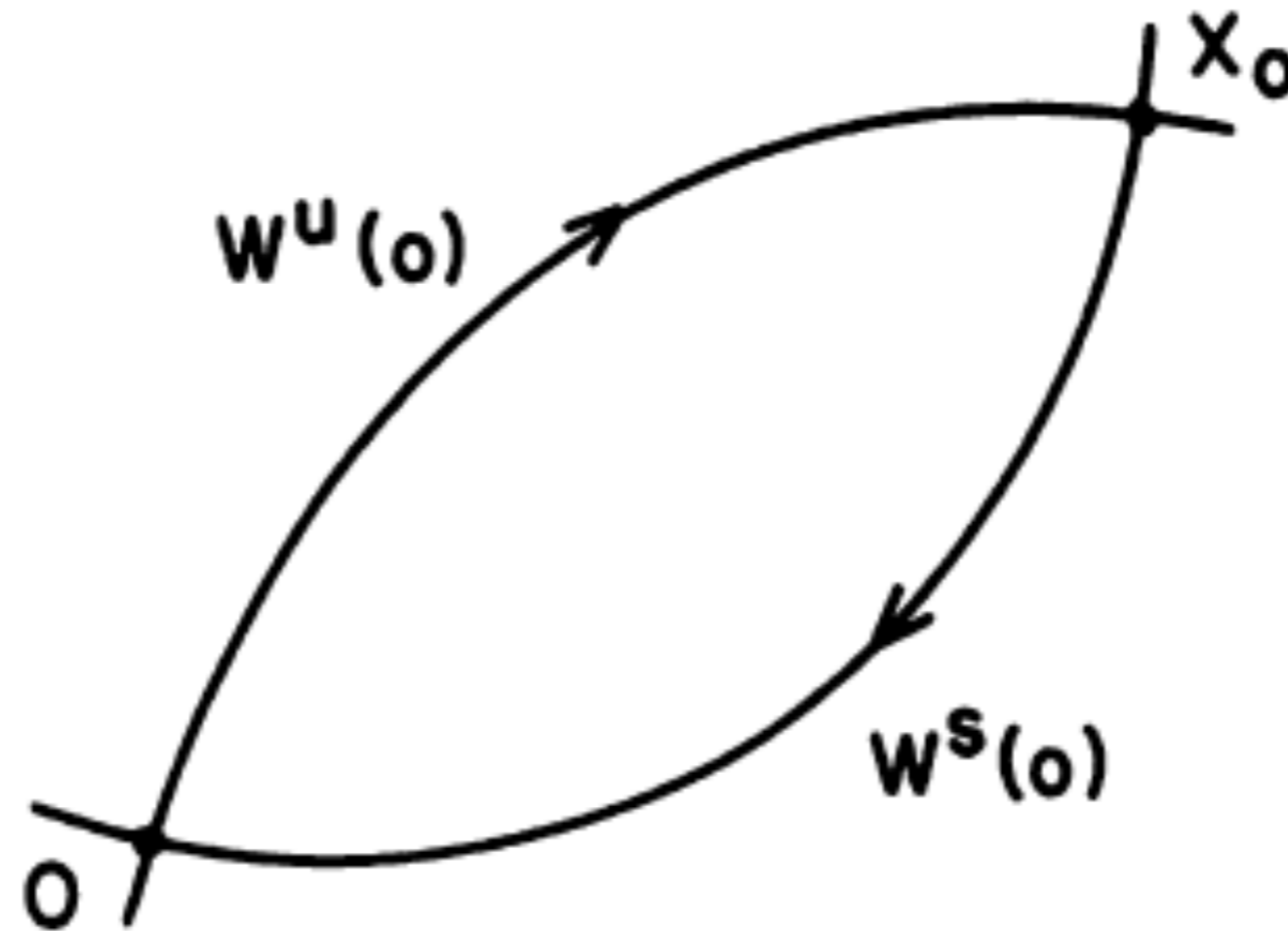
HORSESHOE IN MAPS

Consider a diffeomorphism defining a map P
Assume it has a fixed point at 0

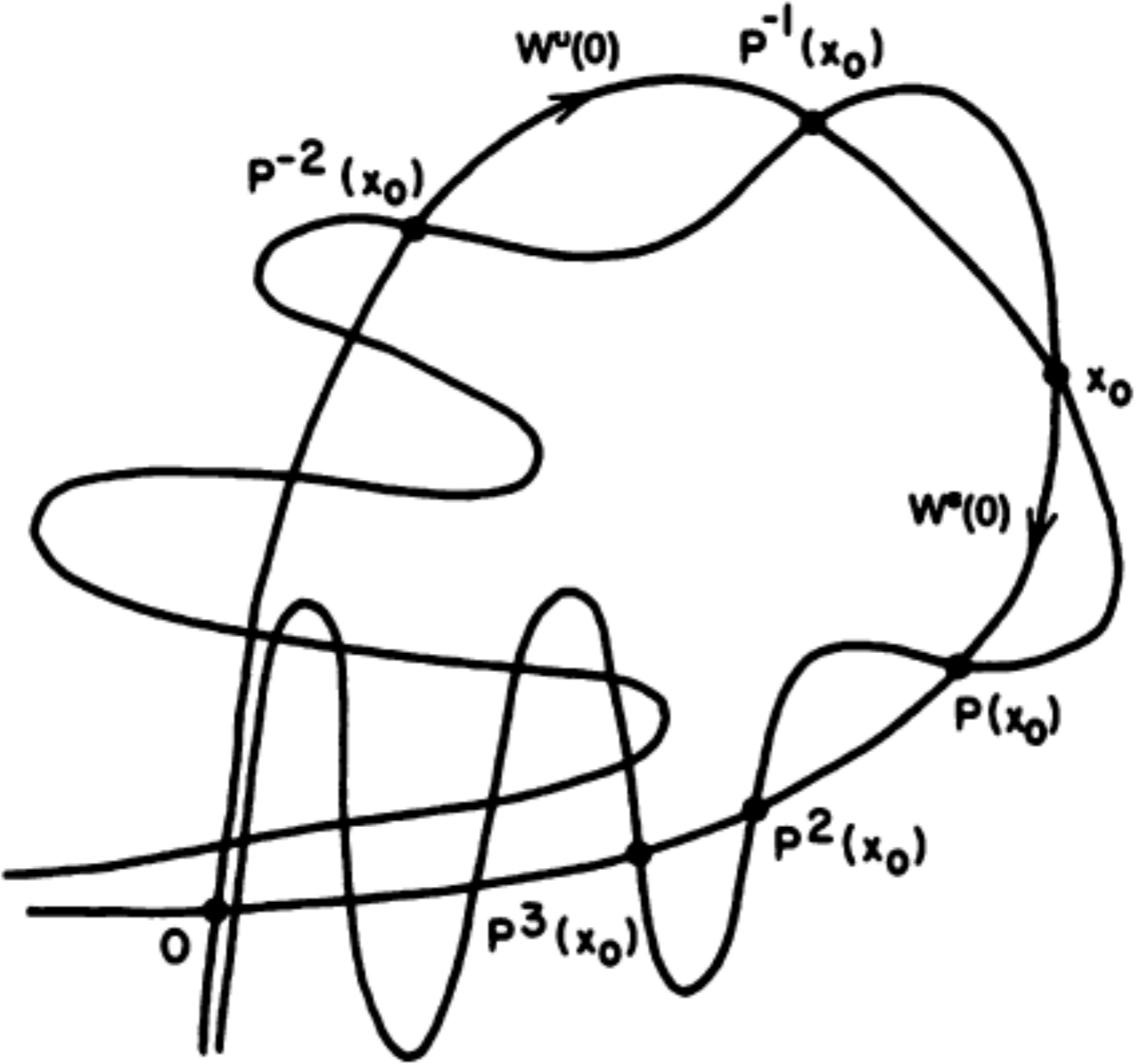
Build the stable and unstable manifolds to this point



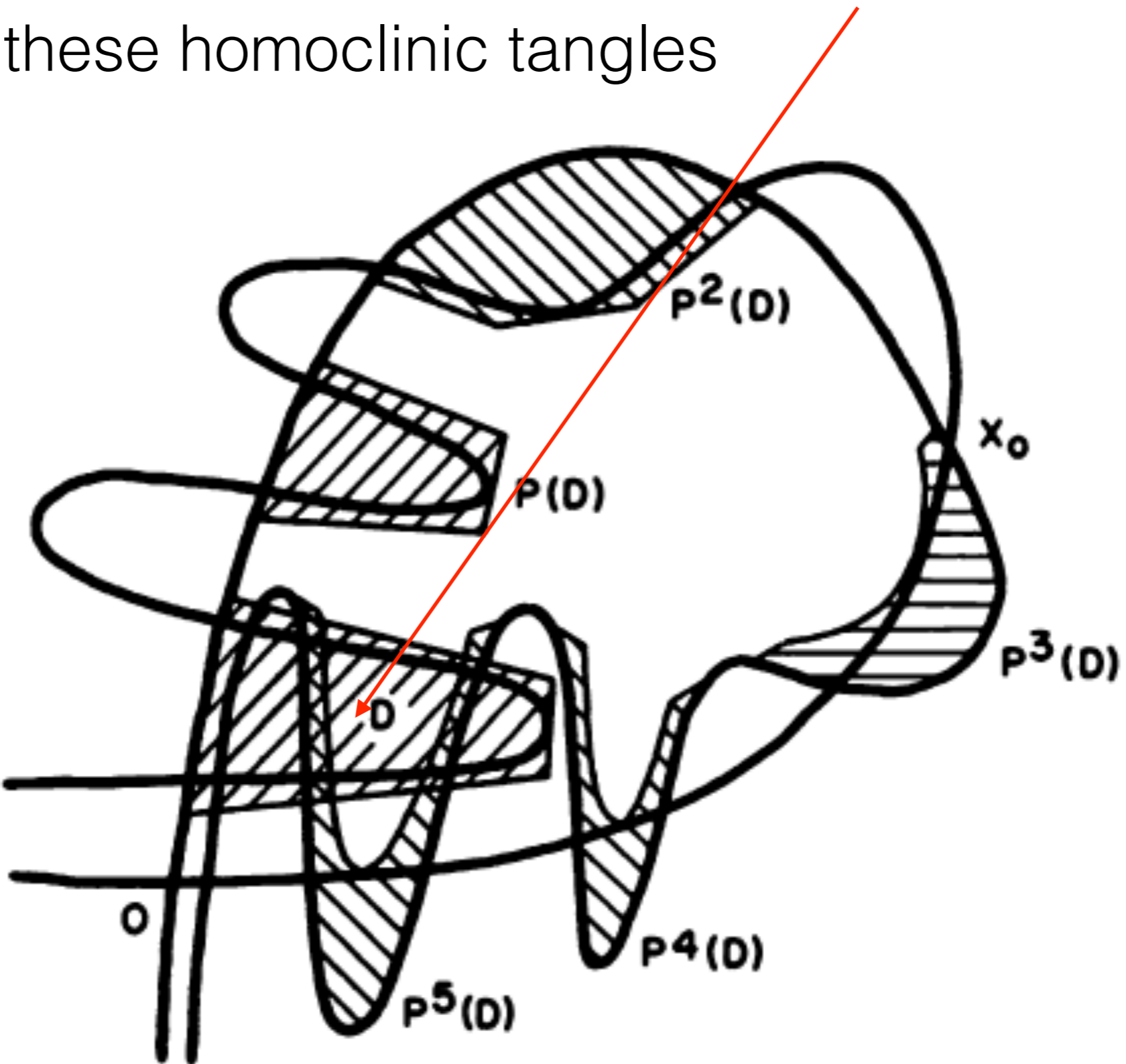
Assume that the stable and unstable manifold intersect transversally at a point x_0

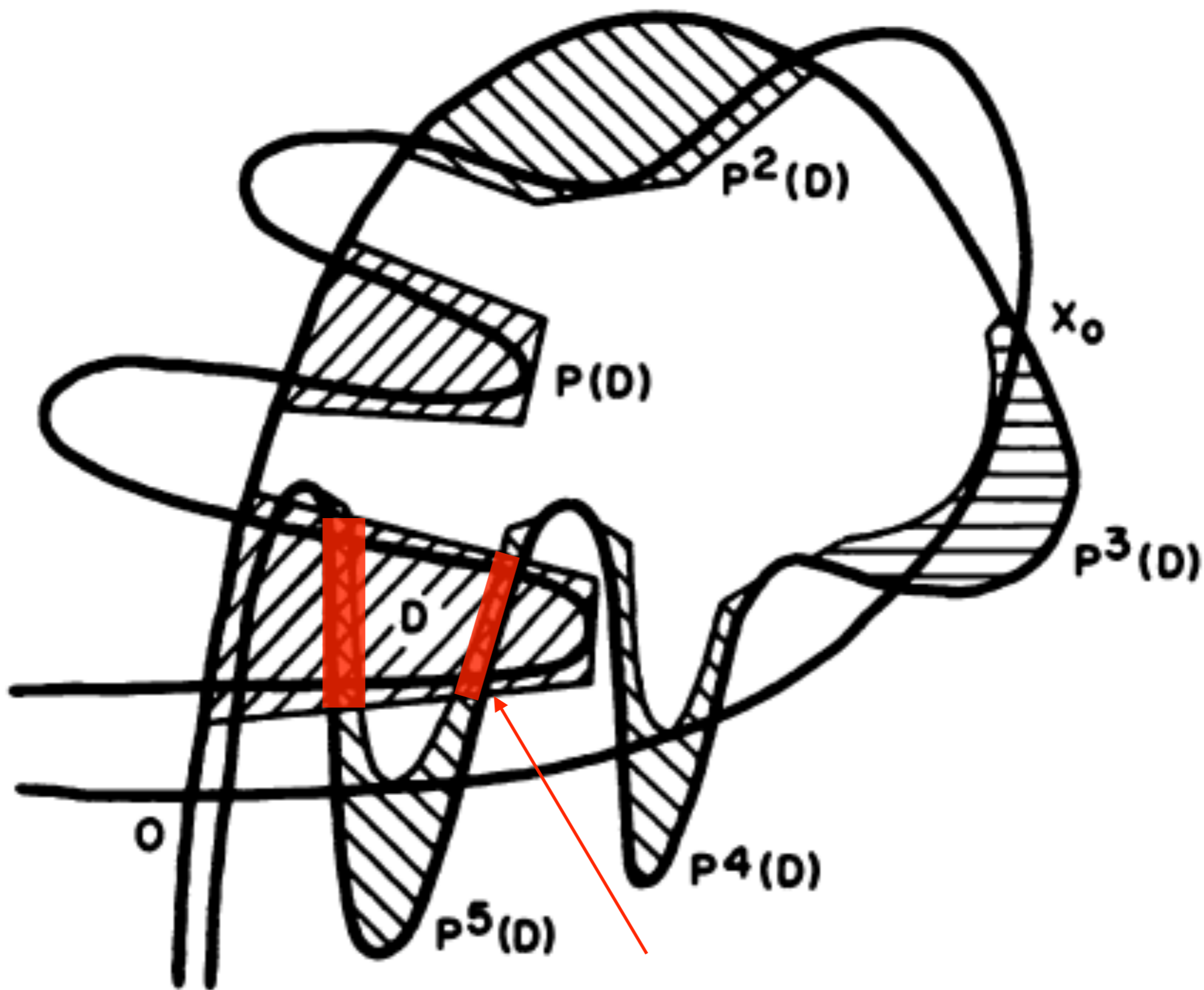


If these manifolds intersect once they MUST intersect infinitely many times



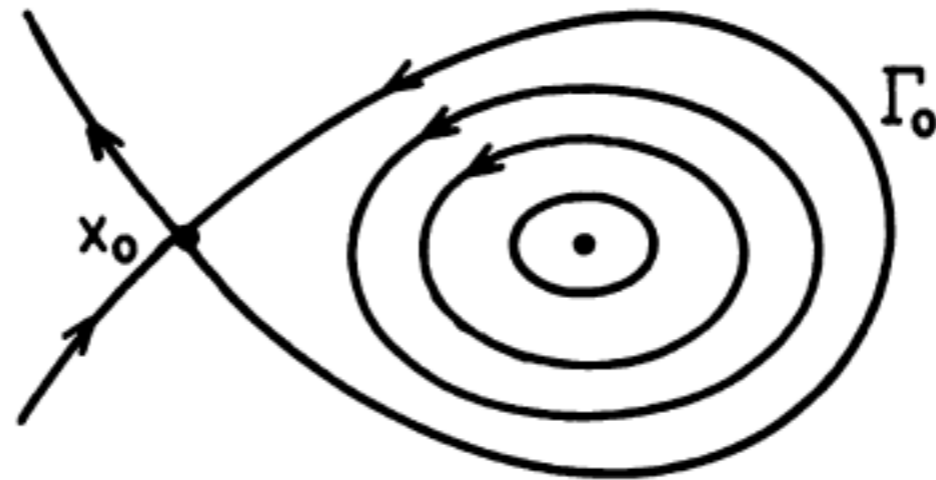
Now consider the evolution of a domain D defined by one of these homoclinic tangles



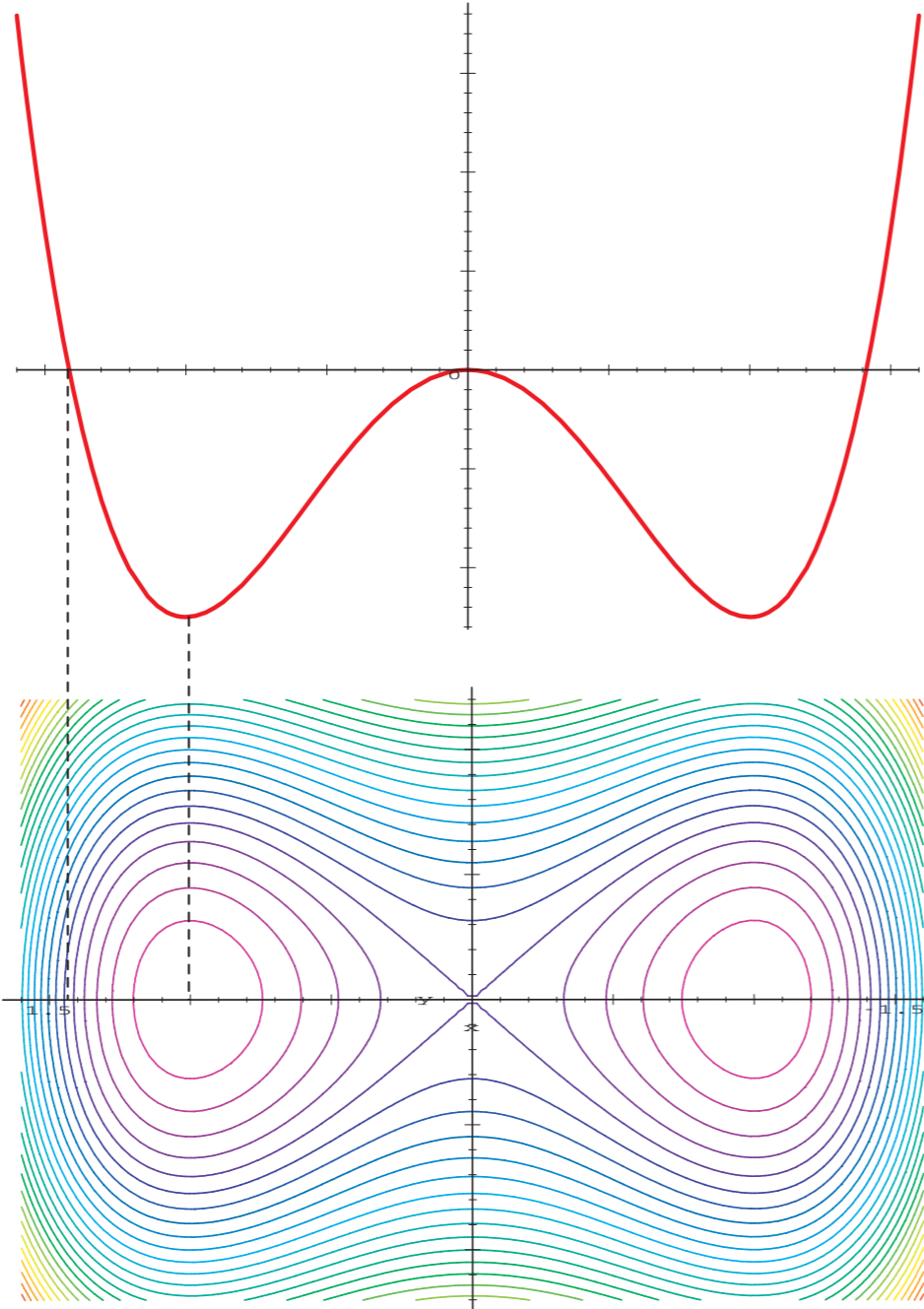


Intersection of D and $P^5(D)$

4. MELNIKOV'S METHOD



Duffing equation



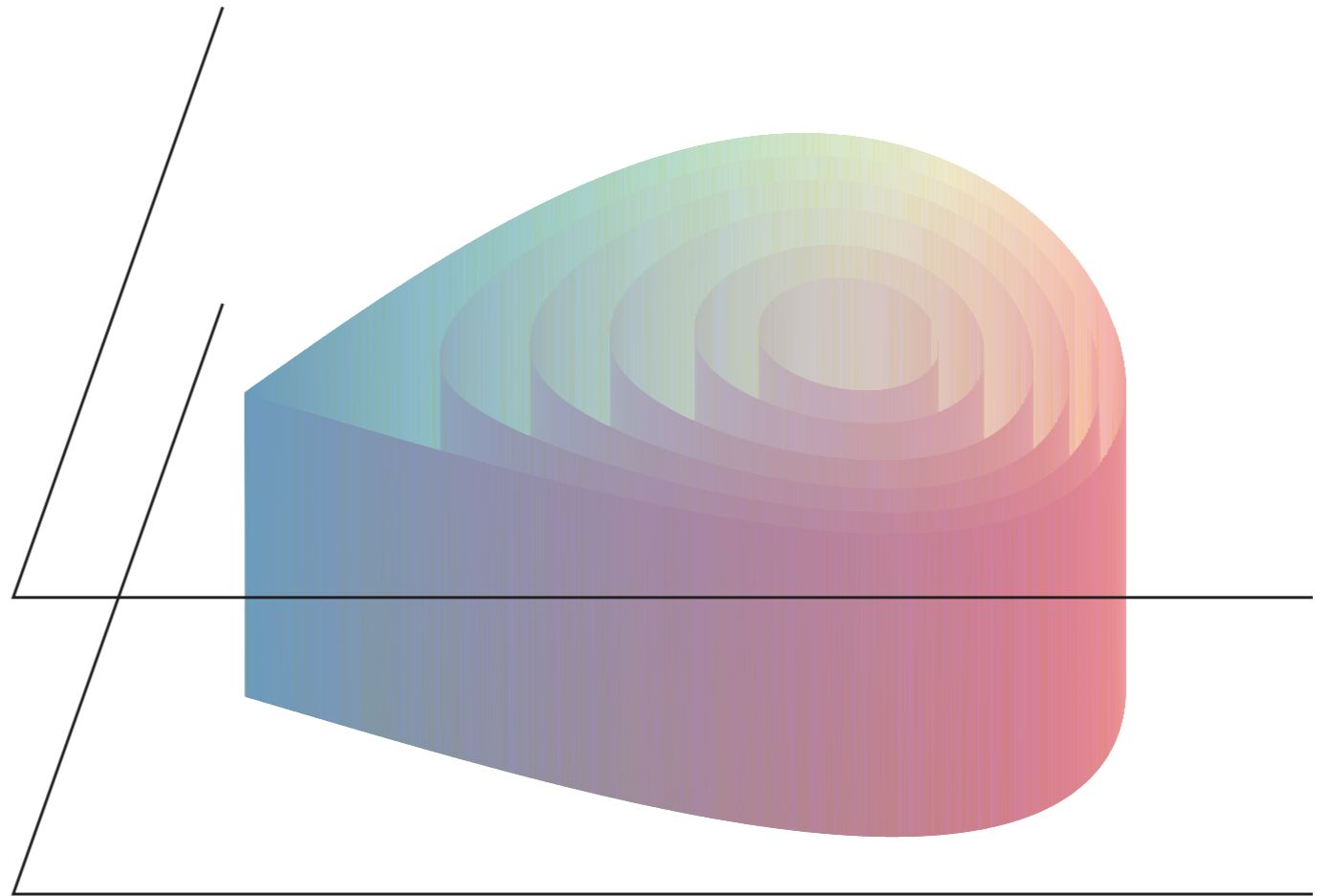
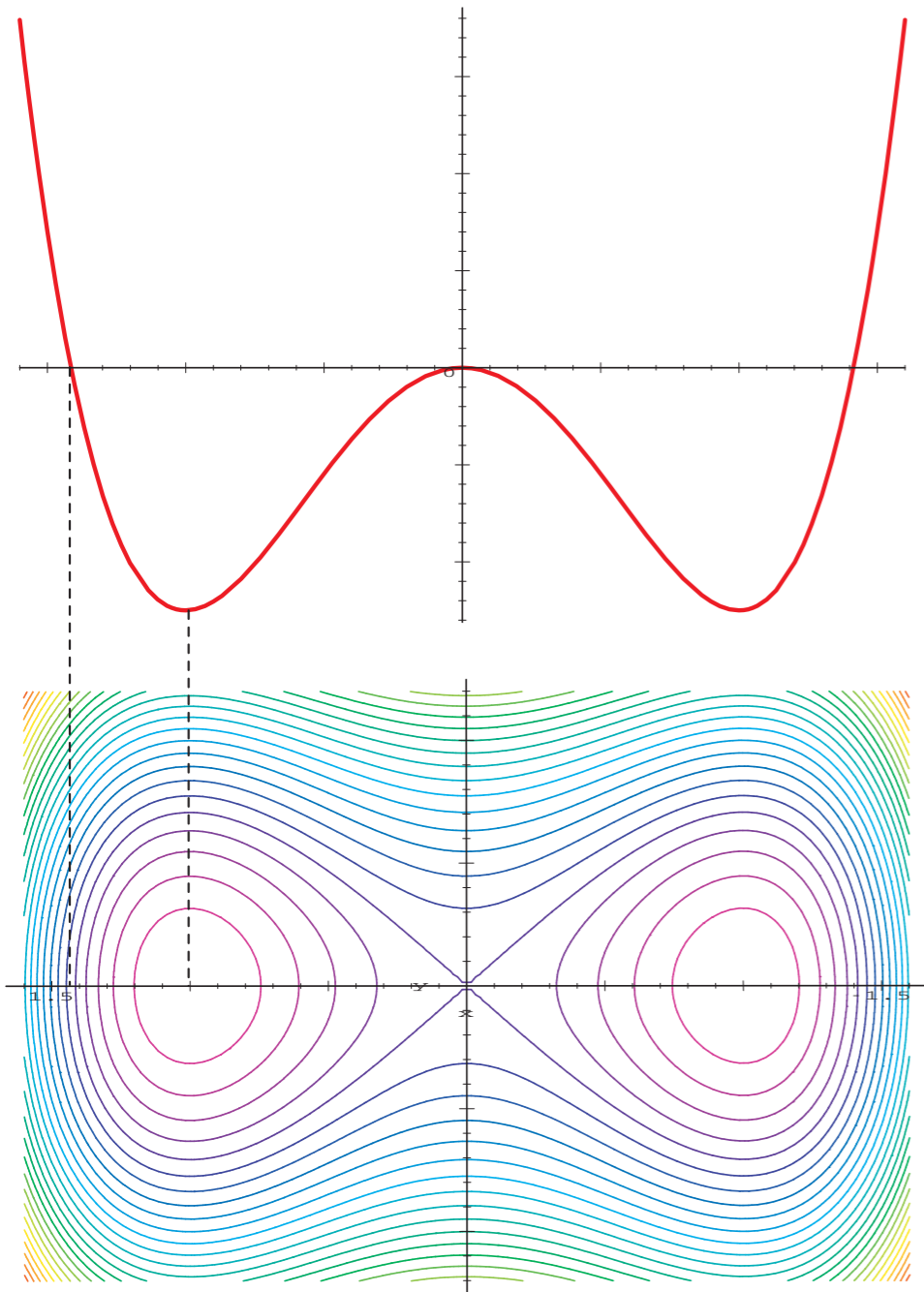
$$\ddot{x} = -\text{grad } V,$$

$$\ddot{x} - x + x^3 = 0.$$

Duffing equation

$$\ddot{x} = -\text{grad } V,$$

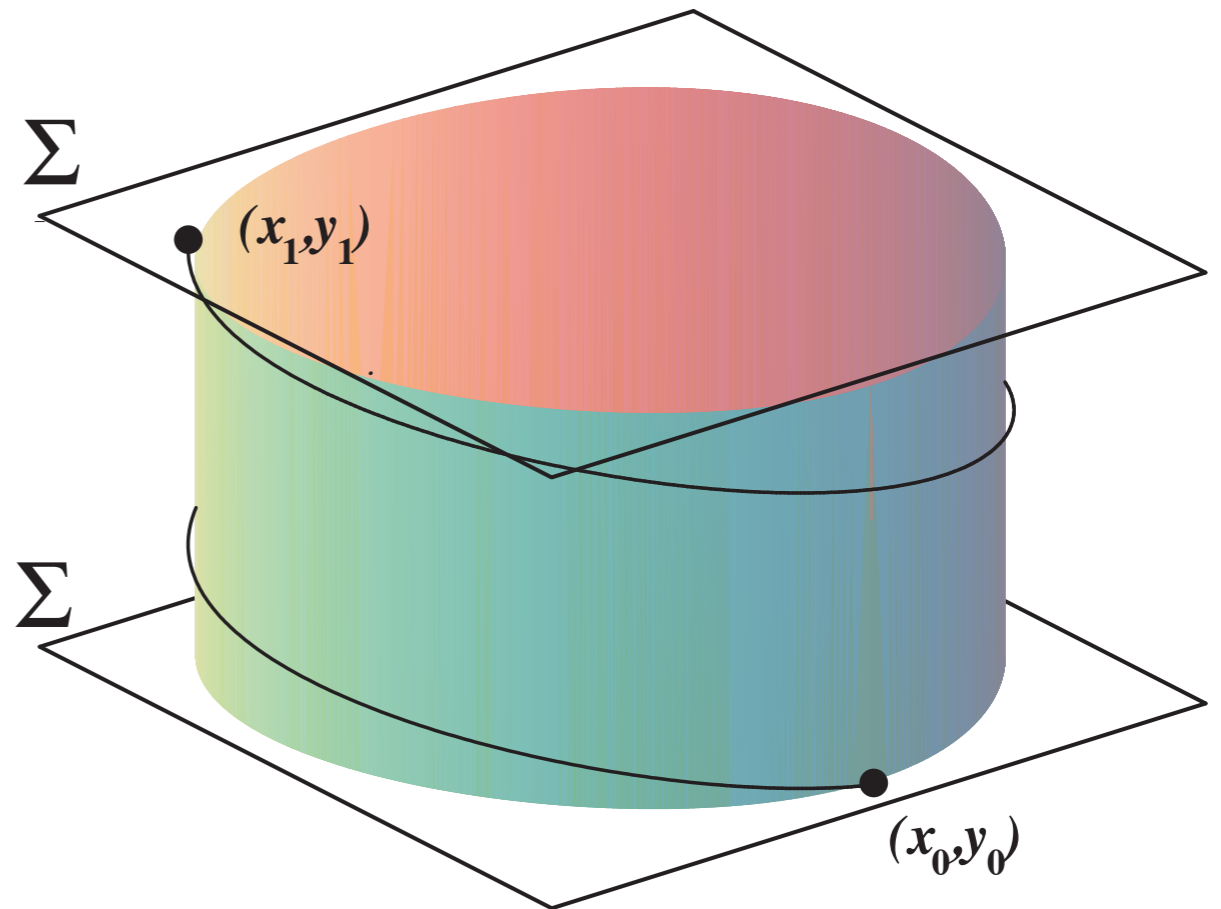
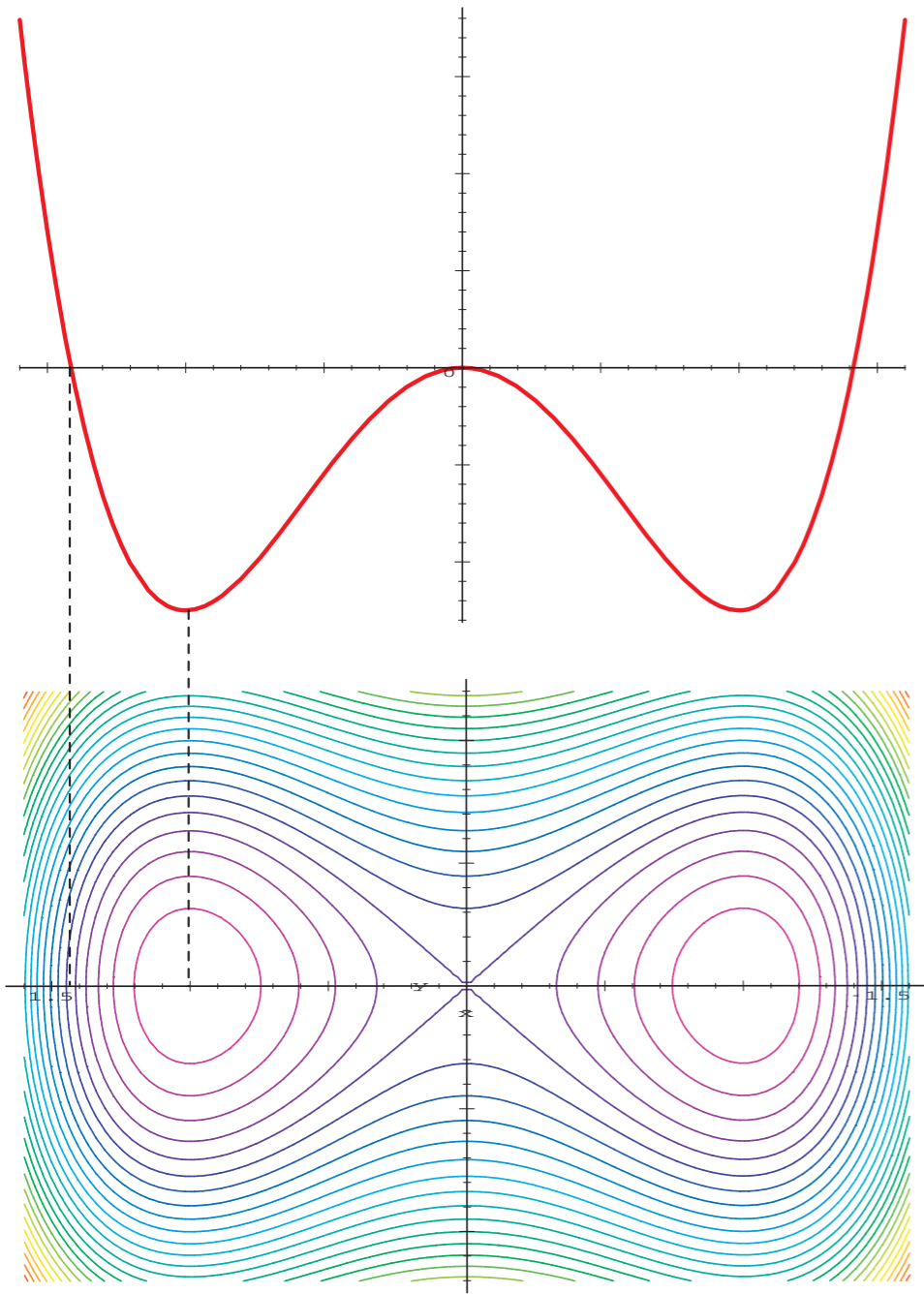
$$\ddot{x} - x + x^3 = 0.$$



Duffing equation

$$\ddot{x} = -\text{grad } V,$$

$$\ddot{x} - x + x^3 = 0.$$

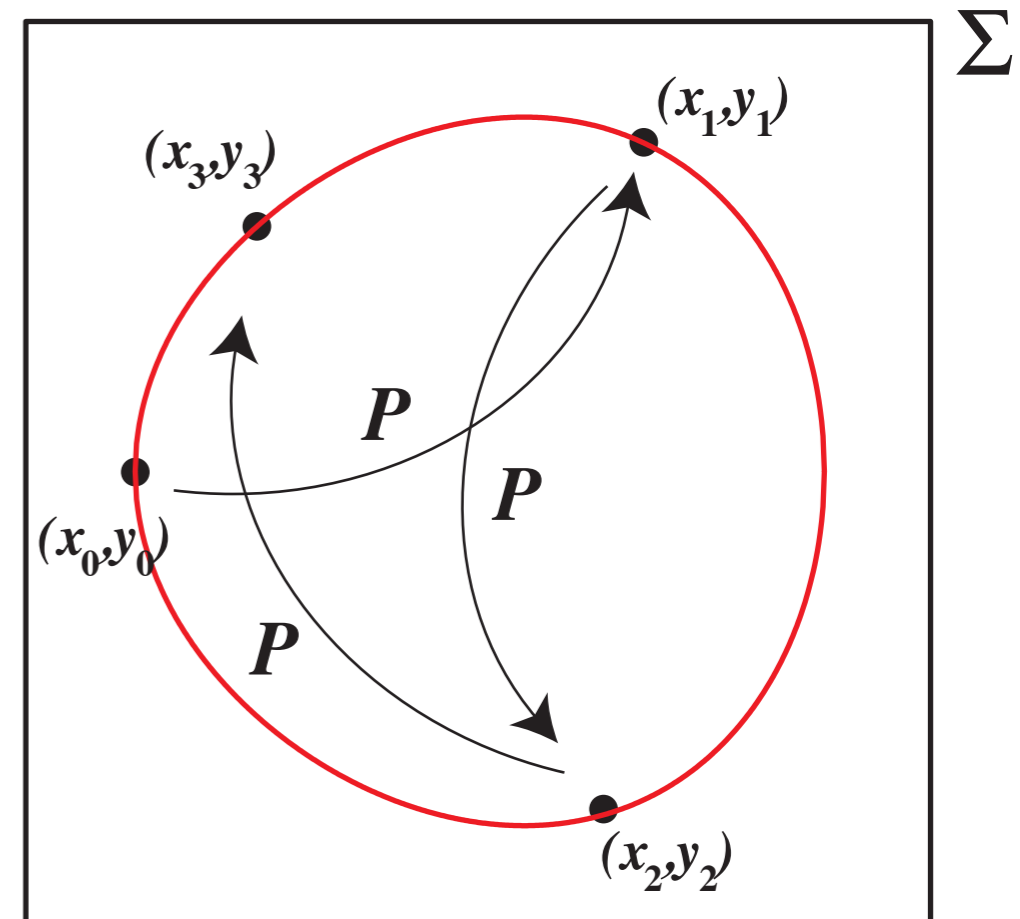
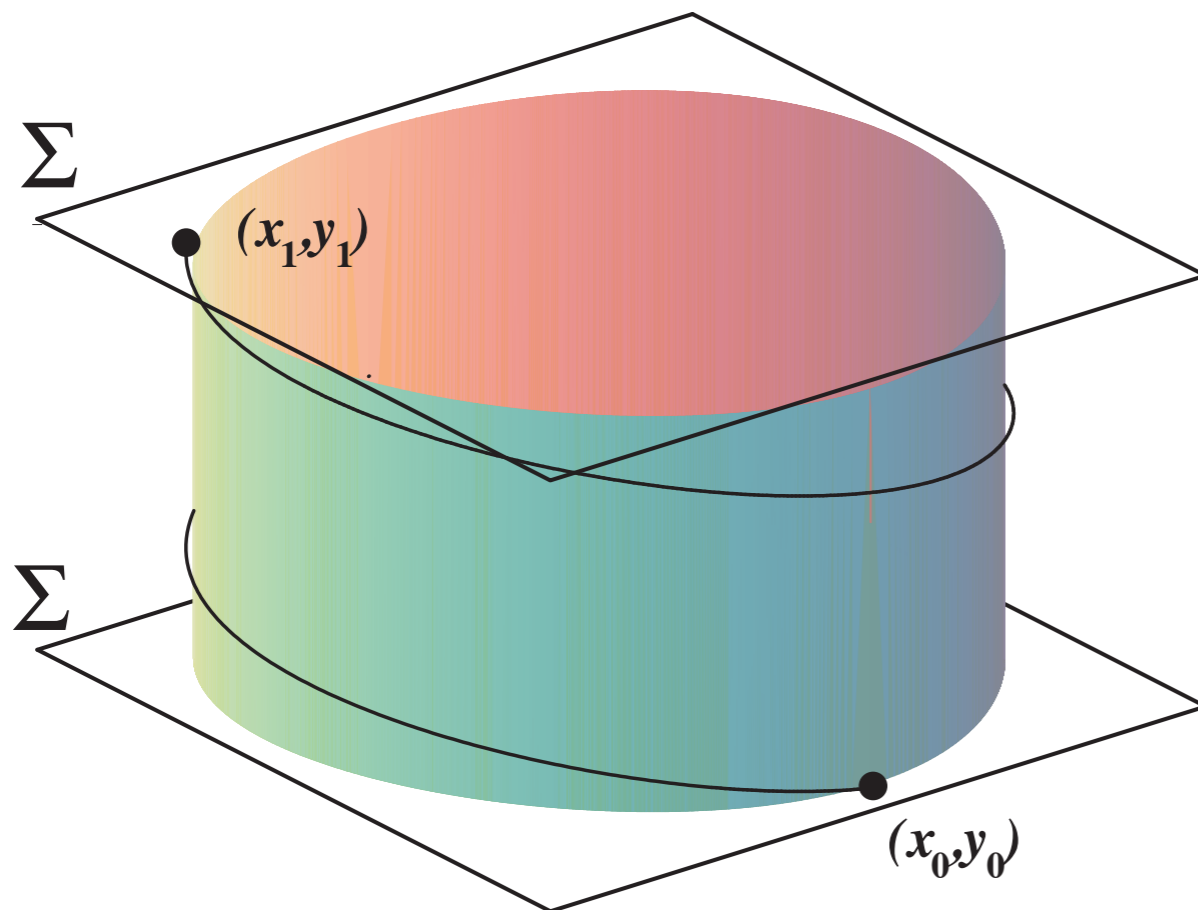


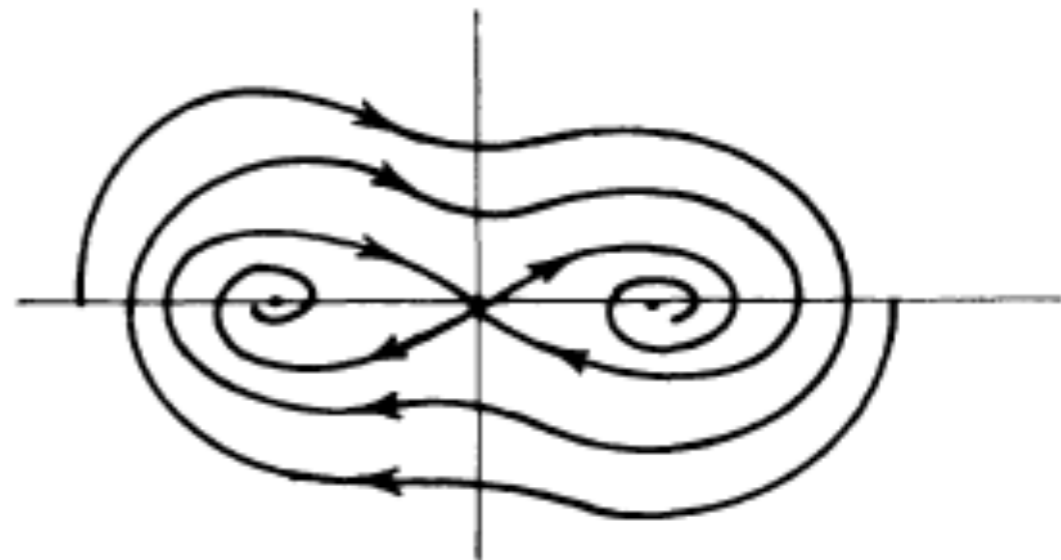
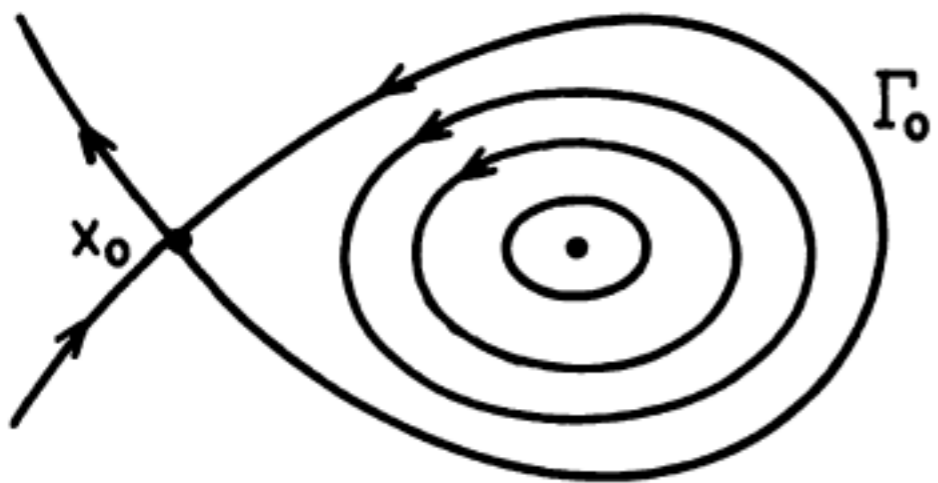
Duffing equation

$$\ddot{x} = -\text{grad } V,$$

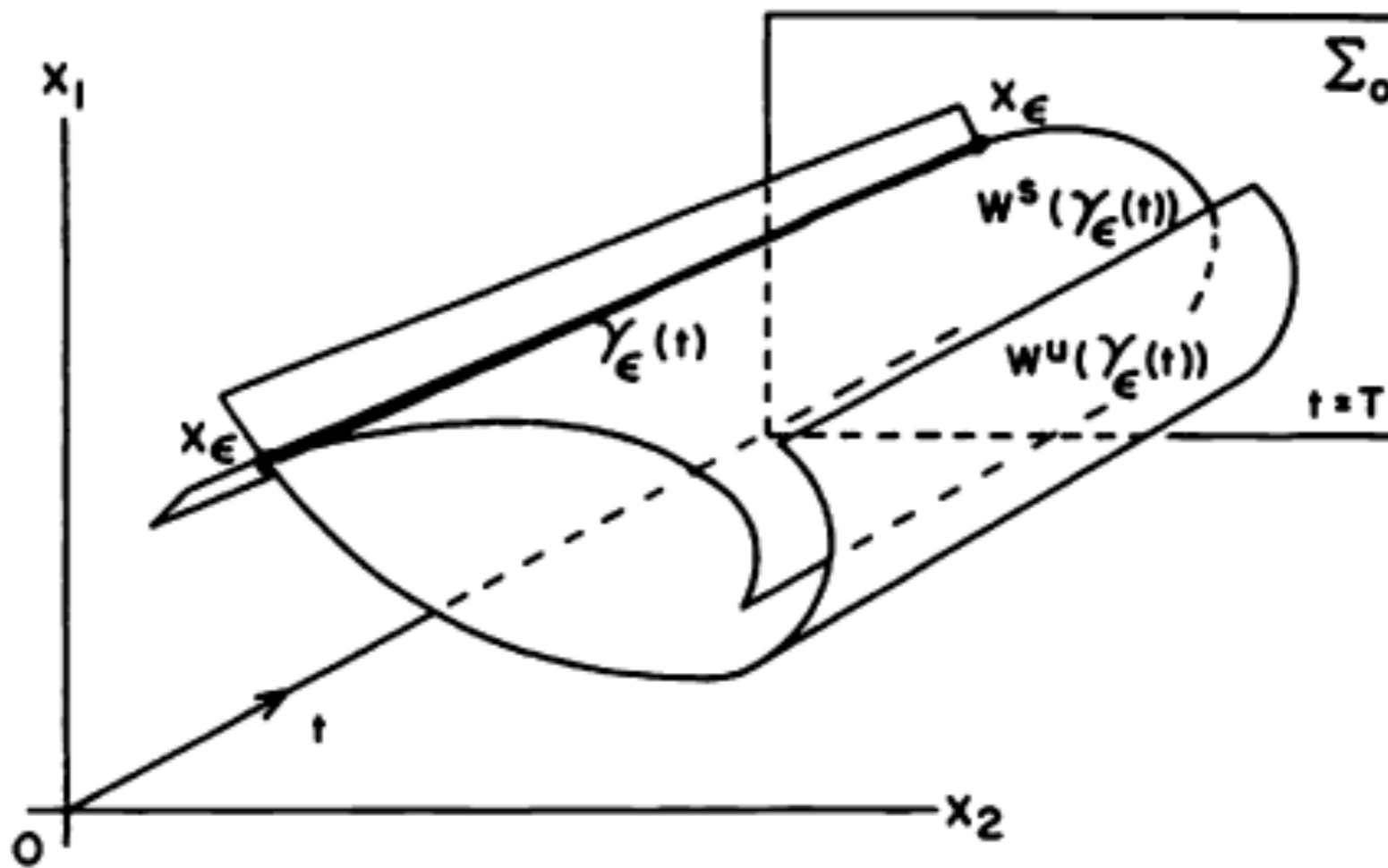
Poincaré map
for the unperturbed system

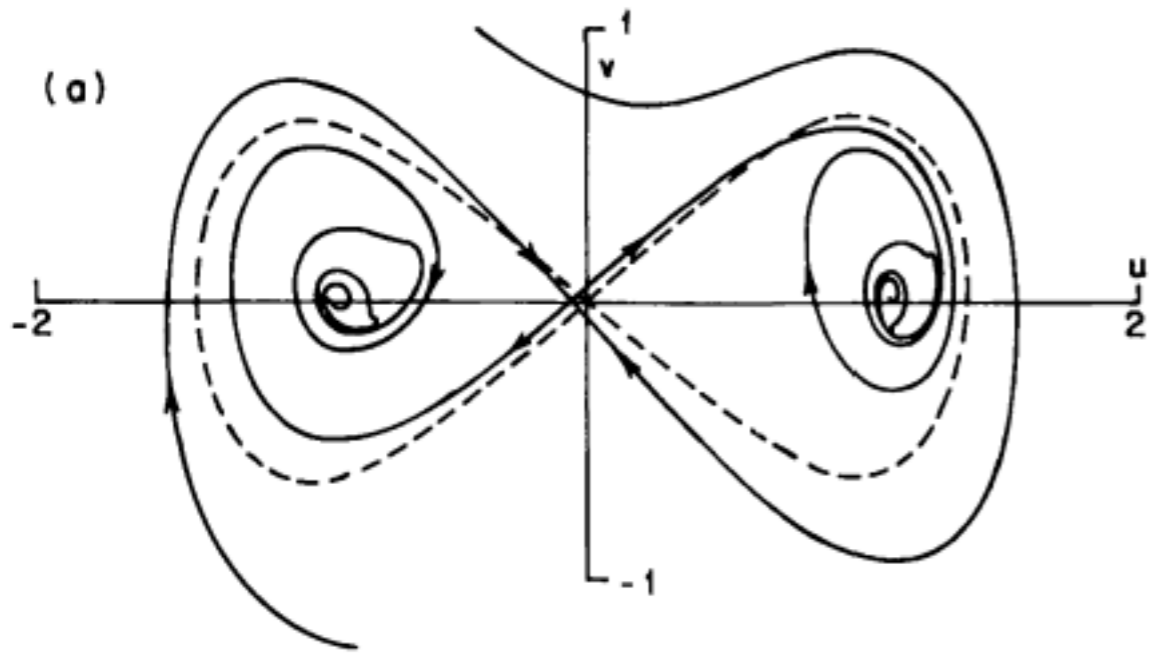
$$\ddot{x} - x + x^3 = 0.$$



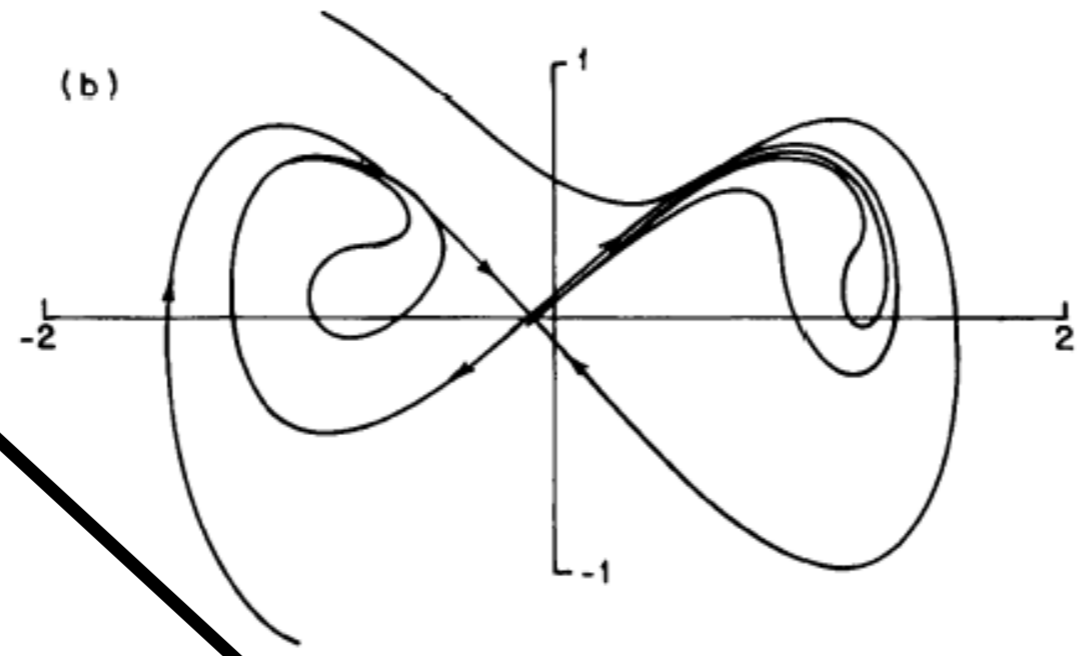


With perturbation

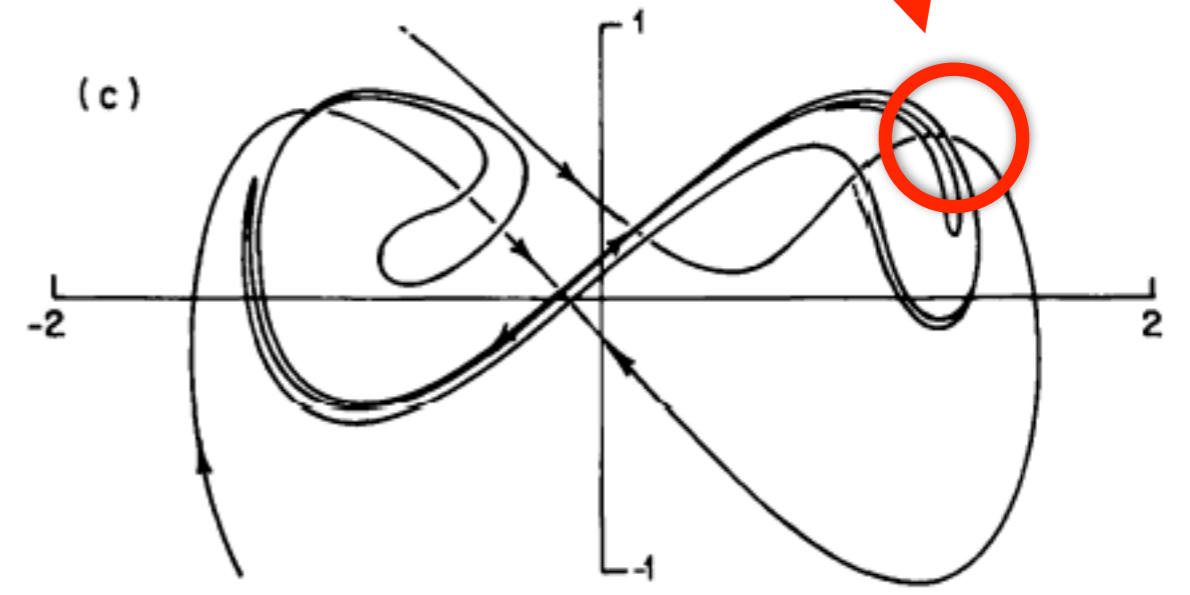




$$x''(t) + \delta x'(t) + x(t)^3 - x(t) = \gamma \cos(t)$$

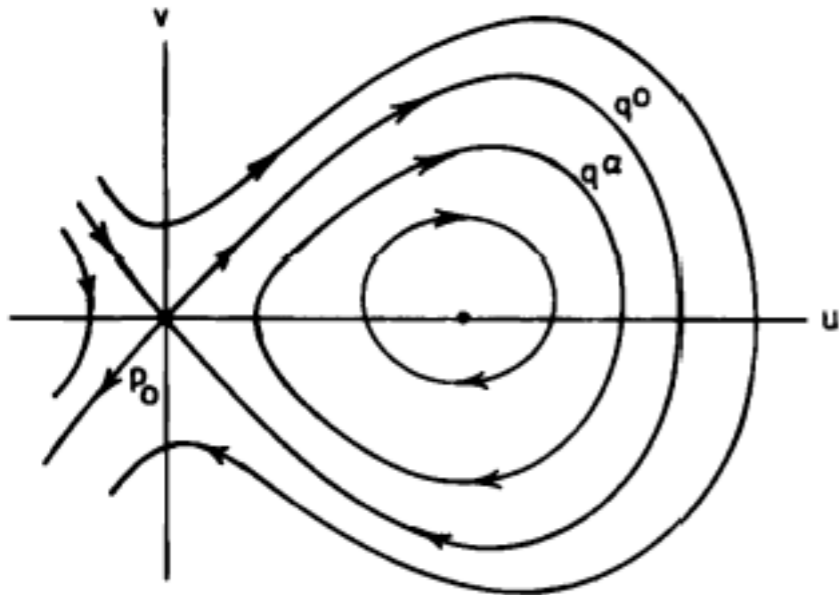


Transverse intersection

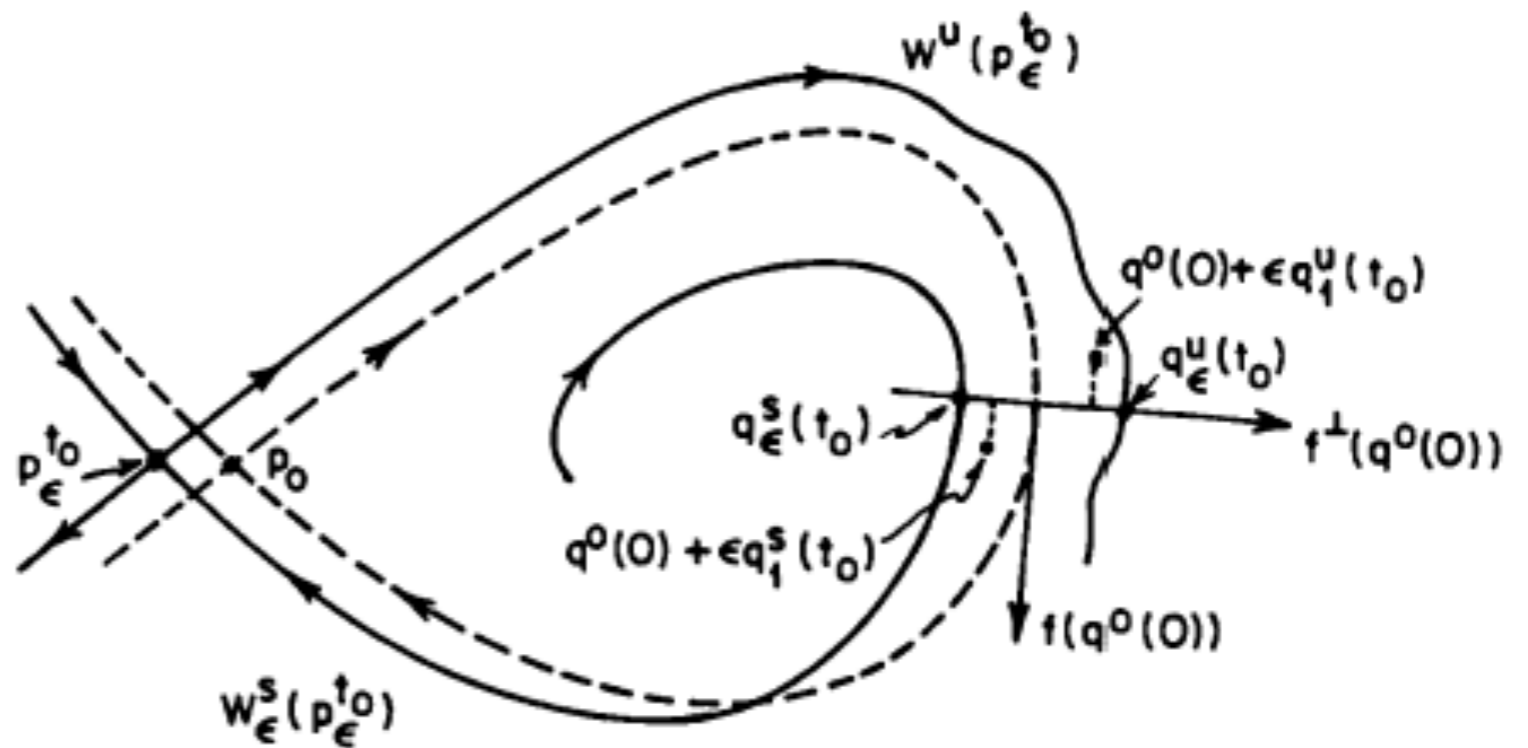


gamma increasing

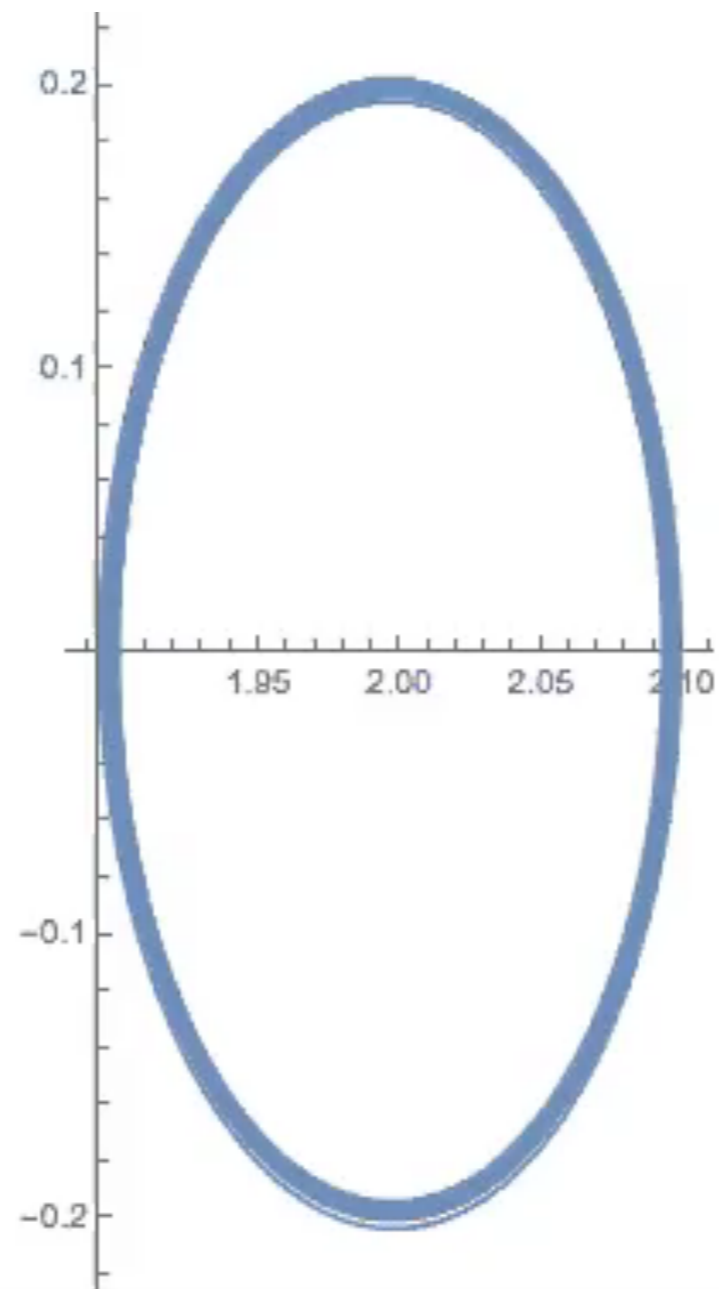
Melnikov's method



Measure separation distance between stable and unstable manifold

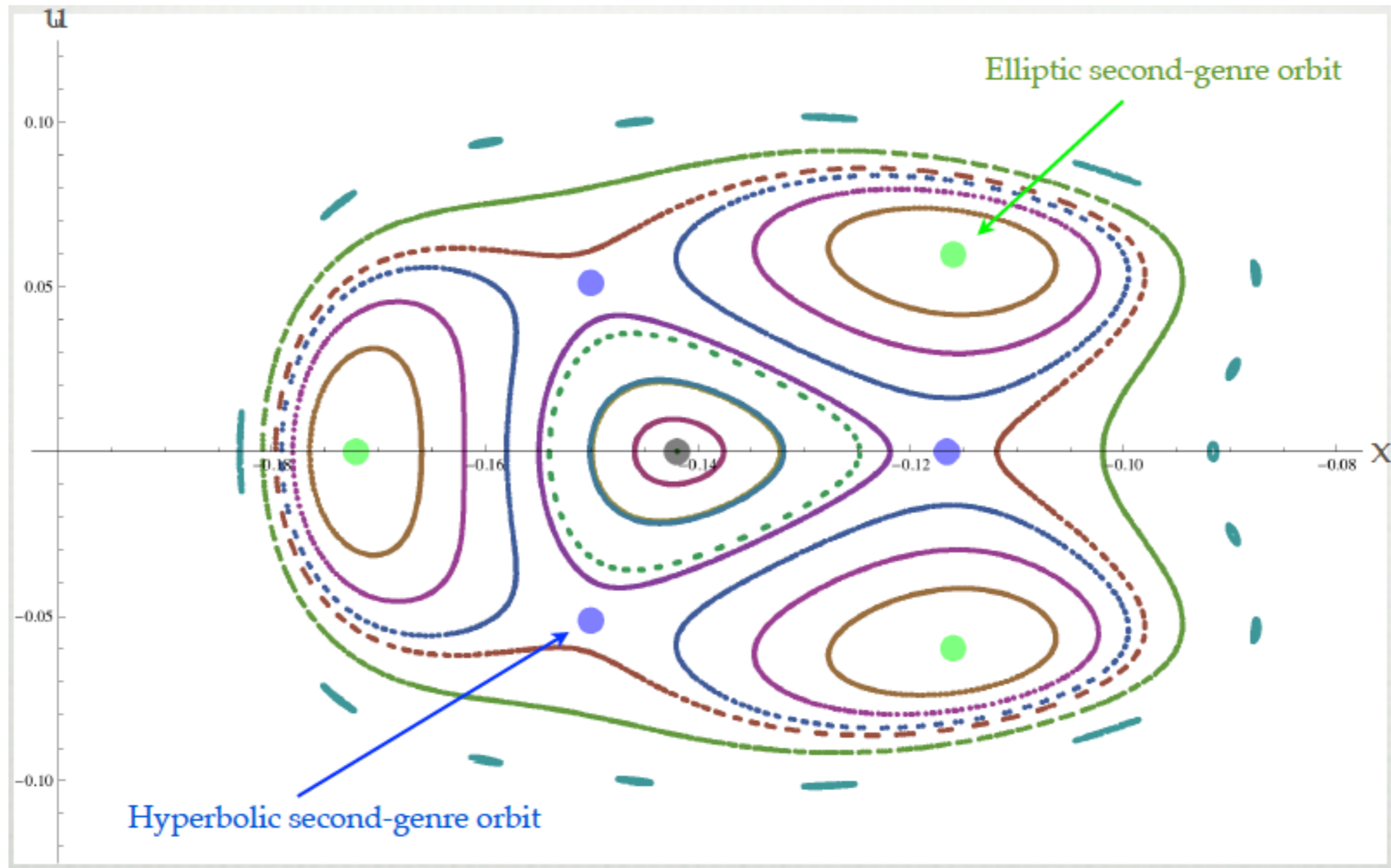


- $$x''(t) + \delta x'(t) + x(t)^3 - x(t) = \gamma \cos(t)$$



Transverse homoclinic
in celestial mechanics

Poincaré section



Study guidelines

- Examinable material=synopsis (the one online)
- Methods:
 - Linear stability analysis (study of Jacobian matrix)
 - Centre manifold reduction (computing manifold and dynamics on manifold)
 - Lyapunov and first integrals (stability and level set)
 - One-degree-of-freedom system (drawing phase portrait from V)
 - bifurcation for flows and maps (identifying the bifurcation: saddle node, transcritical, pitchfork, hopf, period doubling)
 - analysis of one-dimensional maps (fixed point, periodic orbits)
 - Melnikov's method (computing transverse intersection)

Study guidelines

- Examinable material=synopsis (the one online)
Reproduced below:

Course Synopsis:

1. Geometry of linear systems

Basic concepts of stability and linear manifold of solutions. Orbits in phase-space, linear flows, eigenvalues of fixed points.

2. Geometry on nonlinear systems

Notion of flows, invariant sets, asymptotic sets, attractor. Conservative and Non-Conservative systems.

3. Local analysis

Stable manifold theorem, notion of hyperbolicity, center manifold.

4. Bifurcation.

Bifurcation theory: codimension one normal forms (saddle-node, pitchfork, trans-critical, Hopf).

5. Maps

Poincaré sections and first-return maps. Stability and periodic orbits; bifurcations of one-dimensional maps, period-doubling.

6. *Chaos

Maps: Logistic map, Bernoulli shift map, symbolic dynamics, Smale's Horseshoe Map. Melnikov's method. Differential equations: Lorenz equations, Rossler equations.

We have covered it all (except for the Rossler equations, which are not part of the examinable material)

Study guidelines

- Examinable material=synopsis (the one online)
- Concepts and definition:
 - Linear spaces; stable, unstable, centre manifolds
 - Attractor and attracting sets, notions of stability
 - Linear stability theorem, hyperbolic fixed points
 - Notion of bifurcation
 - Poincaré maps, period doubling
 - Orbits: fixed point, periodic, limit cycle non-periodic, homoclinic
 - Shift map, horseshoe, chaotic system